



## Master Informatique EID2

## Deep Learning TP 3 – Cartes Auto-Organisatrices

```
1 #@title Importation library
2 import pandas as pd
3 from sklearn.cluster import KMeans
4 import numpy as np
5 from sklearn import datasets
6 import random
7 import matplotlib.pyplot as plt
```

Som n'existe pas en python, il a fallu trouver une library proche de celle de Matlab

```
1 #@title Telechargement de SOMPY
                                                         Telechargement de SOMPY
      2 !git clone https://github.com/sevamoo/SOMPY/
     Cloning into 'SOMPY'...
     remote: Enumerating objects: 3, done.
     remote: Counting objects: 100% (3/3), done.
     remote: Compressing objects: 100% (3/3), done.
     remote: Total 909 (delta 0), reused 0 (delta 0), pack-reused 906
     Receiving objects: 100% (909/909), 10.12 MiB | 5.52 MiB/s, done.
     Resolving deltas: 100% (492/492), done.
1 #@title Importation library Sompy
                                                   Importation library Sompy
2 import sompy.sompy as sp
3 from sompy.visualization import *
4 import sompy.normalization as norm
5 from sklearn import preprocessing
                                                   Importation library Sompy
1 #@title Importation library Sompy
2 import sompy.sompy as sp
3 from sompy.visualization import *
4 import sompy.normalization as norm
5 from sklearn import preprocessing
                                                   Chargement des Donnés Iris
1 #@title Chargement des Donnés Iris
2 iris = datasets.load_iris()
```

```
1 #@title Apprentissage par default
 2 sm = sp.SOMFactory.build(irisdata,
                            mapsize,
 4
                            mask=None,
                            mapshape='planar',
 5
 6
                            lattice='rect',
 7
                            normalization='var',
                            initialization='pca',
 8
g
                            neighborhood='gaussian
10
                            training='batch',
11
                            name='sompy')
12 sm.train(n_job=1, verbose='info')
```

3 irisdata =iris.data
4 iristarget = iris.target
5 target\_name = iris.target\_names

6 mapsize = [30, 30]

Apprentissage par default

```
Training...
pca_linear_initialization took: 0.015000 seconds
Rough training...
radius_ini: 4.000000 , radius_final: 1.000000, trainlen: 180
epoch: 1 ---> elapsed time: 0.137000, quantization error: 0.469287
epoch: 2 ---> elapsed time: 0.133000, quantization error: 0.408181
epoch: 3 ---> elapsed time: 0.134000, quantization error: 0.364103
 epoch: 178 ---> elapsed time: 0.132000, quantization error: 0.061476
 epoch: 179 ---> elapsed time: 0.133000, quantization error: 0.059010
 epoch: 180 ---> elapsed time: 0.134000, quantization error: 0.056352
 Finetune training...
 radius_ini: 1.000000 , radius_final: 1.000000, trainlen: 240
 epoch: 1 ---> elapsed time: 0.134000, quantization error: 0.052426
 epoch: 2 ---> elapsed time: 0.133000, quantization error: 0.051968
 epoch: 3 ---> elapsed time: 0.137000, quantization error: 0.051968
 epoch: 238 ---> elapsed time: 0.132000, quantization error: 0.051968
 epoch: 239 ---> elapsed time: 0.133000, quantization error: 0.051968
 epoch: 240 ---> elapsed time: 0.133000, quantization error: 0.051968
 Final quantization error: 0.051968
 train took: 58.313000 seconds
```

```
1 #@title Iris Non Normaliser
2 print('Topo errors: ',sm.calculate_topographic_error())
3 print('Quanti errors: ',sm.calculate_quantization_error())
4 print('Map errors:',sm.calculate_map_size(1))
```

Iris Non Normaliser

Topo errors: 0.0 Quanti errors: 0.021588849660151177

Map errors: [4, 16]

```
1 #@title Normalisation + Train
 2 normalized_iris = preprocessing.normalize(irisdata)
 3 som = sp.SOMFactory.build(normalized_iris,
 4
                              mapsize,
 5
                              mask=None,
 6
                              mapshape='planar',
                              lattice='rect',
 7
 8
                              normalization='var',
 9
                              initialization='pca',
 10
                              neighborhood='gaussian',
 11
                              training='batch',
12
                              name='sompy')
13 som.train()
```

Normalisation + Train

```
Training...
pca_linear_initialization took: 0.017000 seconds
Rough training...
radius_ini: 4.000000 , radius_final: 1.000000, trainlen: 180
epoch: 1 ---> elapsed time: 0.133000, quantization error: 0.353632
epoch: 2 ---> elapsed time: 0.133000, quantization error: 0.248149
epoch: 3 ---> elapsed time: 0.134000, quantization error: 0.204631
epoch: 178 ---> elapsed time: 0.134000, quantization error: 0.034656
epoch: 179 ---> elapsed time: 0.145000, quantization error: 0.033172
epoch: 180 ---> elapsed time: 0.132000, quantization error: 0.031627
Finetune training... radius_ini: 1.000000 , radius_final: 1.000000, trainlen: 240
epoch: 1 ---> elapsed time: 0.132000, quantization error: 0.030082
epoch: 2 ---> elapsed time: 0.134000, quantization error: 0.030196
epoch: 3 ---> elapsed time: 0.133000, quantization error: 0.030086
epoch: 238 ---> elapsed time: 0.132000, quantization error: 0.030196
epoch: 239 ---> elapsed time: 0.134000, quantization error: 0.030086
epoch: 240 ---> elapsed time: 0.138000, quantization error: 0.030196
Final quantization error: 0.030196
train took: 57.949000 seconds
```

```
1 #@title Iris Normalisée
2 print('Topo errors: ',som.calculate_topographic_error())
3 print('Quanti errors: ',som.calculate_quantization_error())
4 print('Map errors:',som.calculate_map_size(1))
```

Iris Normalisée

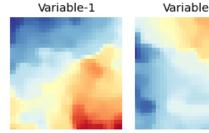
Topo errors: 0.62

Quanti errors: 0.01281660394981175

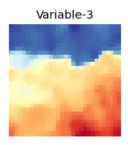
Map errors: [3, 21]

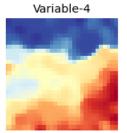
```
1 #@title Visualisation des variables
2 v = mapview.View2DPacked(50, 50, 'test', text_size=12)
3 v.show(sm)
```

Visualisation des variables



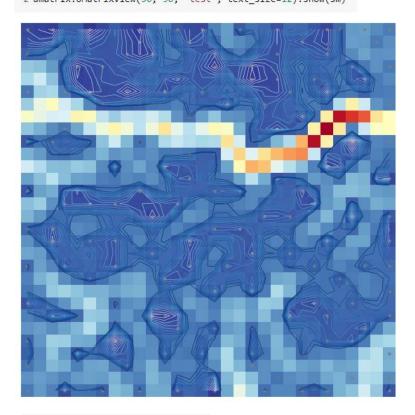






1 #@title Umatrix
2 umatrix.UMatrixView(50, 50, 'test', text\_size=12).show(sm)

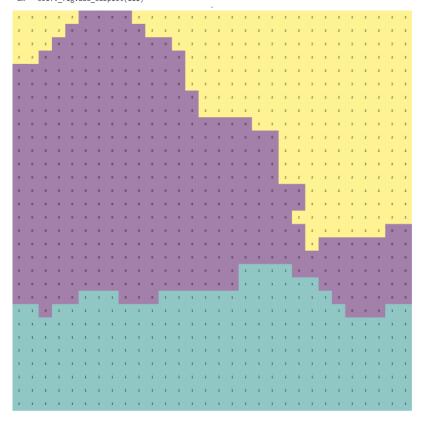
Umatrix



1 #@title Visualisation Hitmap
2 v = hitmap.HitMapView(50,50,'iris')
3 v.show(sm)

Visualisation Hitmap

content/sompy/visualization/hitmap.py:37: MatplotlibDeprecationWarning: Adding an axes using the s
ax = self.\_fig.add\_subplot(111)



1	#@title Clustering Kmeans
2	<pre>c = sm.cluster(n_clusters=3)</pre>
3	print(c)

## Clustering Kmeans

1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1
1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1
1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1
1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1
1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1
1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	0	1	1	1	1	1	1	1	1	1
1	1	1	1	1	1	1	1	1	1	1	1	0	0	0	1	1	0	0	0	0	0	1	1	1	0	0	0	1	1	1	1	1	1	1	1
1	1	1	1	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	1	1	1	1	1	0	0	0
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	1	1	1	0	0	0	0	0	0	0	0	0	0	0	0
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0	0	0	0	2	2	2	2	2	2	0	0	0	0	0	0			0						0	0	0	0	0	0	0	0	0	2	2	2
2	2	2	2	2	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	2	2	2	2	2	2	2	2	0
0	0	0	0	0	0	0				0	0	0	0	0	0	0	0	0	0	2	2	2	2	2	2	2	2	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0	0	2	2	2	2	2	2	2	2	2	2	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
0	0	0	0	2	2	2	2	2	2	2	2	2	2	0	0	0	0	0	0	0	0	0	0				0	0	0	0	0	0	0	2	2
2	2	2	2	2	2	2	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	2	2	2	2	2	2	2	2	2
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	2	2	2	2	2	2	2	2	2	2	2	2	0	0	0	0	0	0
0	0	0	0	0	0	0	2	2	2	2	2	2	2	2	2	2	2	2	2	2	2	2	0	0	0	0	0	0	0	0	0	0	0	0	0
2	2	2	2	2	2	2	2	2	2	2	2	2	2	2	2	0	0	0	0	0	0	0	0	0	0	0	0	0	2	2	2	2	2	2	2
2	2	2	2	2	2	2	2	2	0	0	0	0	0	0	0	0	0	0	0	0	0	2	2	2	2	2	2	2	2	2	2	2	2	2	2
2	2	2	2	0	0	0	0	0	0	0	0	0	0	0	2	2	2	2	2	2	2	2	2	2	2	2	2	2	2	2	2	2	2	2	0
0	0	0	0	0	0	0	2	2	2	2	2	2	2	2	2	2	2	2	2	2	2	2	2	2	2	2	2	2	0	0	0	0	0	0	2
2	2	2	2	2	2	2	2	2	2	2	2	2	2	2	2	2	2	2	2	2	2	2	0	0	0	0	2	2	2	2	2	2	2	2	2
2	2	2	2	2	2	2	2	2	2	2																									
	1 1 1 1 1 1 1 0 0 0 0 2 0 0 2 0 0 2 0 2	$\begin{array}{cccccccccccccccccccccccccccccccccccc$																																	