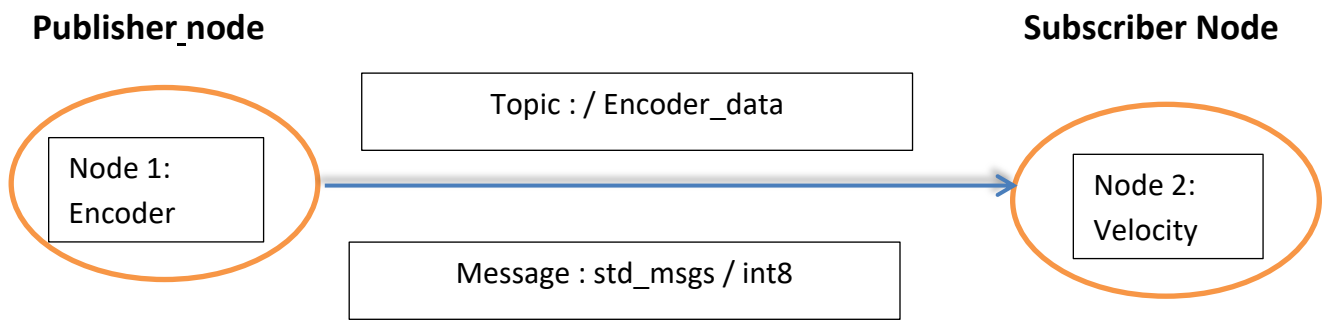


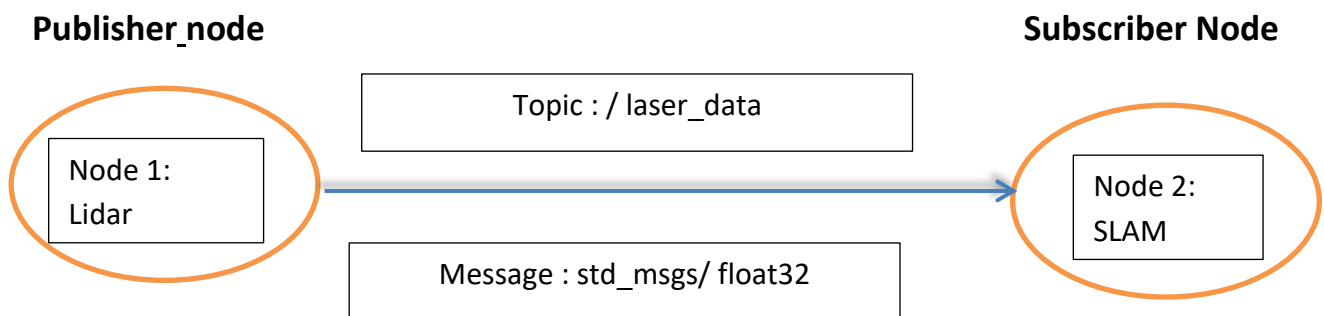
ROS Course Task 4

Task 4.2:

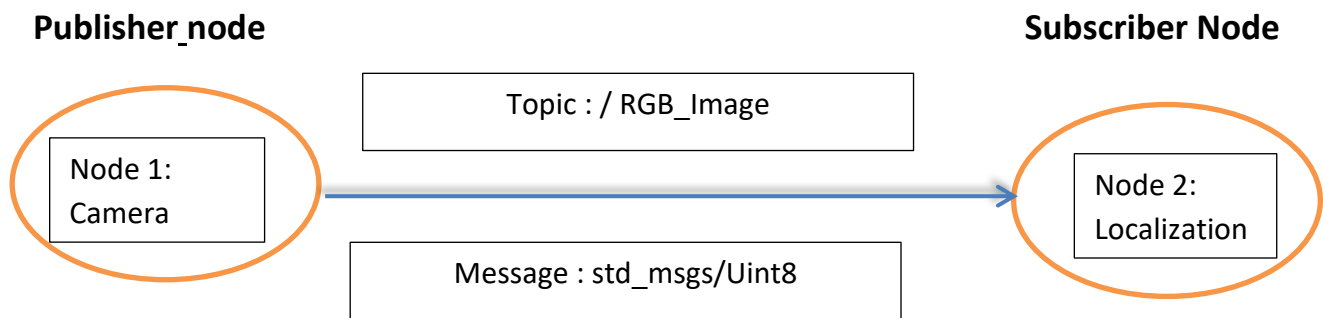
Case 1: Robot moves and publish encoder data to velocity node



Case 2: Lidar sending laser data to SLAM Node



Case 3: Publishing RGB images from camera to Localization Node



Case 4: Publishing IMU Data to Pose estimation & Localization Nodes

