

### Robot Programming

### Compilers and Build Systems

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### **Programs**

### Piece of software executed by

- An interpreter program (Interpreters)
- An emulator program (Virtual Machine)
- Directly by the CPU

For something to happen it has to be executed by the CPU.

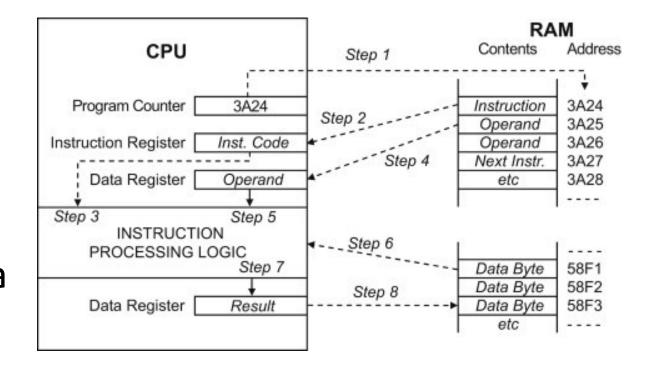
### **Machines: Native**

The CPU processes instructions sequentially

Each instruction consists of one or more binary digits

The CPU fetches instructions and operands from memory

The machine instructions have a 1 to 1 correspondence with architecture specific alphanumeric opcodes (Assembly language)



### **Executing Bytecode**

Some compilers/languages are designed with poerability among architectures in mind.

To this extent, they produce machine language for a virtual processor

To run these binaries, one needs a native program emulating the virtual CPU

For some code chunks the process can be done once, to generate native machine code that is then run faster (Just In time Compilation)

```
Byte Offset
                             // i = j + k
                   ILOAD j
i = j + k;
                                                0x15 0x02
if (i == 3)
                   ILOAD k
                                                0x15 0x03
   k = 0:
                   IADD
                                                0x60
                   ISTORE i
else
                                                0x36 0x01
  j = j - 1;
                   ILOAD i // if (i < 3)
                                                0x15 0x01
                   BIPUSH 3
                                                0x10 0x03
                   IF_ICMPEQ L1
                                                0x9F 0x00 0x0D
                   ILOAD i // i = i - 1
                                                0x15 0x02
                   BIPUSH 1
                                                0x10 0x01
                   ISUB
                                                0x64
                   ISTORE i
                                                0x36 0x02
                   GOTO L2
                                                0xA7 0x00 0x07
            13 L1: BIPUSH 0 // k = 0
                                                0x10 0x00
            14
                   ISTORE k
                                                0x36 0x03
            15 L2:
```

### Running an interpreter script

Interpreters are programs that directly execute a source file, performing the parsing/code execution on the spot

The execution is done **during** the parsing

#### Examples

- BASIC
- BASH
- PYTHON
- Matlab/Octave

```
giorgio@frisbi2:~$ octave-cli
GNU Octave, version 4.2.2
Copyright (C) 2018 John W. Eaton and others.
This is free software; see the source code for copying conditions.
There is ABSOLUTELY NO WARRANTY; not even for MERCHANTABILITY or
FITNESS FOR A PARTICULAR PURPOSE. For details, type 'warranty'.
Octave was configured for "x86 64-pc-linux-gnu".
Additional information about Octave is available at http://www.octave.org.
Please contribute if you find this software useful.
For more information, visit http://www.octave.org/get-involved.html
Read http://www.octave.org/bugs.html to learn how to submit bug reports.
For information about changes from previous versions, type 'news'.
octave:1> A=[1,2,3; 4,5,6]
```

## Program Files and Execution

### A program file contains

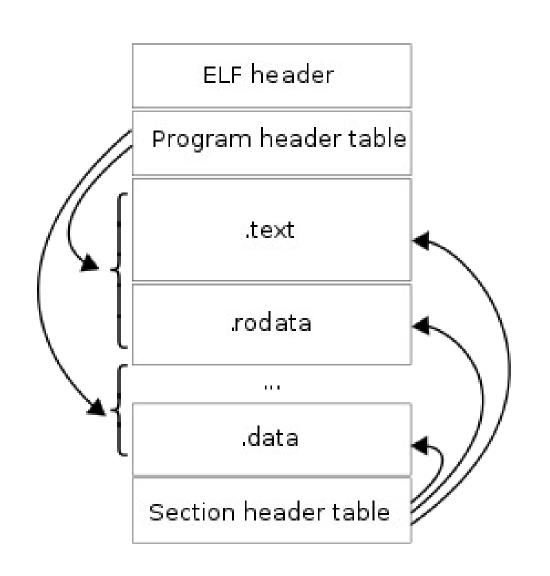
- machine code and
- meta-information

to generate a memory image suitable for CPU execution

Some OS/Environment support is needed to make a memory image of a program file.

A running program is a process.

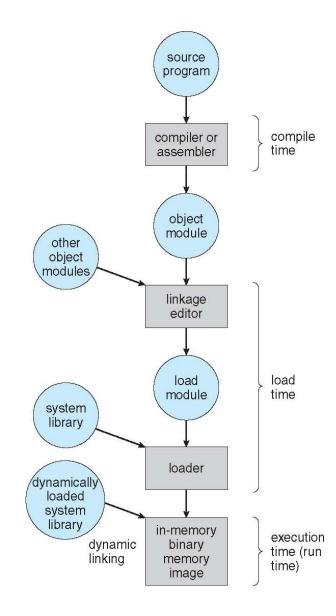
The same program file can be loaded multiple times, leading to different processes.



## Building a Program File

#### Files

- .h .hpp: Headers
- .c.cpp .S: Source Files
- .o: object files
- a: static libraries
- so: shared libraries
- Executables (no extensions on unix)
- Compiling
- Linking



## Building an Executable Program

#### Example:

- compiler+linker+assembler: g++/gcc
- Source file: hello\_world.cpp

#### Commands

- g++ <options> -c <source file>
   generates an object file from a cpp
   e.g hello\_world.cpp → hello\_world.o
- g++ <options> -o <name> <files> links together (and compiles if needed) all files in the command line to generate a program file called <name>

The same machinery holds also if the C compiler (gcc) is used

```
// hello_world.cpp
 #include <iostream>
 using namespace std;
 int main (int argc,
 const char** argv) {
   cout << "hello world" << endl;</pre>
```

# Building an Executable Program

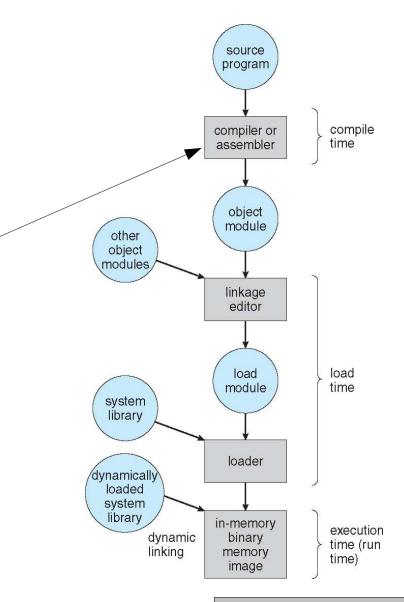
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## Building an Executable Program

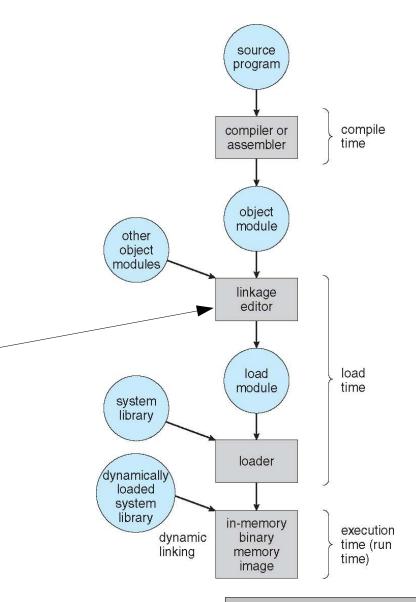
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01\_building\_a\_cpp\_program

## Running an Executable

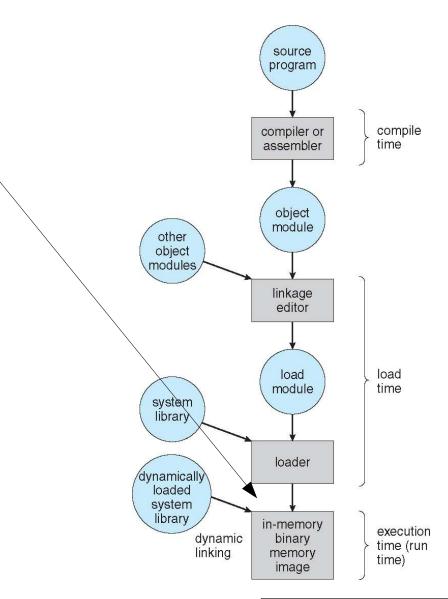
\$> hello\_world

The command shell invokes the OS to create a new process and load the process image from the disk in memory

It deals with loading the necessary shared libraryes (.so, the linux dll)

Information about which shared objects to load at runtime should be provided during the compilation process by using the option

-l <library\_name>



## Large Builds

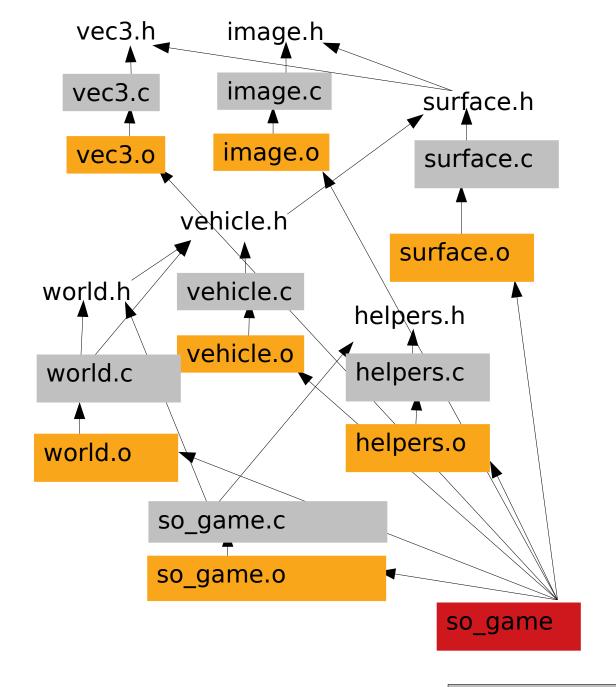
Partition the project in many files

Each file (or set of files), gets compiled in a .o

Upon change of the sources/headers, only the affected parts are recompiled and linked

#### Dependencies: each .o depends o

- the sources that are used to build it and
- the headers included by these sources



### Show the build by hand

Make a script

```
gcc -Wall -O3 -std=gnu99 -I/usr/include/GL -c -o vec3.o vec3.c
gcc -Wall -O3 -std=gnu99 -I/usr/include/GL -c -o surface.o surface.c
gcc -Wall -O3 -std=gnu99 -I/usr/include/GL -c -o image.o image.c
gcc -Wall -O3 -std=gnu99 -I/usr/include/GL -c -o vehicle.o vehicle.c
gcc -Wall -O3 -std=gnu99 -I/usr/include/GL -c -o world.o world.c
gcc -Wall -O3 -std=gnu99 -I/usr/include/GL -c -o helpers.o helpers.c
gcc -Wall -O3 -std=gnu99 -I/usr/include/GL -c -o so_game.o so_game.c
gcc -Wall -O3 -std=gnu99 -I/usr/include/GL -c so_game vec3.o surface.o
image.o vehicle.o world.o helpers.o so_game.o -lglut -lGLU -lGL -lm
```

Each time a file change issue the script and compile all from scratch unacceptable (a clean build of a large project can take hours)

### Makefiles

Way to automate the build process

Made of a set of rules, triggered by the modification time

Rules in the form

<target> : [tab] <dependancies>

<tab> command

e.g

vec3.o: vec3.c vec3.h

gcc -std=gnu99 -c -o vec3.o vec3.c

Executes gcc if the modification time of vec3.o is older than the one of vec3.c or vec3.h

### Dependancies

```
With

gcc (or g++) -MM <source file> you get the "head" of the rule (target and dependancies)

Try executing

$> gcc -MM vec3.c
```

### Makefiles

```
vehicle.o: vehicle.c vehicle.h surface.h vec3.h image.h
#var declarations, expanded with $(name)
                                                                  gcc $(CCOPTS) -c -o vehicle.o vehicle.c
CC=qcc
LIBS=-lqlut -lGLU -lGL -lm
                                                             world.o: world.c world.h image.h surface.h\ vec3.h vehicle.h
INCLUDES=-I/usr/include/GL
                                                            helpers.h
                                                                 gcc $(CCOPTS) -c -o world.o world.c
CCOPTS= -Wall -O3 -std=gnu99 $(INCLUDES)
                                                            helpers.o: helpers.c helpers.h
#1st rule <head>: <dependancies>, root of tree
                                                                 gcc $(CCOPTS) -c -o helpers.o helpers.c
all: so game
                                                             so_game.o: so_game.c world.h image.h surface.h\
                                                                vec3.h vehicle.h helpers.h
#to make vec.o you need vec.h. and vec.c, bottom line
                                                                 qcc $(CCOPTS) -c -o so game.o so game.c
# is the command to execute if the rule matches
# <target> : <dependancies>
                                                             # here we call the linker
                                                             so game: vec3.o surface.o image.o vehicle.o \
             <command>
                                                               world.o helpers.o so game.o
vec3.o: vec3.c vec3.h
           qcc $(CCOPTS) -c -o vec3.o vec3.c
                                                                gcc $(CCOPTS) -o so_game vec3.o surface.o \
                                                                      image.o vehicle.o world.o helpers.o \
                                                                 so game.o $(LIBS)
surface.o: surface.c surface.h vec3.h image.h
      qcc $(CCOPTS) -c -o surface.o surface.c
                                                             clean:
                                                                rm -rf *.o *~ cube main so game
image.o:image.c image.h
      qcc $(CCOPTS) -c -o image.o image.c
```

### Makefiles

Call by issuing the following command in a folder containing a Makefile \$make

It will trigger a object dependant compilation, that verifies which rules to execute based on the modification time

Actualize the change time of **vec3.h** and check what happens by calling make again

\$touch vec3.h

\$make

Modify vec3.c, and see what happens by issiung the same command

## Dealing with External Packages

Complex projects tend to rely on other complex projects/libraries

### E.g. A simulator might rely on

- the OpenGL system to display the data,
- on a finite element simulation system to compute the dynamics
- on a linear algebra library to do some geometric calculation
- on some tool to load/save formatted files and images and so on

#### Finding the packages (specially non standard ones) might be annoying

- Different OS/distributions
- Different revisions
- Different architectures
- Different revisions of a package installed
- Packages can depend on each other

## Dealing with External Packages

#### To the extent of a C++ build, a package comes as

- A set of include files (,h, .hpp)
- A set of libraries (.so, .a)

#### In the .o generation, one needs to specify

- The include paths, that contains the .h files of the project
  - -I<path1> -I<path2>
- Potential defines, that might trigger library specific behaviors
  - -D<statement> (equivalent to #define <statement> in the source file)

#### In the linking phase, one needs to specify

- The directory of the libraries
  - -L <path>
- The libraries
  - -l-lsibname\_without\_prefix>, e.g. -lm links libm.so

# pkg-config

How to automate the retrieval of compilation parameters for the installed libraries and packages

#### Who tells you where are the library files and the includes of a package

- Hardcoding them (usually on the same OS/Release works, but expect plenty of emails)
- Automating the search (given the library package name)

#### Pkg config:

- A database consisting of text files describing the packages
- For each package the include (-I<...>) and the library (-l<...>) files are provided

#### try

```
$pkg-config --libs gl
$pkg-config --cflags gl
```

# pkg-config

\*.pc files contained in **\$PKG\_CONFIG\_PATH** variable

They contain the answer to the potential queries made by pkg config example (roscpp.pc) prefix=/opt/ros/melodic Name: roscpp Description: Description of roscpp Version: 1.14.11 Cflags: -I\${prefix}/include -I/usr/include Libs: -L\${prefix}/lib -lroscpp -lpthread /usr/lib/x86\_64-linux-gnu/libboost\_chrono.so /usr/lib/x86\_64-linuxgnu/libboost\_filesystem.so /usr/lib/x86 64-linux-qnu/libboost system.so Requires: cpp\_common message\_runtime rosconsole roscpp\_serialization roscpp\_traits rosgraph\_msgs rostime std\_msgs xmlrpcpp

## pkg-config and makefiles

```
CC=qcc # CC is our compiler, we can change later if we want
# execute pkg-config to find the libraries
LIBS=$(shell pkg-config --libs glut glu gl) -lm
INCLUDES=$(shell pkg-config --libs glut glu gl)
CCOPTS= -Wall -O3 -std=gnu99 $(INCLUDES)
OBJS=vec3.o surface.o image.o vehicle.o world.o helpers.o so game.o
.phony: clean all
all: $(OBJS)
      $(CC) $(CCOPTS) -o so game $^ $(LIBS)
# generic rule, to make a .o you need a .c and a .h of the same name
%.o:%.c %.h
     $(CC) $(CCOPTS) -c -o $0 $<
clean:
    rm -rf *.o *~ cube main so game
```

### **CMake**

#### A lot of things have been done with make/ pkgconfig

Each package should provide a .pc file

The compiler arguments/options should be canonized

Sometimes between different revisions/OSes the packages do not match and the compiler options differ

The build process might require different steps (think cross-compilation)

#### Solution:

**CMake**: a makefile generator, that requires to write less things

The dependencies are deduced from the sources (by using a compiler toolchain)

### Only tell in CmakeLists.txt

- What packages you need
- Where are your sources

#### For each target:

- The files it requires
- What are the libraries it depends from

### To compile

- \$cmake -c <path to
  CMakeLists.txt>
- \$make (from the same folder)

```
cmake_minimum_required (VERSION 2.8.11)
project (so_game)
```

```
This is the preamble

▶Defines the minimum cmake version and the project name
```

```
find package(OpenGL REQUIRED)
find package(GLUT REQUIRED)
include directories(${OPENGL INCLUDE DIRS} ${GLUT INCLUDE DIRS})
add_executable(so_game
 helpers.c image.c so_game.c
 surface.c vec3.c vehicle.c world.c
#tell the executable the libraries it needs
target_link_libraries(so_game
  ${OPENGL ql LIBRARY} #
  ${OPENGL glu LIBRARY}
  ${GLUT glut LIBRARY}
```

```
cmake minimum required (VERSION 2.8.11)
project (so game)
find package(OpenGL REQUIRED)
find package(GLUT REQUIRED)
include directories(${OPENGL INCLUDE DIRS} ${GLUT INCLUDE DIRS})
add executable (so game
 helpers.c image.c so_game.c
  surface.c vec3.c vehicle.c world.c
#tell the executable the libraries it needs
target_link_libraries(so_game
  ${OPENGL ql LIBRARY}
  ${OPENGL qlu LIBRARY}
  ${GLUT glut LIBRARY}
```

This invokes the routines to find a
 ▶ package called OpenGL.
 If found, some variables, typically
 OPENGL\_LIBRARIES and
 OPENGL\_INCLUDE\_DIR are set

If not found the generation aborts with an error

```
cmake minimum required (VERSION 2.8.11)
project (so game)
find package(OpenGL REQUIRED)
find package(GLUT REQUIRED)
include directories(${OPENGL INCLUDE DIRS}) ${GLUT INCLUDE DIRS})
add_executable(so_game
 helpers.c image.c so_game.c
 surface.c vec3.c vehicle.c world.c
#tell the executable the libraries it needs
target_link_libraries(so_game
  ${OPENGL ql LIBRARY}
  ${OPENGL glu LIBRARY}
  ${GLUT glut LIBRARY}
```

►This adds the to the include path the content of the OPENGL\_INCLUDE\_DIRS and GLUT\_INCLUDE\_DIRS set by the find package

```
cmake minimum required (VERSION 2.8.11)
project (so game)
find package(OpenGL REQUIRED)
find package(GLUT REQUIRED)
include directories(${OPENGL INCLUDE DIRS} ${GLUT INCLUDE DIRS})
add executable (so_game
 helpers.c image.c so game.c
  surface.c vec3.c vehicle.c world.c
#tell the executable the libraries it needs
target_link_libraries(so_game
  ${OPENGL ql LIBRARY}
  ${OPENGL glu LIBRARY}
  ${GLUT glut LIBRARY}
```

This defines an executable **target**, named so\_game built from the source files helpers.c... till world.c.

The dependencies between the objects, the sources and the header files are determined automatically by using the compiler toolchain (gcc -MM, in our case)

```
cmake minimum required (VERSION 2.8.11)
project (so game)
find package(OpenGL REQUIRED)
find package(GLUT REQUIRED)
include directories(${OPENGL INCLUDE DIRS} ${GLUT INCLUDE DIRS})
add executable (so game
 helpers.c image.c so game.c
  surface.c vec3.c vehicle.c world.c
#tell the executable the libraries it needs
target_link_libraries(so_game
  ${OPENGL ql LIBRARY}
  ${OPENGL qlu LIBRARY}
  ${GLUT glut LIBRARY}
 m
```

This specifies that to generate the target so\_game, certain libraries are needed.

Each item in the list will result in a flag -1 <name> appended to the command line

## **CMake: Targets**

A target is a binary executable or library.

```
add_executable (<name> <files...>)
adds an executable named <name>
```

```
add_library(<name> [SHARED] <files...>)
adds a library, if SHARED is omitted the library is static
```

to specify link dependancies for a target use

```
target_link_libraries (target_name <libraries...>)
where <libraries> are the target names of the libraries
```

## CMake: syntax

CMake relies on variables that can be lists or atoms. Variables are global.

Variables are expanded with

```
${<variable_name>}
```

Variables can be assigned with

```
set (<variable name> value) //plain var
set (<variable_name> <value1> <value2> ... <value N>)
set (<variable_name> ${<variable_name>} <value>) appends value to a list
```

Conditional constructs such as if/if-else are supported, and they can enclose all constructs.

To handle projects with nested folders, in the higher level CMake use

```
add_subdirectory(<folder_name>)
```

And in folder name put another CMakeLists.txt that specifies the targets in that folder.

### Exercises

- 1. given the the files stored in the exercise folder of this lesson, write a CMakeLists.txt file that compiles them
- 2. create your own git account on one of the following public services
- Gitlab
- Github
- Bitbucket

and push a robot\_programming repo, where you will add the files and the CMakeLists you created