

First Order System Adjustment:

$$\frac{dy}{dt} = -ay + bu$$

$$G(s) = \frac{Y}{U} = \frac{b}{s+a}$$

$$\frac{dy_m}{dt} = -a_my + b_mu$$

$$G(s) = \frac{Y_m}{U} = \frac{b_m}{s+a_m}$$

Use the control law : $u(t) = t_o u_c(t) - s_o y(t)$

$$U = t_o U_c - s_o Y = Y \frac{s+a}{b} \Rightarrow \frac{Y}{U_c} = \frac{t_o}{\frac{s+a}{b} + s_o} = \frac{b_o t_o}{s+a+b s_o}$$

$$b_m = b t_o$$

$$a_m = a + b s_o$$

$$e = Y - Y_m = \frac{b t_o}{s+a+b s_o} U_c = \frac{b_m}{s+a_m} U_c$$

$$\frac{\partial e}{\partial t_o} = \frac{b}{s+a+b s_o} U_c = \frac{b}{s+a_m} U_c$$

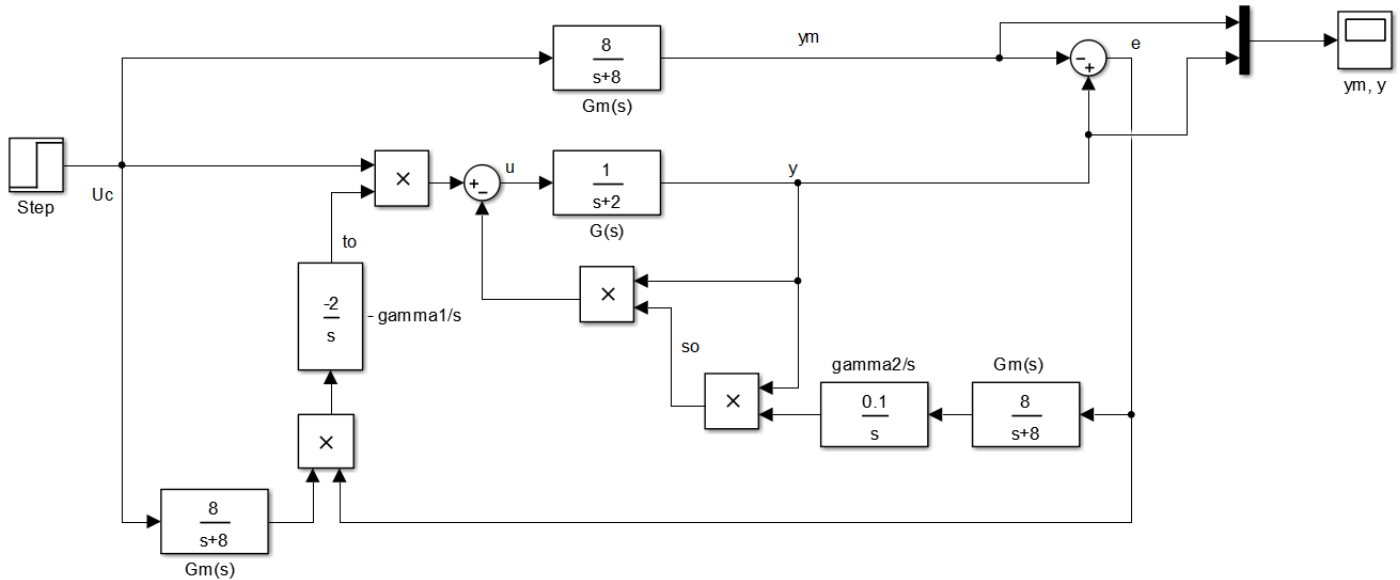
$$\frac{\partial e}{\partial s_o} = \frac{-b^2 t_o}{(s+a+b s_o)^2} U_c = \frac{-b}{s+a+b s_o} Y = \frac{-b}{s+a_m} Y$$

$$\frac{d\theta}{dt} = -\gamma \frac{\partial e}{\partial \theta} e$$

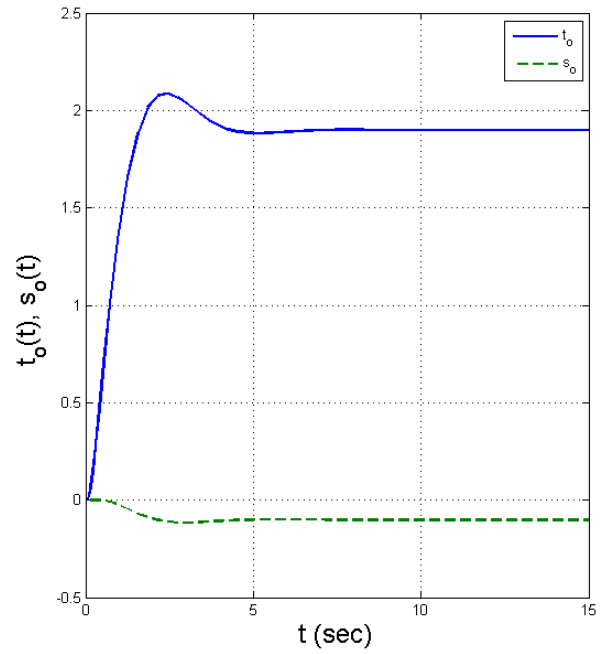
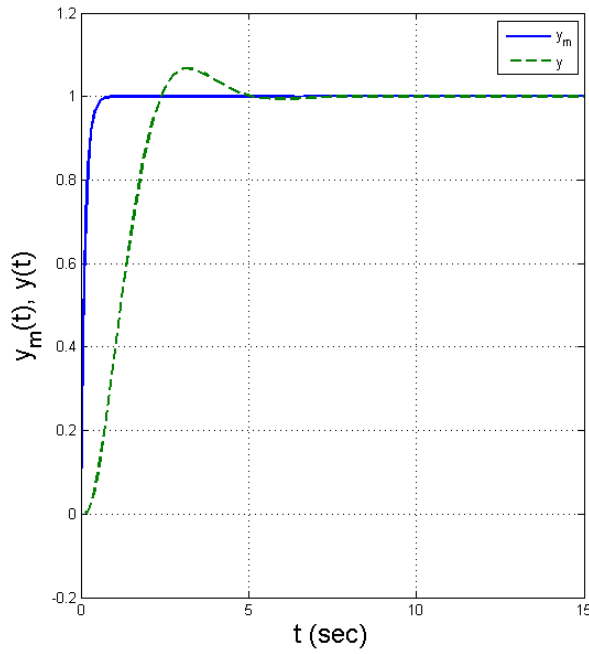
$$\frac{dt_o}{dt} = -\gamma_1 \left[\frac{b}{s+a_m} U_c \right] e$$

$$\frac{ds_o}{dt} = \gamma_2 \left[\frac{b}{s+a_m} Y \right] e$$

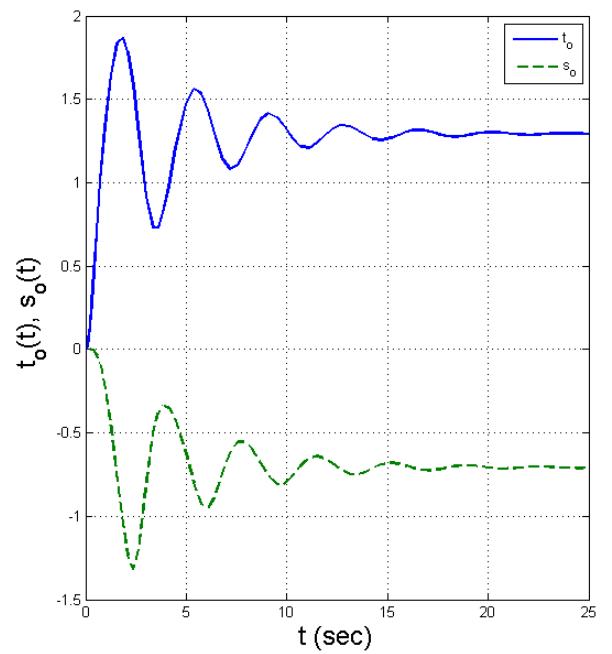
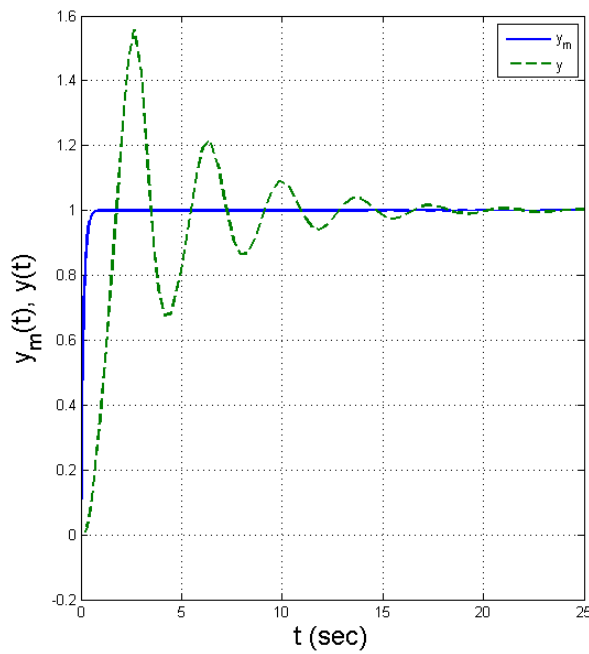
Let $a = 1$, $b = 2$, $a_m = 8$, $b_m = 8$



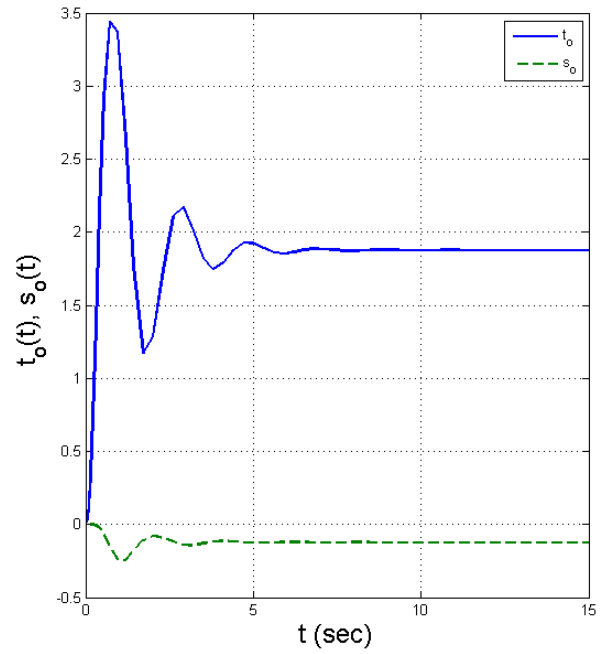
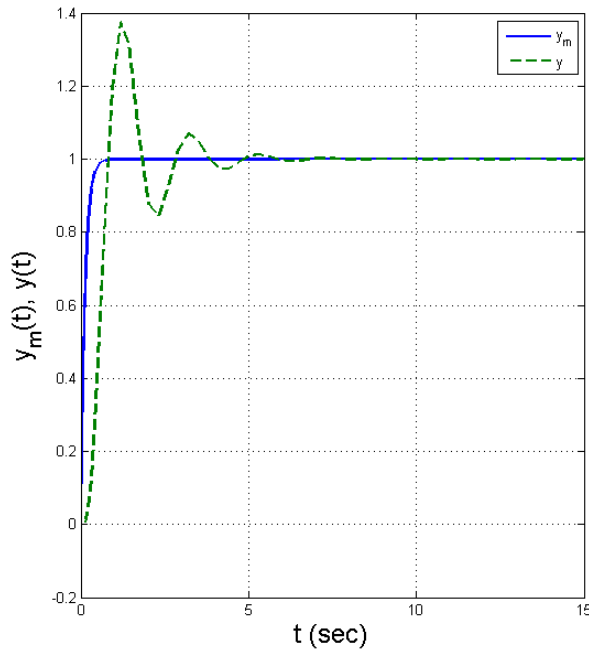
At $\gamma_1 = 2$, $\gamma_2 = 0.1$



At $\gamma_1 = 2$, $\gamma_2 = 1$



At $\gamma_1 = 2$, $\gamma_2 = 0.5$



At $\gamma_1 = 1$, $\gamma_2 = 0.05$

