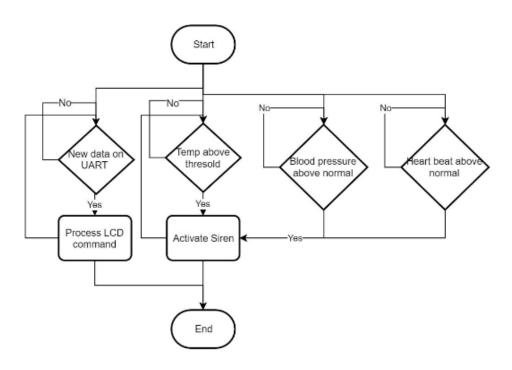
# **RTOS Design Report**



## •Tasks needed:

We can implement this design using 6 tasks:

LCD_Task	[ P:100 , E:2 , D:100 , Pri: 1]
Blood_Sensor_Task	[ P:25 , E:3 , D:25 , Pri: 3]
Heart_Detector_Task	[ P:100 , E:1.5 , D:100 , Pri: 2]
Temp_Sensor_Task	[ P:10 , E:2.5 , D:10 , Pri: 5]
Alert_Siren_Task	[ P:5 , E:1 , D:5 , Pri: 6]
UART_Task	[ P:5 , E:1 , D:5 , Pri: 4]

•Where: P : Periodicity

E: Execution Time

D : Deadline Pri: Priority

Priorities are given according to the Rate-Monotonic scheduling

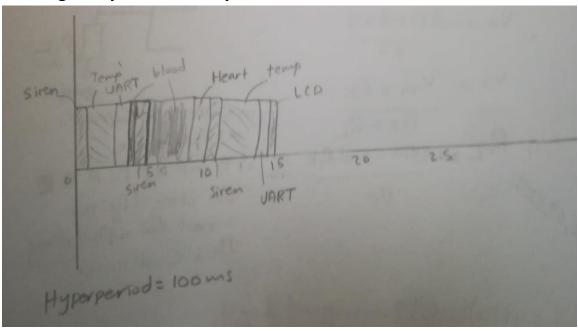
Tick time = 5ms

Hyberperiod = 100ms (The LCM of all the tasks)

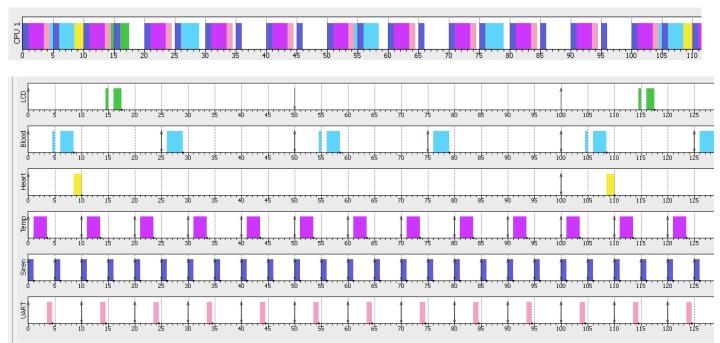
#### CPU load:

U=(E1+E2+E3+E4+E5+E6)/H =((1\*2)+(4\*3)+(1\*1.5)+(10\*2.5)+(20\*1)+(10\*1))/100 = 0.705 ( 70.5 % )

### Drawing the system manually:



#### SimSo's simulation



As we can see , the results are the same and no task miss its deadline