

# **Hands-On Tutorial on Optimization**

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## **Graph Coloring and Solver Parameter**

Day 4

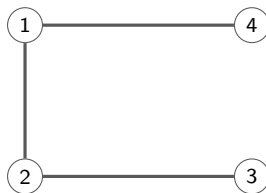
1. The Graph Coloring Problem.
2. Different (I)LP representations for the Graph Coloring Problem.
3. Solving the (I)LPs with different Solver Configurations.
4. (Using different solvers as Backend.)

# Graph Coloring

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**Input:** An undirected graph  $G = (V, E)$ .

**Task:** Assign a color to each vertex  $v \in V$

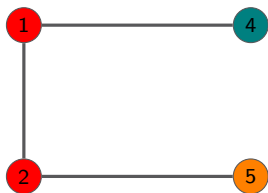


# Graph Coloring

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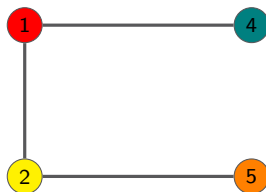
# Graph Coloring

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**Input:** An undirected graph  $G = (V, E)$ .

**Task:** Assign a color to each vertex  $v \in V$

- ▶ such that no neighboring vertices have the same color



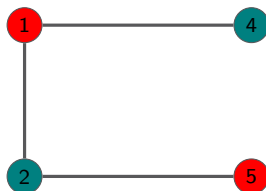
# Graph Coloring

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**Input:** An undirected graph  $G = (V, E)$ .

**Task:** Assign a color to each vertex  $v \in V$

- ▶ such that no neighboring vertices have the same color
- ▶ and minimize the number of used colors.



Famous problem (four color theorem), known to be NP-hard.

We consider a special case.

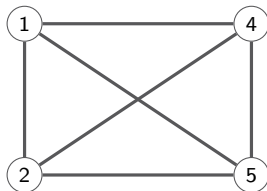
# Graph Coloring on Complete Graphs

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**Input:** A **complete** undirected graph  $G = (V, E)$ .

**Task:** Assign a color to each vertex  $v \in V$

- ▶ such that no neighboring vertices have the same color
- ▶ and minimize the number of used colors.



What is the optimal objective value?

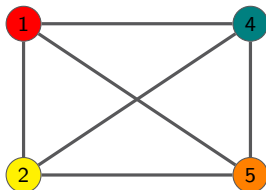
# Graph Coloring on Complete Graphs

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**Input:** A **complete** undirected graph  $G = (V, E)$ .

**Task:** Assign a color to each vertex  $v \in V$

- ▶ such that no neighboring vertices have the same color
- ▶ and minimize the number of used colors.



What is the optimal objective value? For complete graphs  $n = |V|$



# (I)LP Representations

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**Input:** A set of vertices  $V = \{1, \dots, n\}$ , a set of colors  $C = \{1, \dots, n\}$ .

**Task:** Assign a **unique** color to each vertex  $v \in V$ .

(Minimize the number of used colors.)

How to model this as an (I)LP?

$$x_{v,c} := \begin{cases} 1 & \text{if vertex } v \text{ is colored with } c \\ 0 & \text{otherwise} \end{cases} \quad y_c := \begin{cases} 1 & \text{some vertex is colored with } c \\ 0 & \text{otherwise} \end{cases}$$

$$\begin{array}{llll} \min & \sum_{c \in C} y_c & & \\ \text{s.t.} & \sum_{c \in C} x_{vc} = 1 & \forall v \in V & \\ & x_{vc} + x_{uc} \leq 1 & \forall c \in C, \forall u, v \in V: v \neq u & \\ & x_{vc} \leq y_c & \forall c \in C, \forall v \in V & \\ & x_{vc} \in \{0, 1\} & \forall c \in C, \forall v \in V & \\ & y_c \in \{0, 1\} & \forall c \in C & \end{array}$$

The corresponding LP relaxation:

$$x_{v,c} := \begin{cases} 1 & \text{if vertex } v \text{ is colored with } c \\ 0 & \text{otherwise} \end{cases}$$

$$y_c := \begin{cases} 1 & \text{some vertex is colored with } c \\ 0 & \text{otherwise} \end{cases}$$

$$\begin{array}{ll} \min & \sum_{c \in C} y_c \\ \text{s.t.} & \sum_{c \in C} x_{vc} = 1 \quad \forall v \in V \\ & x_{vc} + x_{uc} \leq 1 \quad \forall c \in C, \forall u, v \in V: v \neq u \\ & x_{vc} \leq y_c \quad \forall c \in C, v \in V \\ & 0 \leq x_{vc} \leq 1 \quad \forall c \in C, \forall v \in V \\ & 0 \leq y_c \leq 1 \quad \forall c \in C \end{array}$$

# Additional Constraints

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Suggestions of the course for further constraints to strengthen the model:

$$\sum_{v \in V} x_{vc} \leq 1 \quad \forall c \in C$$

$$\sum_{v \in V} x_{vc} = y_c \quad \forall c \in C$$

# Alternative Representation

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$x_v :=$  Color assigned to vertex  $v$

$$\begin{array}{ll} \min & \max_{v \in V} x_v \\ \text{s.t.} & x_v \neq x_u \quad \forall u, v \in V: v \neq u \\ & x_v \geq 1 \quad \forall v \in V \\ & x_v \leq n \quad \forall v \in V \\ & x_v \in \mathbb{Z} \quad \forall v \in V \end{array}$$

What is the problem with this formulation?

- ▶ A maximum operator in the objective function.
- ▶ Pulp does not accept  $\neq$ -constraints.
- ▶  $\neq$ -constraints can make a problem non-linear.

There are workarounds around these problems (see tricks session on Tuesday)!

# Alternative Representation

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Getting rid of the max in the objective:

$x_v :=$  Color assigned to vertex  $v$        $z :=$  Number of used colors

$$\begin{array}{ll} \min & z \\ \text{s.t.} & x_v \neq x_u \quad \forall u, v \in V: v \neq u \\ & z \geq x_v \quad \forall v \in V \\ & x_v \geq 1 \quad \forall v \in V \\ & x_v \leq n \quad \forall v \in V \\ & x_v \in \mathbb{Z} \quad \forall v \in V \end{array}$$

Getting rid of the  $\neq$ -constraints:

# Alternative Representation

$x_v :=$  Color assigned to vertex  $v$

$z :=$  Number of used colors

$$y_{vu} := \begin{cases} 1 & \text{if } x_v - x_u < 0 \\ 0 & \text{otherwise} \end{cases}$$

$N :=$  Constant of value  $n + 2$

min

$z$

s.t.

$$\begin{aligned} x_v - x_u + y_{vu} \cdot N &\geq 1 & \forall u, v \in V: v \neq u \\ -(x_v - x_u) + (1 - y_{vu}) \cdot N &\geq 1 & \forall u, v \in V: v \neq u \\ z &\geq x_v & \forall v \in V \\ x_v &\geq 1 & \forall v \in V \\ x_v &\leq n & \forall v \in V \\ x_v &\in \mathbb{Z} & \forall v \in V \\ y_{vu} &\in \{0, 1\} & \forall v, u \in V \end{aligned}$$

# Graph Coloring on Complete Graphs

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Why do we care about graph coloring on **complete graphs**?

- ▶ Trivial to solve for humans or problem-specific algorithms.
- ▶ Not necessarily easy for more general solvers.
- ▶ Lots of symmetry and (hidden) structural properties.
- ▶ Size of the problem easily scalable.

We use the problem as a benchmark to test the impact of

- ▶ different (I)LP formulations,
- ▶ solving techniques (cutting planes, symmetry breaking,...)
- ▶ integer or no integer variables,
- ▶ (different solvers).

Solving process of a solver can be configured. Example parameters::

- ▶ The number of **cutting plane** passes.
- ▶ How “aggressively” the solver should **break symmetries**.
- ▶ The usage of **heuristics**.
- ▶ The usage of **presolve** operations.
- ▶ ...

The concrete parameters are **solver-specific**.

Pulp provides ways to set them:

- ▶ Pass an options list to the solver.
- ▶ For Scip: Add a configuration file (`scip.set`) to the directory of your python file.



On StudIP you find:

- ▶ Different models for graph coloring on complete graphs and
- ▶ a Scip configuration file (`scip.set`).
- ▶ A template file if you want to implement the models yourself.

Test how the running time for solving the model changes depending on

- ▶ whether you use the ILP representation or LP relaxation,
- ▶ the ILP representation you use,
- ▶ the solver configuration,
- ▶ the solver you use,
- ▶ the size of the problem instance,
- ▶ ...