

Noeud IoT Pour la maintenance predictive

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Plan

1 Scenario

2 Realisation

3 Résultats

Scenario

- 1 Problématique
- 2 Architecture general
- 3 Spécifications

Problématique

REACTIVE



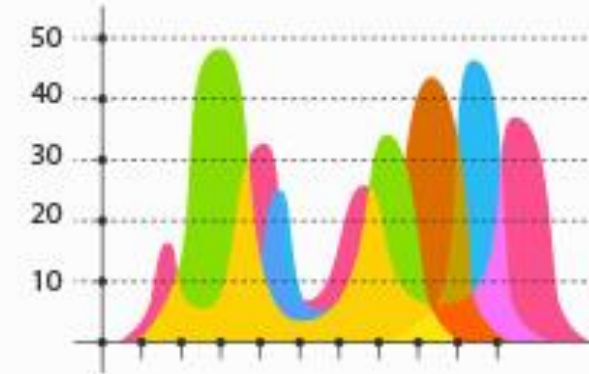
FIX IT WHEN IT BREAKS!

PREVENTIVE



MAINTAIN IT AT REGULAR INTERVALS SO IT DOESN'T BREAK!

PREDICTIVE



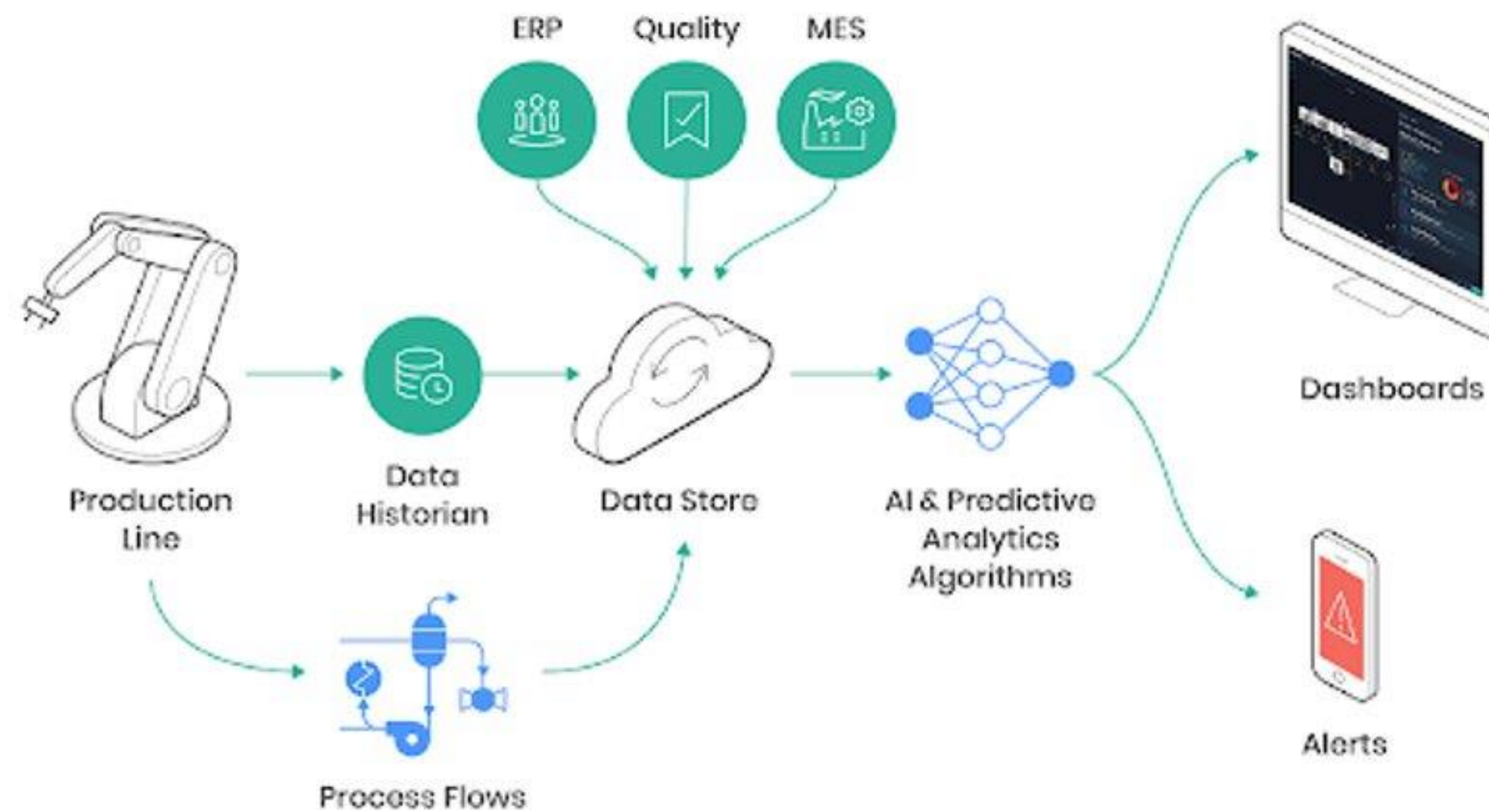
PREDICT EXACTLY WHEN IT WILL BREAK AND MAINTAIN IT ACCORDINGLY!

PRESCRIPTIVE



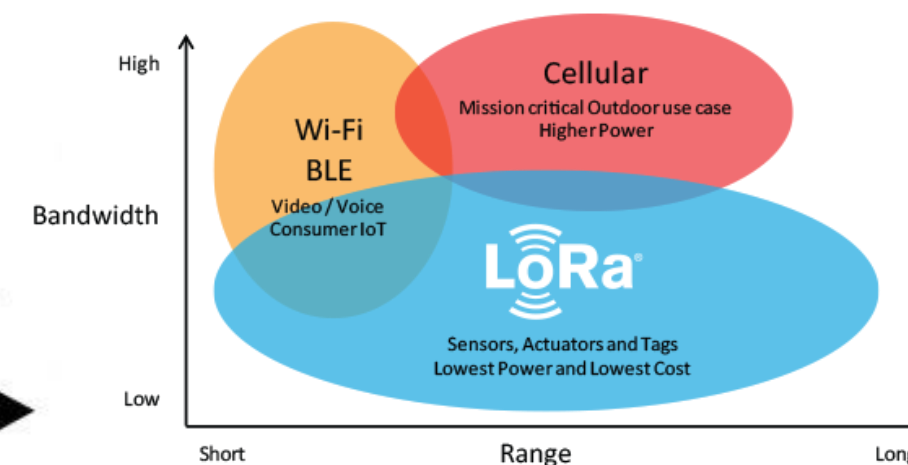
LET THE MACHINES HELP YOU DECIDE HOW TO AVOID PREDICTED FAILURES!

Architecture général



Spécifications

Power	Lower cost and greater power efficiency than other wireless networks and <u>supports</u> a greater number of connected devices over a larger area.
Portability	Devices (sensors, switches) are autonomous-battery powered, wireless and completely cable free.
Range	Range from 1 to 30 km in different environment conditions.
Autonomy	High autonomy of smart devices, with a lifetime up to 10 years.
Data	Data transmitted with low throughput-packet sizes from 10 to 1,000 bytes at uplink speeds up to 200 Kbps.
Cost	Radio modules and chipsets are relatively inexpensive.
Latency	Low latency (although not a key parameter in most IoT applications).
Access points	Fewer access points (base stations, gateways) than other wide-area technologies (ex. cellular) required to cover a wide area such as a city.
Penetration	Good penetration of structures and walls; able to be used underground and inside buildings.
Resistance to exterior Factors	Many devices are environmentally hardened, so can be used year-round in Canadian climates.



Key Factors	
Power	Low consumption
Range	10 -> 15 km
Data rate	10 bps to 10 kbps
Message Size	-----
Mobility	Low speed Mobility
Traffic pattern	Radom
Data rate	-----
Device Density	Low
Bandwidth	50-100 Hz
Latency tolerance	Minutes to hours

Réalisation

1

Architecture

2

Noeud

Cliquez pour ajouter du
texte

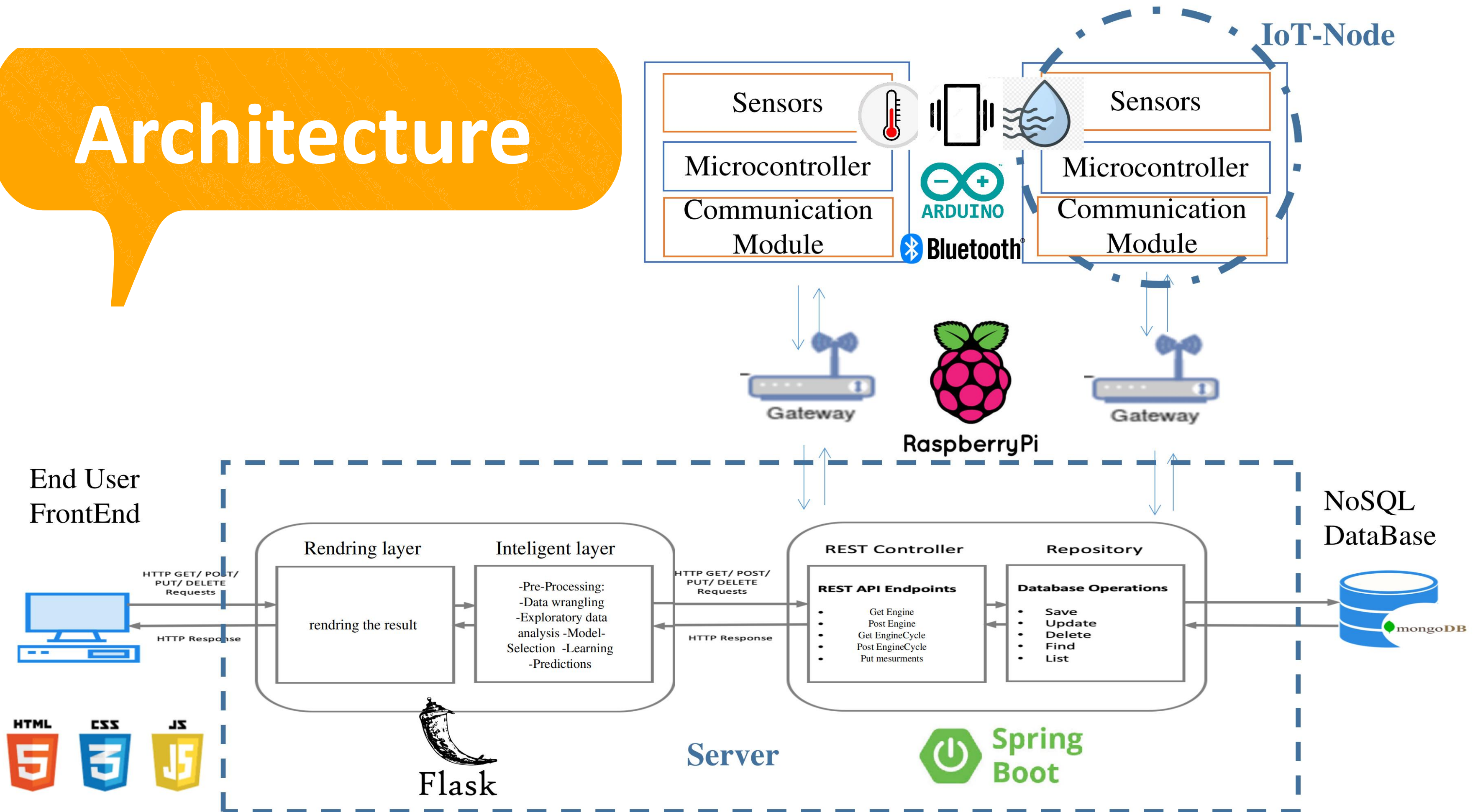
3

Gateway

4

Serveur et stockage

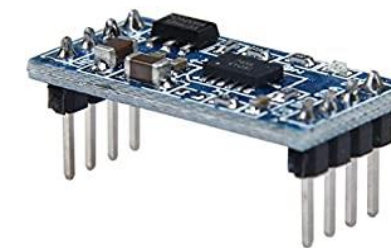
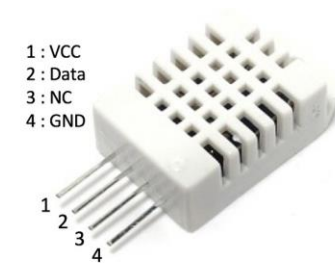
Architecture



Noeud -IoT

1

Capteurs



2

Microcontrôleur



3

Module de communication



```
All | Arduino 1.8.13
Fichier Édition Croquis Outils Aide

All

/*-----EEPROM-----*/
#include <EEPROM.h>
void writeEEPROM(String ch,int from)
{
  for (int i=0;ch[i];i++)
  {
    EEPROM.write(from+i,int(ch[i]));
  }
}
String readEEPROM(int from,int to )
{
  String ch="";
  for (int i=from;i<to+1;i++)
  {
    int ascii = EEPROM.read(i);
    char c = char(ascii);
    ch+=c;
  }
  return ch;
}
String engineId = "-1";
String maintenanceIndex = "-1";
String cycle = "-1";
String lastCycleReached = "-1";

Téléversement terminé
avrdude: verifying ...
avrdude: 15332 bytes of flash verified

avrdude done. Thank you.
```

COM3		
Humidite: 55.20 %	Temperature: 25.70 °C 78.26 °F	Indice de temperature: 25.77 °C 78.38 °F
X = -42 Y = 15 Z = -15		
Humidite: 55.10 %	Temperature: 25.70 °C 78.26 °F	Indice de temperature: 25.76 °C 78.38 °F
X = -43 Y = 12 Z = -15		
Humidite: 55.10 %	Temperature: 25.70 °C 78.26 °F	Indice de temperature: 25.76 °C 78.38 °F
X = -41 Y = 14 Z = -15		
Humidite: 55.10 %	Temperature: 25.70 °C 78.26 °F	Indice de temperature: 25.76 °C 78.38 °F
X = -41 Y = 14 Z = -16		
Humidite: 55.00 %	Temperature: 25.70 °C 78.26 °F	Indice de temperature: 25.76 °C 78.37 °F
X = -42 Y = 14 Z = -17		
Humidite: 54.80 %	Temperature: 25.70 °C 78.26 °F	Indice de temperature: 25.76 °C 78.36 °F
X = -42 Y = 14 Z = -17		
Humidite: 54.70 %	Temperature: 25.70 °C 78.26 °F	Indice de temperature: 25.75 °C 78.36 °F
X = -42 Y = 15 Z = -17		
Humidite: 54.70 %	Temperature: 25.70 °C 78.26 °F	Indice de temperature: 25.75 °C 78.36 °F

☒ Défilement automatique ☐ Afficher l'horodatage

GateWay



The screenshot shows a VNC Viewer window titled "192.168.137.192 (raspberrypi) - VNC Viewer". The window displays a Python script named "BlueTooth.py" in a text editor. The script is designed to communicate with a Raspberry Pi via a serial port and a web API. It includes a while loop that prompts the user for a "Server message" and then sends a POST request to a specific API endpoint. Below the code editor, a terminal window shows the execution of the script, displaying "Device Response" and "Server message" data.

```
22 ser = serial.Serial(  
23     port='/dev/rfcomm3',  
24     baudrate=9600,  
25     parity=serial.PARITY_ODD,  
26     stopbits=serial.STOPBITS_TWO,  
27     bytesize=serial.SEVENBITS  
28 )  
29  
30 ser.isOpen()  
31  
32 print('Enter your message below.\r\nInsert "exit" to leave the application.')  
33 delay = 10000  
34 while 1 :  
35     user_input = input('Server message >> ')  
36     if user_input == 'exit':  
37         ser.close()  
38         myobj={ 'engineCycle': { "id": {  
39             "engine": {  
40                 "id": 10,  
41                 "description": "motor10",  
42                 "maintenanceIndex": 0  
43             },  
44             "cycle": 0,  
45             "maintenanceIndex": 0  
46         }}, "measurements": L}  
47         print(rqs.post('http://192.168.131.1:8080/api/engineCycle/addMeasurement', data=  
48             user_input  
49         ))  
50         exit()  
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98  
99  
100
```

Device Response >> -39.00,16.00,-16.00,25.00,53.00,25.04
Server message >> 1111111111111111
Device Response >> -41.00,16.00,-18.00,25.70,53.70,25.73
Server message >> 1111111111111111
Device Response >> -40.00,15.00,-16.00,25.70,53.70,25.73
Server message >> 1111111111111111
Device Response >> -40.00,16.00,-18.00,25.70,53.60,25.72
Server message >> 1111111111111111
Device Response >> -40.00,16.00,-17.00,25.70,53.70,25.73
Server message >>



Serveur & stockage

1

Base de données

2

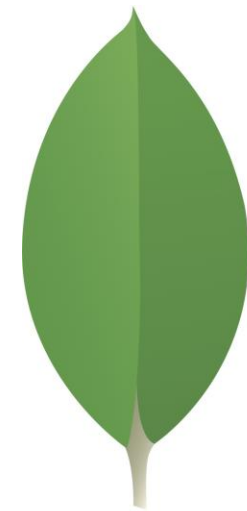
Couche de données

3

Couche intelligente

1

Base de données



mongoDB

1

Database



Engine	100	88.4 B	8.6 KB	1	16.0 KB	
EngineCycle	5	5.5 KB	27.6 KB	1	36.0 KB	

```

object {4}
  _id : 1
  description : vehicula. Pellentesque tincidunt
               tempus risus. Donec egestas. Duis
               ac arcu.
  maintenanceIndex : 0
  lastTimeConnected {1}
    $date : 2021-06-07T23:00:00.000Z

```

```

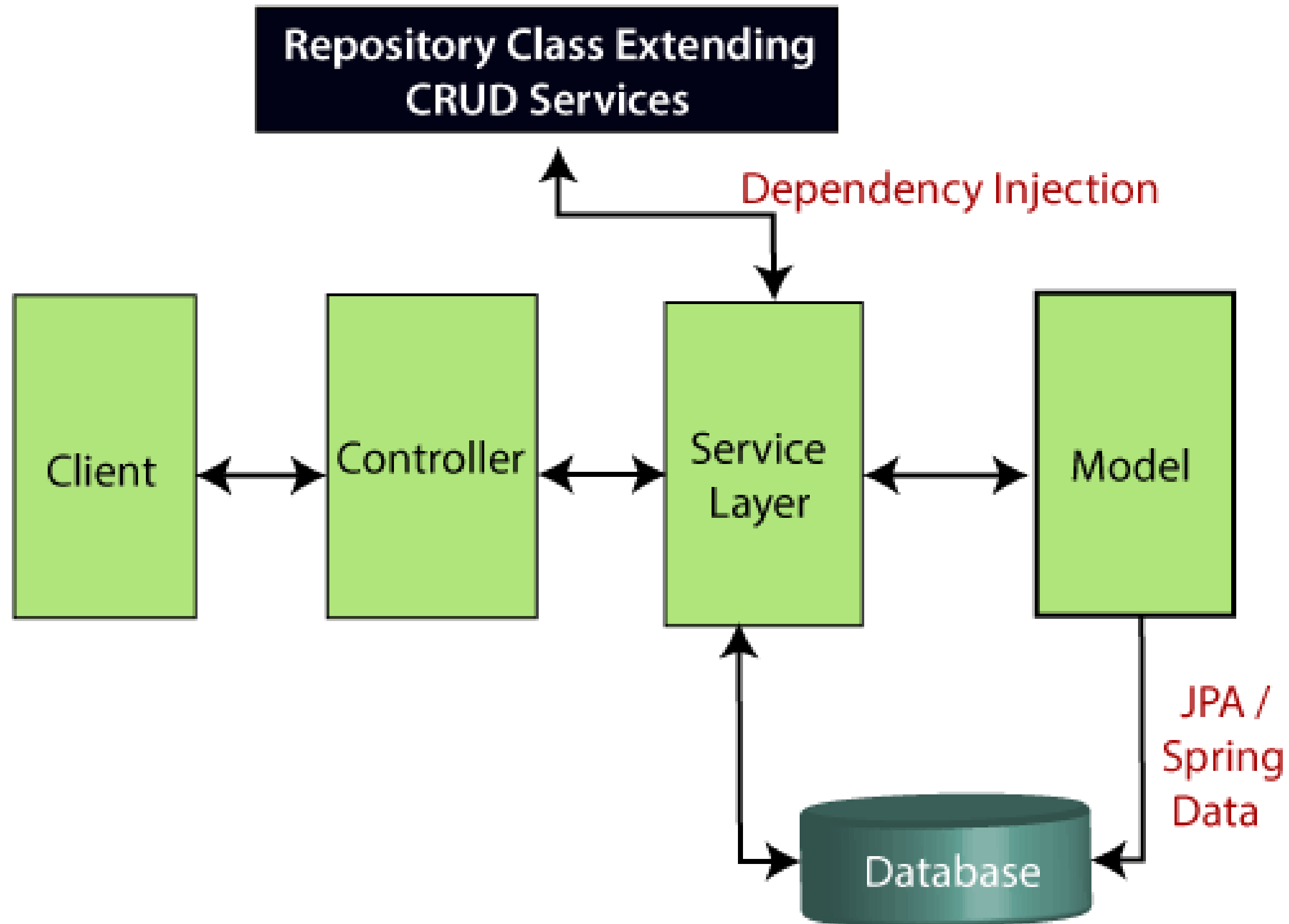
object {4}
  _id {3}
    engine {2}
      $ref : Engine
      $id : 1
      cycle : 0
      maintenanceIndex : 0
      measurementFrequency : 0
    measurements [26]
      0 {5}
        ax : 82.30215
        ay : 43.880162
        az : -66.725855
        temperature : 37.5591
        humidity : 69.1895
      1 {5}
      2 {5}
      3 {5}
      4 {5}
      5 {5}
      6 {5}

```

Couche de données



Spring Boot Flow architecture



Couche de données

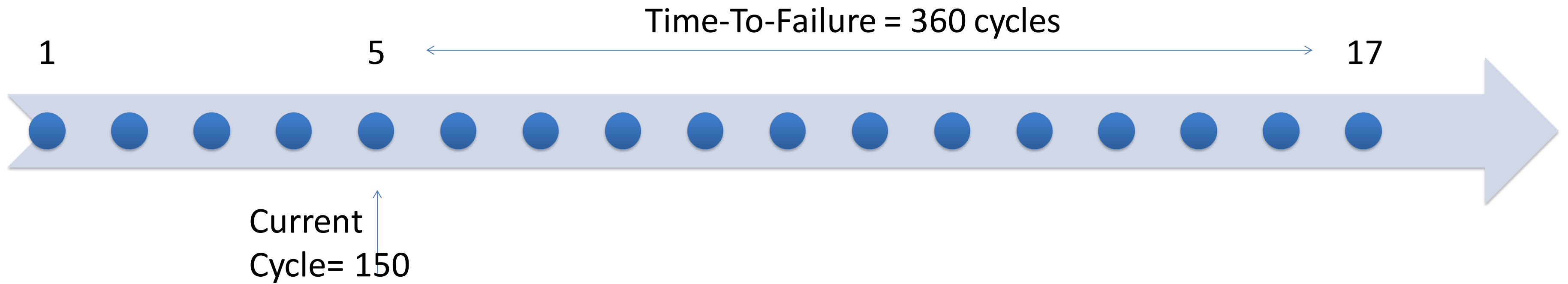
[illegible]

Couche intelligente



L'approche

- 1 Utilisation d'un algorithme de régression pour prédire TTF (Time-To-Failure)
- 2 Utilisation d'un algorithme de classification pour prédire si le moteur va tomber en panne dans cette période
- 3 Utilisation d'un algorithme de classification multi-classe pour prédire la période dans laquelle va tomber en panne



Regression	Binary Classification	Multiclass Classification
TTF (Time-To-Failure)	if the engine will fail in this period	the period an engine will fail
360 cycles	0	0

Pre- traitement de données

- 1 Extraction de nouveaux descripteurs (feature Extraction)
- 2 Calcul des labels

1

Extraction de nouveaux descripteurs (feature Extraction)

- Definition d'une fenetre (Periode)
- Ajout de nouveaux descripteurs (moyenne glissante et ecart type glissant sur la periode definie)
- => à chaque descripteur est associé:
 -_Avg
 -_Std
 -_Max
 -_Min
- Objectif : faire apparaitre de nouveaux descripteurs significatifs en fonction du temps

	Date	Close*	Rolling Close Average
10	Feb 01, 2019	62.44	NaN
9	Feb 04, 2019	62.58	62.510
8	Feb 05, 2019	64.27	63.425
7	Feb 06, 2019	63.44	63.855
6	Feb 07, 2019	61.50	62.470
5	Feb 08, 2019	61.16	61.330
4	Feb 11, 2019	62.57	61.865
3	Feb 12, 2019	62.36	62.465
2	Feb 13, 2019	61.63	61.995
1	Feb 14, 2019	60.75	61.190
0	Feb 15, 2019	61.58	61.165

```
def add_features(df_in, rolling_win_size, columns_to_treat):
    """Add rolling average and rolling standard deviation for sensors readings using
    fixed rolling window size.

    Args:
        df_in (dataframe) : The input dataframe to be processed (training or
        test)
        rolling_win_size (int): The window size, number of cycles for applying
        the rolling function
        columns_to_treat : the list of features to take in consideration and
        treat them
    Returns:
        dataframe: contains the input dataframe with additional rolling mean ,std,
        min and max for each sensor|

    """
```

1

Calcul des labels

- **TTF** : Time-To-Failure = lastCycle – CurentCycle
- **BNC** : Binary-Class-Classification
label = 1 si TTF ≤ Periode sinon 0
- **MCC** : Multi-Class-Classification
label = 2 si TTF ≤ Periode/2 sinon
1 si TTF ≤ Periode sinon 0

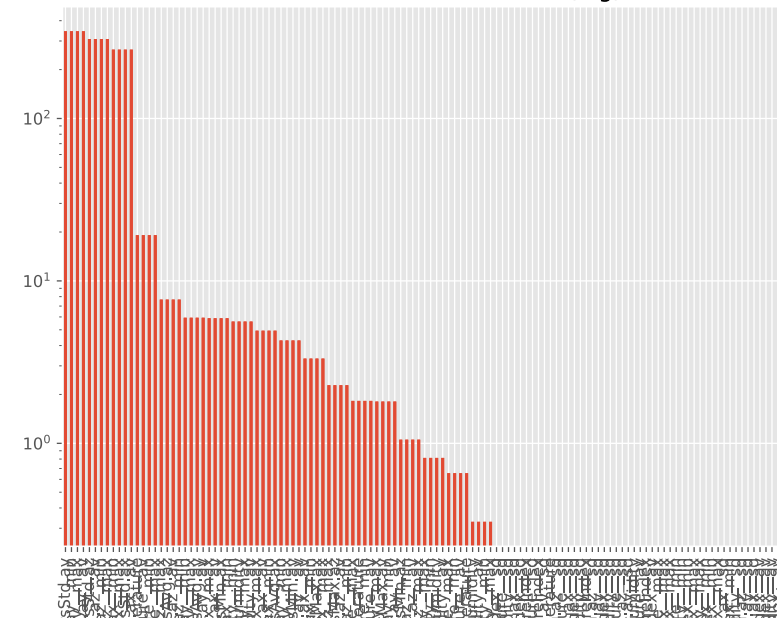
```
def find_labels(df_in, period):  
    """Add regression and classification labels to the training data.  
        Regression label: labels.ttf (time-to-failure) = each cycle# for an engine  
        subtracted from the last cycle# of the same engine  
        Binary classification label: labels.bnc = if ttf is <= period then 1 else 0  
        (values = 0,1)  
        Multi-class classification label: labels.mcc = 2 if ttf <= 0.5* period , 1  
        if ttf<= period, else 2  
  
        Args:  
            df_in (dataframe): The input training data  
            period (int)      : The number of cycles for TTF segmentation. Used to  
            derive classification labels  
  
        Returns:  
            dataframe: The input dataframe with regression and classification labels  
            added  
  
    """
```

Analyse exploratoire des données (EDA)

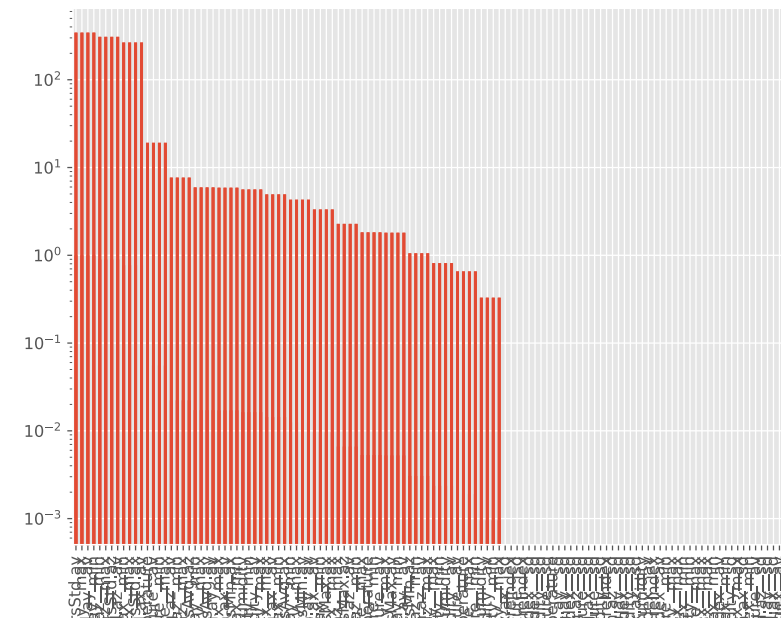
- 1 La variance
- 2 Intercorrelation avec le label
- 2 Intercorrelation entre les descripteurs entre eux

1

Features Standard Deviation (log)



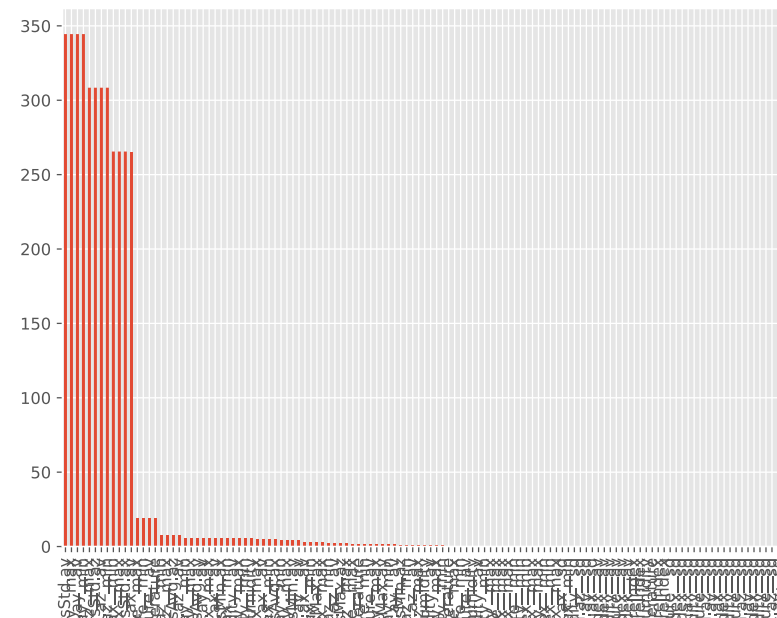
Features normalized Standard Deviation



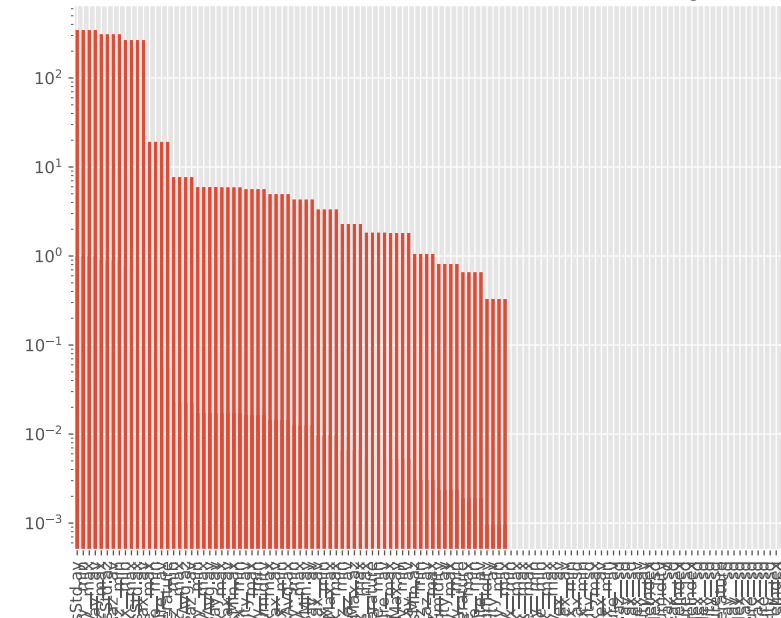
La variance

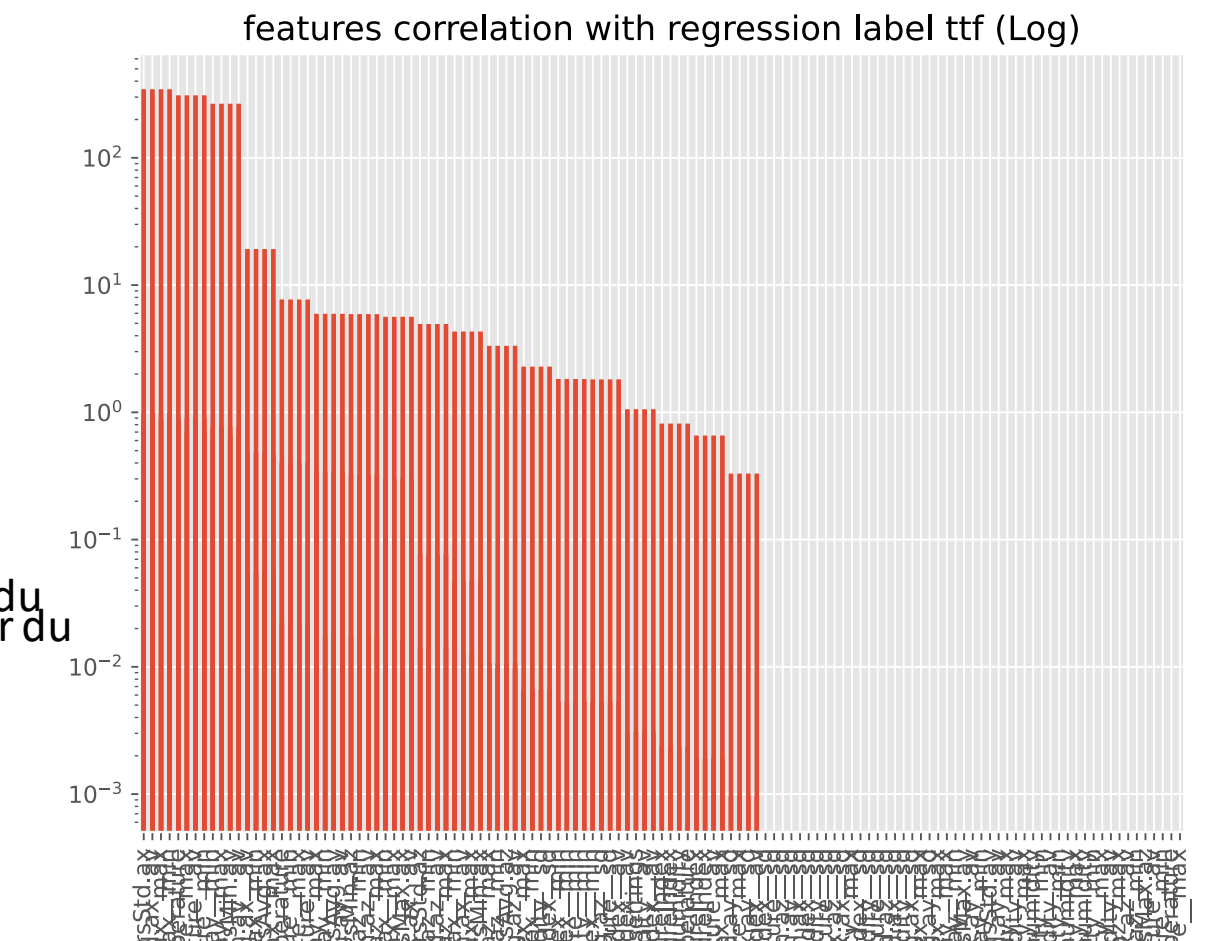
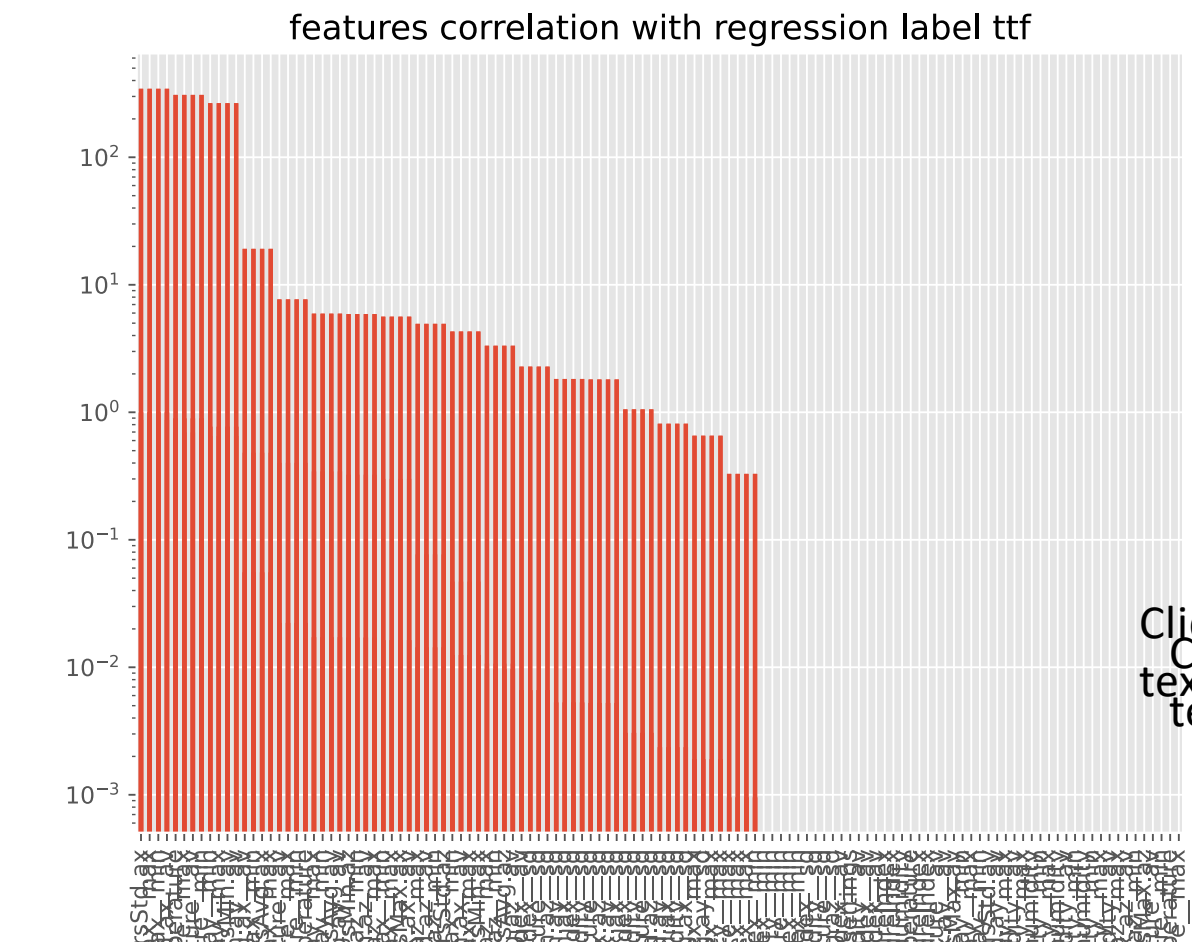
- But : Maximiser la variance

Features Standard Deviation



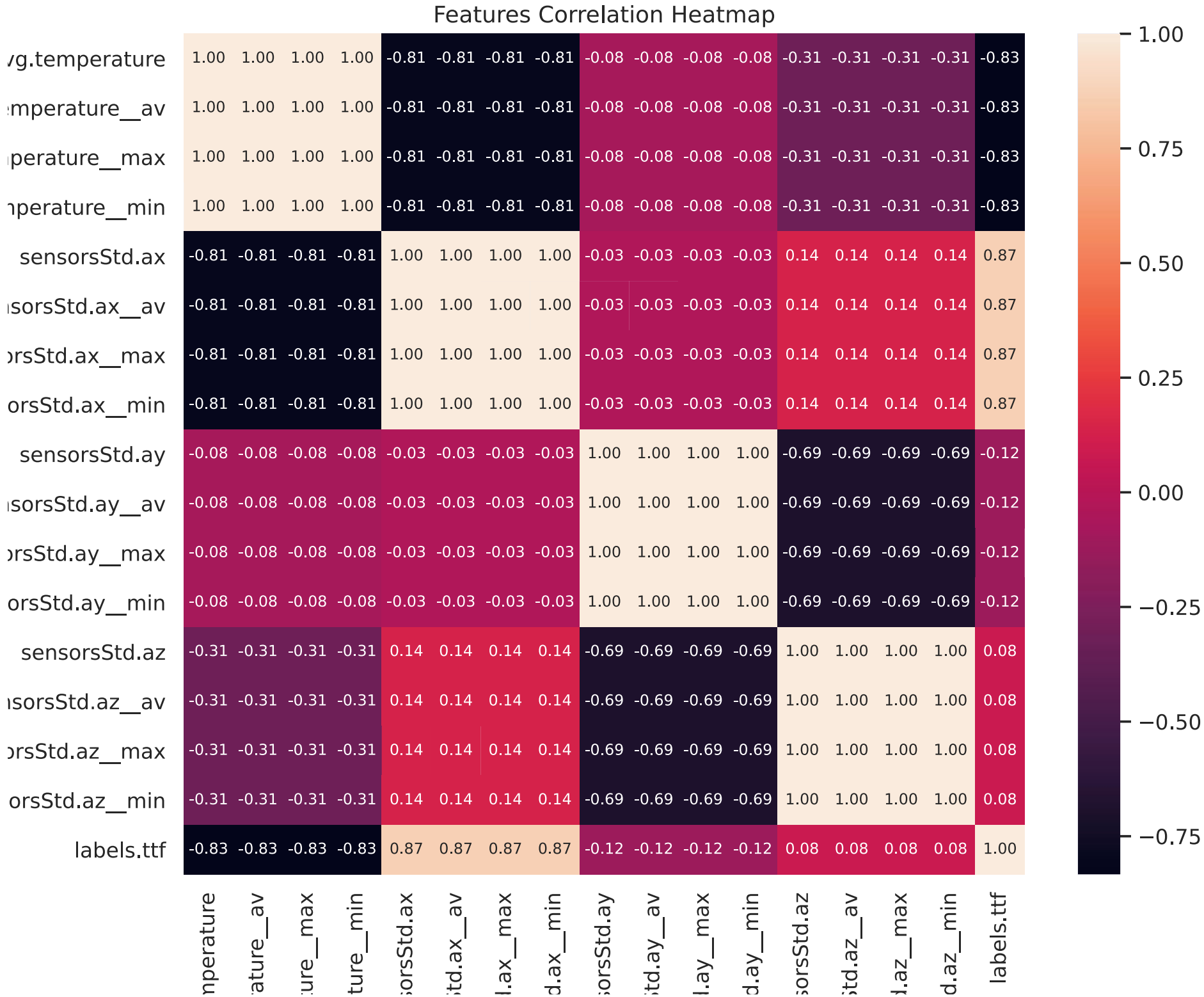
Features Normalized Standard Deviation (Log)





Intercorrelation avec le label

Intercorrelation
entre les
descripteurs
(entre eux)



Selection des modèles

1

**Predicting
Engine's Time-
To-Failure (TTF)**

2

**Which Engines
will fail in the
Current
Period? (BNC)**

3

**How could
Maintenance be
better Planned?
(MCC)**



Regression algorithms	Regression metrics
Linear Regression LASSO Regression Ridge Regression Decision Tree Regression Random Forest	R-squared (R ²) Root Mean Squared Error (RMSE) Mean Absolute Error Explained Variance



Binary Classification algorithms	Binary Classification metrics
Logistic Regression Decision Trees Support Vector Machines Linear Support Vector Gaussian Naive Random Forests	Precision Recall F1 Score Accuracy



Multiclass Classification algorithms	Multiclass Classification metrics
Logistic Regression Decision Trees Support Vector Machines Linear Support Vector Gaussian Naive Random Forests	Precision Recall F1 Score Accuracy

TTF

	index	LinearRegression	DecisionTreeClassifier	RandomForestClassifier	SVC	LinearSVC	GaussianNB
0	Accuracy	0.500000	0.5	0.0	0.5	0.500000	0.5
1	Precision	0.500000	0.0	0.0	0.0	0.500000	0.0
2	Recall	1.000000	0.0	0.0	0.0	1.000000	0.0
3	F1 Score	0.666667	0.0	0.0	0.0	0.666667	0.0

BNC

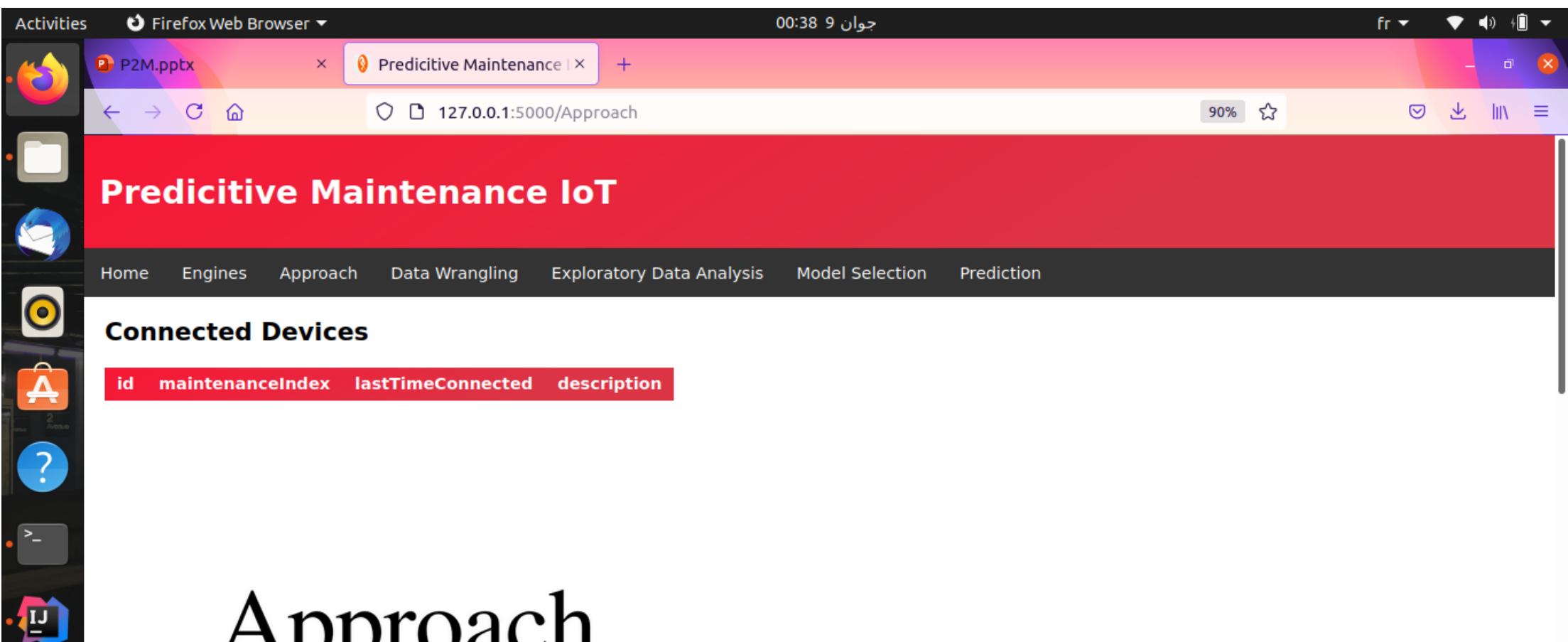
	index	LogisticRegression	DecisionTreeClassifier	RandomForestClassifier	SVC	LinearSVC	GaussianNB
0	Accuracy	0.500000	0.5	0.0	0.5	0.500000	0.5
1	Precision	0.500000	0.0	0.0	0.0	0.500000	0.0
2	Recall	1.000000	0.0	0.0	0.0	1.000000	0.0
3	F1 Score	0.666667	0.0	0.0	0.0	0.666667	0.0

MCC

	index	LogisticRegression	DecisionTreeClassifier	RandomForestClassifier	SVC	LinearSVC	GaussianNB
	Accuracy	0.500000	0.500000	0.0	0.500000	0.500000	0.500000
	macro F1	0.333333	0.333333	0.0	0.333333	0.333333	0.333333
	micro F1	0.500000	0.500000	0.0	0.500000	0.500000	0.500000
	macro Precision	0.250000	0.250000	0.0	0.250000	0.250000	0.250000
	micro Precision	0.500000	0.500000	0.0	0.500000	0.500000	0.500000
	macro Recall	0.500000	0.500000	0.0	0.500000	0.500000	0.500000
	micro Recall	0.500000	0.500000	0.0	0.500000	0.500000	0.500000

Résultats

- 1 Interface utilisateur (Front End User)
- 2 Prédiction



1 Interface utilisateur (Front End User)

Approach

By exploring Drilling Machine engine ’s sensor values over time, machine learning algorithm can learn the relationship between sensor values and changes in sensor values to the historical failures in order to predict

- 1 Use of Regression models (ttf) to predict engine failure (Failure)
- 2 Use of Binary Classification models (bnc) to predict engine failure (Failure)

Regression models (ttf)

index	LinearRegression	LASSO	RIDGE	DecisionTree	RandomForest
Root Mean Squared Error	2.6898906554904816	1.0889562824070187	1.6987203985724153	1.5811388300841898	1.6990732768188663
Mean Absolute Error	2.615926669556348	1.0829530460731567	1.5896059006796328	1.5	1.6749999999999998
R^2	-2.2157829948866725	0.4729663177805712	-0.2825115522337893	-0.11111111111111116	-0.2830444444444444
Explained Variance	-2.041365484664963	0.47876120000038724	-0.1230430753224474	0.0	-0.24694444444444442

Binary Classification models (bnc)

index	LogisticRegression	DecisionTreeClassifier	RandomForestClassifier	SVC	LinearSVC	GaussianNB
Accuracy	0.5	0.5	0.0	0.5	0.5	0.5
Precision	0.5	0.0	0.0	0.0	0.5	0.0
Recall	1.0	0.0	0.0	0.0	1.0	0.0
F1 Score	0.6666666666666666	0.0	0.0	0.0	0.6666666666666666	0.0



Prédiction

Results

we used the following algorithms selected after model selection step to predict TTF BNC MCC respectively

LinearRegression LogisticRegression LogisticRegression							
id.engine.id	id.engine.maintenanceIndex	id.engine.lastTimeConnected	id.engine.description	id.maintenanceIndex	labels.ttf	labels.bnc	labels.mcc
1	0	0	vehicula. Pellentesque tincidunt tempus risus. Donec egestas. Duis ac arcu.	0	4.0000000000000021	0	0
1	0	0	vehicula. Pellentesque tincidunt tempus risus. Donec egestas. Duis ac arcu.	0	3.00000000000000355	0	0
1	0	0	vehicula. Pellentesque	0	2.0000000000000007	0	0

**Merci Pour
votre attention**

*bonne
journée*