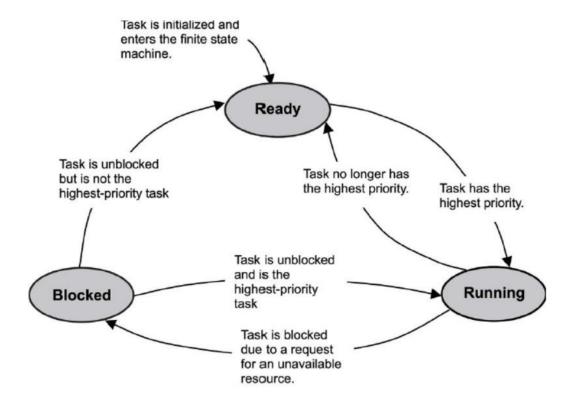
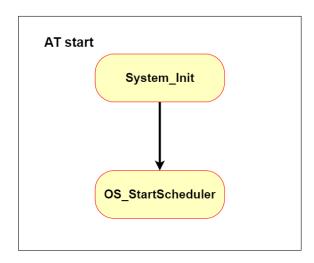
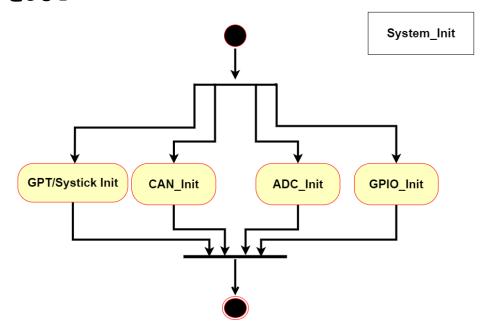
Automotive door control system design (Dynamic Design)

OS(RTOS) StateMachine :

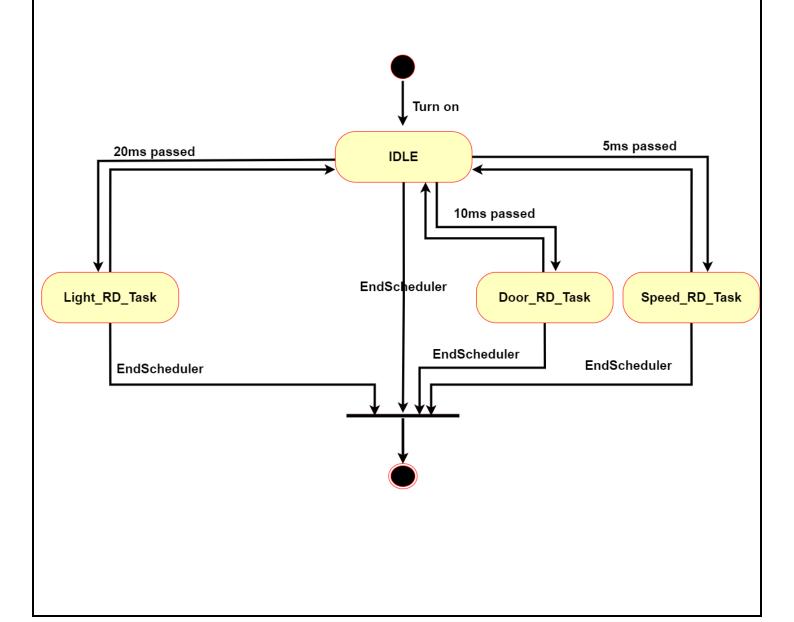




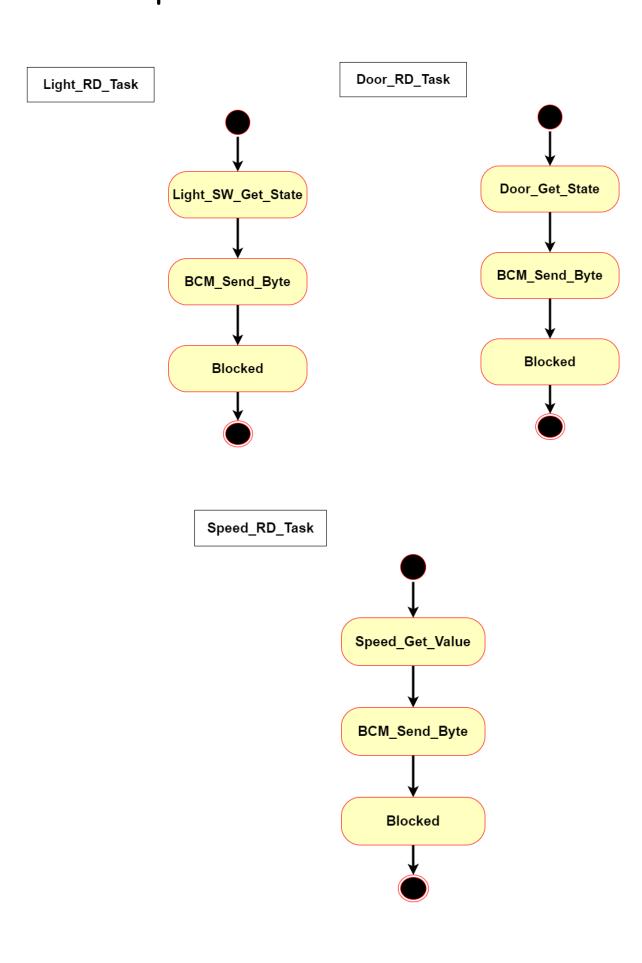
• FOR ECU1:



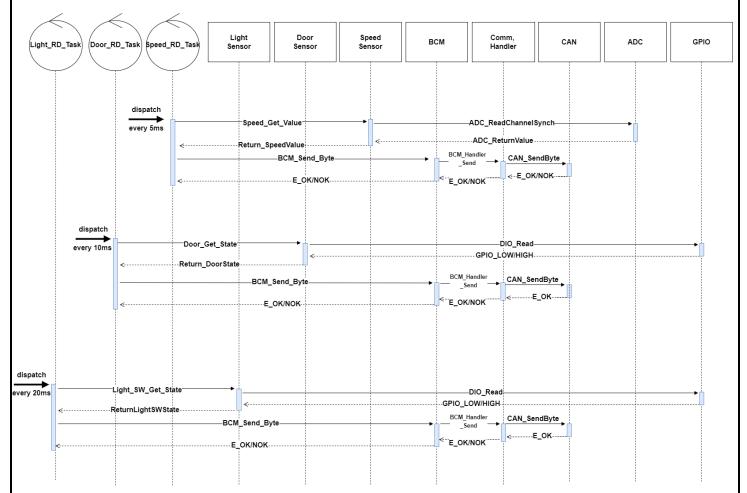
■ ECU1 Operation StateMachine :



■ ECU1 Components:



■ ECU1 Sequence Diagram:



• ECU1 CPU Load:

3 tasks (Light_RD_Task / Door_RD_Task / Speed_RD_Task)

CPU Load = (E1+E2+E3)/hyperperiod

$$=\frac{E1}{P1} + \frac{E2}{P2} + \frac{E3}{P3}$$

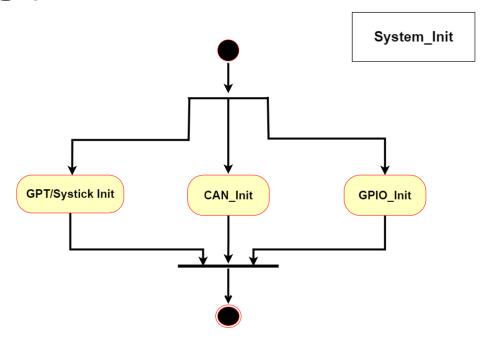
Assume E1 \rightarrow 150 us

Assume E2 → 150 us

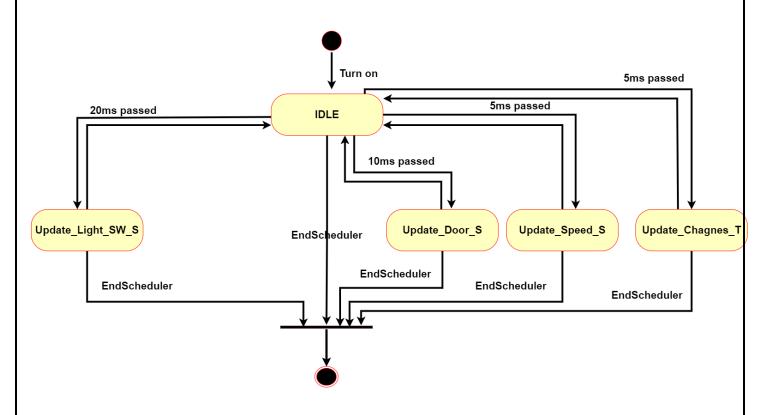
Assume E3 \rightarrow 200 us

SO.. CPU Load =
$$\frac{150us}{5ms} + \frac{150us}{10ms} + \frac{200us}{20ms} = 5.5 \%$$

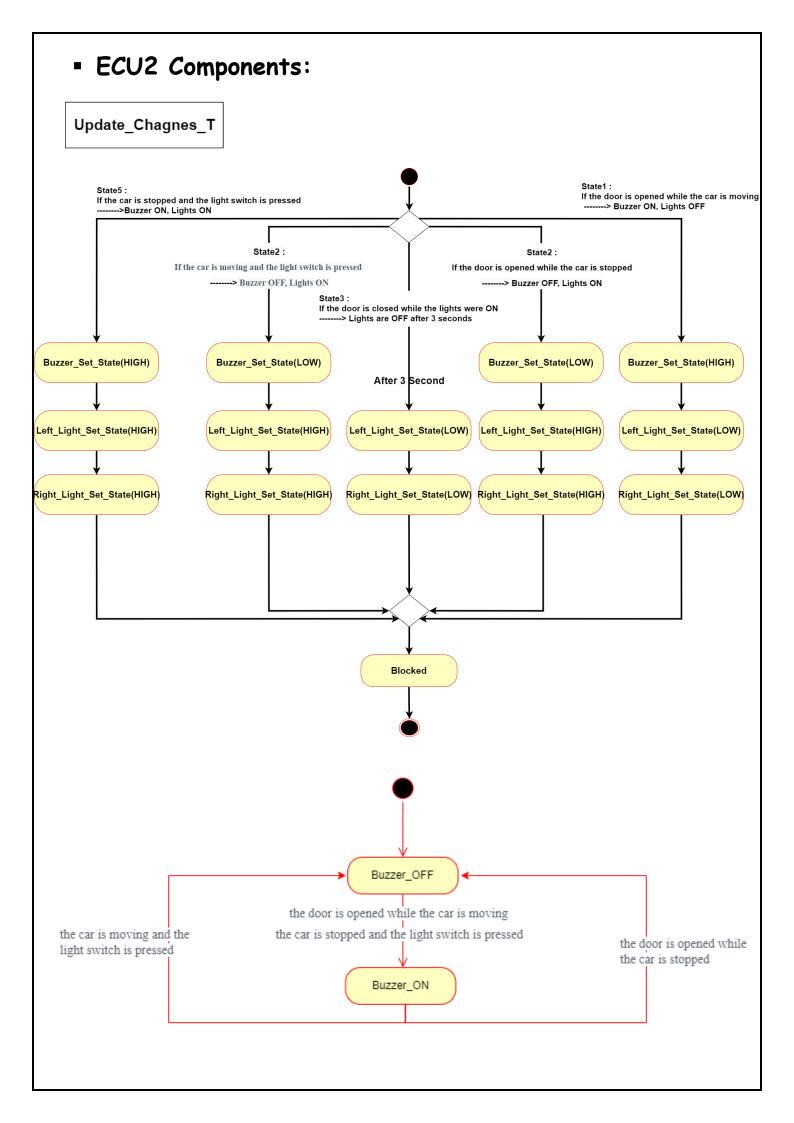
• FOR ECU2:

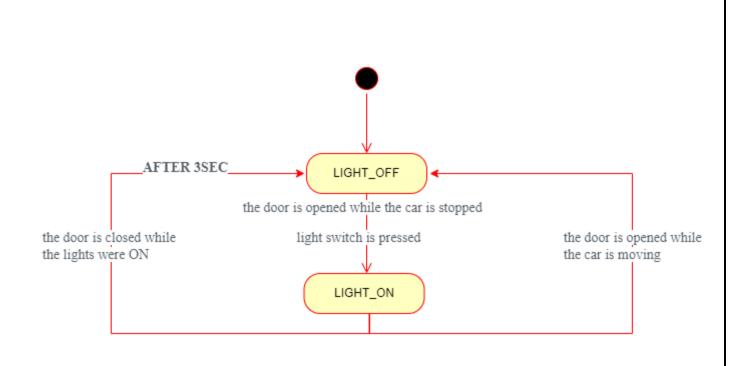


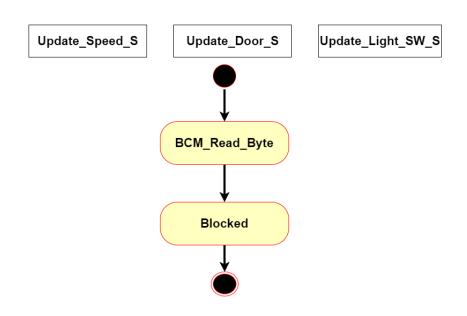
■ ECU2 Operation StateMachine :



Note: Update_Changes_T has lesser priority than other tasks (still bigger than idle task)







ECU2 Sequence Diagram: Right_Light Left_Light GPIO GPT BCM_Handler CAN_ReadByte every 5ms < Return_Byte----- < Return_Byte-Note : this task has lesser priority than others [If the door is opened while the car is moving] Left_Light_Set_State(LOW) Right_Light_Set_State(LOW) Buzzer_Set_State(LOW) [If the door is opened while the car is stopped] Left_Light_Set_State(HIGH) DIO Write -Right_Light_Set_State(HIGH) DIO_Write Buzzer Set State(LOW) [If the car is moving and the light switch is pressed] Left Light Set State(HIGH) -Right_Light_Set_State(HIGH)-DIO_Write Buzzer_Set_State(LOW) DIO_Write Left_Light_Set_State(HIGH) _DIO_Write_ Right_Light_Set_State(HIGH) DIO_Write Buzzer_Set_State(HIGH) [If the door is closed while the lights were ON] Left_Light_Set_State(HIGH) Right_Light_Set_State(HIGH) DIO Write GPT_Start_Timer/// "One shot mode" [If the door is closed while the lights were ON] ISR is triggered Left_Light_Set_State(LOW) -Right_Light_Set_State(LOW)-DIO_Write every 10ms BCM_Handler CAN_ReadByte <Return_Byte------ <Return_Byteevery 20ms «Return_Byte...... «Return_Byte... Return_Light_SW_State

• ECU2 CPU Load:

4tasks(Update_Light_SW_S/Update_Door_S /Update_Speed_S/Update_Changes_Task)

CPU Load = (E1+E2+E3+E4)/hyperperiod

$$=\frac{E1}{P1} + \frac{E2}{P2} + \frac{E3}{P3} + \frac{E4}{P4}$$

Assume E1 \rightarrow 100 us

Assume E1 \rightarrow 100 us

Assume E1 \rightarrow 100 us

Assume E1 \rightarrow 80 us

SO.. CPU Load =
$$\frac{100us}{5ms} + \frac{100us}{10ms} + \frac{100us}{20ms} + \frac{80us}{5ms} = 5.1 \%$$

Bus Load:

- * Assume using 500 kBit/s bit rate
- * Assuming standard identifier, a CAN frame consists of:
- 1 bit start bit.
- 11 bit identifier
- 1 bit RTR
- 6 bit control field
- 0 to 64 bit data field
- 15 bit CRC
- Bit stuffing is possible in the above, for every sequence of 5 consecutive bits of same level. Somewhere around 19 bits worst case.
- 3 bit delimiter, ack etc.
- 7 bit end of frame
- 3 bit intermission field after frame.

Ignoring stuffing, you have an overhead of 47 bits/frame.

If we make our data frame always 8 bit (byte send) so the maximum frame size will be = 47 + 8 + 8 stuffing bits at worst case = 63 bit/frame

SO:-

bit time = 1/bit rate = 1/(500k) = 2us

Approx, time to transfer one frame = 2us * 63bit = 126 us

Having multiple sending intervals:

1 Frame every 5ms = 200 Frame every 1000 ms

1 Frame every 10ms = 100 Frame every 1000 ms

1 frame every 20ms = 50 Frame every 1000 ms

Total time on bus = 350 * 126 us

Bus load per 1 second = (350*126 us) / (1000 ms) = 4.41 %