A new algorithm on constrained sampling : MAPLA

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Paper: High-accuracy sampling from constrained spaces with the Metropolis-adjusted Preconditioned Langevin Algorithm, (SRINIVASAN; WIBISONO; WILSON, 2025)

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Summary

- 1 Background on constrained and unconstrained sampling
- 2 MAPLA procedure
- 3 Analysis of MAPLA: Guarantee on Mixing Time
- 4 Experiments
- 6 Backup

Unconstrained Sampling

PROBLEM: Sampling from a density in the case of smooth log-concave density.

Definition

Given an integer $p \geq 2$ and a measurable function $f: \mathbb{R}^p \longrightarrow \mathbb{R}$ such that the integral $\int_{\mathbb{R}^p} \exp\{-f(\theta)\} d\theta < \infty$. If f is m-strongly convex with a M-Lipschitz continuous gradient then the density

$$\pi(\theta) \propto \exp\{-f(\theta)\}$$

is a smooth log-concave density.

with f satisfies for all $\theta, \bar{\theta} \in \mathbb{R}^p$

$$f(\theta) - f(\bar{\theta}) - \nabla f(\bar{\theta})^{\top} (\theta - \bar{\theta}) \ge \frac{m}{2} \|\theta - \bar{\theta}\|_{2}^{2},$$

$$\|\nabla f(\theta) - \nabla f(\bar{\theta})\|_{2} \le M \|\theta - \bar{\theta}\|_{2}.$$
(1)

Langevin Monte Carlo Algorithm (LMC)

- Given $\theta^{(0)} \in \mathbb{R}^p$ random or deterministic
- For k > 0, $\theta^{(k+1,h)} = \theta^{(k,h)} h\nabla f(\theta^{(k,h)}) + \sqrt{2h}\xi^{k+1}$ with

Where h>0 is the step-size and $\xi^{(k)} \underset{iid}{\sim} \mathcal{N}_p(0,\ I_p)$ independent of $\theta^{(0)}$

Notice that LMC is a gradient descent with an additional Gaussian random perturbation and also the Euler Discretization of the Langevin Dynamic (LD).

- the target distribution P_{π} with density $\pi \propto \exp\{-f\}$
- the distribution of $\theta^{(K,h)}$ when h is small and K is large such that T = Kh is large.

An upper bound

Background on constrained and unconstrained sampling

Theorem

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Let $\theta^* \in \mathbb{R}^p$ be the global minimum of f and assume that for some $\alpha \geq 1$, we have $h \leq 1/(\alpha M)$ and $K \geq \alpha$. Then, for any time horizon T = Kh. The approximation νP_{θ}^K furnished by the LMC algorithm with the initial distribution $\nu = \mathcal{N}_p(\theta^*, M^{-1}I_p)$ satisfies

$$\|\nu P_{\theta}^K - P_{\pi}\|_{TV} \leq \frac{1}{2} \exp\left(\frac{p}{4} \log\left(\frac{M}{m}\right) - \frac{Tm}{2}\right) + \left(\frac{pM^2 Th\alpha}{4(2\alpha - 1)}\right)^{1/2}.$$

GOAL: Same result for constrained sampling

One approach for constrained sampling

See Sampling from a log-concave distribution with Projected Langevin Monte Carlo (BUBECK; ELDAN; LEHEC, 2015)

- Let $\mathcal{K} \subset \mathbb{R}^n$ be a convex body such that $0 \in \mathcal{K}$, $B(0, r) \subset \mathcal{K} \subset B(0, R)$.
- Let $Proj_{\mathcal{K}}$ denote the Euclidean projection onto K.
- Let $f: \mathcal{K} \to \mathbb{R}$ be an L-Lipschitz and β -smooth convex function, i.e., f is differentiable and satisfies the following conditions: for all $|\nabla f(x)| \le L$, and $x, y \in K$, $|\nabla f(x) \nabla f(y)| \le \beta |x y|$.

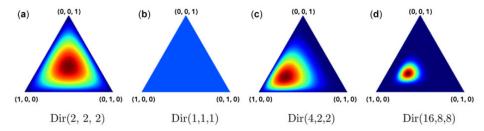
$$X_{k+1} = \mathsf{Proj}_{\mathcal{K}} \left(X_k - \dfrac{\eta}{2}
abla f(X_k) + \sqrt{\eta} \, \xi_k
ight), \; \eta > 0$$

Let
$$K := \Delta_{d+1} = \{ x \in \mathbb{R}^d_+ : \mathbf{1}^\top x \le 1 \}$$
 and

$$\pi(x) \propto \exp(-f(x)); \quad f(x) = -\sum_{i=1}^d a_i \log x_i - a_{d+1} \log \left(1 - \sum_{i=1}^d x_i\right).$$

where $\mathbf{a} \in \mathbb{R}^{d+1}$ and $a_i > 0$,

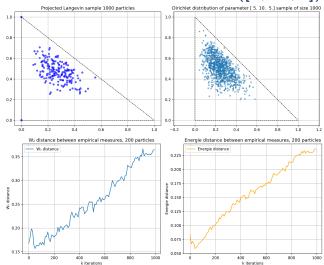
Background on constrained and unconstrained sampling



Metrics

$$\begin{split} W_2^2(P,Q) &= \inf\{\mathbb{E}[\|X-Y\|^2], \ X \sim P \ \text{and} \ Y \sim Q\} \\ ED(\hat{P},\hat{Q}) &= \frac{2}{N^2} \sum_{i,j=1}^N \|X_i - Y_j\| - \frac{1}{N^2} \sum_{i,j=1}^N \|X_i - X_j\| - \frac{1}{N^2} \sum_{i,j=1}^N \|Y_i - Y_j\| \\ \text{where } \hat{P} &= \frac{1}{N} \sum_{i=1}^N \delta_{X_i} \ \text{and} \ \hat{Q} &= \frac{1}{N} \sum_{i=1}^N \delta_{Y_i} \end{split}$$

First case : Corner issue, case of $\mathcal{D}([5, 10, 5])$



Solution: Removing the points on the boundary of the polytope

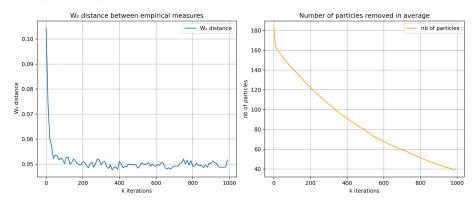


Figure: W_2 distance between the empirical measures (Left) and number of particle removed (Right)

Solution: Metropolis Hasting Adjustment

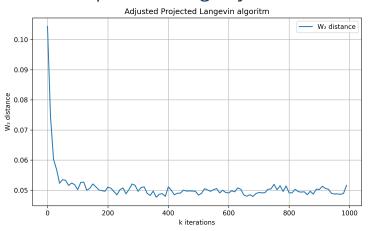
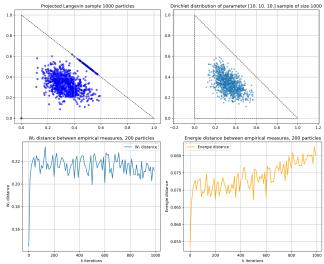


Figure: 200 particles filtered by Metropolis-Hastings and distance to target every 20 iteration



Background on constrained and unconstrained sampling

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Solution: Removing the points on the boundary of the polytope

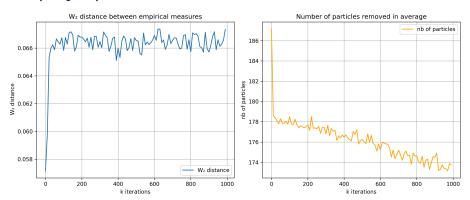


Figure: W_2 distance between the empirical measures (Left) and number of particle removed (Right)

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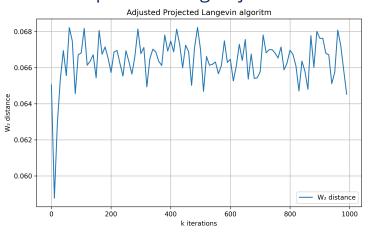


Figure: 200 particles filtered by Metropolis-Hastings and distance to target every 20 iteration

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Metropolis-Adjusted Preconditioned Langevin Algorithm (MAPLA)

Idea: The procedure is adjusting the Markov chain of the discrete version (Euler) of the following SDE with Metropolis Hasting filter.

Given a function \mathscr{G} : int(\mathcal{K}) $\to \mathbb{S}^d_+$ called a metric,

$$dX_t = \mathfrak{m}(X_t)dt + \sqrt{2} \cdot \mathscr{G}(X_t)^{-1/2} dB_t$$
 (2)

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$$\mathfrak{m}(X_t) = -\mathscr{G}(X_t)^{-1} \nabla f(X_t) \tag{3}$$

The discretization gives MAPLA

$$X_{k+1} - X_k = -h \cdot \mathscr{G}(X_k)^{-1} \nabla f(X_k) + \sqrt{2h} \cdot \mathscr{G}(X_k)^{-1/2} \, \xi_k \; ; \quad \xi_k \sim \mathcal{N}\left(0, \; \mathbf{I}_{d \times d}\right)$$

 $(X_k)_{k\geq 0}$ is an homogeneous Markov chain defined by a collection of transition probability $\mathbf{P} = \{\mathcal{P}_x, x \in \mathcal{K}\}$, for any $x \in \mathcal{K}$

$$\mathcal{P}_{x} = \mathcal{N}\left(x - h \cdot \mathcal{G}(x)^{-1} \nabla f(x), \ 2h \cdot \mathcal{G}(x)^{-1}\right)$$

Take this kernel as a proposal in the Metropolis Hasting filter

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Related Algorithms

Other proposal distributions $P_X \sim \mathcal{N}(\mathfrak{m}(X), 2h \cdot \mathscr{G}(X)^{-1})$

Algorithm	Mean $\mathfrak{m}(X)$	
MAPLA	$X - h \cdot \mathscr{G}(X)^{-1} \nabla f(X)$	
ManifoldMALA (GIROLAMI;CALDERHEAD,2011	$X + h \cdot \{ (\nabla \cdot \mathcal{G}^{-1})(X) - \mathcal{G}(X)^{-1} \nabla f(X) \}$	
Dikin (KOOK; VEMPALA, 2024)	X	

Algorithm

Generate $X_0 \sim \Pi_0$ (initialization)

- **1** Generate a proposal Z from \mathcal{P}_X where X is current the iterate
- 2 If $Z \notin \mathcal{K}$, reject Z and set X to be X' (next iterate).
- 3 If $Z \in \mathcal{K}$, compute the Metropolis-Hastings acceptance probability $p_{X\to Z}$.
- 4 With probability $p_{X\to Z}$, set X'=Z (accept); otherwise set X'=X(reject).

Mixing Time and Warm start

Definition

We introduce the important indicator of convergence

$$\tau_{\text{mix}}(\delta; \mathbf{P}, \mathcal{C}) \stackrel{\text{def}}{=} \sup_{\pi_0 \in \mathcal{C}} \inf\{k \geq 0 : d_{\text{TV}}(\mathbb{T}^k_{\mathbf{P}} \pi_0, \nu) \leq \delta\}$$

with the operator $\mathbb{T}_{\mathbf{P}}$, $(\mathbb{T}_{\mathbf{P}}\mu)(S) = \int_{\mathcal{K}} \mathcal{P}_{\mathbf{V}}(S) \cdot d\mu(y)$

How to choose π_0 ? we choose it be *warm* relative to the target π

- Warm $(L_{\infty}, M, \pi) = \{\pi_0 \in \mathcal{P}(\mathcal{K}), \sup_{A \in \mathcal{F}(\mathcal{K})} \frac{\pi_0(A)}{\pi(A)} \leq M\}$
- Warm $(L_1, M, \pi) = \{\pi_0 \in \mathcal{P}(\mathcal{K}), \|\frac{\mu_0}{\nu}\|_{L^1(\mu_0)} = M\}$

Now one can wonder what kind of assumption to do on $K_{\bullet}\mathscr{G}$ and f to derive a bound

Assumptions on \mathscr{G} : Self-concordance

Properties introduced by Nestrerov in optimization.

The metric $\mathscr{G}: \operatorname{int}(\mathcal{K}) \to \mathbb{S}^d_+$ is **self-concordant** if

$$\forall \ x \in \operatorname{int}(\mathcal{K}), \ v \in \mathbb{R}^d, \quad \|\mathscr{G}(x)^{-1/2} \mathrm{D}\mathscr{G}(x)[v] \mathscr{G}(x)^{-1/2} \|_{op} \leq 2 \cdot \|v\|_{\mathscr{G}(x)} \ .$$

The metric is **strongly self-concordant** if for all $x \in \text{int}(\mathcal{K})$ and $v \in \mathbb{R}^d$,

$$\|\mathscr{G}(x)^{-1/2} D\mathscr{G}(x)[v] \mathscr{G}(x)^{-1/2} \|_{F} \leq 2 \cdot \|v\|_{\mathscr{G}(x)}$$
.

Assumptions on f: Curvature and Lipschitzness

The potential $f: \operatorname{int}(\mathcal{K}) \to \mathbb{R}$ satisfies a (μ, \mathcal{G}) -curvature lower bound where $\mu > 0$ if for any $x \in \text{int}(\mathcal{K})$,

$$\nabla^2 f(x) \succeq \mu \cdot \mathscr{G}(x)$$

The potential f satisfies a (λ, \mathcal{G}) -curvature upper bound where $\lambda \geq 0$ if for any $x \in \operatorname{int}(\mathcal{K})$,

$$\nabla^2 f(x) \leq \lambda \cdot \mathscr{G}(x) .$$

the potential f satisfies a (β, \mathcal{G}) -gradient upper bound where $\beta \geq 0$ if for any $x \in \operatorname{int}(\mathcal{K})$,

$$\|\nabla f(x)\|_{\mathscr{G}(x)^{-1}} \leq \beta.$$

Assumption on K: symmetry

The metric \mathscr{G} is said to be **symmetric** with parameter $\nu > 1$ if for any $x \in \operatorname{int}(\mathcal{K}),$

$$\mathcal{E}_{x}^{\mathscr{G}}(1)\subseteq\mathcal{K}\cap(2x-\mathcal{K})\subseteq\mathcal{E}_{x}^{\mathscr{G}}(\sqrt{\nu})$$

With $\mathcal{E}_{\mathbf{v}}^{\mathscr{G}}(r)$ the Dikin ellipsoid of radius r defined as

$$\mathcal{E}_{x}^{\mathscr{G}}(r) = \{y : \|y - x\|_{\mathscr{G}(x)} < r\}$$

First case: Self-concordant version

Define the quantity $b_{SC}(d, \lambda, \beta)$

$$b_{\text{SC}}(d,\lambda,\beta) \stackrel{\text{def}}{=} c_1 \cdot \min \left\{ \frac{1}{d^3}, \ \frac{1}{d \cdot \lambda}, \ \frac{1}{\beta^2}, \frac{1}{\beta^{2/3}}, \frac{1}{(\beta \cdot \lambda)^{2/3}} \right\}$$

For precision $\delta \in (0, 1/2)$ and warmness parameter $M \ge 1$, if the step size h is bounded as $0 < h \le b_{SC}(d, \lambda, \beta)$, $C \in \{Warm(L_{\infty}, M, \pi), Warm(L_{1}, M, \pi)\}$ that

$$au_{ ext{mix}}(\delta; \mathbf{T}, \mathcal{C}) = rac{c_2}{h} \cdot \max \left\{ 1, \min \left\{ rac{1}{\widetilde{\mu}^2},
u
ight\}
ight\} \cdot \log \left(rac{\mathfrak{m}_{\mathcal{C}}}{\delta}
ight) \, ,$$

$$\mathsf{m}_{\mathcal{C}} = \begin{cases} M^{1/2}, & \mathcal{C} = \mathsf{Warm}(L_{\infty}, M, \pi) \\ M^{1/3}, & \mathcal{C} = \mathsf{Warm}(L_{1}, M, \pi) \end{cases}, \quad \widetilde{\mu} = \frac{\mu}{8 + 4\sqrt{\mu}}$$

where c_1 , c_2 are universal positive constants.

Assumptions on \mathscr{G} : Self-concordance₊₊

The metric is said to be **lower trace self-concordant** with parameter $\alpha > 0$ if for all $x \in \text{int}(\mathcal{K})$ and $v \in \mathbb{R}^d$,

$$\operatorname{tr}(\mathscr{G}(x)^{-1}\mathrm{D}^2\mathscr{G}(x)[v,v]) \geq -\alpha \cdot \|v\|_{\mathscr{G}(x)}^2.$$

The metric is said to be **average self-concordant** if for any $x \in \text{int}(\mathcal{K})$ and $\varepsilon > 0$, there exists $r_{\varepsilon} > 0$ such that for any $h \in (0, \frac{r_{\varepsilon}^2}{2d}]$,

$$\mathbb{P}_{\xi \sim \mathcal{N}(x, 2h \cdot \mathcal{G}(x)^{-1})} \left(\|\xi - x\|_{\mathcal{G}(\xi)}^2 - \|\xi - x\|_{\mathcal{G}(x)}^2 \le 4h \cdot \varepsilon \right) \ge 1 - \varepsilon$$

self-concordant₊₊ = **strong**, **lower-trace** and average self-concordance

Summary and main results

Conditions		Mixing time scaling
$f \text{ is } \begin{cases} (\mu, \mathscr{G})\text{-curv. lower-bdd.} \\ (\lambda, \mathscr{G})\text{-curv. upper-bdd.} \\ (\beta, \mathscr{G})\text{-grad. upper-bdd.} \end{cases}$	$\mathcal{G} \text{ is } \begin{cases} \text{self-concordant} \\ \nu\text{-symmetric} \end{cases}$ &&	$\min\left\{\nu, \frac{1}{\mu}\right\} \cdot \max\{d^3, d\lambda, \beta^2\}$ (Theorem 4.1)
	\mathcal{G} is $\begin{cases} \text{self-concordant}_{++} \\ \nu\text{-symmetric} \end{cases}$	$\min \left\{ \nu, \frac{1}{\mu} \right\} \cdot \max\{d\beta, d\lambda, \beta^2\}$ (Theorem 4.2)
f is linear	& \mathcal{G} is $\begin{cases} \text{self-concordant}_{++} \\ \nu\text{-symmetric} \end{cases}$	$ u \cdot d^2 $ (Theorem 4.3)

Elements of proof: One-step overlap technique, Lovász (1999)

Let $s \in (0, 1/2)$. The s-conductance of $\mathbf{T} = \{\mathcal{P}_x : x \in \mathcal{K}\}$ (MAPLA) with stationary distribution π (thanks to MF) supported on \mathcal{K} is defined as

$$\Phi^{\textit{s}}_{\textbf{T}} = \inf_{\substack{\textit{A} \in \mathcal{F}(\mathcal{K})\\ \nu(\textit{A}) \in (\textit{s},1-\textit{s})}} \frac{1}{\min\{\nu(\textit{A}) - \textit{s},\ 1 - \nu(\textit{A}) - \textit{s}\}} \cdot \int_{\textit{A}} \mathcal{P}_{\textit{x}}(\mathcal{K} \setminus \textit{A}) \cdot d\nu(\textit{x}) \; .$$

The (ordinary) conductance $\Phi_{\mathbf{P}}$ of \mathbf{P} is the limit of $\Phi_{\mathbf{P}}^{s}$ as $s \to 0$. (see Vempala 2005) If $\pi_0 \in Warm(L_\infty, M, \pi)$, then

$$\mathrm{d}_{\mathrm{TV}}(\mathbb{T}^k_{\mathbf{T}}\pi_0,\pi) \leq \sqrt{M} \cdot \left(1 - \frac{\Phi_{\mathbf{T}}^2}{2}\right)^k \leq \sqrt{M} \cdot \exp\left(-\frac{k \cdot \Phi_{\mathbf{T}}^2}{2}\right)$$

By setting the right hand side to be less than δ for $\delta \in (0, 1/2)$

$$\tau_{\mathrm{mix}}(\delta; \mathbf{T}, \mathcal{C}) = \frac{2}{\Phi_{\mathbf{T}}^2} \cdot \log \left(\frac{\sqrt{M}}{\delta} \right) \leq \frac{C'}{h} \cdot \max \left\{ 1, \min \left\{ \frac{1}{\widetilde{\mu}^2}, \ \nu \right\} \right\} \cdot \log \left(\frac{\sqrt{M}}{\delta} \right)$$

The most important part is to show that

$$\Phi_{\mathbf{T}} \geq C \cdot \sqrt{h} \cdot \min \left\{ 1, \max \left\{ \widetilde{\mu}, \; rac{1}{\sqrt{
u}}
ight\}
ight\} \; .$$

Let
$$\mathcal{K} := \Delta_{d+1} = \{x \in \mathbb{R}^d_+ : \mathbf{1}^{\top}x \leq 1\}$$
 and

$$\pi(x) \propto \exp(-f(x)); \quad f(x) = -\sum_{i=1}^d a_i \log x_i - a_{d+1} \log \left(1 - \sum_{i=1}^d x_i\right) .$$

where $\mathbf{a} \in \mathbb{R}^{d+1}$ and $a_i > -1$, f is satisfies $(\mathbf{a}_{\min}, \mathcal{G})$ -curvature lower bound, (a_{\max}, \mathcal{G}) -curvature upper bound, and $(\|a\|, \mathcal{G})$ -gradient upper bound.

Which metrics \mathscr{G} ? \mathscr{G} is the norm induced by the Hessian of the log-barrier of the polytope $\Delta_{d+1} K = \{x \in \mathbb{R}^d : Ax \leq b\}, \ \varphi(x) = -\sum_{i=1}^m \log(b_i - a_i^\top x)\}$

and
$$\nabla^2 \varphi(x) = \sum_{i=1}^m \frac{a_i a_i^\top}{(b_i - a_i^\top x)^2}$$

DikinWalk vs MAPLA: Mixing Time

DikinWalk Algorithm (KOOK; VEMPALA, 2024) is the discretization of the process with the drift equal to 0_d

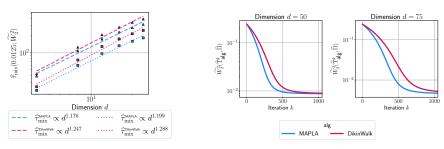


Figure: The dashed and dotted lines correspond to $C_h = 0.1$ and 0.2 respectively. The markers indicate the average over 20 simulations.

DikinWalk vs MAPLA: Acceptance rate

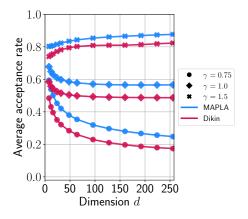


Figure: Variation of $\widehat{R}_{\text{accept}}$ with dimension d when stepsize $h \propto d^{-\gamma}$.

END!

Backup

PI MC bound

Assume that r=1 and let $\epsilon>0$. Then one has

$$d_{\mathsf{TV}}(X_{\mathsf{N}}, \mu) \leq \epsilon$$

provided that $\eta = \widetilde{\mathcal{O}}\left(\frac{R^2}{N}\right)$ and that N satisfies the following: if μ is uniform, then

$$N = \widetilde{\Omega} \left(\frac{R^6 n^7}{\epsilon^8} \right),$$

and otherwise

$$N = \widetilde{\Omega}\left(\frac{R^6 \max(n, RL, R\beta)^{12}}{\epsilon^{12}}\right).$$

MAPLA Algorithm

Algorithm 1: Metropolis-adjusted Preconditioned Langevin Algorithm (MAPLA)

```
Input : Potential f of \Pi, convex support \mathcal{K} \subset \mathbb{R}^d, metric \mathscr{G}: int(\mathcal{K}) \to \mathbb{S}^d_+, step size
                  h > 0, iterations K, initial distribution \Pi_0

 Sample x<sub>0</sub> ∼ II<sub>0</sub>.

 2 for k \leftarrow 0 to K-1 do
         Sample a random vector \xi_k \sim \mathcal{N}(0, I_{d\times d}).
 3
         Generate proposal z = x_k - h \cdot \mathcal{G}(x_k)^{-1} \nabla f(x_k) + \sqrt{2h} \cdot \mathcal{G}(x_k)^{-1/2} \xi_k.
 4
         if z \notin \mathcal{K} then
 5
 6
              Set x_{k+1} = x_k.
         else
 7
              Compute acceptance ratio p_{\text{accept}}(z; x_k) defined in Eq. (1), where p_u is the density
 8
                of \mathcal{N}(y-h\cdot\mathcal{G}(y)^{-1}\nabla f(y), 2h\cdot\mathcal{G}(y)^{-1}).
              Obtain U \sim \text{Unif}([0, 1]).
 9
              if U \le p_{\text{accept}}(z; x_k) then
10
                   Set x_{k+1} = z.
11
              else
12
                   Set x_{k+1} = x_k.
13
              end
14
         end
15
16 end
    Output: x_K
```

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