



## C interfaces to GALAHAD SHA

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# Chapter 1

## GALAHAD C package sha

### 1.1 Introduction

#### 1.1.1 Purpose

Find an approximation to a sparse Hessian using componentwise secant approximation.

Currently, only the control and inform parameters are exposed; these are provided and used by other GALAHAD packages with C interfaces.

#### 1.1.2 Authors

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C interface, additionally J. Fowkes, STFC-Rutherford Appleton Laboratory.

#### 1.1.3 Originally released

April 2013, C interface January 2022.



## Chapter 2

# File Index

### 2.1 File List

Here is a list of all files with brief descriptions:

|   |   |
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## Chapter 3

# File Documentation

### 3.1 galahad\_sha.h File Reference

```
#include <stdbool.h>
#include "galahad_precision.h"
```

#### Data Structures

- struct [sha\\_control\\_type](#)
- struct [sha\\_inform\\_type](#)

#### 3.1.1 Data Structure Documentation

##### 3.1.1.1 struct sha\_control\_type

control derived type as a C struct

#### Data Fields

|      |                         |   |
|------|-------------------------|---|
| bool | f_indexing              | use C or Fortran sparse matrix indexing   |
| int  | error                   | error and warning diagnostics occur on stream error   |
| int  | out                     | general output occurs on stream out   |
| int  | print_level             | the level of output required. $\leq 0$ gives no output, $= 1$ gives a one-line summary for every iteration, $= 2$ gives a summary of the inner iteration for each iteration, $\geq 3$ gives increasingly verbose (debugging) output                                     |
| int  | approximation_algorithm | which approximation algorithm should be used? <ul style="list-style-type: none"><li>• 0 : unsymmetric (alg 2.1 in paper)</li><li>• 1 : symmetric (alg 2.2 in paper)</li><li>• 2 : composite (alg 2.3 in paper)</li><li>• 3 : composite 2 (alg 2.2/3 in paper)</li></ul> |

## Data Fields

|      |                        |   |
|------|------------------------|---|
| int  | dense_linear_solver    | which dense linear equation solver should be used?<br><ul style="list-style-type: none"><li>• 1 : Gaussian elimination</li><li>• 2 : QR factorization</li><li>• 3 : singular-value decomposition</li><li>• 4 : singular-value decomposition with divide-and-conquer</li></ul> |
| int  | max_sparse_degree      | the maximum sparse degree if the combined version is used   |
| bool | space_critical         | if space is critical, ensure allocated arrays are no bigger than needed   |
| bool | deallocate_error_fatal | exit if any deallocation fails  |
| char | prefix[31]             | all output lines will be prefixed by .prefix(2:LEN(TRIM(.prefix))-1) where .prefix contains the required string enclosed in quotes, e.g. "string" or 'string'   |

## 3.1.1.2 struct sha\_inform\_type

inform derived type as a C struct

## Data Fields

|      |                    |   |
|------|--------------------|---|
| int  | status             | return status. See SHA_solve for details                                  |
| int  | alloc_status       | the status of the last attempted allocation/deallocation                  |
| int  | max_degree         | the maximum degree in the adgacency graph                                 |
| int  | differences_needed | the number of differences that will be needed                             |
| int  | max_reduced_degree | the maximum reduced degree in the adgacency graph                         |
| char | bad_alloc[81]      | the name of the array for which an allocation/deallocation error occurred |

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