Pattern Recognition and Neural Networks Writer Identification System

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Abstract—In this work, we present our work pipeline for writer identification from handwriting. Our system uses LBP texture descriptors along with SVM classifier on form-level of IAM Handwriting Database. The system, also, uses form preprocessing techniques to extract separate lines from a single form. The combination of these techniques enables us to achieve up to 93.5% accuracy on the complete dataset and an accuracy between 98.9% to 100% with sampled test. The system can maintain fast execution, while achieving such high accuracy. Furthermore, we compare our approach to other different approaches to illustrate its advantages.

I. INTRODUCTION

Writer identification from handwriting is a challenging problem. Historically, experts with domain knowledge were required to tackle such tricky problem. However, with the rise of AI and machine learning techniques, systems can be built to solve the handwriting identification problem. In machine learning systems, the choice of good features and robust classifiers is the core challenge. For such problem, domainbased features can be used such as codebooks and grapheme signatures. However, with the evolution of general purpose texture descriptors like local binary pattern and local phase quantization, it turns out that these features can perform even better in most cases. For this reason, we decided to adopt the fast and well-known local binary pattern texture descriptor, inspired by [1]. We, also, considered multiple classifiers and decided on support vector machine classifier, which is the best in our case.

II. APPROACH

In this section , we discuss the overall system pipeline. The exact details of each module is discussed in subsequent sections.

Our system can be divided into 3 main modules, shown as follows:

- **Preprocessor:** this module takes the *complete form* image as an input, performs *denoise* and *extracts the written parts* only. Then, it *segment out* each written lines in the document.
- **Feature Extractor**: this module takes each line extracted by the *preprocessor* and perform *local binary*

- pattern texture descriptor on it and calculates the normalized LBP histogram.
- Classifier: this module contains the training and inference of SVM classifier. The training is done on each line as separate train sample, while inference is done on each line separately and then a majority vote is taken.

III. PREPROCESSING MODULE IV. FEATURE EXTRACTION MODULE

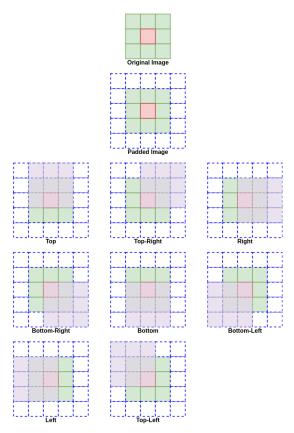


Fig. 1: Illustration of our vectorized implementation of LBP texture descriptor.

The feature extraction module includes **local binary** pattern(*LBP*) texture descriptor. Other feature extractor

were considered, as well. However, after many experiments, we found out *LBP* texture descriptor performs the best in our case. The other feature extractors are discussed in later sections. Although *LBP* features offer high accuracy, **skimage** implementation is not vectorized and heavily depends on *loops*. The extraction of *LBP* features for a single form can take up to 0.5 second. That's why, we come up with a vectorized implementation that speeds up processing to up to 0.02 second per form.

Figure 1 shows the **vectorized implementation** on a simple 3X3 image matrix. The implementation goes as follows:

- 1) The input image is *padded* with *zeros* from all directions with the *LBP* radius size.
- 2) An *LBP* map with the same dimensions as the input image is initialized with zeros.
- 3) The whole original image is displaced to the top and compared to the padded image. Using this method, we compare all pixels in parallel instead of looping over each pixel.
- 4) The resultant map is, then, multiplied by 2 raised to the power of *number of iteration*, then added to the *LBP* map. **Note that,** *number of iteration* ranges from 0 to 7, as only 8 directions are considered to speed up the implementation.
- 5) Steps 3 and 4 are repeated for *top-right*, *right*, *bottom-right*, *bottom*, *bottom-left*, *left* and *top-left* directions.
- 6) A histogram is calculated for the output *LBP* map with 256 bins. The histogram is normalized by its mean, according to the original *LBP* implementation.

V. CLASSIFICATION MODULE

VI. PERFORMANCE ANALYSIS

Classifier	100 test samples	1000 test samples
Support Vector Machine	100%	99.7%
K-Nearest Neighbors	99%	99.4%
Random Forest	99%	99.6%
Logistic Regression	100%	99.5%
Naive Bayes	100%	98.9%

TABLE I: Comparison between accuracies of different classifiers using LBP feature and different sample size.

VII. OTHER APPROACHES

VIII. WORKLOAD DISTRIBUTION

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IX. CONCLUSION AND FUTURE WORK

REFERENCES

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- [2] Text independent writer recognition using redundant writing patterns with contour-based orientation and curvature features.
- [3] An improved online writer identification framework using codebook descriptors.