# CSE440: NATURAL LANGUAGE PROCESSING II

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Lecture 5: Sequence Learning

#### Outline

- Sequence tagging (SLP 8)
- Markov models (SLP Appendix A)
- Recurrent neural networks (SLP 9)

Fully furnished condo in the beautiful Catalina Foothills! Equipped with everything you need - house wares, linens, full-size washer & dryer, cable and Wi-Fi. Relax on your private covered patio or take a dip in the sparkling pool! Close to fine dining and shopping, too. List price is average, please call for exact pricing and availability.

**PRICE** 

Fully furnished condo in the beautiful Catalina Foothills! **LOCATION** WHAT Equipped with everything you need - house wares, linens, full-size washer & dryer, cable and Wi-Fi. Relax on your private covered patio or take a dip in the sparkling pool! **FEATURES** Close to fine dining and shopping, too. List price is NEIGHBORHOOD average, please call for exact pricing and availability.

CONTACT

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•						
ADV	ADJ	NOUN PREP	DET	ADJ	PROPN	PROPN

- Speech recognition
  - Group acoustic signal into phonemes
  - Group phonemes into words
- Natural language processing
  - Part of speech tagging
    - our running example
  - Named entity recognition
  - Information extraction
  - Question answering

#### Parts-of-speech tagging

Why not just make a big table?

badger is a NOUN, trip is a VERB, etc.

Because part-of-speech changes with the surrounding sequence:

- I saw a badger in the zoo.
- Don't badger me about it!
- I saw him trip on his shoelaces.
- She said her trip to Greece was amazing.

How big is this ambiguity issue?

## Part-of-speech ambiguity

	WS	SJ	Brown		
Types:					
1 tag	44,432	(86%)	45,799	(85%)	
2+ tags	7,025	(14%)	8,050	(15%)	

Most words in the English vocabulary are unambiguous.

### Part-of-speech ambiguity

	WS	SJ	Brown		
Types:					
1 tag	44,432	(86%)	45,799	(85%)	
2+ tags	7,025	(14%)	8,050	(15%)	
Tokens:					
1 tag	577,421	(45%)	384,349	(33%)	
2+ tags	711,780	(55%)	786,646	(67%)	

But, most words in running text are ambiguous! That is, ambiguous words are more prevalent.

#### A big table is still a good start

- Only 30-40% of words in running text are unambiguous.
- What if, we have a table for all words, and for ambiguous words, store the most commonly used tag for that word in there?
- This is called Most frequent tag baseline
  - assign each token the tag that it appeared with most frequently in the training data.
  - 92.34% accurate on WSJ corpus.

### A big table is still a good start

- What's the tag for *cut*?

10 cut NN

25 cut VB

13 cut VBD

7 cut VBN

#### Learning sequence taggers

- To improve over the most frequent tag baseline, we should take advantage of the sequence.
- Some options we will cover:
  - Hidden Markov models
    - Parameters estimated by counting (like naïve Bayes)
  - Maximum entropy Markov models
    - Parameters estimated by logistic regression
  - Recurrent neural networks

#### **Hidden Markov Models**

- Maximum entropy Markov models (MEMM)
- (Visible) Markov models for PoS tagging
- Training by counting
- Smoothing probabilities
- Handling unknown words
- Viterbi algorithm

### Why POS Tagging Must Model Sequences

Our running example:

Secretariat is expected to race tomorrow.

Secretariat is \_\_\_\_\_

Race is \_\_\_\_\_

To understand context, we will predict all tags together.

#### Approach 0: Rule-based baseline

- Assign each word a list of potential POS labels using the dictionary
- Winnow down the list to a single POS label for each word using lists of hand-written disambiguation rules

You can learn these rules: see Transformation-based Learning: https://dl.acm.org/citation.cfm?id=218367

### Approach 1: Maximum entropy Markov models

- Maximum entropy = logistic regression
- Markov models
  - Discovered by Andrey Markov
  - Limited horizon



А. А. Марков (1886).

- How would you implement sequence models in the logistic regression algorithm that we know?
- Let's assume we scan the text left to right.

#### Approach 1 continued

- Add the previously seen tags as features!
  - Use gold tags in training
  - Use predicted tags in testing
- Other common features
  - Words, lemmas in a window [-k, +k]
  - Casing info, prefixes, suffixes of these words
  - Bigrams containing the current word

#### See also:

https://github.com/clulab/processors/blob/master/main/src/main/scala/org/clulab/processors/clu/sequences/PartOfSpeechTagger.scala

#### Approach 1: bidirectional MEMMs

- You can stack MEMMs that traverse the text in opposite directions:
  - Left-to-right direction (same as before)
  - Right-to-left: uses the prediction(s) of the above system as features!
    - What is the problem with the predictions of the left-to-right model here?
- Many state-of-the-art taggers use this approach: CoreNLP, processors, SVMTool

### Approach 2: Hidden (visible) Markov Models

- Let's put the probability theory we covered in the previous lecture to use!
- The resulting approach is called (visible) Markov model
- "Visible" to distinguish it from the hidden Markov models, where the tags are unknown
  - Imagine implementing a POS tagger for an unstudied language without POS annotations

Approach 2: Hidden (visible) Markov Models

$$\hat{t}_1^n = \underset{t_1^n}{\operatorname{argmax}} P(t_1^n | w_1^n)$$

- Sentence 1 contains n words
- $t_1^n$  an assignment of POS tags to this sentence
- $w_1^n$  the words in this sentence
- $\hat{t}_1^n$  the estimate of optimal tag assignment

#### Let's formalize this

$$\hat{t}_1^n = \underset{t_1^n}{\operatorname{argmax}} \frac{P(w_1^n | t_1^n) P(t_1^n)}{P(w_1^n)}$$

We have four probabilities: likelihood, prior, posterior and marginal likelihood.

- Prior: Probability distribution representing knowledge or uncertainty of a data object prior or before observing it
- Likelihood: The probability of falling under a specific category or class.
- Posterior: Conditional probability distribution representing what parameters are likely after observing the data object
- Marginal likelihood: likelihood function that has been integrated over the parameter space.
   Does not affect inference

#### Three Approximations

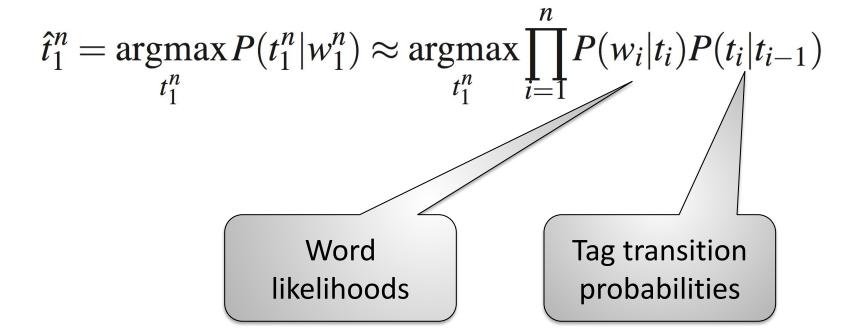
- Words are independent of the words around them
- Words depend only on their POS tags, not on the neighboring POS tags

$$P(w_1^n|t_1^n) \approx \prod_{i=1}^n P(w_i|t_i)$$

A tag is dependent only on the previous tag

$$P(t_1^n) \approx \prod_{i=1}^n P(t_i|t_{i-1})$$

### Replace in the original equation



### **Computing Tag Transition Probabilities**

In the Brown corpus (1M words)

- DT occurs 116,454 times
- DT is followed by NN 56,509 times

$$P(t_i|t_{i-1}) = \frac{C(t_{i-1},t_i)}{C(t_{i-1})}$$

$$P(NN|DT) = \frac{C(DT,NN)}{C(DT)} = \frac{56,509}{116,454} = .49$$

### Computing Word Likelihoods

In the Brown corpus (1M words)

- VBZ occurs 21,627 times
- VBZ is the tag for "is" 10,073 times

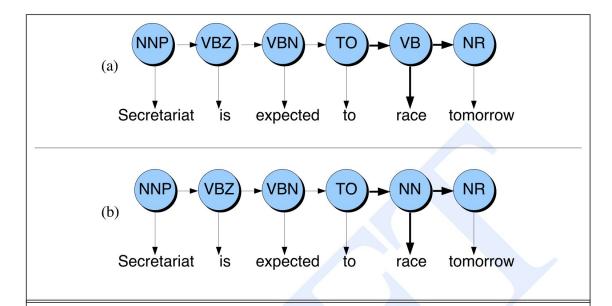
$$P(w_i|t_i) = \frac{C(t_i, w_i)}{C(t_i)}$$

$$P(is|VBZ) = \frac{C(VBZ, is)}{C(VBZ)} = \frac{10,073}{21,627} = .47$$

Secretariat/NNP is/BEZ expected/VBN to/TO race/VB tomorrow/NR

People/NNS continue/VB to/TO inquire/VB the/AT reason/NN for/IN the/AT race/NN for/IN outer/JJ space/NN

Let's see why VB is preferred in the first case



**Figure 5.12** Two of the possible sequences of tags corresponding to the Secretariat sentence, one of them corresponding to the correct sequence, in which *race* is a VB. Each arc in these graphs would be associated with a probability. Note that the two graphs differ only in 3 arcs, hence in 3 probabilities.

#### The first tag transition

- P(NN|TO) = 0.00047
- P(VB|TO) = .83

#### The word likelihood for "race"

- P(race|NN) = 0.00057
- P(race|VB) = 0.00012

#### The second tag transition

- P(NR|VB) = 0.0027
- P(NR|NN) = 0.0012

P(VB|TO)P(NR|VB)P(race|VB) = 0.00000027

P(NN|TO)P(NR|NN)P(race|NN) = 0.00000000032

VB is more likely than NN, even though "race" appears more commonly as a noun!

### Training/Testing an HMM

Just like with any machine learning algorithm, there are two important issues one needs to do to build an HMM:

- Training:
  - Estimating p(t<sub>i</sub>|t<sub>i-1</sub>) and p(w<sub>i</sub>|t<sub>i</sub>)
- Testing (predicting):
  - Estimating the best sequence of tags for a sentence (or sequence or words)

### Training: Two Types of Probabilities

#### A: transition probabilities

- Used to compute the prior probabilities (probability of a tag)
- Often called tag transition probabilities

#### B: observation likelihoods

- Used to compute the likelihood probabilities (probability of a word given tag)
- Often called word likelihoods

### Testing: Viterbi Algorithm

$$\hat{t}_1^n = \underset{t_1^n}{\operatorname{argmax}} P(t_1^n | w_1^n) \approx \underset{t_1^n}{\operatorname{argmax}} \prod_{i=1}^n P(w_i | t_i) P(t_i | t_{i-1})$$

#### Viterbi algorithm

- Computes the argmax efficiently
- Example of dynamic programming

#### What is a viterbi?



#### **Andrew Viterbi**

Engineer

Andrew James Viterbi is an American electrical engineer and businessman who co-founded Qualcomm Inc. and invented the Viterbi algorithm. Wikipedia

Born: March 9, 1935 (age 78), Bergamo, Italy

**Books:** CDMA, Principles of digital communication and coding

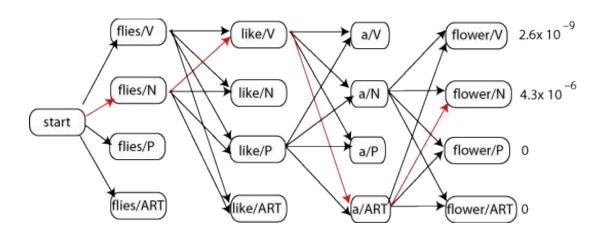
Education: University of Southern

California (1963), More

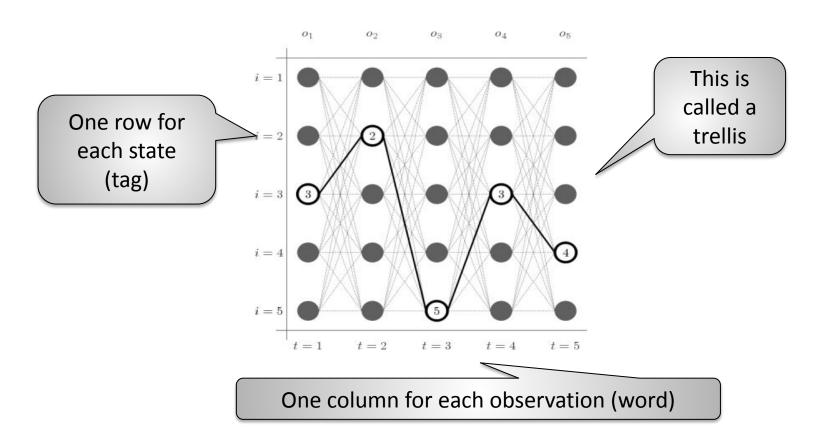
Awards: IEEE Medal of Honor, Claude E.

Shannon Award, More

## Illustration of Search Space



### Illustration of Search Space



## Viterbi Algorithm

#### Input

- State (or tag) transition probabilities (A)
- Observation (or word) likelihoods (B)
- An observation sequence O

#### Output

Most probable state sequence Q together with its probability

Both A and B are matrices with probabilities

## Example of A and B matrices

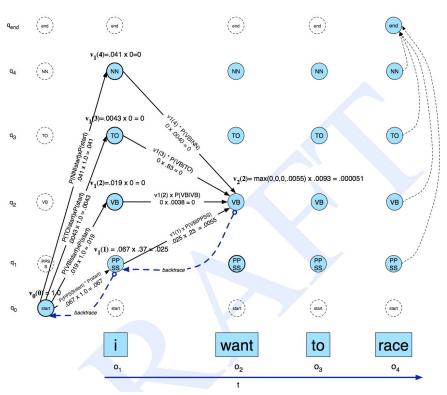
A: The rows are labeled with the conditioning event, e.g., P(PPSS|VB) = .0070

	VB	ТО	NN	PPSS
<s></s>	.019	.0043	.041	.067
VB	.0038	.035	.047	.0070
TO	.83	0	.00047	0
NN	.0040	.016	.087	.0045
PPSS	.23	.00079	.0012	.00014

B: same as A, rows: conditioning events, e.g. P(want|NN) = .000054

	I	want	to	race
VB	0	.0093	0	.00012
TO	0	0	.99	0
NN	0	.000054	0	.00057
PPSS	.37	0	0	0

# **Example Trace**



## Summary of Viterbi Algorithm

$$v_t(j) = \max_{i=1}^N v_{t-1}(i) a_{ij} b_j(o_t)$$

- $v_{t-1}(i)$  the **previous Viterbi path probability** from the previous time step t 1 (i.e., the previous word)
- $a_{ij}$  the **transition probability** from previous state  $q_i$  (i.e., the previous word having POS tag i) to current state  $q_j$  (i.e., the current word having POS tag j)
- $b_j(o_t)$  the **state observation likelihood** of the observation symbol  $o_t$  (i.e., word at position t) given the current state j (i.e., the j POS tag)

# Extending the HMM Algorithm to Trigrams

$$\hat{t}_1^n = \underset{t_1^n}{\operatorname{argmax}} P(t_1^n | w_1^n) \approx \underset{t_1^n}{\operatorname{argmax}} \prod_{i=1}^n P(w_i | t_i) P(t_i | t_{i-1})$$
This is pretty limiting for POS tagging Let's extend it to trigrams of tags!
$$\hat{t}_1^n = \underset{t_1^n}{\operatorname{argmax}} P(t_1^n | w_1^n) \approx \underset{t_1^n}{\operatorname{argmax}} \left[ \prod_{i=1}^n P(w_i | t_i) P(t_i | t_{i-1}, t_{i-2}) \right] P(t_{n+1} | t_n)$$
This is better

- t<sub>n+1</sub> end of sentence tag
- We also need virtual tags,  $t_0$  and  $t_1$ , to be set to the beginning of sentence value.

### TnT

- This is what the TnT (Trigrams'n'Tags) tagger does
- Probably the fastest POS tagger in the world
- Not the best, but pretty close (96% acc)
- http://www.coli.uni-saarland.de/~thorsten/tnt/

### Problems with TnT

$$P(t_i|t_{i-1},t_{i-2}) = rac{C(t_{i-2},t_{i-1},t_i)}{C(t_{i-2},t_{i-1})}$$
 Very sparse!

Backoff model: linear interpolation

$$P(t_i|t_{i-1}t_{i-2}) = \lambda_3 \dot{P}(t_i|t_{i-1}t_{i-2}) + \lambda_2 \dot{P}(t_i|t_{i-1}) + \lambda_1 \dot{P}(t_i)$$

 $\lambda 1 + \lambda 2 + \lambda 3 = 1$ , to guarantee that result is a probability.

### **Deleted Interpolation**

function Deleted-Interpolation(corpus) returns  $\lambda_1, \lambda_2, \lambda_3$ 

```
\lambda_1 \leftarrow 0
\lambda_2 \leftarrow 0
\lambda_3 \leftarrow 0
foreach trigram t_1, t_2, t_3 with f(t_1, t_2, t_3) > 0
    depending on the maximum of the following three values
       case \frac{C(t_1,t_2,t_3)-1}{C(t_1,t_2)-1}: increment \lambda_3 by C(t_1,t_2,t_3)
       case \frac{C(t_2,t_3)-1}{C(t_2)-1}: increment \lambda_2 by C(t_1,t_2,t_3)
       case \frac{C(t_3)-1}{N-1}: increment \lambda_1 by C(t_1,t_2,t_3)
    end
end
normalize \lambda_1, \lambda_2, \lambda_3
return \lambda_1, \lambda_2, \lambda_3
```

# Other Types of Smoothing

• Add one:

$$- P(w \mid t) = \frac{C(w,t)+1}{C(t)+K}$$

- Where K is the number of words with POS tag t
- Variant of add one (Charniak's):

$$- P(t_i \mid t_{i-1}) = (1-\varepsilon) \frac{C(t_i, t_{i-1})}{C(t_{i-1})} + \varepsilon$$

— Not a proper probability distribution!

### **Another Problem for All HMMs**

Massive multiplication here:

$$\hat{t}_1^n = \underset{t_1^n}{\operatorname{argmax}} P(t_1^n | w_1^n) \approx \underset{t_1^n}{\operatorname{argmax}} \prod_{i=1}^n P(w_i | t_i) P(t_i | t_{i-1})$$

### Yet Another Problem: Unknown Words

- Solution 0 (not great): assume uniform emission probabilities (this is what "add one" smoothing does)
  - You can exclude closed-class POS tags such as...
  - This does not use any lexical information such as suffixes
- Solution 1: capture lexical information:

$$P(w^{l}|t^{j}) = \frac{1}{Z}P(\text{unknown word}|t^{j})P(\text{capitalized}|t^{j})P(\text{endings/hyph}|t^{j})$$

- This reduces error rate for unknown words from 40% to 20%

## Main Disadvantage of HMMs

Hard to add features in the model

- Capitalization, hyphenated, suffixes, etc.

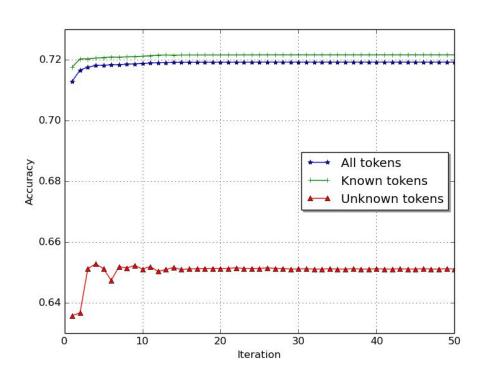
It's possible but every such feature must be encoded in the p(word|tag)

- Redesign the model for every feature!
- MEMMs avoid this limitation, but they take longer to train

### **Evaluation**

- POS tagging accuracy = 100 x (number of correct tags) / (number of words in dataset)
- Accuracy numbers currently reported for POS tagging are most often between 95% and 97%
- But they are much worse for "unknown" words

# Evaluation example



### **Evaluation**

- Accuracy does not work. Why?
- We need precision, recall, F1:
  - P = TP/(TP + FP)
  - R = TP/(TP + FN)
  - F1 = 2PR/(P + R)
- Micro vs. macro F1 measures