

## EECS 2032E - Introduction to Embedded Systems

Summer 2025

### Lab 4

**Due Date:** June 7, 2025

### Lab Objectives

- To write **sed** commands for text processing in **bash**.
- To get familiar with writing and compiling **C** programs.

#### Note:

- This lab should be easy and takes little time to complete.
- The **red text** is what you type and the **blue text** is the computer response.
- Save the **.sed** files and **.c** files in a folder named Lab4. Compress the folder into a ZIP file and submit it on eClass.

### Pre-Lab

Review the course slides of Week 4.

### Problem 1

This problem has two parts:

- a) Write a **sed** command that changes the phone number format in the file, named **phonesA.txt**, as follows:  
(area\_code)prefix-number → area\_code-prefix-number  
For example, (123)456-7890 → 123-456-7890

**Save the file as lab4\_1.sed**

- b) Write a **sed** command to do the opposite, that is, changes the phone number format in the file, named **phonesB.txt** as follows:  
area\_code-prefix-number → (area\_code)prefix-number  
For example, 123-456-7890 → (123)456-7890

Save the file as lab4.2.sed

## Problem 2

Write a C code to read one integer (M) followed by another two integers (i, j). Display the ith through the jth digits of M.

For example if the input is:

1298567 1 4

It should display digits 1 through 4,i.e., display 9856

Integer	1	2	9	8	5	6	7
Digit Number	6	5	4	3	2	1	0

### Hints:

- Read as integer, not string
- Use a combination of integer division and modulus operators to get the result
- For example, in the above case, first you divide the number by  $10^x$ , in that case  $x = 1$  to get 129856
- Then use modulus operator with  $10^y$  ( $y = 4$ ) as a second operand to get 9856
- Your job is to calculate the value of  $x$  and  $y$  and their relation to  $i$  and  $j$ ; you may use a loop that multiply by 10 to get the power of 10 you need

Save the file as lab4.3.c

## Problem 3

In embedded systems, we often read noisy sensor data and need to process it in real time. One simple and powerful technique is a *moving average filter*, which smooths out the data. Write a C program that simulates 10 consecutive readings from a sensor (you can use user input). The program should compute a moving average over the last N readings (say,  $N = 4$ ) and print it every time a new value is added.

### Expected Behavior:

Enter reading 1:10  
Average: 10.00

Enter reading 2:14  
Average: 12.00

Enter reading 3:12  
Average: 12.00

Enter reading 4:8  
Average: 11.00

Enter reading 5:10  
Average: 11.00

Enter reading 5:16  
Average: 11.50

...

Save the file as lab4\_4.c