## AI Project

PAC-MAN GAME



## PEAS

- P → Performance → Challenging, multiple behaviors
- E → Environment → Pac-man, walls, nodes
- $A \rightarrow Actuator \rightarrow up$ , down, left, right
- S → Sensor → Target position, collider

## **ODESA**

- O → Observability → fully observable
- D → Deterministic → Deterministic
- $E \rightarrow Episode \rightarrow Sequential$
- $S \rightarrow Static \rightarrow Static$
- A → agent → Multi-Agent