

Design and Analysis of Algorithms

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Graph Theoretical Problems

- Basec Definitions
- Graph Representation
- Graph Traversal (BFS, DFS)
- Topological Sort
- Strongly Connected Components
- Shortest Paths
 - Single-Source All Destination (Dijkstra and Bellman-Ford Algorithms)
 - All-Pairs (Matrix Multiplication, Floyd-Warshall, and Johnson's Algorithms)
- Minimum Spanning Tree (Kruskal, Prim)

All-Pairs Shortest Paths

Suppose that we are given a weighted directed graph G = (V, E) with a weight function $w : E \mapsto R$. The All-Pairs shortest path problem is to find, for every pair of vertices $u, v \in V$, a shortest path from u to v.

The following solutions are available for this problem:

- 1. Running a single-source shortest-paths algorithm |V| times, once for each vertex as a source.
 - Using Dijkstra's algorithm requires O(|V|3) time complexity.
 - Using Bellman-Ford algorithm requires $O(|V|^2 \times |E|)$ time complexity, which for dense graphs it is $O(|V|^4)$.
- 2. Using Matrix Multiplication
- 3. Using FLOYD-WARSHALL algorithm

let $l_{ij}^{(m)}$ be the minimum weight of any path from vertex i to vertex j that contains at most m edges.

• For m = 0 we have:

$$I_{ij}^{(0)} = \begin{cases} 0 & \text{if } i = j, \\ \infty & \text{if } i \neq j. \end{cases}$$

• For m > 1 we have:

$$I_{ij}^{(m)} = \min \left(I_{ij}^{(m-1)}, \min_{1 \le k \le n} \{ I_{ik}^{(m-1)} + w_{kj} \} \right)$$
$$= \min_{1 \le k \le n} \{ I_{ik}^{(m-1)} + w_{kj} \}$$

Now, any shortest path from i to j contains at most n-1 edges. Also, any longer path can not have lower weight. So,

$$\delta(i,j) = I_{ij}^{(n-1)} = I_{ij}^{(n)} = I_{ij}^{(n+1)} = \cdots$$

Suppose that $W=(w_{ij})$ is the weight matrix for graph G=(V,E). In order to solve All-Pairs shortest path problem, we compute a series of matrices $L^{(1)}, L^{(2)}, \cdots, L^{(n-1)}$, where for $m=1,2,\cdots,n-1$, we have $L^{(m)}=(I_{ij}^{(m)})$.

- The final matrix $L^{(n-1)}$ contains the actual shortest-path weights.
- $I_{ij}^{(1)} = w_{ij}$ for all vertices $i, j \in V$, and so $L^{(1)} = W$.

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EXTEND-SHORTEST-PATHS (L, W)

1 n \leftarrow rows[L]

2 let L' = (l'_{ij}) be an n \times n matrix

3 for i \leftarrow 1 to n

4 do for j \leftarrow 1 to n

5 do l'_{ij} \leftarrow \infty

6 for k \leftarrow 1 to n

7 do l'_{ij} \leftarrow min(l'_{ij}, l_{ik} + w_{kj})

8 return L'
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Relation with Matrix Multiplication: $\begin{cases} + \longrightarrow \min \\ . \longrightarrow + \end{cases}$. The time Complexity is

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SLOW-ALL-PAIRS-SHORTEST-PATHS (W)

1 n \leftarrow rows[W]

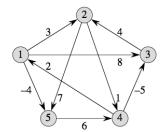
2 L^{(1)} \leftarrow W

3 for m \leftarrow 2 to n-1

4 do L^{(m)} \leftarrow EXTEND-SHORTEST-PATHS (L^{(m-1)}, W)

5 return L^{(n-1)}
```

The total time complexity is $O(n^4)$.



$$L^{(1)} = \begin{pmatrix} 0 & 3 & 8 & \infty & -4 \\ \infty & 0 & \infty & 1 & 7 \\ \infty & 4 & 0 & \infty & \infty \\ 2 & \infty & -5 & 0 & \infty \\ \infty & \infty & \infty & 6 & 0 \end{pmatrix} \quad L^{(2)} = \begin{pmatrix} 0 & 3 & 8 & 2 & -4 \\ 3 & 0 & -4 & 1 & 7 \\ \infty & 4 & 0 & 5 & 11 \\ 2 & -1 & -5 & 0 & -2 \\ 8 & \infty & 1 & 6 & 0 \end{pmatrix}$$

$$L^{(3)} = \begin{pmatrix} 0 & 3 & -3 & 2 & -4 \\ 3 & 0 & -4 & 1 & -1 \\ 7 & 4 & 0 & 5 & 11 \\ 2 & -1 & -5 & 0 & -2 \\ 8 & 5 & 1 & 6 & 0 \end{pmatrix} \qquad L^{(4)} = \begin{pmatrix} 0 & 1 & -3 & 2 & -4 \\ 3 & 0 & -4 & 1 & -1 \\ 7 & 4 & 0 & 5 & 3 \\ 2 & -1 & -5 & 0 & -2 \\ 8 & 5 & 1 & 6 & 0 \end{pmatrix}$$

FASTER-ALL-PAIRS-SHORTEST-PATHS (W)

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\begin{array}{ll} 1 & n \leftarrow rows[W] \\ 2 & L^{(1)} \leftarrow W \\ 3 & m \leftarrow 1 \\ 4 & \textbf{while } m < n-1 \\ 5 & \textbf{do } L^{(2m)} \leftarrow \text{EXTEND-SHORTEST-PATHS}(L^{(m)}, L^{(m)}) \\ 6 & m \leftarrow 2m \\ 7 & \textbf{return } L^{(m)} \end{array}
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The total time complexity is $O(n^3 \log n)$.

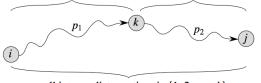
$$L^{(1)} = W,$$
 $L^{(2)} = W^2 = W \cdot W,$
 $L^{(4)} = W^4 = W^2 \cdot W^2$
 $L^{(8)} = W^8 = W^4 \cdot W^4,$
 \vdots
 $L^{(2^{\lceil \lg(n-1) \rceil})} = W^{2^{\lceil \lg(n-1) \rceil}} = W^{2^{\lceil \lg(n-1) \rceil - 1}} \cdot W^{2^{\lceil \lg(n-1) \rceil - 1}}$

Definition

The **intermediate** vertex of a simple path $p = \langle v_1, v_2, \dots, v_l \rangle$ is any vertex of p other than v_1 or v_l , that is, any vertex in the set $\{v_2, v_3, \dots, v_{l-1}\}$.

- Suppose that $V = \{1, 2, \dots, n\}$ and $\{1, 2, \dots, k\} \subset V$.
- For any pair of vertices $i, j \in V$, consider all paths from i to j whose intermediate vertices are all drawn from $\{1, 2, \dots, k\}$, and let p be a minimum-weight path among them.
 - If k is not an intermediate vertex of path p, then a shortest path from vertex i to vertex j with all intermediate vertices in the set $\{1, 2, \dots, k-1\}$ is also a shortest path from i to j.
 - If k is an intermediate vertex of path p, then we break down p into $i \stackrel{p_1}{\leadsto} k \stackrel{p_2}{\leadsto} j$, where p_1 is a shortest path from i to k, p_2 is a shortest path from k to j, and their intermediate vertices are in the set $\{1, 2, \cdots, k-1\}$.

all intermediate vertices in $\{1,2,\ldots,k-1\}$ all intermediate vertices in $\{1,2,\ldots,k-1\}$



p: all intermediate vertices in $\{1, 2, \dots, k\}$

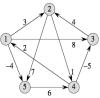
Let $d_{ij}^{(k)}$ be the weight of a shortest path from vertex i to vertex j for which all intermediate vertices are in the set $\{1, 2, \dots, k\}$. A recursive definition following the previous discussion is given by:

$$d_{ij}^{(k)} = \begin{cases} w_{ij} & \text{if } k = 0, \\ \min\left(d_{ij}^{(k-1)}, d_{ik}^{(k-1)} + d_{kj}^{(k-1)}\right) & \text{if } k \ge 1. \end{cases}$$

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FLOYD-WARSHALL(W)

\begin{array}{lll}
1 & n \leftarrow rows[W] \\
2 & D^{(0)} \leftarrow W \\
3 & \text{for } k \leftarrow 1 \text{ to } n \\
4 & \text{do for } i \leftarrow 1 \text{ to } n \\
5 & \text{do for } j \leftarrow 1 \text{ to } n \\
6 & \text{do } d_{ij}^{(k)} \leftarrow \min\left(d_{ij}^{(k-1)}, d_{ik}^{(k-1)} + d_{kj}^{(k-1)}\right) \\
7 & \text{return } D^{(n)}
\end{array}
```

The total time complexity is $\Theta(n^3)$.



$$D^{(0)} = \begin{pmatrix} 0 & 3 & 8 & \infty & -4 \\ \infty & 0 & \infty & 1 & 7 \\ \infty & 4 & 0 & \infty & \infty \\ 2 & \infty & -5 & 0 & \infty \\ \infty & \infty & \infty & 6 & 0 \end{pmatrix} \qquad D^{(3)} = \begin{pmatrix} 0 & 3 & 8 & 4 & -4 \\ \infty & 0 & \infty & 1 & 7 \\ \infty & 4 & 0 & 5 & 11 \\ 2 & -1 & -5 & 0 & -2 \\ \infty & \infty & \infty & 6 & 0 \end{pmatrix}$$

$$D^{(1)} = \begin{pmatrix} 0 & 3 & 8 & \infty & -4 \\ \infty & 0 & \infty & 1 & 7 \\ \infty & 4 & 0 & \infty & \infty \\ 2 & 5 & -5 & 0 & -2 \\ \infty & \infty & \infty & 6 & 0 \end{pmatrix} \qquad D^{(4)} = \begin{pmatrix} 0 & 3 & -1 & 4 & -4 \\ 3 & 0 & -4 & 1 & -1 \\ 7 & 4 & 0 & 5 & 3 \\ 2 & -1 & -5 & 0 & -2 \\ 8 & 5 & 1 & 6 & 0 \end{pmatrix}$$

$$D^{(2)} = \begin{pmatrix} 0 & 3 & 8 & 4 & -4 \\ \infty & 0 & \infty & 1 & 7 \\ \infty & 4 & 0 & 5 & 11 \\ 2 & 5 & -5 & 0 & -2 \\ \infty & \infty & \infty & 6 & 0 \end{pmatrix} \qquad D^{(5)} = \begin{pmatrix} 0 & 1 & -3 & 2 & -4 \\ 3 & 0 & -4 & 1 & -1 \\ 7 & 4 & 0 & 5 & 3 \\ 2 & -1 & -5 & 0 & -2 \\ 8 & 5 & 1 & 6 & 0 \end{pmatrix}$$

Exercises

- Show how to express the single-source shortest-paths problem as a product of matrices and a vector. Describe how evaluating this product corresponds to a Bellman-Ford-like algorithm.
- Suppose we also wish to compute the vertices on shortest paths in the algorithms of this lecture. Show how to compute the predecessor matrix Π from the completed matrix L of shortest-path weights in O(n³) time.
- 3. The vertices on shortest paths can also be computed at the same time as the shortest-path weights. Let us define $\pi_{ij}^{(m)}$ to be the predecessor of vertex j on any minimum-weight path from i to j that contains at most m edges. Modify EXTEND-SHORTEST-PATHS and SLOW-ALL-PAIRS-SHORTEST-PATHS to compute the matrices $\Pi^{(1)}, \Pi^{(2)}, \cdots, \Pi^{(n-1)}$ as the matrices $L^{(1)}, L^{(2)}, \cdots, L^{(n-1)}$ are computed.
- Modify FASTER-ALL-PAIRS-SHORTEST-PATHS so that it can detect the presence of a negative-weight cycle.
- 5. How can the output of the Floyd-Warshall algorithm be used to detect the presence of a negative-weight cycle?
- 6. The transitive closure of G = (V, E) is defined as the graph $G^* = (V, E^*)$, where

$$E^* = \{(i,j) \mid \text{ there is a path from vertex } i \text{ to vertex } j \text{ in } G\}.$$

- a) Describe how we can compute the transitive closure of a graph G = (V, E).
- b) Give an $O(|V| \cdot |E|)$ -time algorithm for computing the transitive closure of a directed graph G = (V, E).

