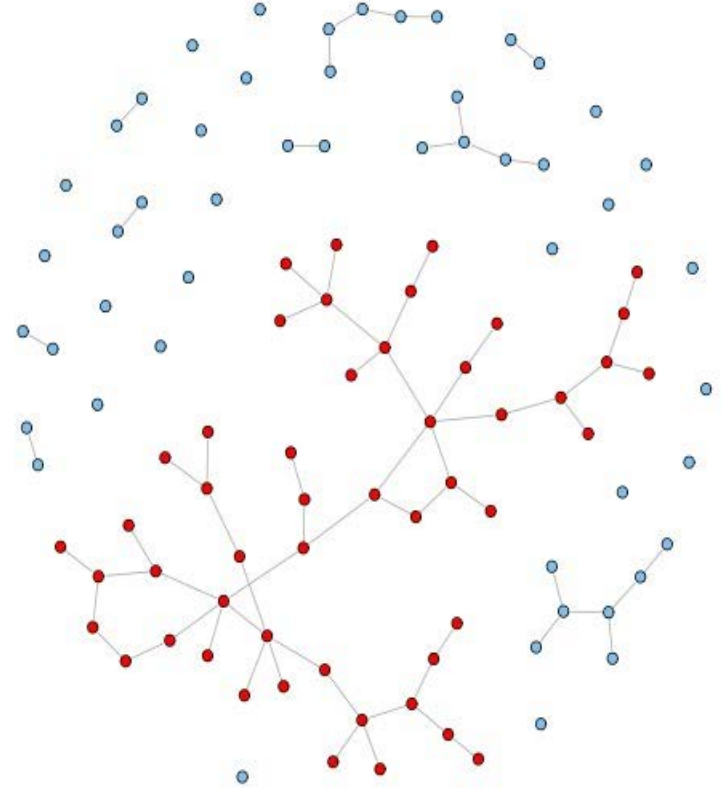




Largest connected component of a graph (LCC)





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The background features a light gray dashed grid. Overlaid on this grid are several wavy, organic lines in dark gray and teal colors, creating a modern, fluid aesthetic.

Agenda

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Introduction

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Approaches

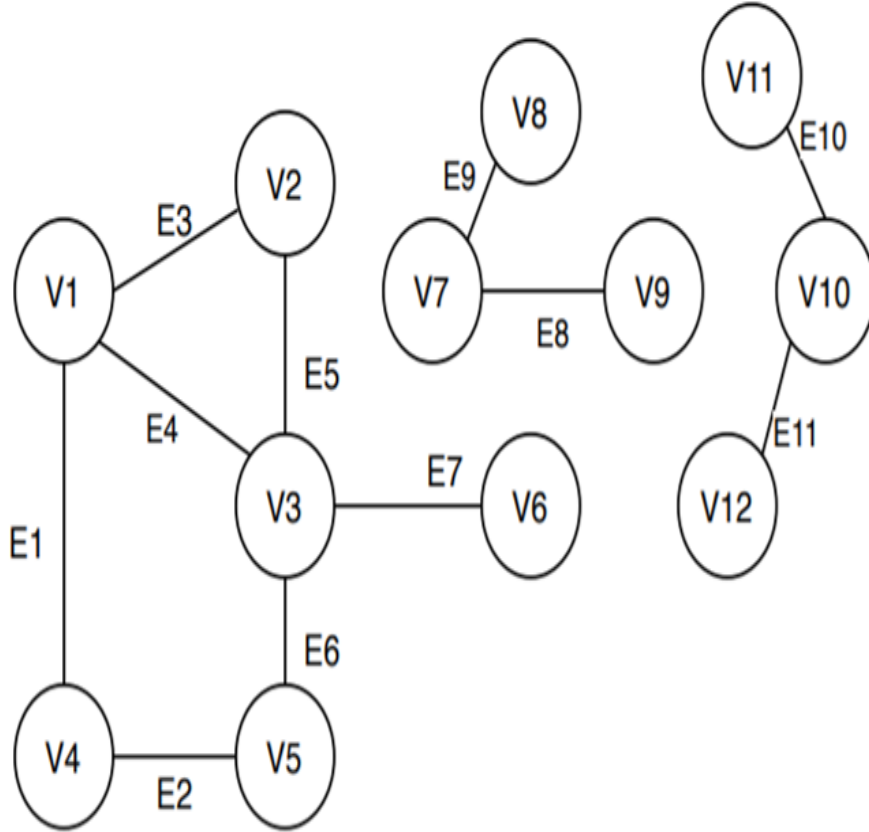
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Code

01

Introduction





LCC Definition

A connected component or simply component of an undirected graph is a subgraph in which each pair of nodes is connected with each other via a path.

02

Applications



Applications

**Fine MRI brain
images**

01

**protein-protein
interaction graph**

02

03

**Iso-surface Topology
Simplification**

03

Approaches



Approaches

DFS

01

02

BFS

Disjoint Sets

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Partitioning

04

Code

```
31 self.file = None
32 self.fingerprints = set()
33 self.logdups = True
34 self.debug = debug
35 self.logger = logging.getLogger(__name__)
36 if path:
37     self.file = open(os.path.join(path, 'requests.log'),
38                     'a')
39     self.file.seek(0)
40     self.fingerprints.update(self.request_fingerprint(request) for request in self.requests)
41
42 @classmethod
43 def from_settings(cls, settings):
44     debug = settings.getbool('supervisord.debug')
45     return cls(job_dir(settings), debug)
46
47 def request_seen(self, request):
48     fp = self.request_fingerprint(request)
49     if fp in self.fingerprints:
50         return True
51     self.fingerprints.add(fp)
52     if self.file:
53         self.file.write(fp + os.linesep)
54
55 def request_fingerprint(self, request):
56     return request_fingerprint(request)
```

```
[10]: import networkx as nx
import matplotlib.pyplot as plt

class Menu_For_Cc:

    def __init__(self):
        print('Welcome\n')

    def show_menu(self):
        while True:
            menu = ['/new', '/change', '/exit']
            choose = input('please choose what do you want to do:\n \
to Make New Graph >> /new\n \
to change The approach for solving the problem >> /change\n \
to close the program please enter >> /exit\n').strip().lower()
            flag = False
            while not flag:
                if choose not in menu:
                    choose = input('Value Error >>> please enter Valid command\n').strip().lower()
                else:
                    flag = True
            if choose == '/new':
                ipType = self.input_type()
                if ipType == 1:
                    self.graph = self.input_to_graph()
                else:
                    self.graph = self.make_graph()
                self.draw(self.graph)
                plt.show()
                plt.clf()
                mode = self.choose_mode()
                cc = connectedComponentsSolver(mode, self.graph, self.graph.get_adj())
                print(f'Largest Connected Component =\n{cc.largest_connected_component()}')
            elif choose == '/change':
                mode = self.choose_mode()
                cc = connectedComponentsSolver(mode, self.graph, self.graph.get_adj())
                print(f'Largest Connected Component =\n{cc.largest_connected_component()}')
            else:
                print('GoodBye')
                break

    def input_type(self):
        while True:
            try:
                ip_type = int(input("Please choose how you want to enter the graph\n (1 for copy paste the graph as a list of lists) or (2 for inputting the graph node by node):\n"))
            except:
                print('Value Error >>> how you want to enter the graph correctly\n')
            else:
                if ip_type == 1 or ip_type == 2:
                    break
        return ip_type
```

Menu..

```
def make_graph(self):
    while True:
        try:
            graph_number_of_nodes = int(input('Please enter the number of nodes in your graph\n').strip())
        except:
            print('Value Error >>> please enter the number of nodes in your graph correctly\n')
        else:
            break
    graph = Graph(graph_number_of_nodes)

    node = input('Please Enter the edges in your graph each per line\nin the following format:>> \n\
source      destination\nexample:\n 1 0 \nthat\'s mean there is an edge from node 1 to node 0 and vise versa\n\
after finishing please enter /finish\n')
    while True:
        if node == '/finish':
            break
        try:
            node0,node1 = map(int, node.split())
        except:
            print(f'Value Error >>> Expect two space separated numbers but gets >> {node}')
        else:
            graph.addEdge(node0,node1)
            node = input()
    return graph

def input_to_graph(self):
    while True:
        try:
            ip = input('Please copy paste the graph as a list of lists:\n ')
        except:
            print('Value Error >>> please enter graph correctly\n')
        else:
            break

    ip = ip.replace(" ", "")
    ip = ip[1:-1]
    ip = ip.split(",")
    op = []
    for g in ip:
        entry = []
        g = g.replace('[', '')
        g = g.replace(']', '')
        if len(g) == 0:
            op.append(entry)
            continue
        g = g.split(',')

        for n in g:
            entry.append(int(n))
        op.append(entry)

    graph_number_of_nodes = len(op)
    graph = Graph(graph_number_of_nodes)
```

Menu..

```

for i in range(graph_number_of_nodes):
    e = op[i]
    if len(e) > 0:
        for j in e:
            graph.addEdge(i,j)

return graph

def draw(self, _graph):
    graph = {}
    for i in range(len(_graph.adj)):
        graph[i] = _graph.adj[i]
    shape = nx.Graph(graph)
    nx.draw(shape, with_labels = True)

def choose_mode(self):
    modes = ['dfs', 'bfs', 'disjoint', 'partitioning']

    while True:
        try:
            m = int(input("Please enter the algorithm number to solve the problem with >>\n"+
                          "(1 for DFS) or (2 for BFS)\n(3 for disjoint) or (4 for partitioning)\n"))

        except:
            m = int(input('Value Error >>> please enter the algorithm number correctly\n'+
                          "\n(1 for DFS) or (2 for BFS)\n(3 for disjoint) or (4 for partitioning)\n"))

        if (m == 1 or m == 2 or m == 3 or m == 4):
            self.mode = modes[m-1]
            break

    return self.mode

def Start(self):
    ipType = self.input_type()
    if ipType == 1:
        self.graph = self.input_to_graph()
    else:
        self.graph = self.make_graph()
    self.draw(self.graph)
    plt.show()
    plt.clf()
    mode = self.choose_mode()
    cc = connectedComponentsSolver(mode, self.graph, self.graph.get_adj())
    print(f'Largest Connected Component = \n{cc.largest_connected_component()}')

if __name__ == "__main__":
    prog = Menu_For_Cc()
    prog.Start()
    prog.show_menu()

```

Menu..

```
[3]: class stack:
    def __init__(self,size):
        self.size=size
        self.counter=0
        self.element=[]

    def add(self,val):
        if self.counter<self.size:
            self.element.append(val)
            self.counter+=1
        else:
            print("queue is full.")
    def pop(self):
        if self.counter>0:
            return self.element[-1]
    def remove(self):
        if self.counter>0:
            self.counter-=1
            self.element.remove(self.element[-1])

    def isempty(self):
        if self.counter==0:
            return True
        else:
            return False
```

Stack..

```
[2]: class queue:
    def __init__(self,size=100):
        self.values=[]
        self.size=size
        self.curr_size=0

    def is_full (self):
        return (self.size == self.curr_size)

    def is_empty(self):
        return (self.curr_size==0)

    def enqueue(self,data):
        if not self.is_full():
            self.values.append(data)
            self.curr_size+=1

    def dequeue(self):
        if not self.is_empty():
            self.curr_size-=1
            return self.values.pop(0)

    def peek(self):
        if not self.is_empty():
            return self.values[0]

    def __str__(self):
        return "Queue = {}".format(self.values)
```

Queue..

```
[5]: class Graph:
    def __init__(self,number_of_nodes):
        self.number_of_nodes = number_of_nodes
        self.adj = [[] for i in range(number_of_nodes)]

    def addEdge(self, node1, node2):
        try:
            if node1 not in self.adj[node2]:
                self.adj[node1].append(node2)
                self.adj[node2].append(node1)
            return True
        except IndexError:
            print("You have Entered node number larger than your graph size please be careful")

        return False
```

Graph..

```
[1]: class connectedComponentsSolver:

    def __init__(self,algorithm,graph):
        self.algorithm = algorithm
        self.graph = graph
        self.all_connected_components = self.solve()

    def solve(self):
        if self.algorithm == 'dfs':
            dfs = DFS(self.graph)
            dfs.Solve_DFS()
            return dfs.get_connected_components()

        elif self.algorithm == 'disjoint':
            ds = Disjoint(self.graph)
            return ds.connected_comp_by_disjoint()

    def largest_connected_component(self):
        lengthes = list(map(len,self.all_connected_components))
        return self.all_connected_components[lengthes.index(max(lengthes))]
```

Solver..


```
[4]: class DFS:
    def __init__(self, graph):
        self.graph = graph
        self.all_connected_components = []

    def Solve_DFS(self, index=0):
        visited = []
        stck = stack(self.graph.number_of_nodes)
        connected_component = []

        visited.append(index)
        stck.add(index)

        while not stck.isempty():
            current_node = stck.pop()
            stck.remove()
            connected_component.append(current_node)

            if index < self.graph.number_of_nodes:
                index += 1

            else:
                return

            for neighbour in self.graph.adj[current_node]:
                if neighbour not in visited:
                    visited.append(neighbour)
                    stck.add(neighbour)

        self.all_connected_components.append(connected_component)
        return self.Solve_DFS(index)

    def get_connected_components(self):
        return self.all_connected_components
```

DFS..

Time complexity: $O(V+E)$

Space complexity: $O(n)$

```

[4]: class BFS:
    def __init__(self, graph, l):
        self.graph = graph
        self.l = l

    def Solve_BFS(self):
        Graph = self.l
        frontier = queue()
        visited = []
        connected = []
        list_of_lists = []

        for index in range(len(Graph)):
            if not (index in visited):
                frontier.enqueue(index)
                while frontier.is_empty() == False:
                    node = frontier.dequeue()
                    if not (node in visited):
                        visited.append(node)
                        connected.append(node)
                        for child in Graph[node]:
                            if not (child in visited):
                                frontier.enqueue(child)
                        #print(visited)
                        #print("The connected Nodes are {}".format(connected))
                        list_of_lists.append(connected)
                        connected = []

        return list_of_lists
    
```

BFS..

Time complexity: $O(V+E)$

Space complexity: $O(n)$

```
[2]: class Disjoint:
    def __init__(self, graph):
        self.graph = graph

    class Subset:
        def __init__(self, parent, rank):
            self.parent = parent
            self.rank = rank

    def set_parent(self, subsets, node):
        if subsets[node].parent != node:
            subsets[node].parent = self.set_parent(subsets, subsets[node].parent)
        return subsets[node].parent

    def union(self, subsets, parent1, parent2):
        if subsets[parent1].rank > subsets[parent2].rank:
            subsets[parent2].parent = parent1
        elif subsets[parent2].rank > subsets[parent1].rank:
            subsets[parent1].parent = parent2
        else:
            subsets[parent1].rank += 1
            subsets[parent2].parent = parent1

    def connected_comp_by_disjoint(self):
        subsets = []
        for u in range(self.graph.number_of_nodes):
            subsets.append(self.Subset(u, 0))

        for u in range(len(self.graph.adj)):
            u_per = self.set_parent(subsets, u)
            for v in self.graph.adj[u]:
                v_per = self.set_parent(subsets, v)
                self.union(subsets, u_per, v_per)
        connected_components = {}
        v = 0
        for _subset in subsets:
            if _subset.parent not in connected_components:
                connected_components[_subset.parent] = [v]
            else:
                connected_components[_subset.parent].append(v)
            v += 1
        return list(connected_components.values())
```

Disjoint sets..

Time complexity: $O(n^2)$

Space complexity: $O(n)$

```
[6]: class Partitioning:
    def __init__(self, graph, l):
        self.graph = graph
        self.l = l

    def Solve_Partitioning(self):

        ip = self.l
        graph = dict()

        for i in range(len(ip)):
            e = ip[i]
            graph[i] = e

        All_cc = []

        nodes = []
        for k in graph:
            nodes.append(k)

        while len(nodes) != 0:
            pivot_index = 0
            pivot = nodes[pivot_index]
            connected = True

            while connected:
                connected = False
                for i in range(nodes.index(pivot)+1, len(nodes)):
                    if nodes.index(pivot) == 0:
                        if nodes[i] in graph[pivot]:
                            nodes.insert(0, nodes[i])
                            del(nodes[i+1])
                            pivot_index += 1
                            connected = True
                            break
                    else:
                        for j in range(0, nodes.index(pivot)):
                            if nodes[i] in graph[nodes[j]]:
                                nodes.insert(0, nodes[i])
                                del(nodes[i+1])
                                pivot_index += 1
                                connected = True
                                break

            cc = nodes[0:pivot_index+1]
            All_cc.append(cc)
            del(nodes[0:pivot_index+1])

        return All_cc
```

Partitioning..

Time complexity: $O(n^2)$

Space complexity: $O(n)$

Welcome

Please choose how you want to enter the graph (1 for copy paste the graph as a list of lists) or (2 for inputting the graph node by node):

1

Please copy paste the graph as a list of lists: `[[], [2, 3], [1, 4], [1, 4], [2, 3], [7], [8], [5, 8, 10], [7, 6, 9], [8], [7, 12], [12], [10, 11, 13, 14, 15], [12, 23], [12], [12, 16], [15, 17, 18], [16], [16, 19, 20], [18], [18, 21], [20, 22, 24], [21, 23], [13, 22], [21, 25, 26], [24], [24], [29], [29], [27, 28, 32], [31], [30, 32, 33], [29, 31, 33], [31, 32, 34], [33, 35], [34, 36], [35]]`

You have Entered node number larger than your graph size please be careful

Please enter the algorithm name to solve the problem with >>(1 for DFS) or (2 for BFS) or (3 for disjoint) or (4 for partitioning)

4

Largest Connected Component =

`[11, 6, 26, 25, 24, 23, 22, 21, 20, 19, 18, 17, 16, 15, 14, 13, 12, 10, 9, 8, 7, 5]`



Output..

1]:

Test Graph

`[[], [2, 3], [1, 4], [1, 4], [2, 3], [7], [8], [5, 8, 10], [7, 6, 9], [8], [7, 12], [12], [10, 11, 13, 14, 15], [12, 23], [12], [12, 16], [15, 17, 18], [16], [16, 19, 20], [18], [18, 21], [20, 22, 24], [21, 23], [13, 22], [21, 25, 26], [24], [24], [29], [29], [27, 28, 32], [31], [30, 32, 33], [29, 31, 33], [31, 32, 34], [33, 35], [34, 36], [35]]`

1]:

`g = [[], [2, 3], [1, 4], [1, 4], [2, 3], [7], [8], [5, 8, 10], [7, 6, 9], [8], [7, 12], [12], [10, 11, 13, 14, 15], [12, 23], [12], [12, 16], [15, 17, 18], [16], [16, 19, 20], [18], [18, 21], [20, 22, 24], [21, 23], [13, 22], [21, 25, 26], [24], [24], [29], [29], [27, 28, 32], [31], [30, 32, 33], [29, 31, 33], [31, 32, 34], [33, 35], [34, 36], [35]]`

1]:



Thank you

Do you have any questions?