

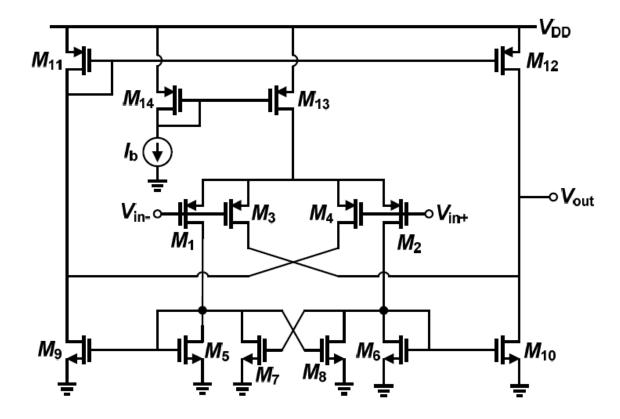
# Amirkabir University of Technology (Tehran Polytechnic)

## **Electronics3**

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Summer99

## Information:

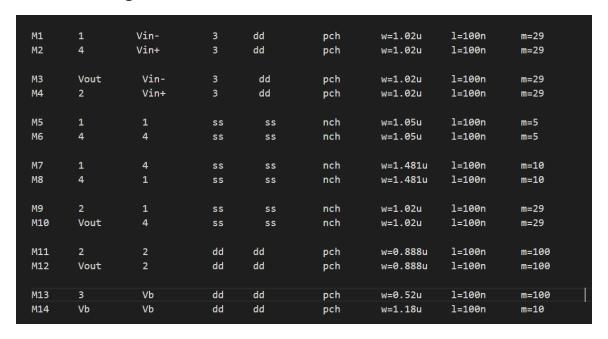


- ➤ Open-loop DC gain ≥ 25 V/V
- ightharpoonup Output voltage swing  $\geq 0.5~V_{pp}$
- ightharpoonup CMRR  $\geq$  35 dB
- $\triangleright$  Settling time with 0.2% settling error in unity-gain sample & hold configuration  $\le 4$  ns
- $\triangleright$  Load capacitance:  $C_L = 1 \text{ pF}$
- Sample & hold capacitance:  $C_{\rm H} = 1 \text{ pF}$
- ➤ Input common-mode voltage:  $V_{\text{cmi}} = 0.3 \text{ V}$
- $\triangleright$  Output common-mode voltage:  $V_{\rm cmo} = 0.5 \text{ V}$
- $\triangleright$  Ideal DC voltage:  $V_{\rm dc} = 0.2 \text{ V}$
- ➤ Power supply voltage:  $V_{DD} = 1.0 \text{ V}$
- Power dissipation: as low as possible
- ➤ Technology: 90 nm CMOS

### Design:

We designed the circuit using the above information and entered the numbers obtained in the software ,but the results were not obtained according to the design and a number of transistors were in the linear and cut-off area and the amount of gain and phase margin was less ,so we must We changed the design a bit to achieve the desired result ,so with experimental changes we tried the execution and made changes to get new results.

## Initial design:



Preliminary design results:

#### subckt

element 0:m13 0:m14 model 0:pch.15 0:pch.10 region Saturati Saturati

id -675.8475u -199.9964u

ibs 0. 0.

ibd 27.4244p 4.4002p

vgs -440.0156m -440.0156m

vds -274.2425m -440.0156m

gain= 1.9605E+01

unity\_gain= 5.2808**E**+09

phase\_margin= 5.1642E+00

#### subckt

element 0:m7 0:m8 0:m9 0:m10 0:m11 0:m12 model 0:nch.8 0:nch.8 0:nch.8 0:nch.8 0:pch.15 0:pch.15 region Cutoff Cutoff Cutoff Cutoff Saturati Saturati id 166.3552u 166.3552u 498.2067u 498.2047u -381.2198u -381.2214u ibs 0. 0. 0. 0. 0. 0.

ibd -3.4396p -3.4396p -18.6769p -18.6769p 35.5980p 35.5984p

vgs 343.9433m 343.9433m 343.9433m 343.9433m -355.9773m -355.9773m

vds 343.9433m 343.9433m 644.0227m 644.0196m -355.9773m -355.9804m

#### subckt

element 0:m1 0:m2 0:m3 0:m4 0:m5 0:m6
model 0:pch.10 0:pch.10 0:pch.10 0:pch.10 0:nch.8 0:nch.8
region Saturati Saturati Saturati Cutoff Cutoff
id -220.9372u -220.9372u -116.9848u -116.9824u 54.5809u 54.5809u
ibs 7.9531p 7.9531p 7.9531p 7.9531p 0. 0.
ibd 19.0258p 19.0258p 10.3235p 10.3234p -1.7198p -1.7198p
vgs -425.7575m -425.7575m -425.7575m -425.7575m 343.9433m 343.9433m
vds -381.8143m -381.8143m -81.7379m -81.7348m 343.9433m 343.9433m

## Design after changes:

M1	1	Vin-	3	dd	pch	w=1.02u	l=100n	m=29
M2	4	Vin+	3	dd	pch	w=1.02u	l=100n	m=29
М3	Vout	Vin-	3	dd	pch	w=1.02u	l=100n	m=29
M4	2	Vin+	3	dd	pch	w=1.02u	l=100n	m=29
M5	1	1	SS	SS	nch	w=1.05u	l=100n	m=4
M6	4	4	SS	SS	nch	w=1.05u	l=100n	m=4
M7	1	4	SS	SS	nch	w=1.481u	l=100n	m=3
M8	4	1	SS	SS	nch	w=1.481u	l=100n	m=3
M9	2	1	SS	SS	nch	w=1.02u	l=100n	m=120
M10	Vout	4	SS	SS	nch	w=1.02u	l=100n	m=120
								_
M11	2	2	dd	dd	pch	w=0.888u	l=100n	m=40
M12	Vout	2	dd	dd	pch	w=0.888u	l=100n	m=40
M13	3	Vb	dd	dd	pch	w=0.52u	l=100n	m=100
M14	Vb	Vb	dd	dd	pch	w=1.18u	l=100n	m=10
Ib	Vb	dd	dc=2	00u				
VDD	dd	0	dc=1					
VSS	ss	0	dc=0					

Results after changes:

gain= 3.1033E+01 unity\_gain= 5.1556E+09 phase\_margin= 6.7645E+01

#### subckt

element 0:m13 0:m14 model 0:pch.15 0:pch.10 region Saturati Saturati id -683.5266u -199.9965u ibs 0. 0. ibd 28.4371p 4.4002p vgs -440.0156m -440.0156m vds -284.3695m -440.0156m

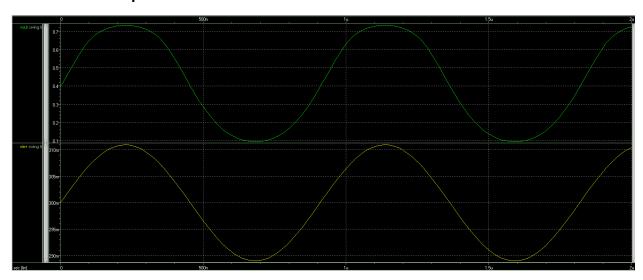
#### subckt

element 0:m7 0:m8 0:m9 0:m10 0:m11 0:m12 model 0:nch.8 0:nch.8 0:nch.8 0:nch.8 0:pch.15 0:pch.15 region Saturati Saturati Saturati Saturati Saturati 92.0080u 92.0080u 2.4338m 2.4338m -2.2654m -2.2654m ibs 0. 0. 0. 0. 0. 0. ibd -1.1343p -1.1343p -47.6996p -47.6994p 24.1007p 24.1007p 378.0890m 378.0890m 378.0890m 378.0890m -602.5133m -602.5133m vgs 378.0890m 378.0890m 397.4867m 397.4852m -602.5133m -602.5148m vds

```
subckt
element 0:m1
             0:m2 0:m3 0:m4 0:m5
                                        0:m6
model 0:pch.10 0:pch.10 0:pch.10 0:pch.10 0:nch.8 0:nch.8
region Saturati Saturati Saturati Saturati Saturati
id -173.3389u -173.3389u -168.4217u -168.4214u 81.3256u 81.3256u
     8.2468p 8.2468p 8.2468p 0.
ibs
ibd 18.0355p 18.0355p 17.4730p 17.4730p -1.5124p -1.5124p
vgs -415.6305m -415.6305m -415.6305m -415.6305m 378.0890m 378.0890m
vds -337.5415m -337.5415m -318.1453m -318.1439m 378.0890m 378.0890m
subckt
element 0:m1
             0:m2 0:m3 0:m4 0:m5
                                        0:m6
model 0:pch.10 0:pch.10 0:pch.10 0:pch.10 0:nch.8 0:nch.8
region Saturati Saturati Saturati Saturati Saturati
id -173.3389u -173.3389u -168.4217u -168.4214u 81.3256u 81.3256u
ibs 8.2468p 8.2468p 8.2468p 0.
ibd 18.0355p 18.0355p 17.4730p 17.4730p -1.5124p -1.5124p
vgs -415.6305m -415.6305m -415.6305m -415.6305m 378.0890m 378.0890m
vds -337.5415m -337.5415m -318.1453m -318.1439m 378.0890m 378.0890m
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### So the circuit has obtained the desired values

For swinging, we apply a sinusoidal input to the circuit so that the output wave does not break



## Transient mode response:

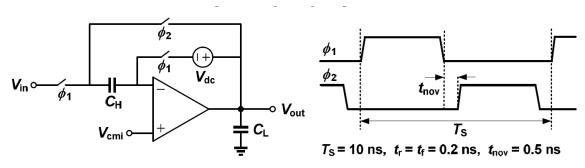
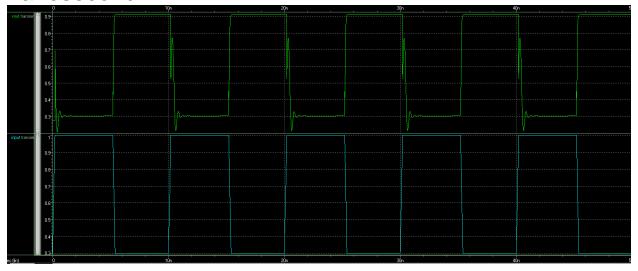


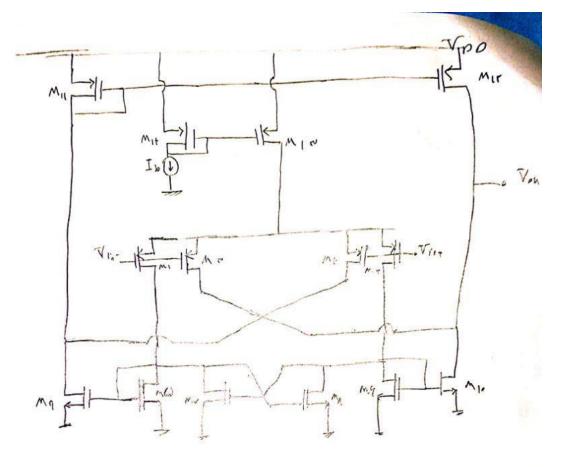
Fig. 2: Transient simulation circuit.

We need to add two capacitors and a switch that have two phase difference switches and follow the input output with phase difference.

The settling time is about one nanosecond



Theoretical calculations:



$$I_{01} = I_{0r} = I_{0m} = I_{01} = 0$$
,  $A_{0m} = 0$ ,  $A$ 

$$I_{00} = I_{01} = \frac{|\frac{w}{w}|_{0}}{(\frac{w}{w})_{0}} \times I_{00} = Y_{00} = Y_{$$

rdg(1,1,00) = 1/10 = 1.Kl rds(0,1) = rDKl Vds(V,N) = \00K1 Vds(9,1) = DK1 Vds(11,17) = 4,44K1 Rout = Ndsix | rds = | rdsi = Y.K2 | DK2 | 19,44K = YDKA Isc = iar + id, - idir ids = ( o + Via) gmr = Prrcm Vin ide = 164 + 1dn = 1 (1 - Vin) gmr = VAgr - VAgnn -Mrm m Vin = VA ( D, Mrm - 1, Mrm) VA = - 1777/0 = -0/1707/0 1d1. = VASMI = - TT, 19 10 Tin 129 = - VA ama = Y (119(m) Vin ile = idr = YY,19 m (Via) + T, TT(m) Vin = YD, WYm (Via) 1211 = 129 - 12+ id It = id II = YDYDYM Vin Isc = ( 1, 22 - 17, 19 - 72, 27) (M) Vin = - (f, 12 (n)) = 6 m

Ade = - Gm Rout = FF, Th mxr, DK = 11.19 W

$$I_{SC} = I_{d_{1}} + I_{d_{1}} - I_{d_{1}}$$

$$\frac{0 - V_{A}}{V_{d_{1}} r} = f(V_{A} - V_{CM}) g_{M_{1}} = \sum V_{A} = 0.99 V_{CM}$$

$$I_{d_{1}} = I_{d_{1}} = (V_{A} - V_{CM}) g_{M_{1}} = 9.44 \times 1.^{-2} V_{i_{1}}$$

$$I_{d_{1}} = I_{d_{2}} + I_{d_{2}} = 9.44 \times 1.^{-2} V_{i_{3}}$$

$$I_{d_{1}} = I_{d_{2}} + I_{d_{2}} = 9.44 \times 1.^{-2} V_{i_{3}}$$

$$I_{d_{1}} = V_{B} g_{M_{1}} = Y_{4} Y_{4} \times 1.^{-2} V_{i_{3}}$$

$$I_{d_{1}} = I_{d_{2}} - I_{d_{1}} = Y_{4} Y_{4} \times 1.^{-2} V_{i_{3}}$$

$$I_{d_{1}} = V_{B} g_{M_{1}} = Y_{4} Y_{4} \times 1.^{-2} V_{i_{3}}$$

$$I_{d_{1}} = V_{d_{2}} g_{M_{1}} = Y_{4} Y_{4} \times 1.^{-2} V_{i_{3}} = I_{d_{1}} V_{i_$$

Isc = ( 14,44 + 4,44 - 1) x 10 Vin = 15, 17 x 10 Vin

Gm = 17, 17 x 10

Acm = - Gn Rout = 0188 THA

 $CMMR = Y_0 L_{0} \frac{Adm}{Acm} = Y_0 L_{0} \frac{11_{0}90}{0_{1}878} = \Omega_{0} \nearrow P_{0}$   $W_{P_1} = \frac{1}{C_L R_{001}} = \frac{1}{1P_X Y_{1} O K} = \left\{ \times 1.^{\Lambda} \frac{V_{0} J_{0}}{S} \right\}$ 

Wt = WP, Ade = fxlo^x 110,90 = f, FTAxlo" rad

SR=> Mr, Mr: off => My, Mn: off => M1. : off, M1, Mr: on

$$(SR)^{\dagger} = \frac{I_{CL}}{C_L} = \frac{\Delta m}{I_{I}} = \Delta x 1.9 \frac{V}{S}$$

$$I_{DII} = -I_{DF} = -I_{MA}$$

$$I_{OII} = I_{IV} = -I_{MA}$$

$$(SR) = \frac{\partial M}{10} = \partial x 1.9 \frac{\nabla}{5}$$

1/00s + 1/60s = 1/20ns

$$\left(\frac{\omega}{L}\right) = \frac{YIp}{\mu_{\text{Cox}}Veif} \left(\frac{\omega}{L}\right)_{16} = \frac{f_{\text{on}}}{|\delta_{\text{ox}}(m)|^{2}} = ||\Lambda/\Omega|$$

$$W_{1}f = 11/\Lambda \Omega UM$$
  $\left(\frac{W}{L}\right)_{1}F = \frac{Y_{000}}{10 \times 9^{-5} \Gamma_{0}} = 0.79/\Omega 9 = 0.000 W_{1}C = 0.000 W_{1$ 

$$\left(\frac{\omega}{L}\right)_{l,l,r} = \frac{r_{000}}{90 \times 200 \text{ [TD]}} = \Lambda \Lambda \Lambda \Lambda = 0$$
  $\omega_{l,l,r} = \Lambda \Lambda_{l} \Lambda \Lambda \Lambda \Lambda \Lambda \Lambda \Lambda$