

```

1  import gym, gym_prescan
2
3  env_dict = {
4      'id':      'prescan-without-matlabengine-v0',
5      'host':    '172.21.217.140',
6      'verbose': True,
7      'nget':    152
8  }
9  env = gym.make(**env_dict)
10 for i_episode in range(20):
11     observation = env.reset()
12     for t in range(100):
13         env.render()
14         print(observation)
15         action = env.action_space.sample()
16         observation, reward, done, info = env.step(action)
17         if done:
18             print("Episode finished after {} timesteps".format(t+1))
19             break
20 env.close()

```