

Convex Optimization

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% Project 6:

In this project, the problem is to maximize diversification in a portfolio so that we have maximum diversity in equity at a certain portfolio. ==> Meaning we have to choose maximum number of shares in a market!

The Diversity function here is defined and given as:

$$D(x) = \frac{\sigma^T x}{(x^T \Sigma x)^{1/2}}$$

with some given constraints the problem becomes:

$$\begin{array}{ll} \text{maximize} & D(x) \\ \text{subject to} & \mathbf{1}^T x = 1, \quad 0 \preceq x \preceq M, \end{array}$$

Maximum value of a share is equal to M.

Summation of shares shall be unique value.

We always seek for ultimate score so we want to get the full credit! ==>

we solve this problem with a convex optimization format not a quasiconvex which can be solved via bi-section method!

In solving this question a feature helps the most and it is given in the hint as:

"Note also that $D(tx) = D(x)$ for any $t > 0$. "

So, the change of variable with this hint can be:

$$x = \frac{y}{\tau}; \Rightarrow D(x) = D(\tau x) = D(y) \Rightarrow$$

$$\frac{(\sigma^T x)}{(x^T \Sigma x)^{\frac{1}{2}}} = \frac{\left(\sigma^T \frac{y}{\tau}\right)}{\frac{1}{\tau} (y^T \Sigma y)^{\frac{1}{2}}} \Rightarrow \text{choose } y \text{ and } \tau \text{ so that } \sigma^T y = 1;$$

and the constraint $1^T x = 1$ becomes :

$$\sum_i y_i = \tau \Rightarrow$$

our objective will look like :

$$\text{maximize } \frac{1}{(y^T \Sigma y)^{\frac{1}{2}}} \text{ which is equivalent to :}$$

$$\text{maximize } \frac{1}{(y^T \Sigma y)} \text{ which is equivalent to :}$$

$$\text{minimize } (y^T \Sigma y);$$

S.t.

$$\sum_i y_i = \tau;$$

$$\tau > 0;$$

$$0 \leq y \leq \tau M;$$

```
% As we saw, this will be a Convex Optimization problem!
% It can be solved using CVX_MATLAB!
% So we get the full credit out of this project :)
```

Part (b)

```
% Load Data:
clear; clc; close all;
load('max_divers_data.mat'); % Given M(20*1) , n =20; sigma(20*1) and Sigma(20*20)
n = double(n);
M = double(M);
```

```
% Solve:

cvx_begin
    variables y(n,1) Tau(1)
    minimize(quad_form(y,Sigma))
% Constraints:
    subject to
        sum(y) == Tau ;
        Tau >= 0 ;
        sigma'*y == 1 ;
        y >= 0 ;
```

```

y      <=      M      ;
cvx_end

```

Calling SDPT3 4.0: 64 variables, 21 equality constraints
 For improved efficiency, SDPT3 is solving the dual problem.

```

-----
num. of constraints = 21
dim. of socp var = 22,   num. of socp blk = 1
dim. of linear var = 41
dim. of free var = 1 *** convert ublk to lblk
*****
SDPT3: Infeasible path-following algorithms
*****
version predcorr gam expon scale_data
NT      1      0.000 1      0
it pstep dstep pinfeas dinfeas gap      prim-obj      dual-obj      cputime
-----
0|0.000|0.000|2.9e+01|4.1e+01|6.7e+05| 5.860071e+03  0.000000e+00| 0:0:00| chol 1 1
1|1.000|0.973|8.8e-07|1.5e+00|3.4e+04| 5.861406e+03 -2.569144e+02| 0:0:00| chol 1 1
2|1.000|0.970|5.6e-07|2.8e-01|6.4e+03| 2.471626e+03 -1.603800e+02| 0:0:00| chol 1 1
3|0.951|0.994|1.2e-07|1.3e-01|6.4e+02| 1.210284e+02 -1.135202e+02| 0:0:00| chol 1 1
4|0.985|1.000|1.1e-07|3.7e-02|2.5e+02| 5.097040e+01 -1.150978e+02| 0:0:00| chol 1 1
5|0.941|0.923|8.3e-09|1.3e-02|2.6e+01| -9.629621e+01 -1.133925e+02| 0:0:00| chol 1 1
6|0.862|0.881|1.5e-09|2.6e-03|9.0e+00| -1.057403e+02 -1.139525e+02| 0:0:00| chol 1 1
7|0.969|0.661|2.2e-10|9.5e-04|6.7e-01| -1.133321e+02 -1.139322e+02| 0:0:00| chol 1 1
8|0.933|0.617|2.3e-10|3.7e-04|1.3e-01| -1.138160e+02 -1.139269e+02| 0:0:00| chol 1 1
9|1.000|0.335|1.1e-10|2.5e-04|5.4e-02| -1.138851e+02 -1.139256e+02| 0:0:00| chol 1 1
10|0.956|0.547|9.2e-11|1.1e-04|1.8e-02| -1.139121e+02 -1.139245e+02| 0:0:00| chol 1 1
11|1.000|0.661|1.8e-11|3.8e-05|3.5e-03| -1.139231e+02 -1.139247e+02| 0:0:00| chol 1 1
12|0.818|0.782|4.8e-12|1.5e-05|7.7e-04| -1.139249e+02 -1.139252e+02| 0:0:00| chol 1 1
13|0.977|0.879|7.2e-13|3.0e-06|6.9e-05| -1.139253e+02 -1.139254e+02| 0:0:00| chol 1 1
14|0.954|0.894|3.4e-13|2.7e-07|7.0e-06| -1.139254e+02 -1.139254e+02| 0:0:00| chol 1 1
15|0.982|0.975|2.9e-13|2.6e-08|6.9e-07| -1.139254e+02 -1.139254e+02| 0:0:00| chol 1 1
16|1.000|0.985|5.8e-13|2.6e-09|2.6e-08| -1.139254e+02 -1.139254e+02| 0:0:00|
stop: max(relative gap, infeasibilities) < 1.49e-08
-----
number of iterations = 16
primal objective value = -1.13925393e+02
dual objective value = -1.13925393e+02
gap := trace(XZ) = 2.55e-08
relative gap = 1.12e-10
actual relative gap = 1.01e-10
rel. primal infeas (scaled problem) = 5.79e-13
rel. dual " " " = 2.56e-09
rel. primal infeas (unscaled problem) = 0.00e+00
rel. dual " " " = 0.00e+00
norm(X), norm(y), norm(Z) = 1.6e+02, 5.1e-01, 1.1e+00
norm(A), norm(b), norm(C) = 6.9e+01, 2.3e+02, 2.9e+00
Total CPU time (secs) = 0.20
CPU time per iteration = 0.01
termination code = 0
DIMACS: 5.8e-13 0.0e+00 3.8e-09 0.0e+00 1.0e-10 1.1e-10
-----

-----
Status: Solved
Optimal value (cvx_optval): +0.0267303

```

Problem is SOLved!

```
disp("Optimal Value of Tau: "+num2str(Tau));
```

Optimal Value of Tau: 0.28542

```
disp("Optimal Values of y :");
```

Optimal Values of y :

```
disp(y'/Tau);
```

Columns 1 through 11

0.0260	0.0000	0.0235	0.0219	0.0000	0.0838	0.0445	0.0196	0.0176	0.2296	0.1075
--------	--------	--------	--------	--------	--------	--------	--------	--------	--------	--------

Columns 12 through 20

0.0129	0.1483	0.0550	0.0105	0.0338	0.0990	0.0082	0.0334	0.0247
--------	--------	--------	--------	--------	--------	--------	--------	--------

```
Optimal_cvx_y = cvx_optval;
disp(cvx_optval);
```

0.0267

```
% Long-only portfolio:
cvx_begin
    variables x_long(n,1)
    minimize(quad_form(x_long,Sigma))
    % Constraints:
    subject to
        sum(x_long) == 1 ;
        x_long >= 0 ;
        x_long <= M ;
cvx_end
```

Calling SDPT3 4.0: 63 variables, 21 equality constraints
For improved efficiency, SDPT3 is solving the dual problem.

```
num. of constraints = 21
dim. of socp var = 22, num. of socp blk = 1
dim. of linear var = 40
dim. of free var = 1 *** convert ublk to lblk
*****
SDPT3: Infeasible path-following algorithms
*****
version predcorr gam expon scale_data
NT 1 0.000 1 0
it pstep dstep pinfeas dinfeas gap prim-obj dual-obj cputime
-----
0|0.000|0.000|9.5e-01|2.1e+01|5.8e+05| 5.788165e+03 0.000000e+00| 0:0:00| chol 1 1
1|1.000|1.000|3.4e-07|5.0e-01|1.8e+04| 5.396913e+03 -2.156547e+02| 0:0:00| chol 1 1
2|1.000|1.000|1.3e-07|2.5e-01|1.7e+03| 6.021244e+02 -1.086685e+02| 0:0:00| chol 1 1
3|1.000|1.000|1.4e-08|7.5e-02|1.6e+02| -8.456995e+00 -1.120715e+02| 0:0:00| chol 1 1
4|0.962|0.934|1.5e-08|1.2e-02|1.7e+01| -9.941549e+01 -1.146531e+02| 0:0:00| chol 1 1
5|1.000|0.058|1.8e-08|1.2e-02|9.1e+00| -1.072503e+02 -1.146429e+02| 0:0:00| chol 1 1
6|0.635|0.835|6.3e-09|2.0e-03|5.0e+00| -1.095941e+02 -1.144073e+02| 0:0:00| chol 1 1
7|1.000|0.415|7.4e-10|1.2e-03|2.1e+00| -1.122817e+02 -1.143158e+02| 0:0:00| chol 1 1
```

```

8|0.960|0.448|4.7e-10|6.4e-04|8.8e-01|-1.133755e+02 -1.142116e+02| 0:0:00| chol 1 1
9|1.000|0.413|1.7e-10|3.8e-04|4.3e-01|-1.137310e+02 -1.141351e+02| 0:0:00| chol 1 1
10|1.000|0.514|5.5e-11|1.8e-04|1.5e-01|-1.139451e+02 -1.140832e+02| 0:0:00| chol 1 1
11|1.000|0.468|2.8e-11|9.8e-05|6.9e-02|-1.139940e+02 -1.140573e+02| 0:0:00| chol 1 1
12|1.000|0.625|8.9e-12|3.7e-05|1.8e-02|-1.140233e+02 -1.140397e+02| 0:0:00| chol 1 1
13|1.000|0.743|3.3e-12|9.4e-06|3.8e-03|-1.140292e+02 -1.140325e+02| 0:0:00| chol 1 1
14|0.895|0.787|4.2e-13|1.4e-05|7.3e-04|-1.140303e+02 -1.140309e+02| 0:0:00| chol 1 1
15|0.989|0.913|6.1e-14|2.7e-06|5.5e-05|-1.140304e+02 -1.140305e+02| 0:0:00| chol 1 1
16|0.996|0.880|2.3e-14|2.1e-07|1.4e-05|-1.140305e+02 -1.140305e+02| 0:0:00| chol 1 1
17|1.000|0.977|1.6e-13|5.1e-08|8.6e-07|-1.140305e+02 -1.140305e+02| 0:0:00| chol 1 1
18|1.000|0.987|3.4e-12|3.2e-09|2.3e-08|-1.140305e+02 -1.140305e+02| 0:0:00|
stop: max(relative gap, infeasibilities) < 1.49e-08

```

```

-----
number of iterations    = 18
primal objective value = -1.14030461e+02
dual   objective value = -1.14030461e+02
gap := trace(XZ)       = 2.29e-08
relative gap           = 9.99e-11
actual relative gap    = 8.66e-11
rel. primal infeas (scaled problem) = 3.37e-12
rel. dual      "      "      "      = 3.23e-09
rel. primal infeas (unscaled problem) = 0.00e+00
rel. dual      "      "      "      = 0.00e+00
norm(X), norm(y), norm(Z) = 1.6e+02, 6.3e-01, 1.1e+00
norm(A), norm(b), norm(C) = 1.1e+01, 2.3e+02, 2.9e+00
Total CPU time (secs) = 0.16
CPU time per iteration = 0.01
termination code       = 0
DIMACS: 3.4e-12  0.0e+00  4.8e-09  0.0e+00  8.7e-11  1.0e-10
-----

```

```

-----
Status: Solved
Optimal value (cvx_optval): +0.131798

```

```

long_only_cvx_opt_val = cvx_optval;
long_only_x = x_long;
disp("Optimal Value: "+num2str(cvx_optval))

```

```
Optimal Value: 0.1318
```

```
disp(long_only_x')
```

```
Columns 1 through 11
```

```
0.0219    0.0000    0.0042    0.0035    0.1053    0.0122    0.0137    0.0129    0.1671    0.1535    0.0412
```

```
Columns 12 through 20
```

```
0.0039    0.2000    0.0201    0.0000    0.2000    0.0180    0.0000    0.0069    0.0155
```

```

% we can see that Optimal Value of heuristic method is:
disp(Optimal_cvx_y/cvx_optval*100)

```

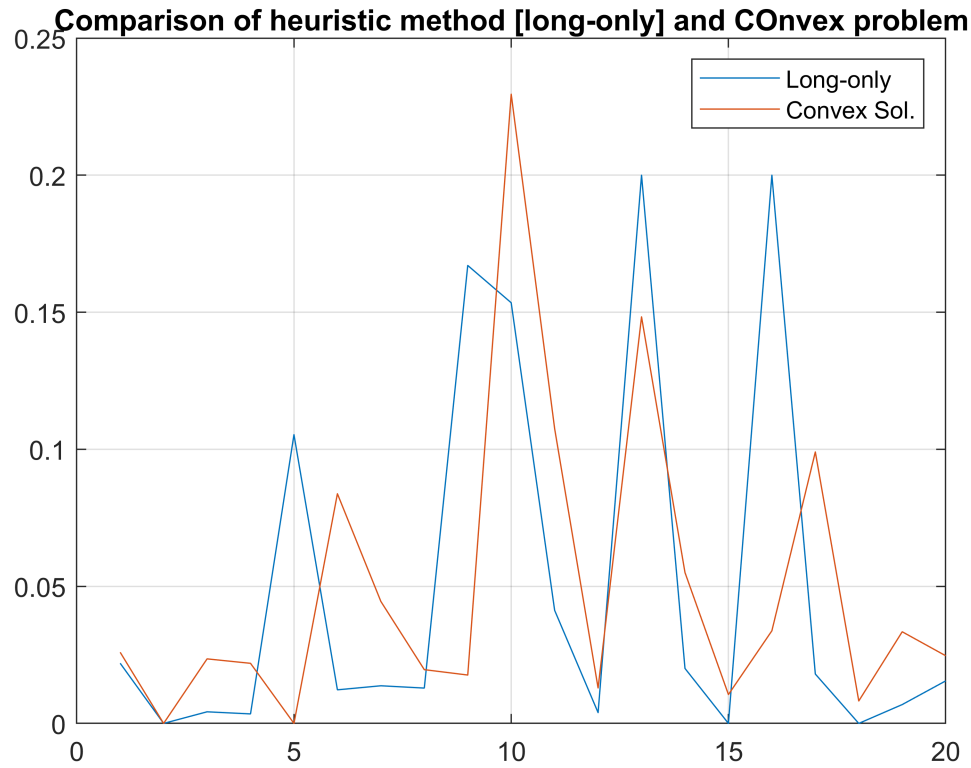
```
20.2812
```

```
%percentage meaning we were 5 times better using Convex Optimization!
```

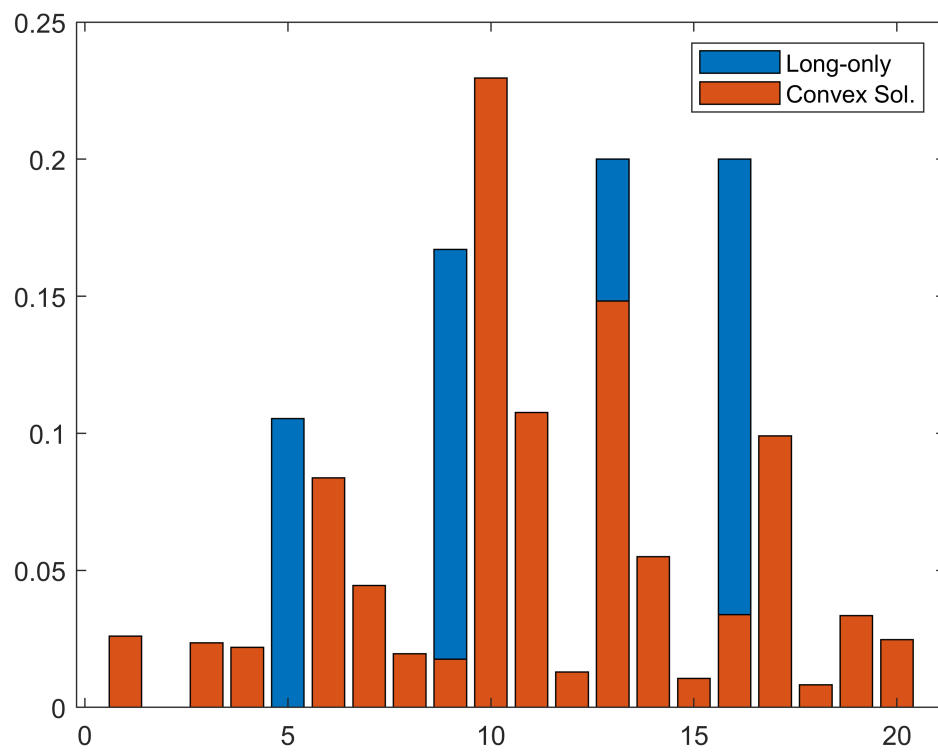
Figures

```
Fig1 = figure();  
plot(x_long);  
hold on  
plot(y/Tau);  
grid on  
legend('Long-only', 'Convex Sol.');
```

title('Comparison of heuristic method [long-only] and COnvex problem');



```
% Using Bar plot:  
Fig2 = figure();  
bar(x_long);  
hold on  
bar(y/Tau);  
legend('Long-only', 'Convex Sol.');
```



% we can see that the orange color which represents Convex solution of the
 % problem is more Diverse than Long-only solution!
 % Please Note that both Solutions satisfies the given conditions!