

## Hw-2 :::

# Numerical Methods in Electromagnetics

Mohammadreza Arani

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810100511

```
clear; close all; clc;
```

### Problem:

### 3.2

3.2 Solve  $y'' - y = -1$ ,  $0 < x < 1$  with  $y'(0) = 0$ ,  $y(1) = 2$ . You should use finite difference method and take  $\Delta x = 0.25$ .

using CD (Central Difference):

$$y'' = \frac{y(i+1, j) - 2y(i, j) + y(i-1, j)}{(h^2)} ; \implies y(i+1, j) - 2y(i, j) + y(i-1, j) - h^2 y(i, j) = -h^2$$

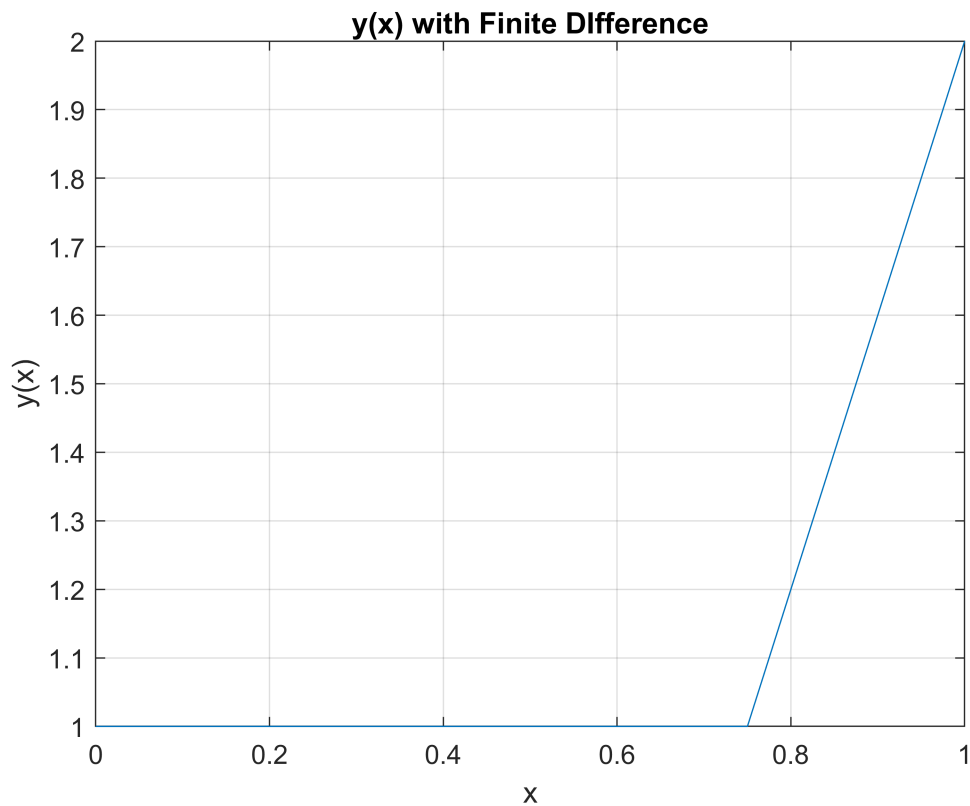
```
del_x = 0.25;
L=1; % Length of 1-D geometry
x = 0:del_x:L;
n = length(x);
y = zeros(1,n)+1;
% Boundary conditions:
y(1,n) = 2 ;
```

from  $y'(0) = 0 \rightarrow y(1, -1) = y(1, 1) \rightarrow$  Symmetry

```
% for:
h = del_x;
% Finite DIfference Formula:
for i = 1:length(y)-2
    if(i-1>0 )
        y(1,i+1) = (h^2+2)*y(1,i) -h^2 - y(1,i-1) ;
    else
        y(1,i+1) = (h^2+2)*y(1,i) -h^2 - y(1,1) ;
    end
end

% Illustrate the figure:
figure()
plot(x,y)
title("y(x) with Finite DIfference")
xlabel("x")
ylabel("y(x)")
```

grid on



Or we can use more than 1 row and have a system of equations:

```
A = zeros(n-2);
B = zeros(1,n-2);

for i=1:n-2
    A(i,i) = -(h^2+2) ;
end
for i=2:n-2
    A(i,i-1) = 1 ;
    A(i-1,i) = 1 ;
end

B(1,1) = -h^2 - y(1,1) ;
B(1,n-2) = -h^2 - y(1,n) ;
for i=2:n-3
    B(1,i) = -(h^2) ;
end
BB = B';

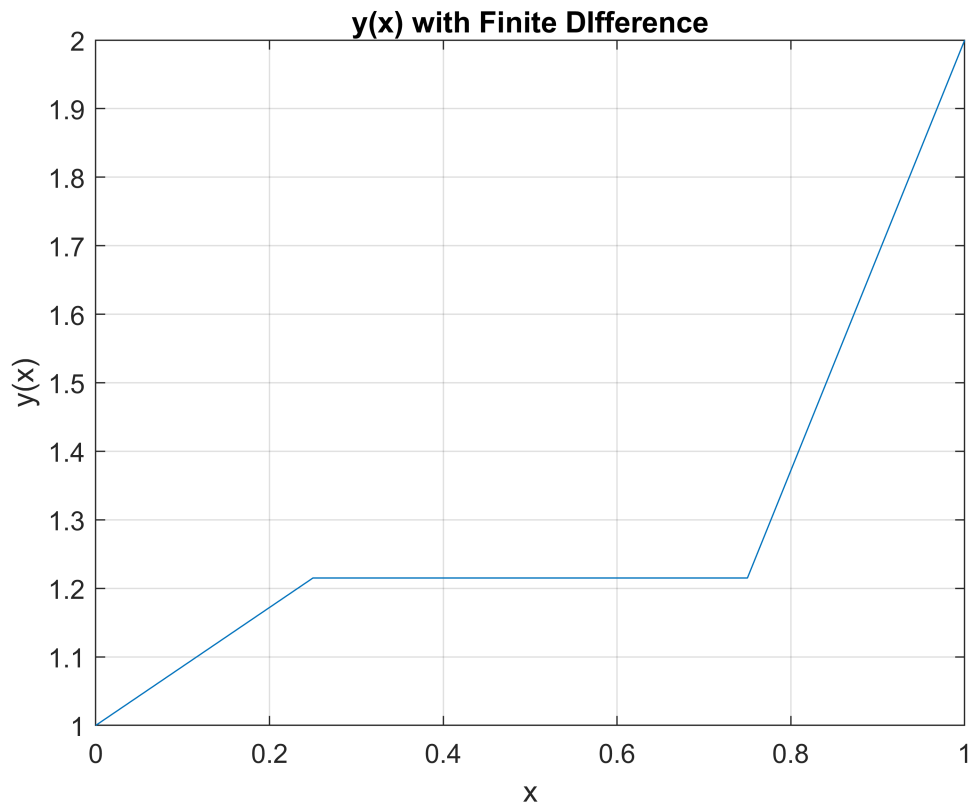
% Solve the system:
YY = mldivide(A,BB) ;
```

```

y(2:end-1) = YY(1,:) ;

% Illustrate the figure:
figure()
plot(x,y)
title("y(x) with Finite DIfference")
xlabel("x")
ylabel("y(x)")
grid on

```



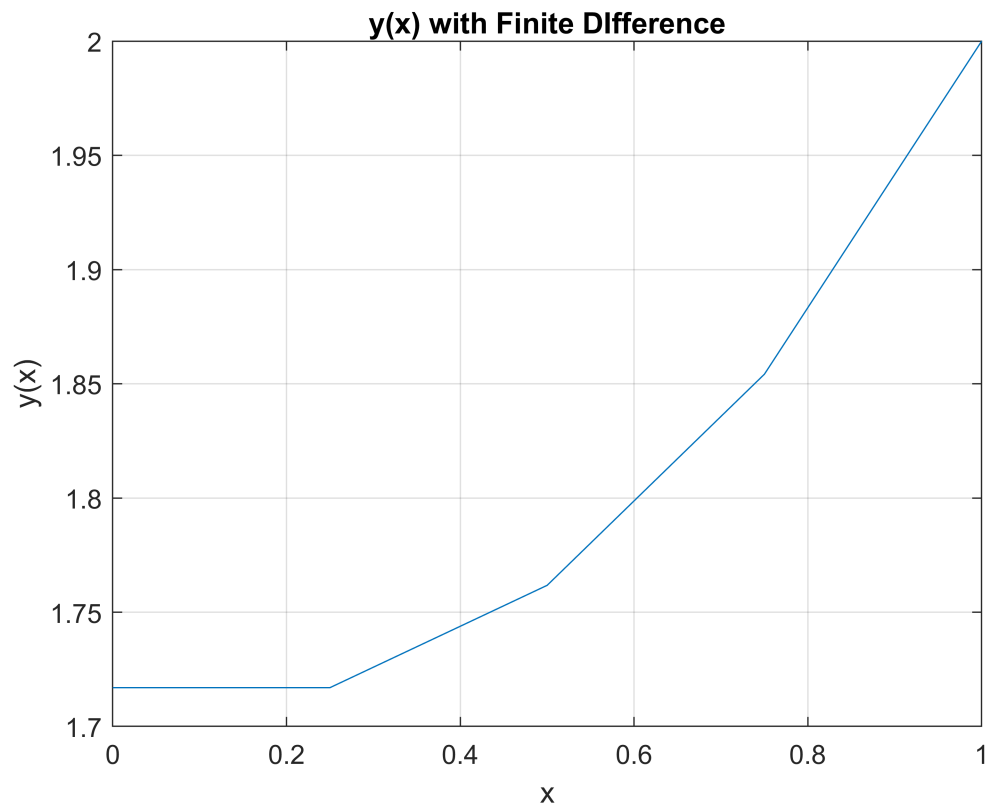
## Hand written solution:

```

% The solution is in the paper:
Afinal = [-17,16,0,0 ; 16,-33,16,0; 0,16,-33,16; 0,0,0,1 ];
Bfinal = [-1;-1; -1;2] ;

Yfinal = mldivide(Afinal,Bfinal) ;
% Illustrate the figure:
figure()
plot(x,[Yfinal(1);Yfinal])
title("y(x) with Finite DIfference")
xlabel("x")
ylabel("y(x)")
grid on

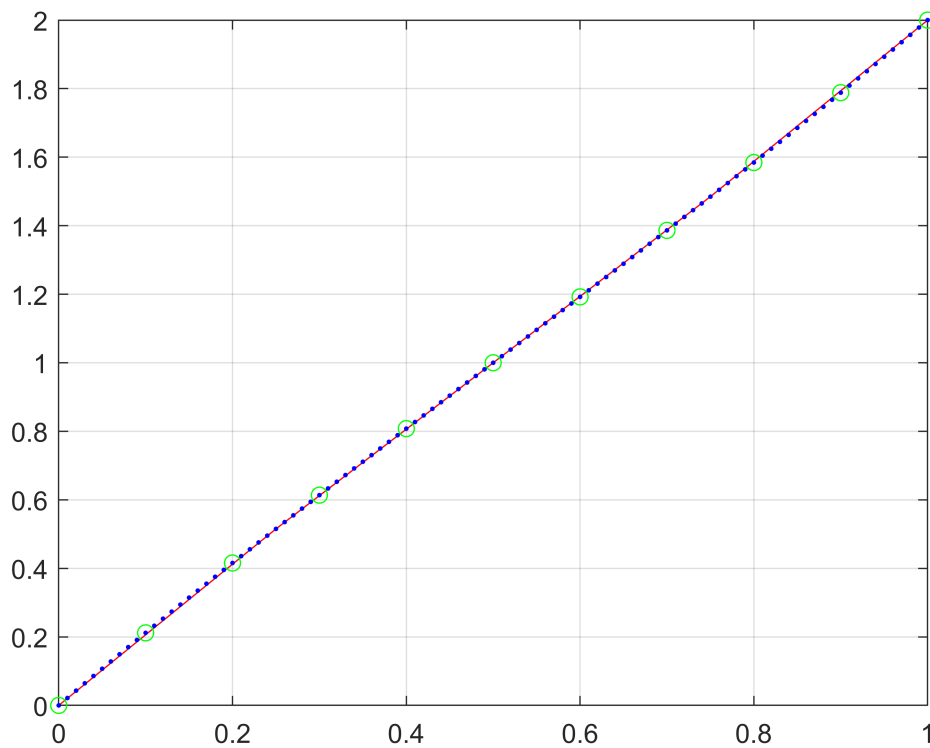
```



## MATLAB Solution:

```
xlim = [0 1];
y0 = 0;
y1 = 2;
% 0:.25:1
[y5,x5] = mybvpsolve(xlim,y0,y1,5);

% 0:.1:1
[y11,x11] = mybvpsolve(xlim,y0,y1,11);
% 0:.01:1
[y101,x101] = mybvpsolve(xlim,y0,y1,101);
figure()
plot(x5,y5, 'r- ',x11,y11, 'go',x101,y101, 'b. ')
grid on
```



```
function [y,x] = mybvpsolve(xlim,y0,y1,n)
% y''+2y'+y=x^2
% xlim is a vector of length 2
% y0, y1 are the BC at each end
% n is the number of elements in the final result

x = linspace(xlim(1),xlim(2),n)';

% stride
h = x(2) - x(1);

% discretize the ODE into a tridiagonal matrix
% ((y(i+1)-2y(i)+y(i-1))/h^2) + 2*(y(i+1)-y(i-1))/2h + y(i)=x(i)^2;

% ((y(i+1)-2y(i)+y(i-1))/h^2) - y(i)=-1;

% so the main diagonal has coefficients
% the 1 at each end brings the boundary conditions into the problem.
maindiag = [1;repmat(-2/h^2 -1 ,n - 2,1);1];
% be careful to create the sub and super diagonals as the correct lengths
subdiag = [repmat(1/h^2 ,n-2,1);0];
supdiag = [0;repmat(1/h^2 ,n-2,1)];
```

```
% 3 calls to diag will do the trick here. For large problems, a
% sparse matrix would be faster and better yet.
ODEmat = diag(maindiag) + diag(subdiag,-1) + diag(supdiag,1);

% create the right hand side for the solve:
rhs = [y0;-1*ones(n-2,1);y1];

% solve. This is just a call to backslash
y =ODEmat\rhs;

end
```