## Computational Electromagnetics

### Hw3

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#### Q-3.25:

3.25 Use the FDM to calculate the characteristic impedance of the high-frequency, air-filled rectangular transmission line shown in Figure 3.55. Take advantage of the symmetry of the problem and consider cases for which

a. 
$$B/A = 1.0$$
,  $a/A = 1/2$ ,  $b/B = 1/2$ ,  $a = 1$ ,

b. 
$$B/A = 1/2$$
,  $a/A = 1/3$ ,  $b/B = 1/3$ ,  $a = 1$ .

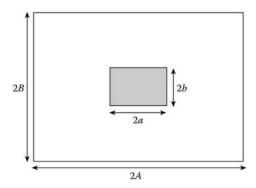
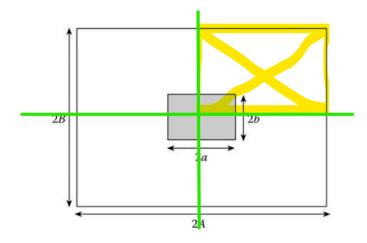


FIGURE 3.55 For Problem 3.25.

To take advantage of the symmetry we can consider a quadrature and then extend the result for the whole geometry! ==> what we consider is:



The Conductor at the core will be:

0 < x < a; 0 < y < b;

The area is filled with air;

We have to consider symmetry condition along X-Axis and Y-Axis! -->

Not Important due to the fact that the conductor potential stays zero within but on the surface!

The Tranmission line is filled with air! --> eps0

We can solve this for Tm or TE modes!

The Equation to satisfy is:

$$\nabla^2 \Phi + k^2 \Phi = 0 \tag{3.64}$$

For TM --> Hz=0; Ez != 0; PHI = EZ --> Boundary Condition becomes: PHI = 0; at PEC --> Dirichlet Condition

For TE --> Hz != 0 ; Ez = 0 ; PHI = HZ --> Boundary Condition becomes: dPHI/dn = 0; at PEC ---> Neumann Condition

If we have to solve an eigne value problem we have to form the Matrix A and initialize Maxtrix PHI!

The Correct FD formula for this problem is:

$$\Phi(i+1,j) + \Phi(i-1,j) + \Phi(i,j+1) + \Phi(i,j-1) - (4-h^2k^2)$$

```
clear; clc; close all;
% SOlving for TM modes:
% Case 1:

eps0 = 8.854178128e-12; % Vacuum Permitivity [F.m-1]

a=1;
A = 2*a;
B = A;
b = 1/2*B;

% h=1.0;
% w = h;
% t=0.01;
```

```
% A = a; B=b/2; D=h; W=w/2;

H = 0.01;
NT = 1000;

ER = 1;
EO = 8.81e-12;
U = 3.0e+8;

NX = A/H;
NY = B/H;
ND = b/H;
NW = a/H;
VD = 1.0;
```

#### **Iterative Method**

The second option is the *iterative method*. In this case, the matrix elements are usually generated rather than stored. We begin with  $\Phi_1 = \Phi_2 = \cdots = \Phi_m = 1$  and a guessed value for k. The field  $\Phi_{ij}^{k+1}$  at the (i, j)th node in the (k+1)th iteration is obtained from its known value in the kth iteration using

$$\Phi^{k+1}(i,j) = \Phi^k(i,j) + \frac{\omega R_{ij}}{(4 - h^2 k^2)}$$
(3.72)

where  $\omega$  is the acceleration factor,  $1 < \omega < 2$ , and  $R_{ij}$  is the residual at the (i, j)th node given by

$$R_{ij} = \Phi(i, j+1) + \Phi(i, j-1) + \Phi(i+1, j) + \Phi(i-1, j) - \left(4 - h^2 k^2\right) \Phi(i, j)$$
(3.73)

After three or four scans of the complete mesh using Eq. (3.73), the value of  $\lambda = h^2 k^2$  should be updated using Raleigh formula

$$k^2 = \frac{-\int_S \Phi \nabla^2 \Phi \, dS}{\int_S \Phi^2 \, dS} \tag{3.74}$$

The finite difference equivalent of Eq. (3.74) is

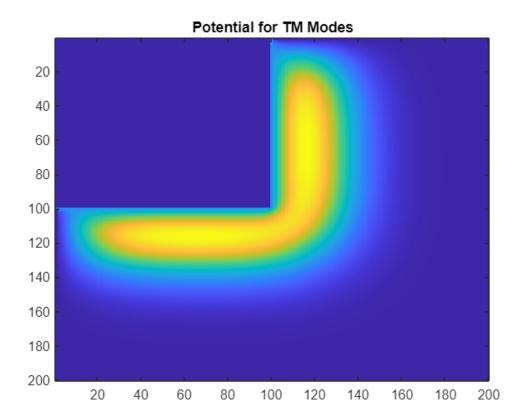
$$k^2 = \frac{-\sum_{i=1} \sum_{j=1} \Phi(i,j) [\Phi(i+1,j) + \Phi(i-1,j) + \Phi(i,j+1) + \Phi(i,j-1) - 4\Phi(i,j)]}{h^2 \sum_{i=1} \sum_{j=1} \Phi^2(i,j)} \quad (3.75)$$

```
Iters=1e2;
PHI = zeros(NX,NY);R = PHI; K = zeros(Iters,1);
w= 1.5; % shall be between 1,2
flag=0; thresh = 1e-2;
% Air Filled:
for k=1:Iters
                            if (flag)
                                                         return
                            end
                            if (k>4)
                                                        % Update k using Raleigh Formula:
                                                        SUM1= 0;
                                                        SUM2=0;
                                                        for i=1:NX-1
                                                                                    for j=1:NY-1
                                                                                                                 if (i==1)
                                                                                                                                              if(j==1)
                                                                                                                                                    SUM1 = SUM1 + PHI(i,j)* (PHI(i+1,j) + 0 + PHI(i,j+1) + 0 - 4*PHI(i,j) );
                                                                                                                                              else
                                                                                                                                                    SUM1 = SUM1 + PHI(i,j)* (PHI(i+1,j) + 0 + PHI(i,j+1) + PHI(i,j-1) - 4*PHI(i,j-1)
                                                                                                                                              end
                                                                                                                 elseif (j==1)
                                                                                                                                              if(i==1)
                                                                                                                                                                          SUM1 = SUM1 + PHI(i,j)* (PHI(i+1,j)+0+PHI(i,j+1)+0- 4*PHI(i,j) );
                                                                                                                                              else
                                                                                                                                                                          SUM1 = SUM1 + PHI(i,j)* (PHI(i+1,j)+PHI(i-1,j)+PHI(i,j+1)+0- 4*PHI(i,j+1)+0- 4*PHI(i,j+1)+0-
                                                                                                                                              end
                                                                                                                 else
                                                                                                                                              SUM1 = SUM1 + PHI(i,j)* (PHI(i+1,j)+PHI(i-1,j)+PHI(i,j+1)+PHI(i,j-1)- 4*PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI(i,j+1)+PHI
```

```
SUM2 = SUM2 + H^2*PHI(i,j)^2;
            end
        end
        K(k) = sqrt(-SUM1/SUM2);
        if(abs(K(k)-K(k-1)) < thresh)
            flag = 1; % SOLVED
        end
    else
        K(k) = k;
    end
    for i=1:NX
        for j=1:NY
            if((i<NW)& (j<ND))</pre>
                PHI(i,j) = 0;
            elseif ( (i<NW)& (j==ND) )</pre>
                PHI(i,j) = VD; % On the surface of PEC Ez = 0; for TM modes where we have PHI
            elseif ( (i==NW) & (j<ND) )</pre>
                PHI(i,j) =VD;
            elseif ( i==1 )
                PHI(i,j) = 0;
            elseif (j==1)
                PHI(i,j) = 0;
            elseif (j==NY)
                PHI(i,j) = 0;
            elseif (i==NX)
                PHI(i,j) = 0;
            else
                R(i,j) = PHI(i,j+1) + PHI(i,j-1) + PHI(i+1,j) + PHI(i-1,j) - (4 - H^2*K(k)^2)
                PHI(i,j) = PHI(i,j) + w*R(i,j)/(4-H^2*K(k)^2);
            end
        end
    end
end
figure()
imagesc(PHI)
```

end

title("Potential for TM Modes")

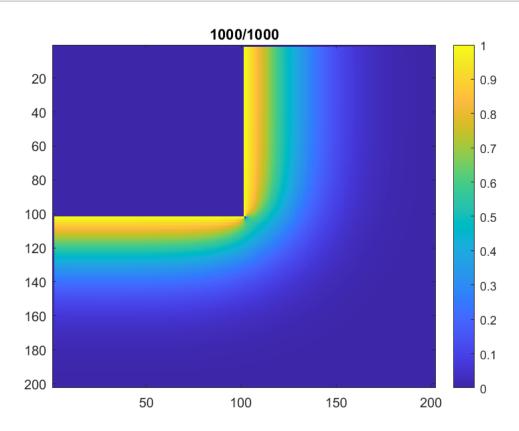


### **QUA-SI TEM Solution**

```
clear;
a=1;
A = 2*a;
B = A;
b = 1/2*B;
H = 0.01;
NT = 1000;
ER = 1;
E0 = 8.81e-12;
U = 3.0e + 8;
NX = A/H;
NY = B/H;
% ND = D/H;
% NW = W/H;
Na = a/H;
Nb = b/H;
```

```
VD = 1.0;
% Calculate charge with and without DIELECTRIC
E1 = E0;
% INITIALIZATION
    V = zeros(NX+2,NY+2);
% Set POTENTIAL ON INNER CONDUCTOR (FIXED NODES) EQUAL TO VD
    V(2:Na+1,Nb+2) =VD; % Parallel to Y-Axis
    V(Na+2,2:Nb+1) =VD; % Parallel to X-Axis
% CALCULATE POTENTIAL AT FREE NODES --> Laplace Equation --> a TEM
% structure
    for K=1:NT
        for I=0:NX-1
            for J=0:NY-1
                if( (J<=Nb)&(I<=Na) ) % In The PEC</pre>
                    % do nothing
                  elseif (J==Nb)
%
%
                      % IMPOSE BOUNDARY Condition at the Interface
%
                      V(I+2,J+2) = 0.25*(V(I+3,J+2) + V(I+1,J+2)) + P1*V(I+2,J+3) + P2*V
                elseif (I==0)
                    % IMPOSE Symmetry COndition Along with Y-AXIS
                    V(I+2,J+2) = (2*V(I+3,J+2) + V(I+2,J+3) + V(I+2,J+1))/4.0;
                elseif (J==0)
                    % IMPOSE Symmetry COndition Along with X-AXIS
                    V(I+2,J+2) = (V(I+3,J+2) + V(I+1,J+2) + 2*V(I+2,J+3))/4.0;
                else
                    V(I+2,J+2) = (V(I+3,J+2) + V(I+1,J+2) + V(I+2,J+3) + V(I+2,J+1))/4.0;
                end
            end
        end
        % ANimation of Calculation
          figure(1);
%
          imagesc(V);
%
%
          colorbar;
%
          title([num2str(K),'/' , num2str(NT) ])
%
          drawnow
    end
```

```
figure(1);
   imagesc(V);
   colorbar;
   title([num2str(K),'/' , num2str(NT) ])
```

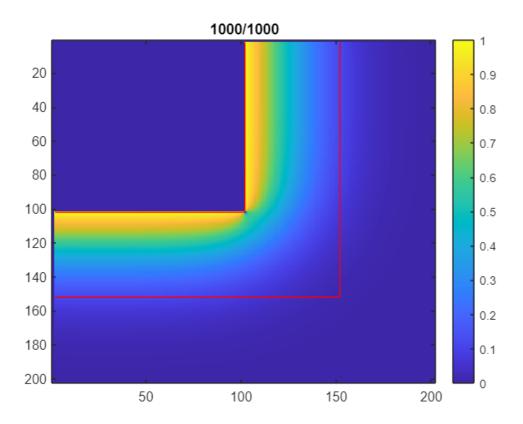


```
end
    SUM2 = SUM2 + 2.0* E1* V(IOUT+2,JOUT+2); % Corner Point
%
     SUM2 = E1* sum( V(3:Na+1 , Nb+2) ) + E1*V(2,Nb+2)/2 + E1*V(Na+2,2)/2;
%
     for J=1:Nb+2
%
             SUM2 =SUM2 + E1*V(Na+2,J+2); % A Parallel Line along Y-Axis from The bottom up.
%
     end
%
     SUM2 = SUM2 + 2.0* E1* V(Na+2,Nb+2); % Corner Point
   Q = abs(SUM1 - SUM2);
 % Calculate the Z0:
    C0 = 4.0*Q/VD; % *4 --> Due to Symmetry
   Z0 = 1.0/(U*C0); % u = 1/sqrt(LC); --> L = 1/(u2c), Z0 = sqrt(L/C) --> Z0 = 1/(cu)
   disp([H,NT]);
  1.0e+03 *
   0.0000
           1.0000
   disp(Z0)
```

58.5036

```
figure(2);
imagesc(V);
colorbar;
title([num2str(K),'/' , num2str(NT) ])
hold on
line([IOUT+2,IOUT+2], [2,JOUT+2], 'Color', 'r');
line([2,IOUT+2], [JOUT+2,JOUT+2], 'Color', 'r');

line([Na+2,Na+2], [2,Nb+2], 'Color', 'r');
line([2,Na+2], [Nb+2,Nb+2], 'Color', 'r');
```



```
Init.a=1; Init.A=2*Init.a; Init.B= Init.A; Init.b= 1/2 * Init.B; Init.ER =1; Init.H= 1e-2;
Init.NT= 5e3;

Answer1 = FDM_Solver(Init);
Init.H= 1e-2;
Init.NT= 1e3;

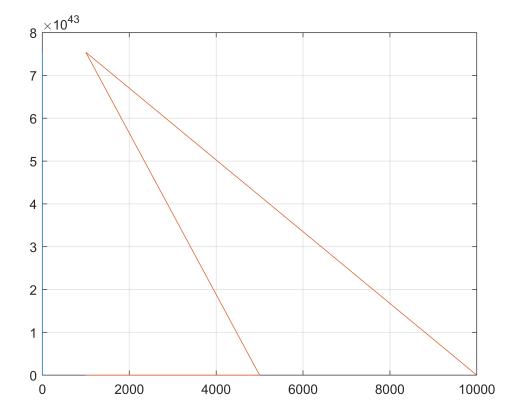
Answer2 = FDM_Solver(Init);
Init.H= 1e-1;
Init.NT= 1e3;
Answer3 = FDM_Solver(Init);

Init.H= 1e-1;
Init.H= 1e-1;
Init.H= 1e-3;
Init.NT= 5e3;
```

```
Answer5 = FDM_Solver(Init);
```

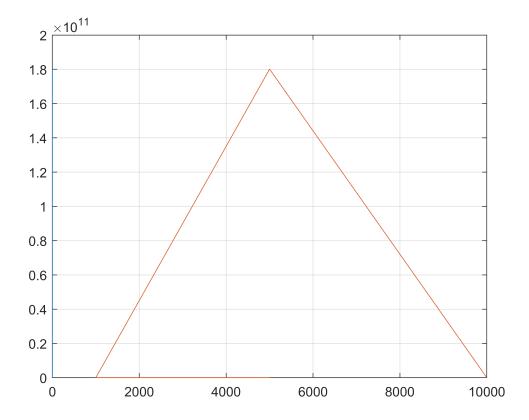
```
Init.H= 1e-3;
Init.NT= 1e3 ;
Answer6 = FDM_Solver(Init);
Init.H= 1e-3;
Init.NT= 10e3 ;
Answer7 = FDM_Solver(Init);
```

```
H_vec = [ 1e-1;1e-1;1e-2;1e-2;1e-3;1e-3;1e-3];
Z0_vec = [Answer1.Z0, Answer2.Z0,Answer3.Z0,Answer4.Z0,Answer5.Z0,Answer6.Z0,Answer7.Z0 ];
NT_vec = [ 1e3, 5e3 , 5e3 , 1e3 ,5e3 ,1e3 ,10e3 ];
figure()
plot(H_vec,Z0_vec);
hold on
plot(NT_vec,Z0_vec);
grid on
```



we can see that there is a an abnormal answer above! --> removing that answer!

```
Z0_vec = Z0_vec(1,[1:5,7]);
H_vec = H_vec([1:5,7],1);
NT_vec = NT_vec(1,[1:5,7]);
figure()
plot(H_vec,Z0_vec);
hold on
plot(NT_vec,Z0_vec);
grid on
```



Again we have another abnormality! --> removing that one too!

```
H_vec = [ 1e-1;1e-1;1e-2;1e-2;1e-3;1e-3;1e-3];
Z0_vec = [Answer1.Z0, Answer2.Z0,Answer3.Z0,Answer4.Z0,Answer5.Z0,Answer6.Z0,Answer7.Z0 ];
NT_vec = [ 1e3, 5e3 , 5e3 , 1e3 ,5e3 ,1e3 ,10e3 ];
disp(Z0_vec(1,[1:4]));
```

73.9536 112.0905 69.5867 69.5867

```
disp(H_vec');
   0.1000
             0.1000
                       0.0100
                                 0.0100
                                           0.0010
                                                      0.0010
                                                                0.0010
disp(NT_vec)
       1000
                   5000
                                5000
                                            1000
                                                        5000
                                                                    1000
                                                                               10000
```

for smaller H -->0.001 we could not reach a certain point! -->

```
disp(Z0_vec(1,7)); % Answer 7 --> for 10e3 iterations , H = 0.001
```

2.2974e+06

```
disp(Z0_vec(1,6)); % Answer 6 --> for 1e3 iterations , H = 0.001 --> shall be a bad answer
```

7.5398e+43

```
disp(Z0_vec(1,5)); % Answer 5 --> for 5e3 iterations , H = 0.001 --> shall be a better answer
```

1.8011e+11

It is clear that with increase in Number of iterations the answer is getting closer to what it should be! Need more iterations for such H! -->

The Answer Converges for H = 0.1, 0.01.

#### Scenario 2:

b. 
$$B/A = 1/2$$
,  $a/A = 1/3$ ,  $b/B = 1/3$ ,  $a = 1$ .

```
Init.a=1; Init.A=3*Init.a; Init.B= 1/2* Init.A; Init.b= 1/3 * Init.B; Init.ER =1;
Init.H= 1e-1;
Init.NT= 1e3;
Answer1_2 = FDM_Solver(Init);

Init.H= 1e-1;
Init.NT= 5e3;
Answer2_2 = FDM_Solver(Init);

Init.H= 1e-1;
Init.NT= 10e3;
Answer3_2 = FDM_Solver(Init);

Init.H= 1e-2;
Init.NT= 1e3;
Answer4_2 = FDM_Solver(Init);
```

```
Init.H= 1e-2;
Init.NT= 5e3 ;
Answer5_2 = FDM_Solver(Init);
Init.H= 1e-2;
Init.NT= 10e3 ;
Answer6_2 = FDM_Solver(Init);
Init.H= 0.5e-2;
Init.NT= 1e3 ;
Answer7_2 = FDM_Solver(Init);
Init.H= 0.5e-2;
Init.NT= 5e3 ;
Answer8_2 = FDM_Solver(Init);
Init.H= 0.5e-2;
Init.NT= 10e3 ;
Answer9_2 = FDM_Solver(Init);
disp("Z0 = "+Answer1_2.Z0 + "with H = " +Answer1_2.H + " for NT = "+Answer1_2.NT )
Z0 = 72.4708with H = 0.1 for NT = 1000
disp("Z0 = "+Answer2_2.Z0 + "with H = " +Answer2_2.H + " for NT = "+Answer2_2.NT )
Z0 = 72.4708with H = 0.1 for NT = 5000
disp("Z0 = "+Answer3_2.Z0 + "with H = " +Answer3_2.H + " for NT = "+Answer3_2.NT )
Z0 = 72.4708with H = 0.1 for NT = 10000
disp("Z0 = "+Answer4_2.Z0 + "with H = " +Answer4_2.H + " for NT = "+Answer4_2.NT )
Z0 = 121.9418with H = 0.01 for NT = 1000
disp("Z0 = "+Answer5_2.Z0 + "with H = " +Answer5_2.H + " for NT = "+Answer5_2.NT )
Z0 = 80.5942with H = 0.01 for NT = 5000
disp("Z0 = "+Answer6_2.Z0 + "with H = " +Answer6_2.H + " for NT = "+Answer6_2.NT )
Z0 = 76.7403with H = 0.01 for NT = 10000
disp("Z0 = "+Answer7_2.Z0 + "with H = " +Answer7_2.H + " for NT = "+Answer7_2.NT )
Z0 = 2163.2999with H = 0.005 for NT = 1000
```

 $disp("Z0 = "+Answer8_2.Z0 + "with H = " +Answer8_2.H + " for NT = "+Answer8_2.NT )$ 

```
disp("Z0 = "+Answer9_2.Z0 + "with H = " +Answer9_2.H + " for NT = "+Answer9_2.NT )
```

```
Z0 = 87.5667with H = 0.005 for NT = 10000
```

The Convergence is obvious and needs no discussion! --> The Exact solution is 50 ohm --> Convergence is to [72-87] interval!

```
function OBJ = FDM_Solver(Init)
a = Init.a;
A =Init.A;
B = Init.B;
b = Init.b;
H = Init.H;
NT = Init.NT;
OBJ.H = H;
OBJ.NT = NT;
ER = Init.ER;
EO = 8.81e-12; % Constant
U = 3.0e+8; % COnstant
OBJ.NX = A/H;
OBJ.NY = B/H;
OBJ.Na = a/H;
OBJ.Nb = b/H;
OBJ.VD = 1.0; % a favorable Value
E1 = E0; % The Area is filled with Air!
% INITIALIZATION
    OBJ.V = zeros(OBJ.NX+2,OBJ.NY+2);
% Set POTENTIAL ON INNER CONDUCTOR (FIXED NODES) EQUAL TO VD
    OBJ.V(2:OBJ.Na+1,OBJ.Nb+2) = OBJ.VD; % Parallel to Y-Axis
    OBJ.V(OBJ.Na+2,2:OBJ.Nb+1) = OBJ.VD; % Parallel to X-Axis
% CALCULATE POTENTIAL AT FREE NODES --> Laplace Equation --> a TEM
% structure
    for K=1:NT
        for I=0:0BJ.NX-1
            for J=0:0BJ.NY-1
                if( (J<=OBJ.Nb)&(I< OBJ.Na) ) % In The PEC</pre>
```

```
% do nothing
%
                                       elseif (J==Nb)
%
                                                % IMPOSE BOUNDARY Condition at the Interface
%
                                                V(I+2,J+2) = 0.25*(V(I+3,J+2) + V(I+1,J+2)) + P1*V(I+2,J+3) + P2*V
                                   elseif (I==0)
                                            % IMPOSE Symmetry COndition Along with Y-AXIS
                                            OBJ.V(I+2,J+2) = (2*OBJ.V(I+3,J+2) + OBJ.V(I+2,J+3) + OBJ.V(I+2,J+1)
                                                                                                                                                                                                             )/4
                                   elseif (J==0)
                                            % IMPOSE Symmetry COndition Along with X-AXIS
                                            OBJ.V(I+2,J+2) = (OBJ.V(I+3,J+2) + OBJ.V(I+1,J+2) + 2*OBJ.V(I+2,J+3)
                                                                                                                                                                                                             )/4
                                   else
                                            OBJ.V(I+2,J+2) = (OBJ.V(I+3,J+2) + OBJ.V(I+1,J+2) + OBJ.V(I+2,J+3) + OBJ.V(I+2,J+3) + OBJ.V(I+2,J+3) + OBJ.V(I+3,J+3) + OBJ
                                   end
                          end
                 end
                 % ANimation of Calculation
                 if(Init.animate)
                 figure(1);
                 imagesc(OBJ.V);
                 colorbar;
                 title([num2str(K),'/' , num2str(NT) ])
                 drawnow
                 end
        end
        % Now Calculate the TOTAL CHARGE ENCLOSED IN A Rectangular Path Surrounding the Inner COND
        OBJ.IOUT = round((OBJ.NX+OBJ.Na)/2);
        OBJ.JOUT = round((OBJ.NY+OBJ.Nb)/2);
        % SUM Potential on Inner and Outer LOOPS:
        OBJ.SUM1 =0;
        OBJ.SUM1 = E1* sum( OBJ.V(3:OBJ.IOUT+1 , OBJ.JOUT+2) ) + E1*OBJ.V(2,OBJ.JOUT+2)/2 + |E1*O|
        for J=1:0BJ.JOUT-1
                          OBJ.SUM1 = OBJ.SUM1 + E1*OBJ.V(OBJ.IOUT+2,J+2); % A Parallel Line along Y-Axis from
        end
        %SUM1 = SUM1 + 2.0* E1* V(IOUT+2, JOUT+2); % Corner Point
        OBJ.IOUT = OBJ.IOUT-1;
        OBJ.JOUT = OBJ.JOUT -1;
        OBJ.SUM2 = E1* sum( OBJ.V(3:OBJ.IOUT+1 , OBJ.JOUT+2) ) + E1*OBJ.V(2,OBJ.JOUT+2)/2 + E1*OBJ.V(3:OBJ.JOUT+2)
        for J=1:0BJ.JOUT-1
                          OBJ.SUM2 = OBJ.SUM2 + E1*OBJ.V(OBJ.IOUT+2,J+2); % A Parallel Line along Y-Axis fro
        end
        OBJ.SUM2 = OBJ.SUM2 + 2.0* E1* OBJ.V(OBJ.IOUT+2,OBJ.JOUT+2); % Corner Point
        OBJ.Q = abs(OBJ.SUM1 - OBJ.SUM2);
    % Calculate the Z0:
        OBJ.C0 = 4.0*OBJ.Q/OBJ.VD ; % *4 --> Due to Symmetry
        OBJ.Z0 = 1.0/( U*OBJ.C0 ); % u = 1/sqrt(LC) ;--> L = 1/(u2c) , Z0 = sqrt(L/C) --> Z0 = sqrt(L/C)
```

```
end
```

# **Eigen Value Solution**

```
% for i=1:Nx
%
     for j=1:NY
         if( (i<NW) & (j<ND) ) % Inside the Conductor
%
             A(i,j) = 0;
%
%
          end
         if( (i == Nx) & (j<=ND) )
%
             A(i,j) = ;
%
%
          end
%
%
%
%
%
%
      end
%
% end
```