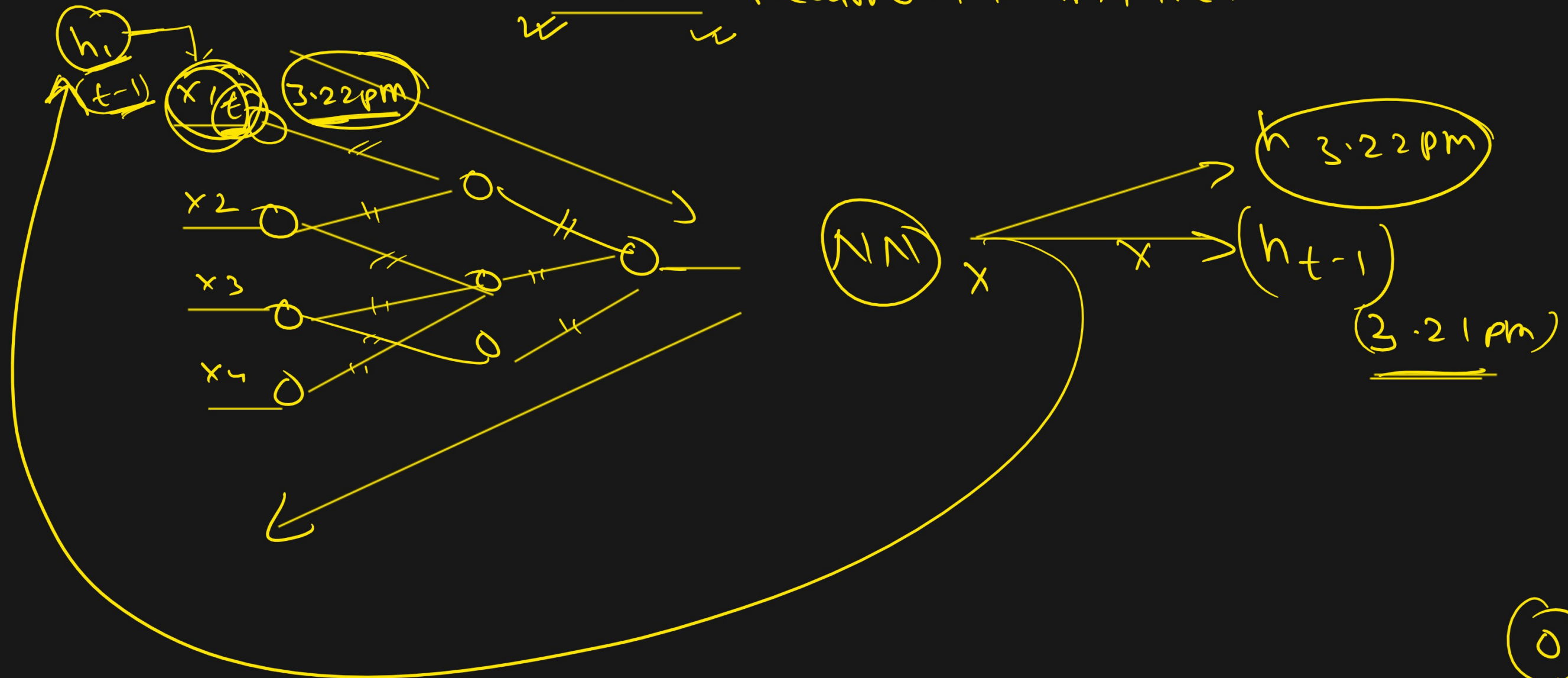
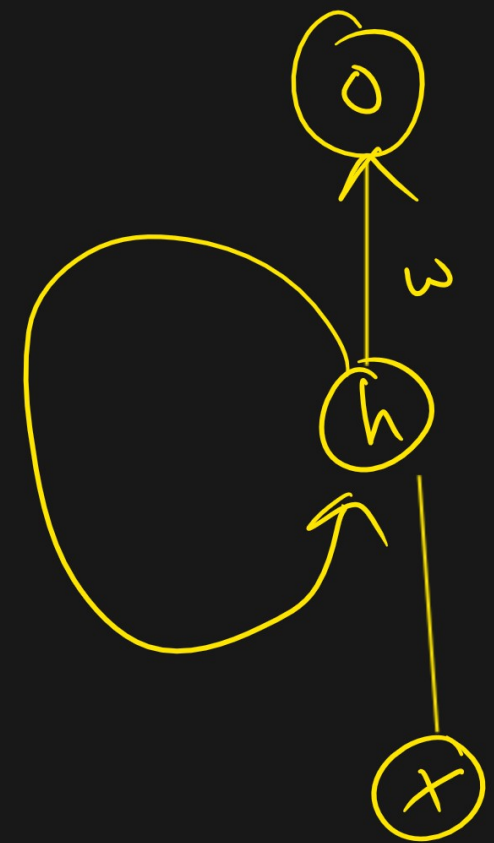
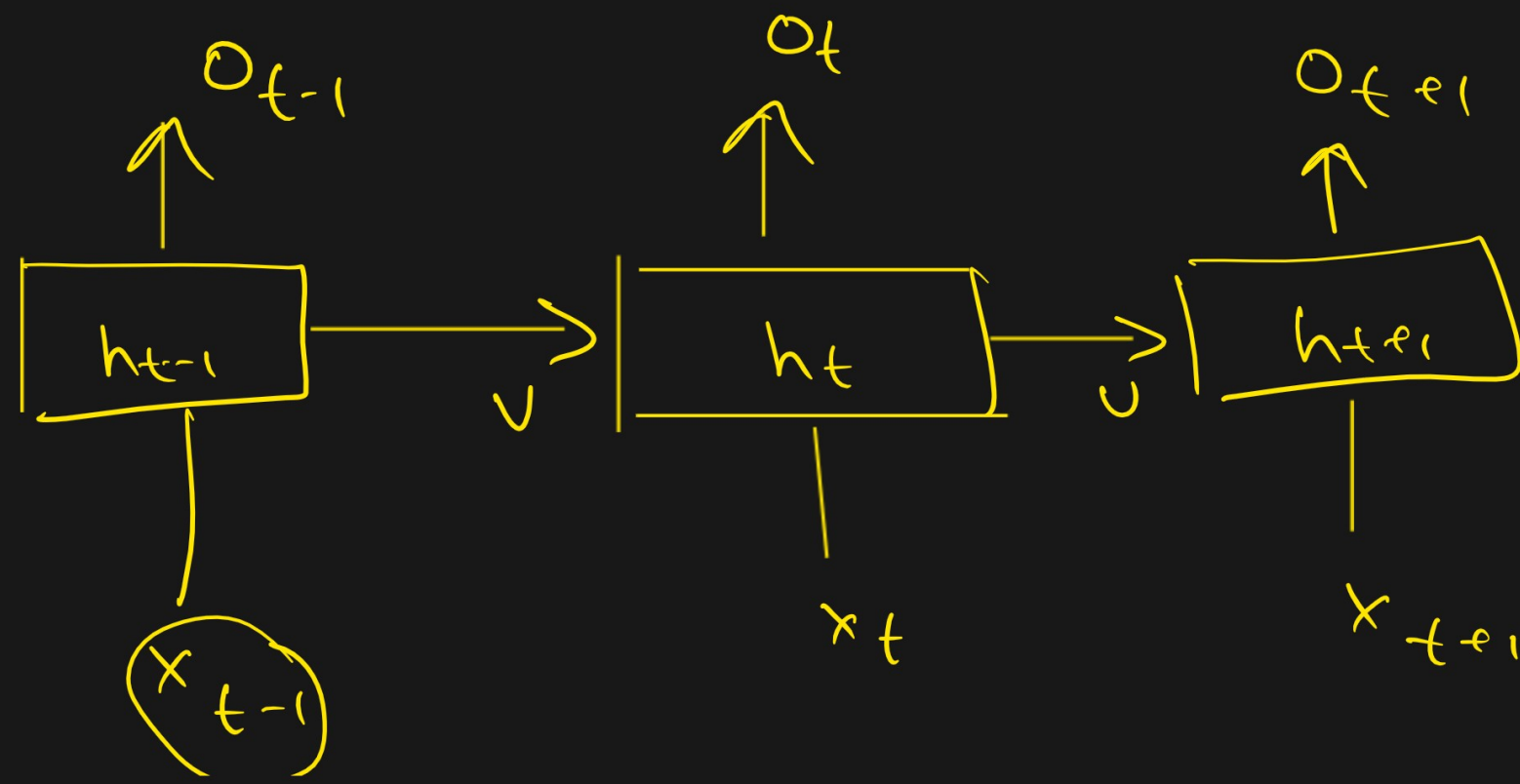
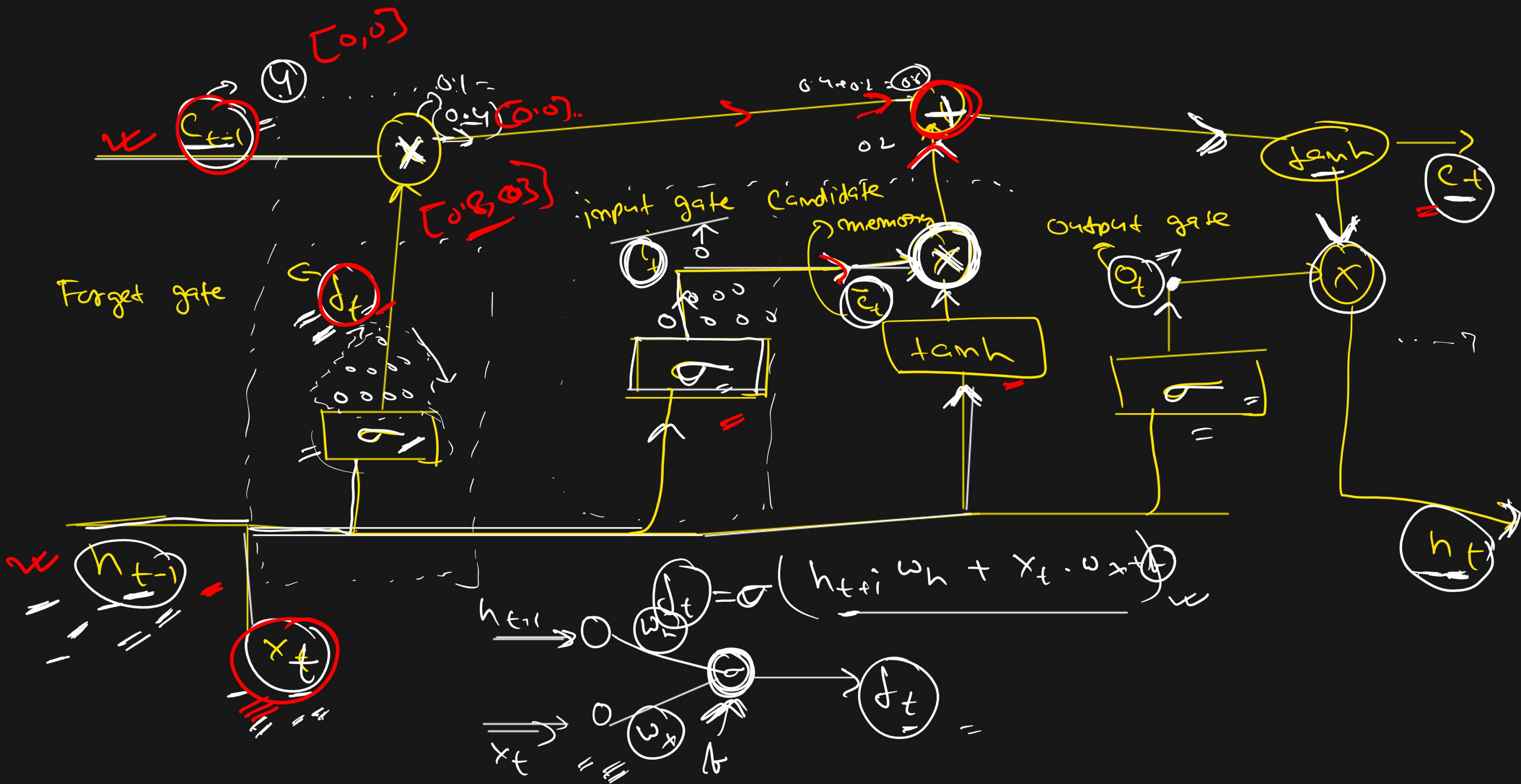


RNN \rightarrow Recurrent Neural Network.



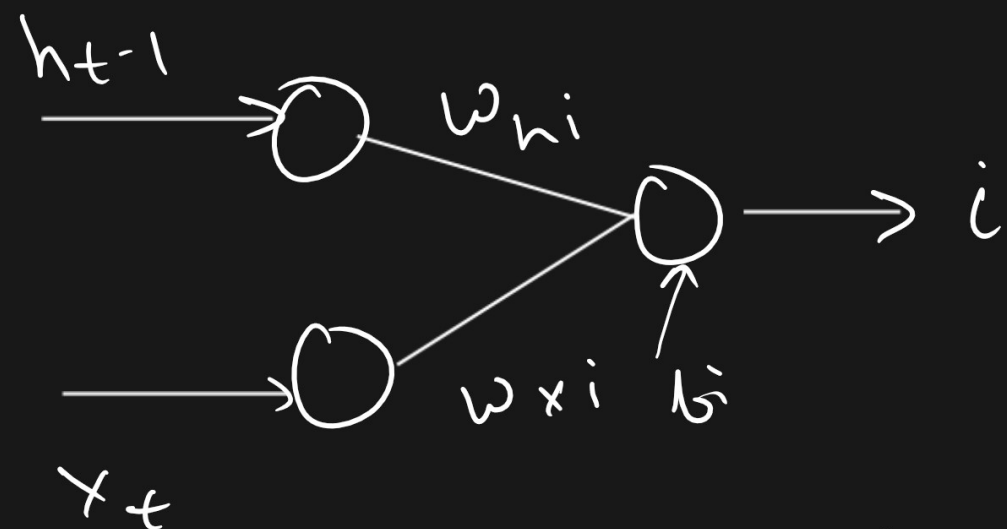
RNN





$f_t =$ Decide what to forget from the previous cell

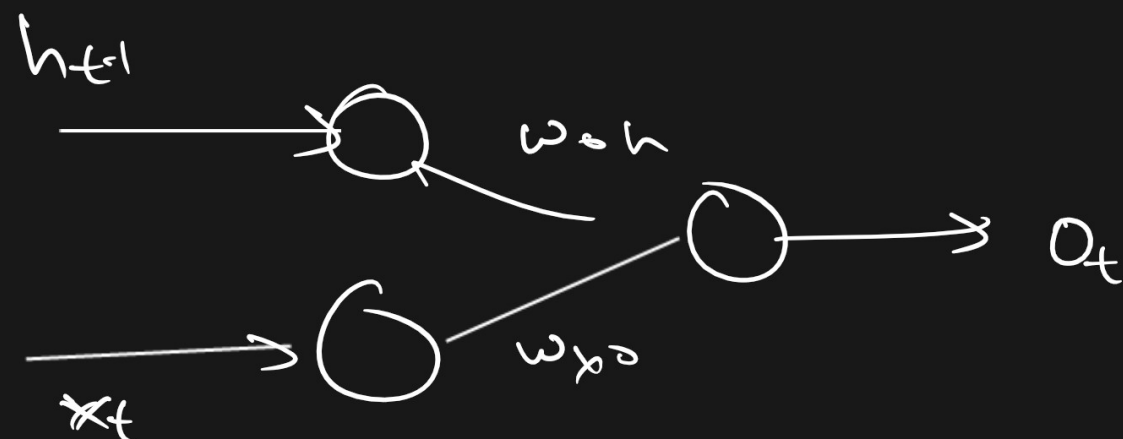
$$j_t = \sigma(w_x \cdot x_t + h_{t-1} \cdot w_h + b)$$



$$\tilde{l} = \sigma(h_{t-1} \cdot w_{hi} + x_t \cdot w_{xi} + b_i)$$

$$\tilde{c}_t = \tanh(x_t \cdot w_c + h_{t-1} \cdot w_c + b_c)$$

→ Decide what new information I have to store



$$o_t = \sigma(h_{t-1} * w_{ho} + x_t w_{xo} + b_o)$$

→ Decide what to output as a new hidden state

$$\left(\frac{\partial L}{\partial w_{ho}}, \frac{\partial L}{\partial w_{xi}}, \frac{\partial L}{\partial c_c}, \frac{\partial L}{\partial w_o} \right)$$

$$w_t = w_{t-1} - \eta \frac{\partial L}{\partial w_x}$$

$$C = \text{hel}(P)$$

h e l ?

$$C = \begin{bmatrix} 'h' & 'e' & 'l' & 'p' \end{bmatrix}$$

$$\text{input size} = 4$$

$$x_t = \underline{h} = [1, 0, 0, 0]$$

$$\underline{h_{t-1}} = [0, 0]$$

$$\underline{c_{t-1}} = [0, 0]$$

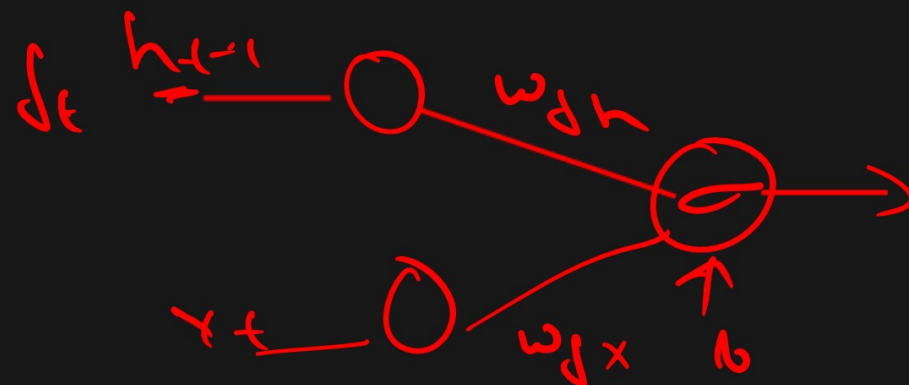
$$w_f, w_i, w_c, w_o$$

$$\underline{\text{forget Gate}} \rightarrow [0.8, 0.3]$$

$$\text{input Gate} \rightarrow [0.5, 0.2]$$

$$\text{Candidate mem} \rightarrow [0.2, -0.1]$$

→ h	[1, 0, 0, 0]
⇐ e	[0, 1, 0, 0]
⇐ l	[0, 0, 1, 0]
⇐ p	[0, 0, 0, 1]



$$d_t = \sigma(h_{t-1} \cdot w_{fh} + x_t \cdot w_{fx})$$

$$= [0.8, 0.3]$$

c_t (update cell state) $\rightarrow [0.1, -0.07]$

o_t (output gate) $\rightarrow [0.9, 0.6]$

h_t (hidden state) $\rightarrow [0.089, -0.041]$

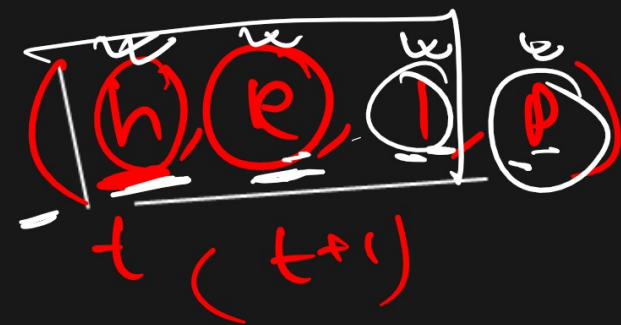
$y_t = \text{softmax}(w \cdot h_t + b) \rightarrow$

(d)

$x_t = [0, 1, 0, 0]$

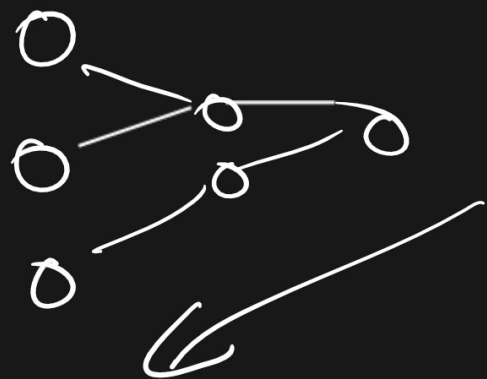
$h_{t-1} = [0.089, -0.041]$

$c_{t-1} = [0.1, -0.07]$



$h \rightarrow \left(\frac{y_t}{t} \right) \rightarrow \underline{1}$

$\hat{y} = 1$



$$\psi \quad \frac{[h, e, L]}{\quad} \quad \frac{[e, L, p]}{\quad}$$

$$\psi \quad \frac{[h, e, L]}{\quad} \quad \frac{p}{\quad}$$

$$\psi \quad \frac{[he]}{\quad} \quad \frac{[L, p]}{\quad}$$