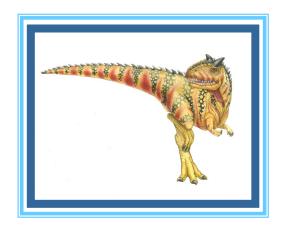
Lecture 7: Deadlocks





Lecture 7: Deadlocks

- System Model
- Deadlock Characterization
- Methods for Handling Deadlocks
- Deadlock Prevention
- Deadlock Avoidance
- Deadlock Detection
- Recovery from Deadlock





Lecture Objectives

- To Develop a Description of Deadlocks, which Prevent sets of Concurrent Processes from Completing their Tasks
- To Present a number of Different Methods for Preventing or Avoiding Deadlocks in a Computer System





System Model

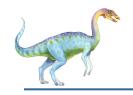
- System Consists of Resources
 - To be distributed among a number of competing processes
- Resource Types $R_1, R_2, ..., R_m$ *E.g.*; *CPU cycles, memory space, I/O devices*
- Each Resource Type R_i has W_i instances
- Each Process Utilizes a Resource as follows
 - Request, Use, Release
 - Accomplished using system calls such as request() and release() device or open() and close() file, OR



System Model (cont.)

- Physical Resources
 - Printers, tape drives, memory space, or CPU cores/cycles
- Logical Resources
 - Files, semaphores, and monitors
- Example: Consider a system with 3 CD RW drives and 3 running processes
 - Each process holds one CD RW drive and now requests another drive → Deadlock
- Multithreaded Programs:
 - Good candidate for deadlock
 - Multiple threads compete for shared resources





Deadlock Characterization

Deadlock can arise if four conditions hold simultaneously

- Mutual Exclusion: only one process at a time can use a resource
- Hold and Wait: a process holding at least one resource is waiting to acquire additional resources held by other processes
- No Preemption: a resource can be released only voluntarily by process holding it, after that process has completed its task



Deadlock Characterization (cont.)

■ Circular Wait: there exists a set $\{P_0, P_1, ..., P_n\}$ of waiting processes such that P_0 is waiting for a resource that is held by P_1, P_1 is waiting for a resource that is held by $P_2, ..., P_{n-1}$ is waiting for a resource that is held by P_n , and P_n is waiting for a resource that is held by P_0 .





Resource-Allocation Graph

A set of vertices *V* and a set of edges *E*.

- V is partitioned into two types:
 - $P = \{P_1, P_2, ..., P_n\}$, set consisting of all processes in the system
 - $R = \{R_1, R_2, ..., R_m\}$, set consisting of all resource types in the system
- Request Edge directed edge $P_i \rightarrow R_j$
- Assignment Edge directed edge $R_j \rightarrow P_i$





Resource-Allocation Graph (cont.)

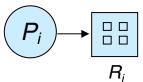
Process



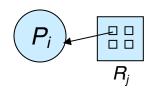
■ Resource Type with 4 instances



 $\blacksquare P_i$ requests instance of R_j



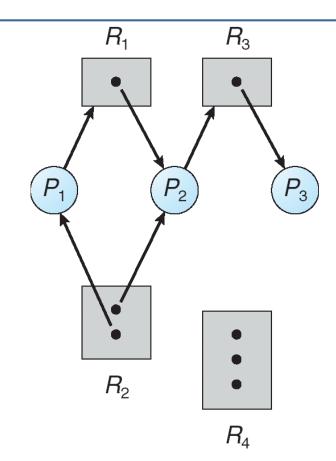
 $\blacksquare P_i$ is holding an instance of R_i



7.9



Example of a Resource Allocation Graph



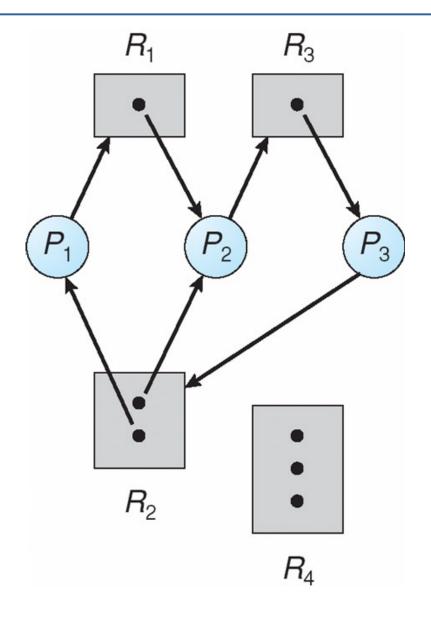
- \blacksquare P = {P1, P2, P3}
- \blacksquare R = {R1, R2, R3, R4}
 - R1: one instance, R2 two instances, R3 one instance, and R4 three instances

7.10

 \blacksquare E = {P1 \rightarrow R1, P2 \rightarrow R3,, R3 \rightarrow P3}

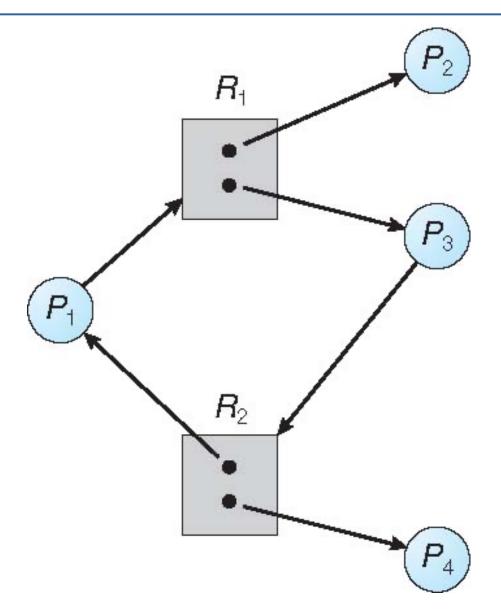


Resource Allocation Graph With a Deadlock

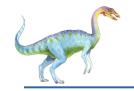




Graph With A Cycle But No Deadlock







Basic Facts

- If Graph Contains no Cycles ⇒ No Deadlock
- If Graph Contains a Cycle ⇒
 - Only one instance per resource type -> deadlock
 - Cycle involves only a set of resource types, each of which has only a single instance → deadlock
 - In the above two cases, cycle is necessary & sufficient condition for existence of deadlock
 - Several instances per resource type ->
 possibility of deadlock
 - In this case, cycle is necessary but not sufficient



Methods for Handling Deadlocks

- Ensure that System will Never Enter a Deadlock State
 - Deadlock prevention: try to violate one of necessary conditions for deadlock
 - Deadlock avoidance: try to regulate how/when requests can be made to acquire resources
 - More conservative approach than deadlock prevention
- Allow System to enter a Deadlock State and then recover



Methods for Handling Deadlocks (cont.)

- Ignore Problem and Pretend that Deadlocks Never occur in system
 - Used by most OSes, including UNIX
 - Up to application developer to detect and handle deadlocks
- What if Deadlocks are not Resolved?
 - Deterioration of system performance
 - Eventually need a manual restart
 - Deadlock occur very infrequent -> cheaper approach in mainstream applications
 - Instead of employing prevention, avoidance, or detection and recovery methods



Deadlock Prevention

■ Mutual Exclusion

- Not required for sharable resources
- A process never needs to wait for a sharable resources
- Must hold for non-sharable resources
- Example
 - Read-only files





Deadlock Prevention (cont.)

- Hold and Wait must guarantee that whenever a process requests a resource, it does not hold any other resources
 - Solution 1: Require process to request and be allocated all its resources before it begins execution
 - Solution 2: Or allow process to request resources only when process has none allocated to it
 - Cons
 - ▶ Low resource utilization ⊗
 - ▶ Starvation possible ⊗





Deadlock Prevention (cont.)

■ No Preemption

- If a process that is holding some resources requests another resource that cannot be immediately allocated to it, then all resources currently being held are released
- Preempted resources are added to list of resources for which the process is waiting
- Process will be restarted only when it can regain its old resources, as well as new ones
- This protocol applicable only to resources whose state can be easily saved and restored later
 - ▶ CPU registers and memory space: applicable ☺
 - ▶ Printers and tape drives: not (easily) applicable ⊗





Deadlock Prevention (cont.)

- Circular Wait impose a total ordering of all resource types, and require that each process requests resources in an increasing order of enumeration
 - A process which holds R(i), can request instance of R(j) if F(Rj) > F(Ri)
 - Ensuring order is possibility of application developer
 - Can use lock-order verifier (e.g., witness in FreeBSD)
- Example
 - F(tape)=1, F(disk drive)=5, and F(printer)=12



Deadlock Example

```
/* thread one runs in this function */
void *do work one(void *param)
  pthread mutex lock(&first mutex);
  pthread mutex lock(&second mutex);
   /** * Do some work */
  pthread mutex unlock(&second mutex);
  pthread mutex unlock(&first mutex);
  pthread exit(0);
/************************
/* thread two runs in this function */
void *do work two(void *param)
  pthread mutex lock(&second mutex);
  pthread mutex lock(&first mutex);
   /** * Do some work */
  pthread mutex unlock(&first mutex);
  pthread mutex unlock(&second mutex);
  pthread exit(0);
```



Deadlock Example with Lock Ordering

- Lock Ordering does not Guarantee Deadlock Prevention if Locks can be acquired Dynamically
 - Ordering is broken with unordered arguments

```
void transaction(Account from, Account to, double amount)
{    mutex lock1, lock2;
    lock1 = get_lock(from);
    lock2 = get_lock(to);
    acquire(lock1);
        acquire(lock2);
        withdraw(from, amount);
        deposit(to, amount);
        release(lock2);
    release(lock1);
}
```

- Transactions 1 and 2 execute concurrently.
- Transaction 1 transfers \$25 from account A to account B.

Transaction 2 transfers \$50 from account B to account A Operating System Concepts – 9th Edition 7.21 Silberschatz, Galvin and Gagne ©2013, Edited by H. Asadi, Fall 20



Deadlock Avoidance

Requires that system has some additional *a priori* information available

- Simplest and most useful model requires that each process declare *maximum number* of resources of each type that it may need
- Deadlock-avoidance algorithm dynamically examines resource-allocation state to ensure that there can never be a circular-wait condition
- "Resource-allocation state" is defined by number of available and allocated resources, and maximum demands of processes

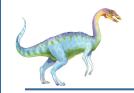




Safe State

- When a process requests an available resource, system must decide if immediate allocation leaves system in a safe state
- System is in **safe state** if there exists a sequence $\langle P_1, P_2, ..., P_n \rangle$ (aka, safe sequence) of ALL processes in systems such that for each P_i , resources that P_i can still request can be satisfied by currently available resources + resources held by all P_i , with j < i





Safe State (cont.)

■That is:

- If P_i resource needs are not immediately available, then P_i can wait until all P_j have finished
- When P_j is finished, P_i can obtain needed resources, execute, return allocated resources, and terminate
- When P_i terminates, P_{i+1} can obtain its needed resources, and so on





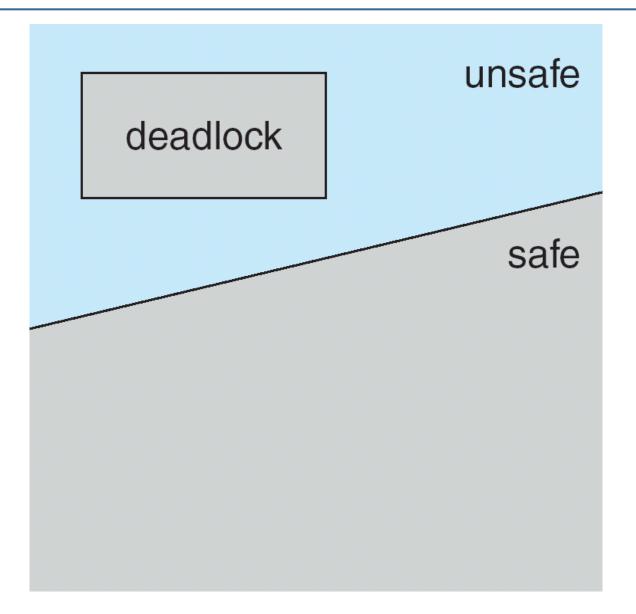
Basic Facts

- If a System is in Safe State ⇒ No Deadlocks
- ■If a System is in Unsafe State ⇒ Possibility of Deadlock
- Avoidance ⇒ Ensure that a System will Never enter an Unsafe State





Safe, Unsafe, Deadlock State







Avoidance Algorithms

- Single Instance of a Resource Type
 - Use a resource-allocation graph

- Multiple Instances of a Resource Type
 - Use banker's algorithm
 - Reading assignment



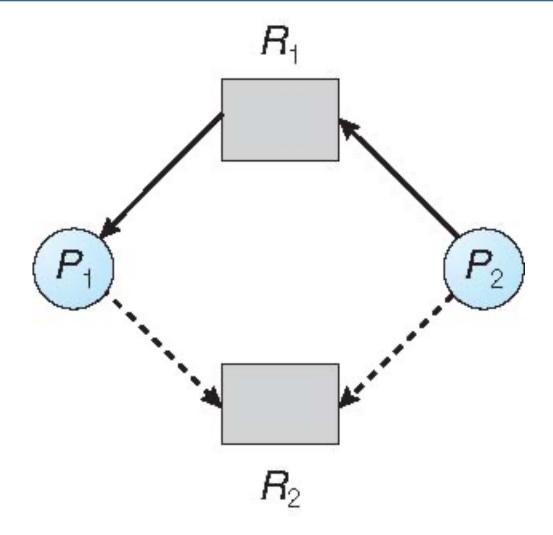
Resource-Allocation Graph Scheme

■ Claim edge

- $ullet P_i
 ightharpoonup R_j$ indicates that process P_i may request resource R_i (represented by a dashed line)
- Claim edge converts to request edge when a process requests a resource
- Request edge converted to an assignment edge when resource is allocated to process
- Resource is Released by a process → Assignment Edge reconverts to a claim edge
- Resources must be claimed a priori in system

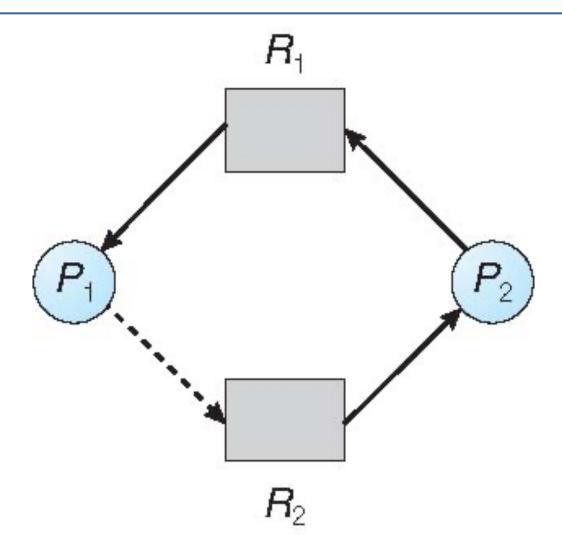


Resource-Allocation Graph





Unsafe State In Resource-Allocation Graph



Why not assigning R2 to P2 after making sure that P1 doesn't need R2 in the near future?

Resource-Allocation Graph Algorithm

- Suppose that P_i requests a R_j
- Request can be Granted only if Converting Request Edge to an Assignment Edge does not Result in Formation of a Cycle in Resource Allocation Graph
- Algorithm Complexity O(n²)
- Low Resource Utilization
 - Resources might be available and not be allocated to processes



Deadlock Detection

- Allow System to Enter Deadlock State
- ■Detection Algorithm
 - Single instance of each resource type
 - Multiple instances of a resource type
 - Reading assignment
- Recovery Scheme

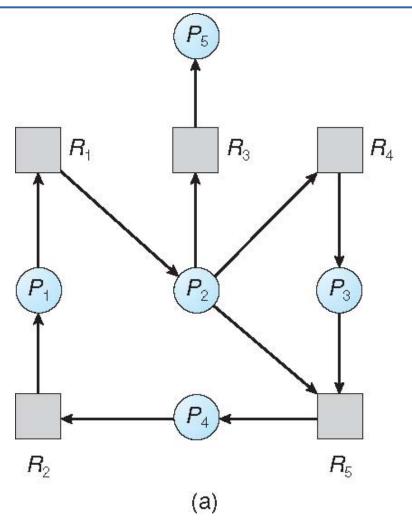


Single Instance of Each Resource Type

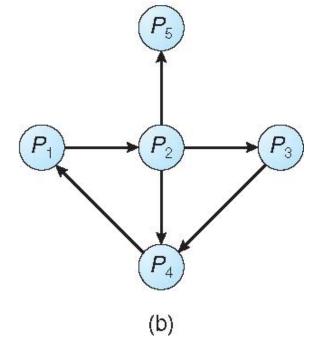
- Maintain wait-for graph
 - Nodes are processes
 - $lackbox{P}_i
 ightarrow P_i$ if P_i is waiting for P_j
- Periodically invoke an Algorithm that Searches for a Cycle in graph
 - If there is a cycle → there exists a deadlock
- ■An Algorithm to Detect a Cycle in a Graph Requires an Order of n² operations
 - Where *n* is number of vertices in graph



Resource-Allocation Graph and Wait-for Graph



Resource-Allocation Graph



Corresponding wait-for Graph



Detection-Algorithm Usage

- When, and How often, to Invoke depends on:
 - How often a deadlock is likely to occur?
 - How many processes will need to be rolled back?
 - One for each disjoint cycle
- If Detection Algorithm is Invoked Arbitrarily, there may be many cycles in resource graph and so we would not be able to tell which of many deadlocked processes "caused" deadlock



- Abort all Deadlocked Processes
 - Significant expense
 - Most processes need to be restarted for recomputation
- Abort one process at a time until Deadlock Cycle is Eliminated
 - After each process is aborted, a deadlockdetection algorithm must be invoked
 - To see if any process is still deadlocked





- Issues with Aborting a Process
 - Updating a file
 - Printing data
- In which Order should we Choose to Abort?
 - 1. Priority of process
 - How long process has computed, and how much longer to completion
 - 3. Resources process has used
 - 4. Resources process needs to complete
 - 5. How many processes will need to be terminated
 - 6. Is process interactive or batch?

Recovery from Deadlock: Resource Preemption

- Selecting a Victim minimize cost
- Rollback return to some safe state, restart process for that state
- Starvation same process may always be picked as victim, include number of rollback in cost factor





Reading Assignment

- Banker's Algorithm
- Deadlock Detection
 - Multiple instances of a resource type





Banker's Algorithm

- Multiple Instances
- Each Process must a Priori Claim Max Use
- When a Process Requests a Resource it may have to Wait
- When a Process Gets all its Resources it must Return them in a Finite Amount of Time



ata Structures for Banker's Algorithm

Let n = number of processes, and m = number of resources types.

- Available: Vector of length m. If available [j] = k, there are k instances of resource type R_i available
- Max: $n \times m$ matrix. If Max[i,j] = k, then process P_i may request at most k instances of resource type R_j
- Allocation: $n \times m$ matrix. If Allocation[i,j] = k then P_i is currently allocated k instances of R_i
- Need: $n \times m$ matrix. If Need[i,j] = k, then P_i may need k more instances of R_j to complete its task Need[i,j] = Max[i,j] Allocation[i,j]





Safety Algorithm

1. Let *Work* and *Finish* be vectors of length *m* and *n*, respectively. Initialize:

```
Work = Available
Finish [i] = false for i = 0, 1, ..., n-1
```

- 2. Find an *i* such that both:
 - (a) *Finish* [*i*] = *false*
 - (b) $Need_i \leq Work$ If no such *i* exists, go to step 4
- 3. Work = Work + Allocation_i
 Finish[i] = true
 go to step 2
- 4. If *Finish* [*i*] == *true* for all *i*, then the system is in a safe state



Resource-Request Algorithm for Process P_i

 $Request_i$ = request vector for process P_i .

- If $Request_i[j] = k \rightarrow P_i$ wants k instances of R_i
 - 1. If *Request_i* ≤ *Need_i* go to step 2. Otherwise, raise error condition (as process has exceeded its maximum claim)
 - 2. If $Request_i \le Available$, go to step 3. Otherwise P_i must wait, since resources are not available
 - 3. Pretend to allocate requested resources to P_i by modifying the state as follows:

```
Available = Available - Request<sub>i</sub>;
Allocation<sub>i</sub> = Allocation<sub>i</sub> + Request<sub>i</sub>;
Need<sub>i</sub> = Need<sub>i</sub> - Request<sub>i</sub>;
```

- If safe \Rightarrow the resources are allocated to P_i
- If unsafe $\Rightarrow P_i$ must wait, and old resource-allocation state is restored



Example of Banker's Algorithm

5 processes P₀ through P₄;
 3 resource types:

A (10 instances), B (5 instances), and C (7 instances)

 \blacksquare Snapshot at time T_0 :

	<u>Allocation</u>	<u>Max</u>	<u>Available</u>
	ABC	ABC	ABC
P_0	010	753	332
P_1	200	322	
P_2	302	902	
P_3	211	222	
P_4	002	433	





Example (cont.)

Content of Need is defined to be Max – Allocation

```
\frac{Need}{ABC}
ABC
P_0 743
P_1 122
P_2 600
P_3 011
P_4 431
```

- System is in a Safe State
 - Since sequence $\langle P_1, P_3, P_4, P_2, P_0 \rangle$ satisfies safety criteria



Example: P_1 Request (1,0,2)

■ Check that Request \leq Available (i.e., $(1,0,2) \leq (3,3,2) \Rightarrow$ true

<u>Allocation</u>		<u>Need</u>	<u>Available</u>
	ABC	ABC	ABC
P_0	010	7 4 3	230
P_1	302	020	
P_2	302	600	
P_3	211	0 1 1	
P_4	002	431	

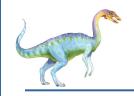
- Executing safety algorithm shows that sequence $< P_1, P_3, P_4, P_0, P_2>$ satisfies safety requirement
- \blacksquare Can request for (3,3,0) by P_4 be granted?
- \blacksquare Can request for (0,2,0) by P_0 be granted?

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Several Instances of a Resource Type

- Available: A vector of length *m* indicates number of available resources of each type
- Allocation: An *n* x *m* matrix defines number of resources of each type currently allocated to each process
- Request: An n x m matrix indicates current request of each process
 - If Request [i][j] = k, → process P_i is requesting k more instances of resource type R_i





Detection Algorithm

- 1.Let *Work* and *Finish* be vectors of length *m* and *n*, respectively Initialize:
 - (a) Work = Available
 - (b) For *i* = 1,2, ..., *n*, if *Allocation*_i ≠ 0, then *Finish*[i] = *false*; otherwise, *Finish*[i] = *true*
- 2. Find an index *i* such that both:
 - (a) Finish[i] == false
 - (b) *Request*_i ≤ *Work*

If no such i exists, go to step 4





Detection Algorithm (cont.)

- 3. Work = Work + Allocation; Finish[i] = true go to step 2
- 4.If *Finish[i]* == *false*, for some i, $1 \le i \le n$, then the system is in deadlock state. Moreover, if *Finish[i]* == *false*, then P_i is deadlocked

Algorithm requires an order of $O(m \times n^2)$ operations to detect whether the system is in deadlocked state





Example of Detection Algorithm

Five Processes P_0 through P_4 ; three Resource types

A (7 instances), B (2 instances), and C (6 instances)

 \blacksquare Snapshot at time T_0 :

	<u>Allocation</u>	<u>Request</u>	<u>Available</u>
	ABC	ABC	ABC
P_0	010	000	000
P_1	200	202	
P_2	303	000	
P_3	211	100	
$P_{\scriptscriptstyle A}$	002	002	

Sequence $\langle P_0, P_2, P_3, P_1, P_4 \rangle$ will result in *Finish[i] = true* for all *i*



Example (cont.)

P₂ requests an additional instance of type C
Request

```
\begin{array}{ccc} & A & B & C \\ P_0 & 0 & 0 & 0 \\ P_1 & 2 & 0 & 2 \\ P_2 & 0 & 0 & 1 \\ P_3 & 1 & 0 & 0 \\ P_4 & 0 & 0 & 2 \end{array}
```

- State of system?
 - Can reclaim resources held by process P₀, but insufficient resources to fulfill other processes; requests
 - Deadlock exists, consisting of processes

End of Lecture 7

