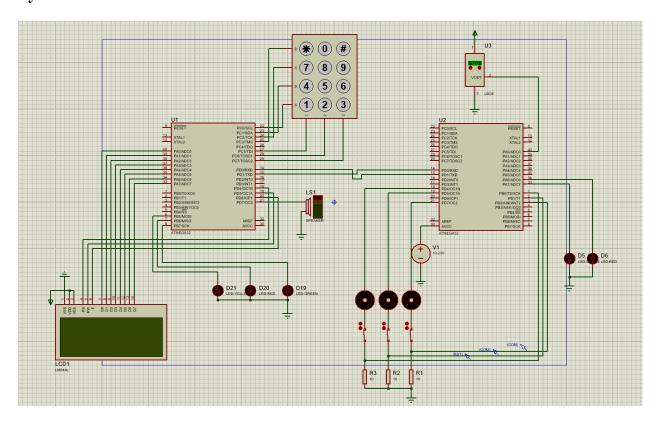
A master/slave temperature control system using two Atmega32 microcontrollers

System Overview



Hardware Components

- Atmega32 Microcontrollers: Master unit handles user interface; Slave unit manages temperature control.
- **LCD Screen**: Connected to PORTA on the Master, displays menus and system information.
- **Keypad**: Connected to PORTC on the Master, used for password entry and menu navigation.
- **LED Indicators and Speaker**: Connected to PORTD on the Master, indicate system status and alarm.
- **Temperature Sensor (LM35)**: Connected to ADC0 on the Slave, measures server temperature.
- **Motors**: Controlled via Timer/Counter 1A, 1B, and 2 on the Slave, manage cooling based on temperature.
- **Speaker for Alarm**: Uses Timer/Counter2 and Fast PWM on the Master to generate sound.

Software Design

• Password Entry and Verification:

- o User enters a password via the keypad.
- o The Master transmits the encrypted password to the Slave using USART.
- o The Slave decrypts the password and verifies it.
- The Slave sends a response back to the Master indicating success or failure.

• Temperature Monitoring and Motor Control:

- The Slave reads temperature data from the LM35 sensor connected to ADC0.
- Motor duty cycles are adjusted based on the temperature:
 - Duty cycle increases by 10% per 10°C.
 - If motors are disconnected via switches, the duty cycle is redistributed among the connected motors.

• Alarm System:

o If a critical error occurs, the Master activates the speaker using Timer/Counter2 and Fast PWM to generate an alarm.

• LCD Display:

o Displays system menus, current temperature, and motor status.

• LED Indicators:

- o Green LED: Normal operation.
- o Yellow LED: One or two motors failed.
- o Red LED: Critical error (all motors failed or insufficient cooling capacity).

System Functionality

- Initial Lock State: System is locked and prompts for a password on the LCD.
- **Password Entry and Verification**: User enters the password; the Master sends it to the Slave for verification.
- **System Start**: On successful password verification, the system unlocks and the Slave starts sending data to the Master.

• Motor Control Logic:

- o Motors are controlled based on the temperature read from the LM35 sensor.
- Duty cycle adjustments:
 - 10% per 10°C per motor.
 - Redistribution of duty cycle if motors are disconnected.

• Error Handling:

- o Display error messages on the LCD.
- o Activate LED indicators and speaker alarm.

User Interface

• LCD Display:

- o Main menu with options for checking motor status and temperature.
- Motor status menu shows individual motor information (working status and duty cycle).
- Temperature menu displays the current temperature.

Keypad:

o Used for password entry and menu navigation.

• LED Indicators:

- o Green: Everything is functioning normally.
- Yellow: One or two motors failed.
- o Red: Critical error.

• Speaker:

o Activated for alarms using Fast PWM on Timer/Counter2.

Communication Protocol

• USART Communication:

- o Master and Slave communicate via USART without interrupt.
- o Passwords are encrypted using AES before transmission.
- o The Slave decrypts and verifies the password.
- o Communication includes commands for password verification, temperature data requests, and motor status updates.

Bonus Features

• Password Attempts and Lockout Mechanism:

After three incorrect password attempts, system locks the user out for 30 seconds.

• Encrypted Communication:

o AES encryption ensures secure password transmission.

• Alarm System:

- Activated for critical errors using the speaker connected to PORTD on the Master.
- Documentation