

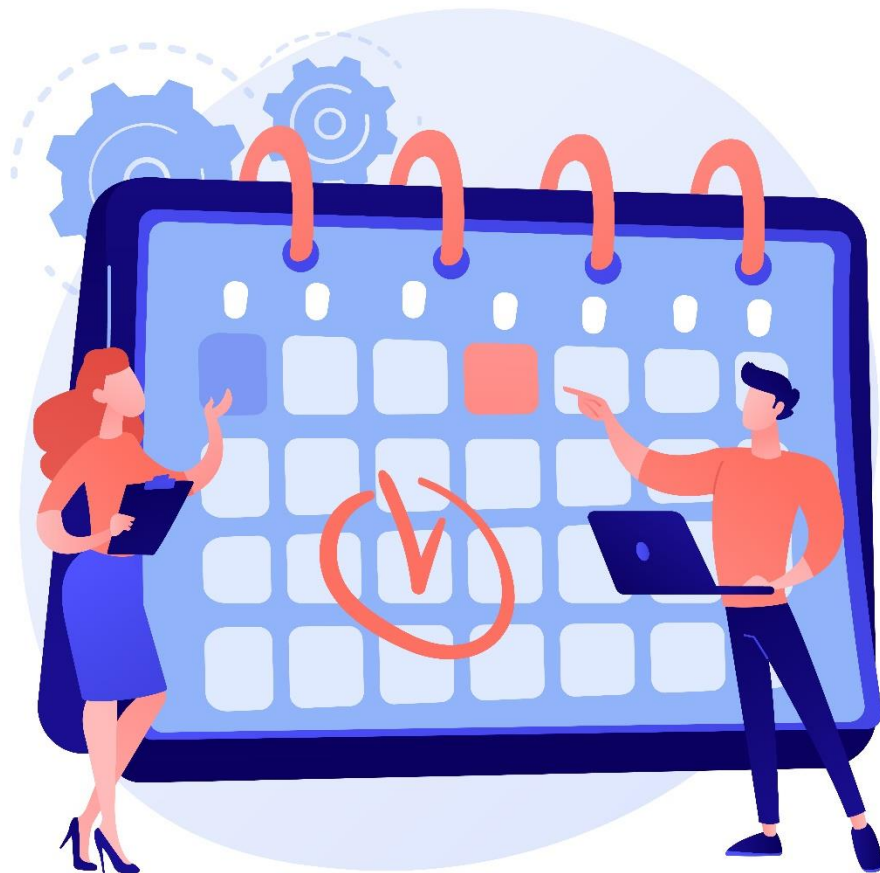
Legend Group

Work Plan

Work as group.....

-We are going to work in parallel as much as we can to save time but some of task's does not support working in that way so we have to wait for each other, but we will try to decrease it. - Our robot will be useful for carries food less than 5kg.

-We will work on improve the performance of battery to walk 2km.



Distribution of tasks

1. Mechanics engineers will design the arm using cinema 4D
2. Electronics engineers will use a program a microcontroller to control motors.
3. Connecting the electric signal to internet
4. Building a database.
5. Testing.

Weeks plan to timeline

	Week 1	Week 2	Week 3	Week 4	Week 5
Mech					
EE					
AI					
IOT					
Industrial					

Production line

1. Designing the robot arm using 3d program
2. Printing the robot
3. Control the electric circuit
4. Combine the robot
5. testing