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- The R(A) stands for the **range** of A, which is essentially the column space of A. Let $f(x) = A_{m \times n} x$:
 - The domain of $f = \mathbb{R}^n$
 - The range of $f = \{b \in \mathbb{R}^m | Ax = b\} = R(A) = C(A)$
 - The kernel of $f = \{x \in \mathbb{R}^n | Ax = 0\} = N(A)$
- If U is the row echelon form of A, C(A) ≠ C(U), but they have the same dimension. For U, the columns w/ pivots are a basis for C(U). Then, the corresponding columns of A form a basis for C(A). Since the two systems Ax = 0 and Ux = 0 are equivalent and have the same solutions. A nontrivial solution x means a linear combination of columns of U, hence the same linear combination of columns of A. So, if a set of columns of U is independent, then so are the corresponding column of A and vice versa. To find a basis of C(A), we pick those columns of A, which corresponds to the columns of U w/ pivots.
- The dimension of the column space = the rank r, which also equals the dimension of the row space. # of independent columns = # of independent rows. Or, column rank = row rank.
- Given $A_{m \times n}$. For A, dimension of C(A) + dimension of N(A) = # of columns of A, i.e., r + (n r) = n. For A^{\top} , dimension of $C(A^{\top})$ + dimension of $N(A^{\top})$ = # of columns of A^{\top} , i.e., r + (m r) = m.
- To find the left nullspace of $A_{m \times n}$, we compute $L^{-1}PA = U$. The last m r rows of $L^{-1}P$ must be a basis for the left nullspace since the last m r rows of $L^{-1}P$ are independent and dimension of the left nullspace is also m r.
- Orthogonality: $C(A) \perp N(A^{\top}) \leq \mathbb{R}^m$. $C(A^{\top}) \perp N(A) \leq \mathbb{R}^n$.
- Existence and Uniqueness of solution to Ax = b. Given $A_{m \times n}$:
 - Existence: The system Ax = b has at least one solution x for every b iff the columns span \mathbb{R}^m (r = m). In this case, \exists a right inverse $R_{n \times m}$ s.t. $AR = I_m$. This is possible only if $m \le n$.
 - Uniqueness: The system Ax = b has at most one solution x for every b iff the columns are linearly independent (r = n). In this case, \exists a left inverse $L_{n \times m}$ s.t. $LA = I_n$. This is possible only if $m \ge n$.
- The following statements about a matrix $A_{n \times n}$ are equivalent:
 - A is nonsingular.
 - The rows/columns of A span \mathbb{R}^n .
 - The rows/columns of A are linearly independent.
 - Elimination can be completed: PA = LDU.
 - A is invertible.
 - Determinant of $A \neq 0$.
 - \circ 0 is not an eigenvalue of A.
 - A is positive definite.
- A transforms x into Ax:
 - Stretch: $A = \begin{bmatrix} c & 0 \\ 0 & c \end{bmatrix}$

• Rotation of 90°:
$$A = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$$

• Reflection about
$$x = y$$
: $A = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$

• Projection onto *x*-axis:
$$A = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$$

- Let V and V' be vector spaces of F. A linear transformation T from V to V' is a function from V to V' that preserves the operations on V and V', i.e., $\forall x, y \in V$, $\forall \alpha \in F$, $T(\alpha x + y) = \alpha Tx + Ty$.
- Linear transformation $T = \frac{d}{dt} : P_n(\mathbb{R}) \to P_{n-1}(\mathbb{R})$.
 - Nullspace: $N(T) = P_0(\mathbb{R})$. Dimension = 1.
 - Range: $C(T) = P_{n-1}(\mathbb{R})$. Dimension (rank) = n.
- Linear transformation $T = \int_0^t : P_n(\mathbb{R}) \to P_{n+1}(\mathbb{R})$.
 - Nullspace: $N(T) = \{0\}$. Dimension = 0.
 - Range: $P_{n+1}(\mathbb{R}) P_0(\mathbb{R})$. Dimension (rank) = n+1.