# **Discrete Mathematics Final**

### 2017-05-04

### • Graphs:

- Undirected graph and edges
- Directed graph (digraph) and arcs
- **Multigraph** : *E* is a multiset of edges.
- **Simple graph**: no *loops* and no more than one edge connecting the same pair of vertices.
- $\circ$  Complete graph: each pair of distinct vertices is connected by an edge. Denoted as  $\emph{K}_{|\emph{V}|}$
- $\circ$  **Bipartite graph**: there exist X and Y such that  $V=X\cup Y(X\cap Y=\emptyset)$  and  $E=\{(i,j)|i\in X,j\in Y\}.$
- Complete bipartite graph: each vertex of X is connected to each vertex of Y. Denoted as  $K_{|X|,|Y|}$ .
- Regular graph: every vertex has the same degree.
- Subgraph: if G' = (V', E') is a subgraph of G = (V, E), then  $V' \subseteq V$  and  $E' \subseteq E$ .
- **Spanning subgraph**: a subgraph that contains all the vertices of the original graph.
- Induced subgraph: a subset of the vertices of the graph together with any edges connecting pairs of vertices in that subset.
- **Underlying graph**: the undirected graph that replaces all arcs in a digraph with edges.

### 2017-05-11

- Isomorphism:  $G_1=(V_1,E_1)$  and  $G_2=(V_2,E_2)$  are isomorphic iff there exists a one-to-one and onto mapping  $f:V1\to V2$  such that  $(i,j)\in E_1 \Leftrightarrow (f(i),f(j))\in E_2$ .
- Walk: an arbitrary sequence of vertices and edges
  - Trail: all edges are distinct.
  - Path: all vertices are distinct.
  - Circuit: a trail which starts and ends at the same vertex.
  - **Cycle**: a path which starts and ends at the same vertex.
- Connected components:
  - **Connected**: each pair of vertices forms the endpoints of a path.
  - **Component**: a maximal connected subgraph.

- Connected graph: a graph consists of one single connected component.
- Strongly connected digraph: each pair of vertices has a directed path to each other.
- Weakly connected digraph: whose underlying graph is connected.

#### • Theorems:

- If G = (V, E) is a connected graph with |V| > 1, then G contains either a vertex of degree 1 or a cycle (or both).
- If G = (V, E) is a connected graph, and  $(i, j) \in E$  be an edge that is contained in one cycle of G. Then, G (i, j) remains connected.
- Every n-vertex connected undirected graph contains at least n-1 edges.
- Every *n*-vertex strongly connected digraph contains at least *n* arcs.

#### • Tree:

- Tree: a tree of n vertices is an n-vertex connected undirected graph that contains exactly n-1 edges.
- **Spanning tree**: a tree which is also a spanning subgraph of an undirected graph.
- Minimum spanning tree (MST): Kruskal's algorithm, Prim's algorithm, Sollin's
  algorithm.
- The number of spanning tress:  $S(G) = S(G e) + S(G \cdot e)$ 
  - S(G e): the number of spanning trees that do not contain edge e.
  - $S(G \cdot e)$ : the number of spanning trees that contains edge e.
- Algorithms for searching MSTs: Kruskal's algorithm, Prim's algorithm, and Sollin's algorithm.
- **G** has a unique MST if its edge costs are all distinct.

### 2017-05-18

### • Connectivity:

- Let G=(V,E) be a connected undirected graph. A subset S of V is called a **vertex cut** of G iff  $G-S=(V-S,E-\{(i,j)|i\in S\lor j\in S,(i,j)\in E\})$  is disconnected.
- A **k**-vertex cut is a vertex cut of **k** vertices.
- The **connectivity** of *G* is the minimum *k* such that *G* has a *k*-vertex cut.
- The connectivity of  $K_n$ , which has no vertex cut, is defined to be n-1.
- G is k-connected, if its connectivity  $\geq k$ .
- v is an **articulation point** of G iff  $\{v\}$  is a vertex cut of G.
- A connected graph G is **biconnected** (or 2-connected) iff G has no articulation point.
- Finding articulation points:
  - **DFN**(*i*): the visiting sequence of vertices by DFS.

- L(i): the least DFN reachable from i through a path consisting of zero or more
   (downward) tree edges followed by zero or one back edge.
- $i \in V$  is an articulation point of G iff either
  - *i* is the root and has at least two children.
  - i is not the root and has a child j with  $L(j) \ge DFN(i)$ .
- Theorem: Suppose G is a connected graph and T is a depth-first spanning tree of G. Then, G contains no cross edge with respect to T.
- Edge connectivity:
  - Given G = (V, E),  $S \subset E$  is an edge cut of G iff G S = (V, E S) is disconnected.
  - A **k**-edge cut is an edge cut of **k** edges.
  - The **edge connectivity** of G is the minimum k such that G has a k-edge cut.
  - G is k-edge-connected, if its edge connectivity  $\geq k$ .
  - (i,j) is a **bridge** of G iff  $\{(i,j)\}$  is an edge cut of G.
- Finding bridges:
  - **DFN**(i) and **L**(i) are defined in the same way as in articulation points.
  - $\circ \ (i,j) \in E$  is a bridge of G iff  $\mathrm{L}(j) = \mathrm{DFN}(j)$  given  $\mathrm{DFN}(i) < \mathrm{DFN}(j)$

# 2017-05-25

- **Euler trails** & **Euler circuits**: A trail (circuit) is called an Euler trail (Euler circuit) of G iff it traverses each edge of G exactly once.
- Theorem: Let G=(V,E) be a connected undirected graph, where  $|V|\geq 1$ . Then,
  - $\circ$  **G** has an Euler trail, but not an Euler circuit, iff it has exactly two vertices of odd degrees.
  - *G* has an Euler circuit iff all vertices have even degrees.
- Theorem: Suppose that G=(V,E) is a directed graph, where |V|>1. Let  $d^{\mathrm{in}}$  and  $d^{\mathrm{out}}$  denote the indegree and outdegree of vertex i, respectively. Then, G has a u-to-v Euler trail iff the underlying graph of G is connected and either
  - $\circ u = v$  and  $d^{\text{in}} = d^{\text{out}}$  for every  $i \in V$ .
  - $\circ \ u 
    eq v$ ,  $d^{ ext{in}} = d^{ ext{out}}$  for every  $i \in V \{u,v\}$ ,  $d^{ ext{in}}_u = d^{ ext{out}}_u 1$ , and  $d^{ ext{in}}_u = d^{ ext{out}}_u + 1$ .
- Hamiltonian paths & Hamiltonian cycles: A path (cycle) is called a Hamiltonian path (cycle) of
   *G* iff it goes through each vertex (exclusive of the starting vertex and ending vertex) of *G* exactly once.
- Theorem: Suppose that G = (V, E) is a directed graph and between every two vertices u, v of G, there is one arc (either  $\langle u, v \rangle$  or  $\langle v, u \rangle$ ). Then, there exists a directed *Hamiltonian path* in G.
- ullet Theorem: Suppose that G=(V,E) is an undirected graph where |V|=n. Let  $d_i$  be the degree

of vertex  $v_i$ .

- $\circ$  If  $d_i+d_j\geq n-1$  for every  $(v_i,v_j)\not\in E$  and  $v_i
  eq v_j$ , then G has a Hamiltonian path.
- $\circ$  If  $d_i+d_j\geq n$  for every  $(v_i,v_j)\not\in E$  and  $v_i
  eq v_j$ , then G has a Hamiltonian cycle.
- Theorem: Suppose that G=(V,E) is an undirected graph where |V|=n. If for every  $1 \le i \le \lfloor (n-1)/2 \rfloor$ , G has fewer than i vertices with degrees at most i, then G has a Hamiltonian cycle. When n is odd, G has a Hamiltonian cycle, even if G has (n-1)/2 vertices of degrees (n-1)/2.
- Shortest paths: Dijkstra's algorithm.

# 2017-06-01

- Closure:
  - $\circ$  Transitive closure:  $A^+ = \sum_{i=1}^\infty A^i$
  - Reflexive transitive closure:  $A^+ = \sum_{i=0}^\infty A^i$  , where  $A^0$  is the identity.
  - A transitive relation implies *reachability*.
- **Planar graph**: A graph is **planar** iff it can be drawn so that no two edges cross. Such a drawing is called a **planar drawing**.
- Theorems: Let G = (V, E) be a connected planar graph, and r be the number of regions.
  - |V| |E| + r = 2
  - $|E| \le 3|V| 6$  if  $|E| \ge 2$
  - $\circ$  Every planar drawing of a connected planar graph G has the same number r=2-|V|+|E| of regions.
  - Suppose G has k connected components. Then, |V| |E| + r = k + 1.
- Contractible: *H* is contractible to *G* iff *G* can be obtained from *H* by a series of elementary contractions.
- **Homeomorphic**: two graphs are said to be **homeomorphic** if they can be obtained from the same graph by adding vertices onto some of its edges, or one can be obtained from the other by the same way.
- Theorems:
  - A graph G is planar iff no subgraph of G is contractible to  $K_{3,3}$  or  $K_5$ .
  - A graph G is planar iff no subgraph of G is homeomorphic to  $K_{3,3}$  or  $K_5$ .
- Matching:
  - $M \subseteq E$  is a **matching** in G = (V, E) if no two edges in M are incident on the same vertex.
  - **Maximal matching**: M is a **maximal matching** if there exists no matching M' with

- |M'| > |M| in **G**.
- Perfect matching: M is a perfect matching if  $|V| = 2 \times |M|$ .
- Complete matching: M is a complete matching iff  $|M| = \min\{|S|, |R|\}$  for a bipartite graph.
- Theorem: Suppose that  $G = (R \bigcup S, E)$  is a bipartite graph, where  $|R| \leq |S|$  is assumed. For any  $W \subseteq R$ , let ADJ(W) be the set of vertices adjacent to any vertex in W. Then, G has a complete matching iff  $|W| \leq |ADJ(W)|$  for every  $W \subseteq R$ .

# 2017-06-08

- Cliques, independent sets, vertex covers:
  - **Clique**: a set of vertices every two of which are adjacent.
  - **Independent set**: a set of vertices no two of which are adjacent.
  - **Vertex cover**: a set of vertices such that each edge in the graph is incident with at least one vertex in the set.
- Theorem: suppose that G = (V, E) is an undirected graph and  $V' \subseteq V$ . The following statements are equivalent:
  - V' is a clique of G.
  - $\circ$  V' is an independent set of  $ar{G}$ .
  - $\circ V V'$  is a vertex cover of  $\bar{G}$ .
- Maximum flow and minimum cut:
  - Transport network N = (V, E) has a pair of **source** node a and **sink** node z.
  - A **flow** is a function f from E to the set of nonnegative integers, satisfying
    - Capacity constraint:  $0 \le f(e) \le c(e)$  for each  $e \in E$
    - Conservation constraint:  $\psi^+(v) = \psi^-(v)$  for  $v \notin \{a, z\}$
  - The **total flow** (or **net flow**) of **f** is defined to be  $F = \psi^-(a) = \psi^+(z)$ .
  - The **maximum flow problem** is to determine f such that F is maximum.
  - Cut:  $E(S;S') \cup E(S';S)$  is called a cut (or a-z cut) of N, where  $S \subset V, S = V S, a \in S, z \in S'$ .
  - Capacity of the cut induced by  $S: c(S) = \sum_{e \in E(S:S')} c(e)$
  - **Minimum cut**:  $E(S; S') \cup E(S'; S)$  is a minimum cut if c(S) is minimum.
- Lemmas and theorems:
  - $\circ$  Conservation of flow: F=f(S,S')-f(S',S) for any  $S\subset V$  and  $a\in S$ .
  - If F = c(S) for some  $S \subset V$ , then F is maximum and c(S) is minimum.
  - $\circ F = c(S)$  iff (a) f(e) = c(e) for each  $e \in E(S; S')$ ; (b) f(e) = 0 for each  $e \in E(S'; S)$ .

### • Ford & Fulkerson's algorithm

- Augmenting path: a path in N is an augmenting path if its each forward edge is unsaturated and its each backward edge e has f(e) > 0.
- The maximal increment of flow by an augmenting a-to-z path P is equal to

 $\Delta_P = \min\{\min\{c(e) - f(e)|e \text{ is a forward edge}\}, \min\{f(e)|e \text{ is a backward edge}\}\}.$ 

- $\text{o The updated flow } f^+(e) = \left\{ \begin{array}{l} f(e) + \Delta_P, \text{ if e is a forward edge} \\ f(e) \Delta_P, \text{ if e is a backward edge} \\ f(e), \text{ if e is not an edge of P} \end{array} \right.$
- F is maximum iff there is no augmenting a-to-z path in N.
- The capacities must be rational numbers; otherwise, Ford & Fulkerson's algorithm may cause an infinite sequence of flow augmentations, and the flow finally converges to a value that is 1/4 of the maximum total flow.
- Ford & Fulkerson's algorithm takes exponential time in the worst case.

### • Edmonds & Karp's algorithm:

- Overcomes the two flaws of Ford & Fulkerson's algorithm.
- Uses BFS to find shortest augmenting paths iteratively.

#### Coloring:

- A proper coloring of a graph *G* is an assignment of colors to the vertices of *G* so that no
  two adjacent vertices are assigned with the same color.
- The **chromatic number** of G, denoted by  $\chi(G)$ , is the smallest number of colors needed to properly color G.
- A graph is k-colorable iff it can be properly colored with k colors.

#### • Properties and theorems:

- $\circ \ \chi(K_n) = n$
- An undirected graph G is 2-colorable (i.e., bipartite) iff G has no cycle of odd length.