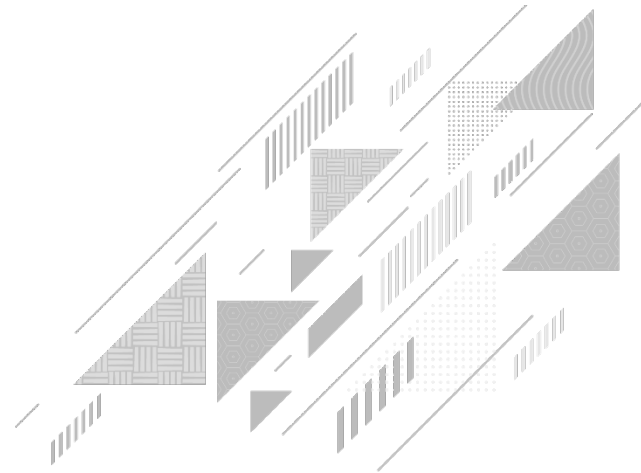


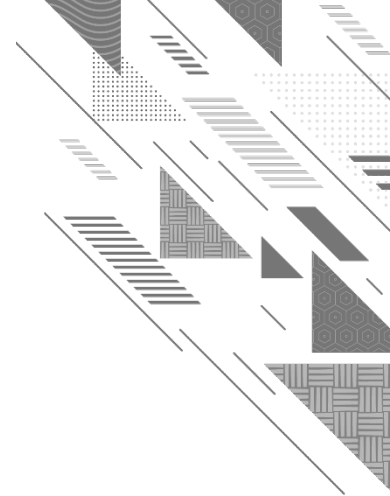
8085 Microprocessor





Topics to be covered

- Introduction
- 8085 Programming Model
- Bus Organization of 8085
- 8085 pin diagram
- 8085 Architecture/Block Diagram



Introduction



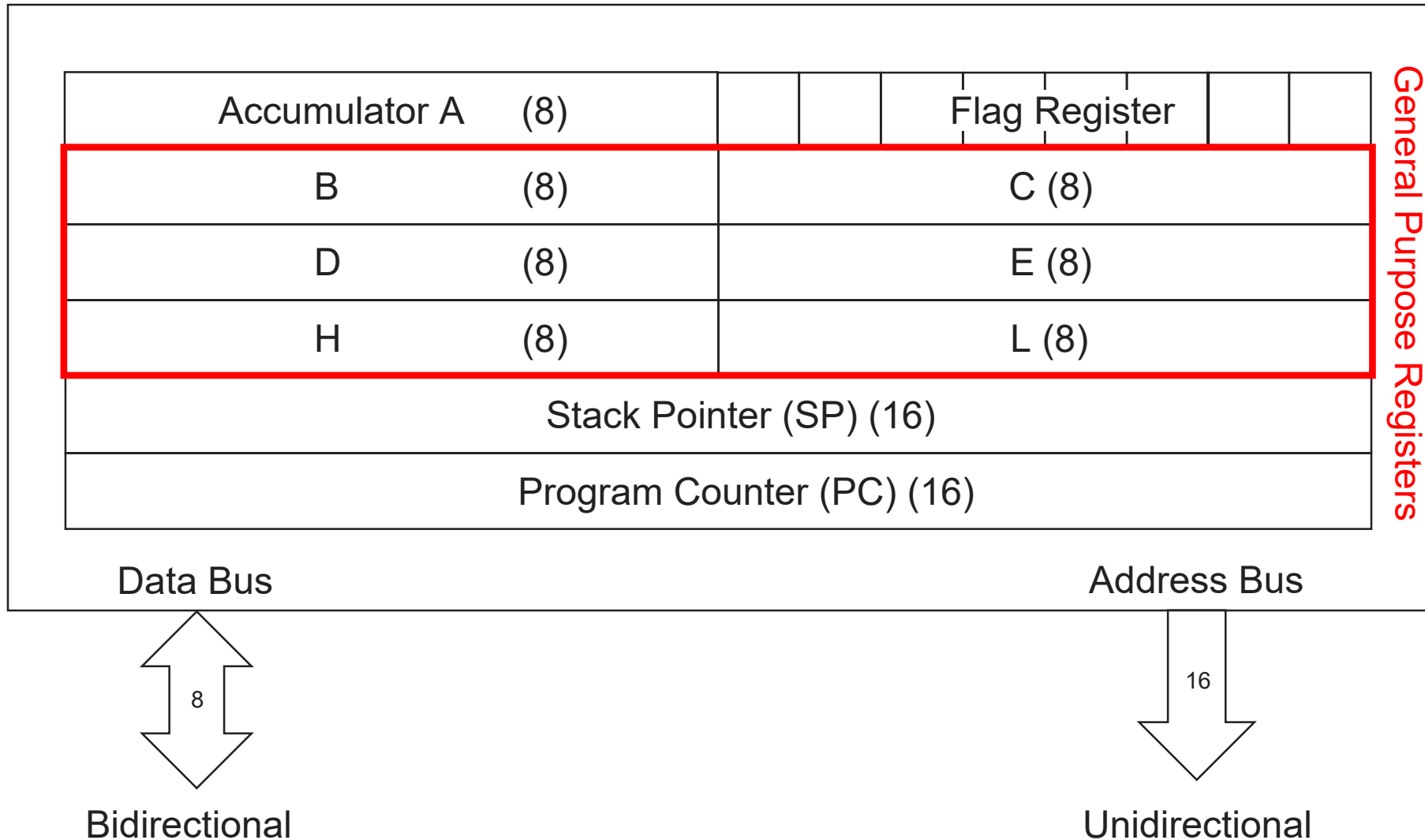
Introduction

- ▶ 8085 is pronounced as "eighty-eighty-five" microprocessor
- ▶ It is an 8-bit microprocessor designed by Intel in 1977 using NMOS technology
- ▶ 8 bit General purpose microprocessor (i.e. 8 bit databus)
- ▶ It is a single chip NMOS device with 40 pins.
- ▶ It has multiplexed address and databus ($AD_0 - AD_7$).
- ▶ It works on 5-Volt DC power supply
- ▶ The maximum clock frequency is 3MHz while minimum frequency is 500kHz
- ▶ It provides 16 address lines, therefore capable of addressing $2^{16} = 64K$ of memory
- ▶ It supports external interrupt request
- ▶ It has two 16 bit registers named program counters (PC) and stack pointer (SP)
- ▶ It generates 8 bit I/O address so it can access $2^8 = 256$ input ports.
- ▶ It provides 5 hardware interrupts

8085 Programming Model



8085 Programming Model

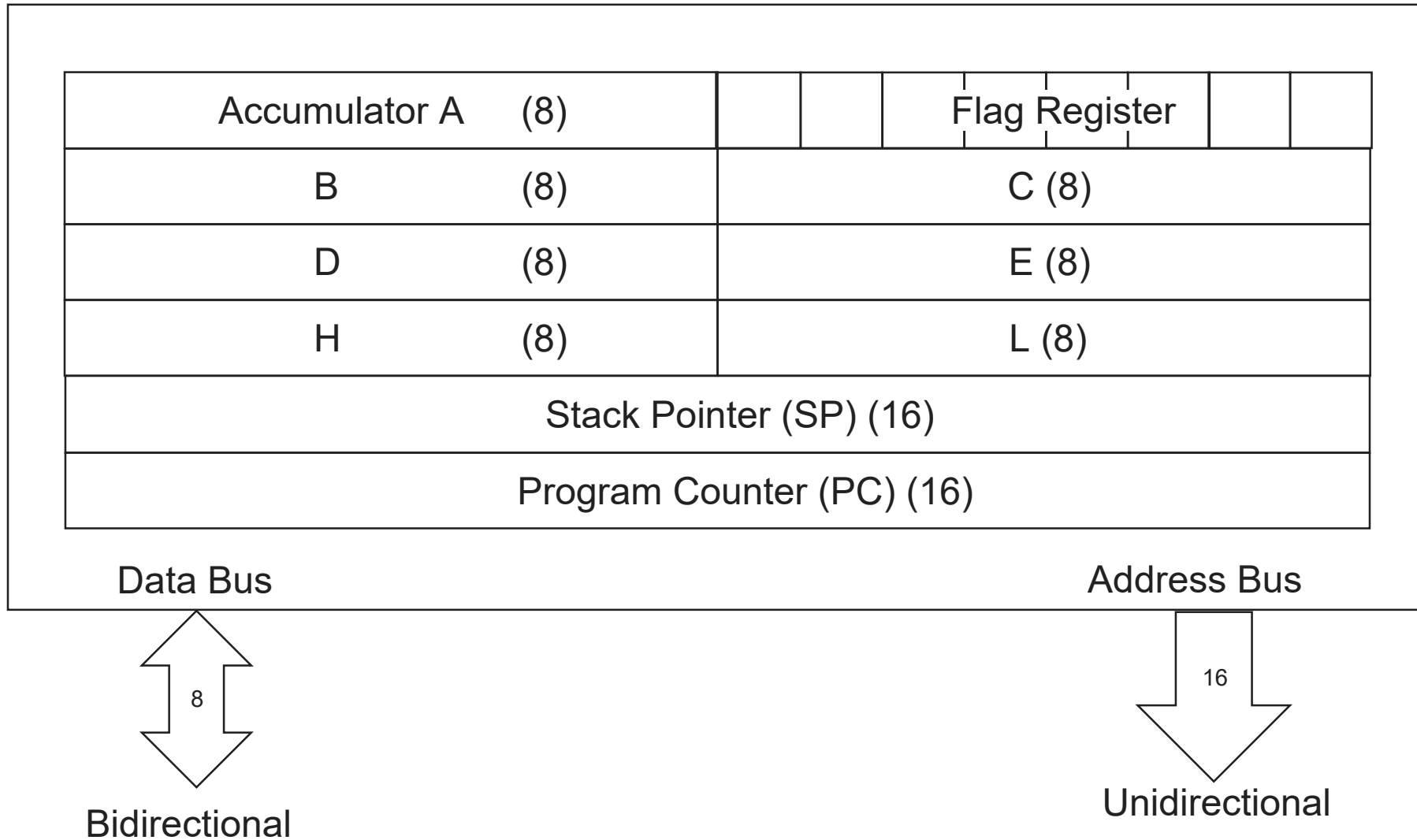


General Purpose Registers

- ▶ 6 general purpose registers to store 8-bit data B, C, D, E, H & L.
- ▶ Can be combined as fixed register pairs – BC, DE, HL to perform 16 bit operations
- ▶ Used to store or copy data using data copy instructions

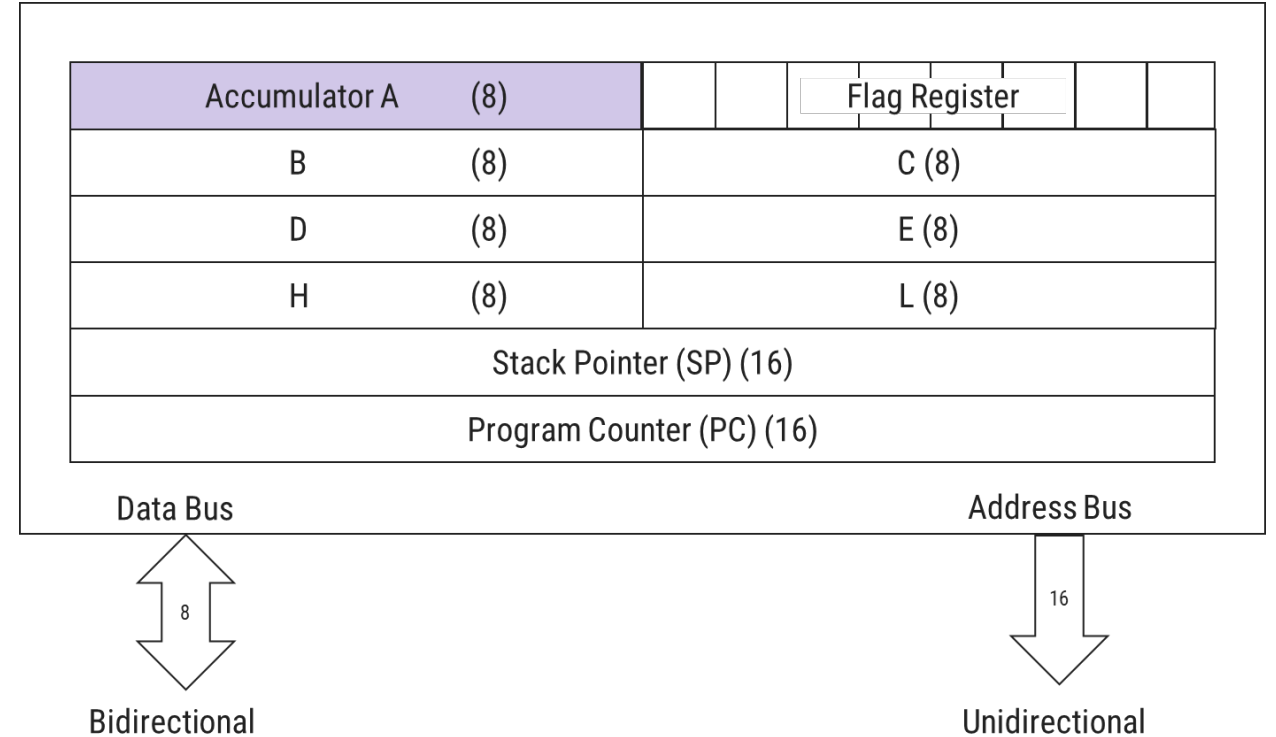
B (8)	C (8)
D (8)	E (8)
H (8)	L (8)

8085 Programming Model

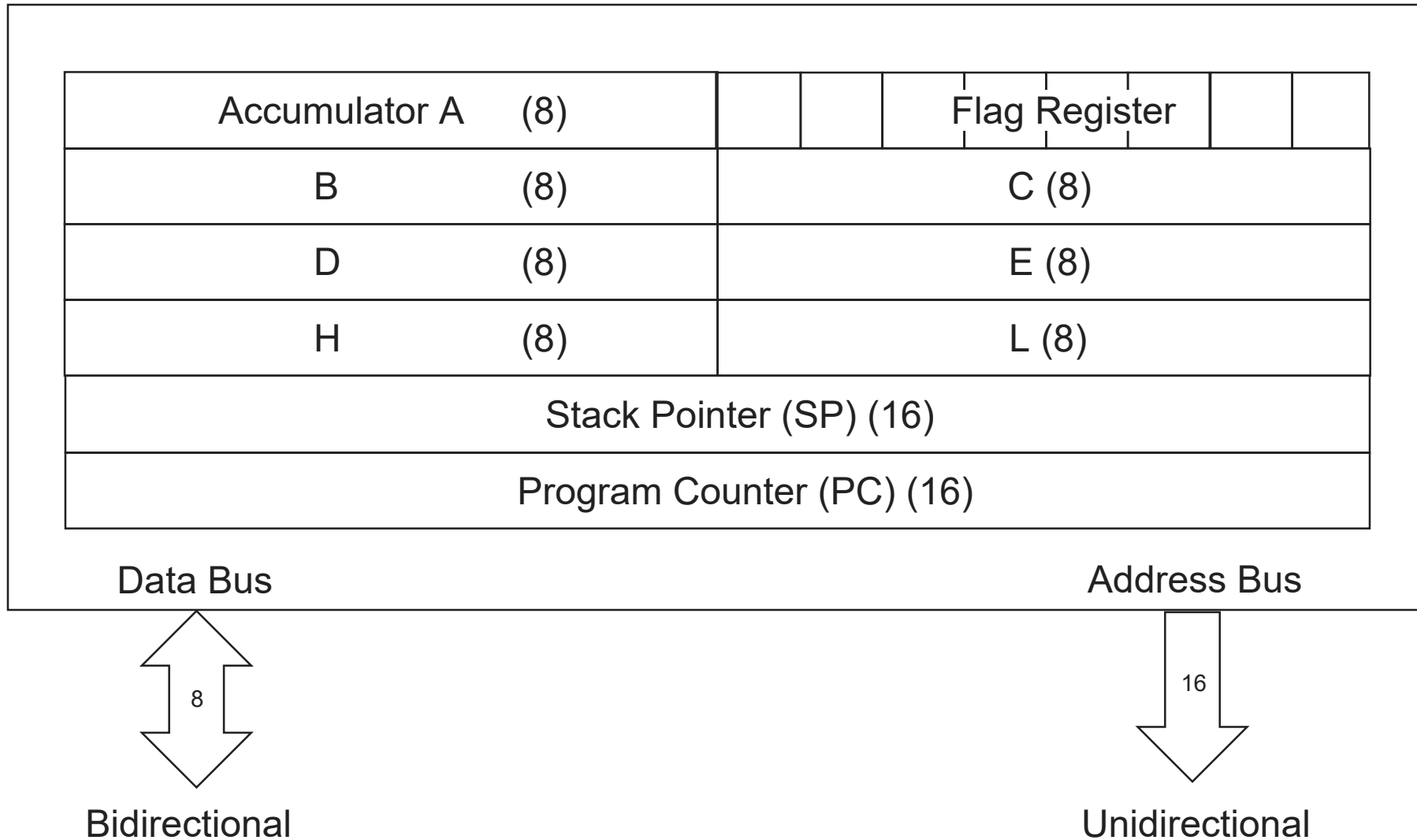


Accumulator

- ▶ 8 - bit register, identified as **A**
- ▶ Part of ALU
- ▶ Used to store 8-bit data to perform **arithmetic & logical** operations
- ▶ Result of operation is stored in **Accumulator**



8085 Programming Model



Flag Register

D ₇	D ₆	D ₅	D ₄	D ₃	D ₂	D ₁	D ₀
S	Z	X	AC	X	P	X	CY

X:Undefined

S-Sign Flag

Set (1) if 7th bit of result is 1;
otherwise reset (0)

1 0 1 0 1 0 1 0
S = 1

Z-Zero Flag

Set (1) when result is zero;
otherwise reset(0)

1 0 1 0
- 1 0 1 0

0 0 0 0
Z = 1

P-Parity Flag

Set (1) if result has even no. of 1's &
Reset (0) if result has odd no. of 1's

AC-Auxiliary Carry Flag

Set (1) when carry bit is
generated by 3rd bit &
passed to bit 4th bit.

1 1 1
0 0 1 0 1 0 1 0
+ 0 1 1 0 1 0 0 1

1 0 0 1 0 0 1 1
AC = 1

CY-Carry Flag

Set (1) if arithmetic
operation results in
carry;
otherwise reset(0)

1 1 1
1 0 1 0 1 0 1 0
+ 0 1 1 0 1 0 0 1

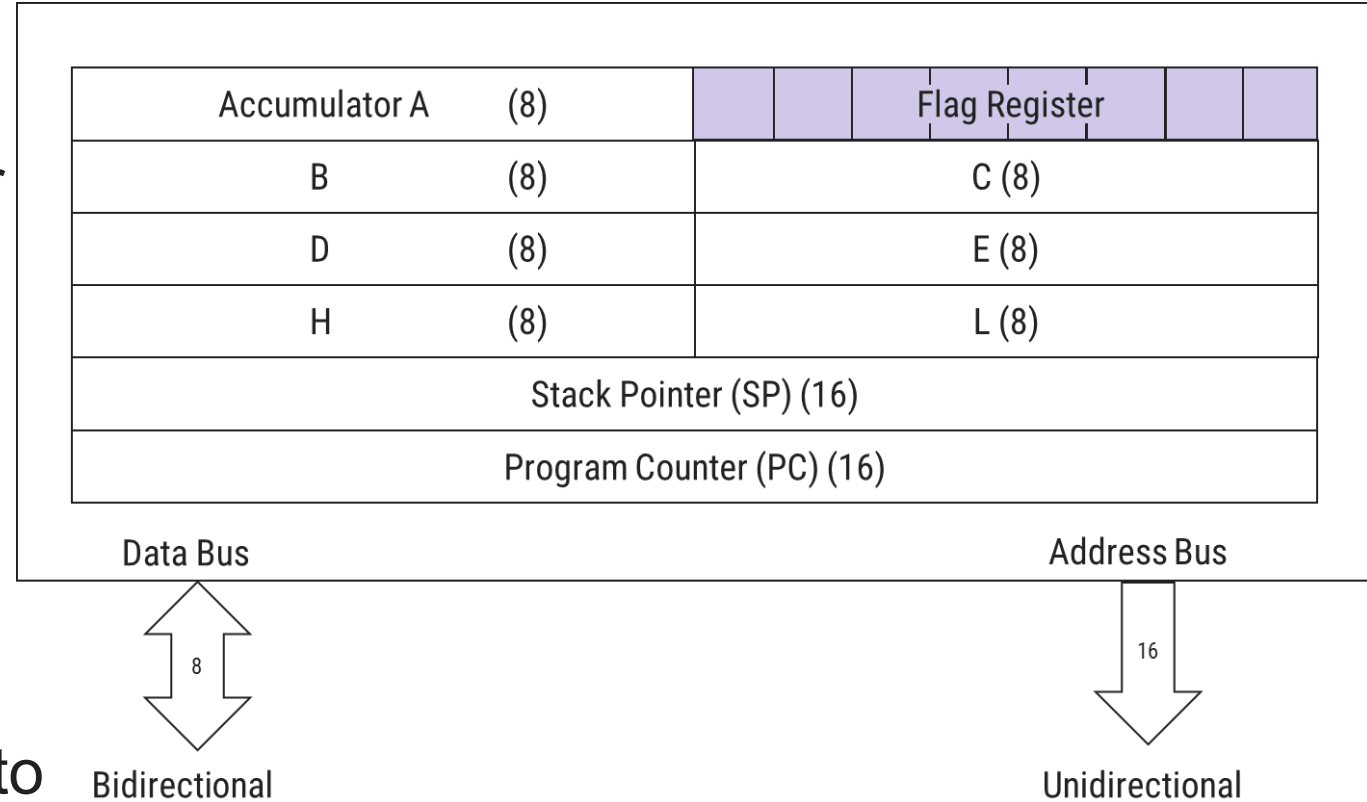
1 0 0 0 1 0 1 1
CY = 1

Flag Register

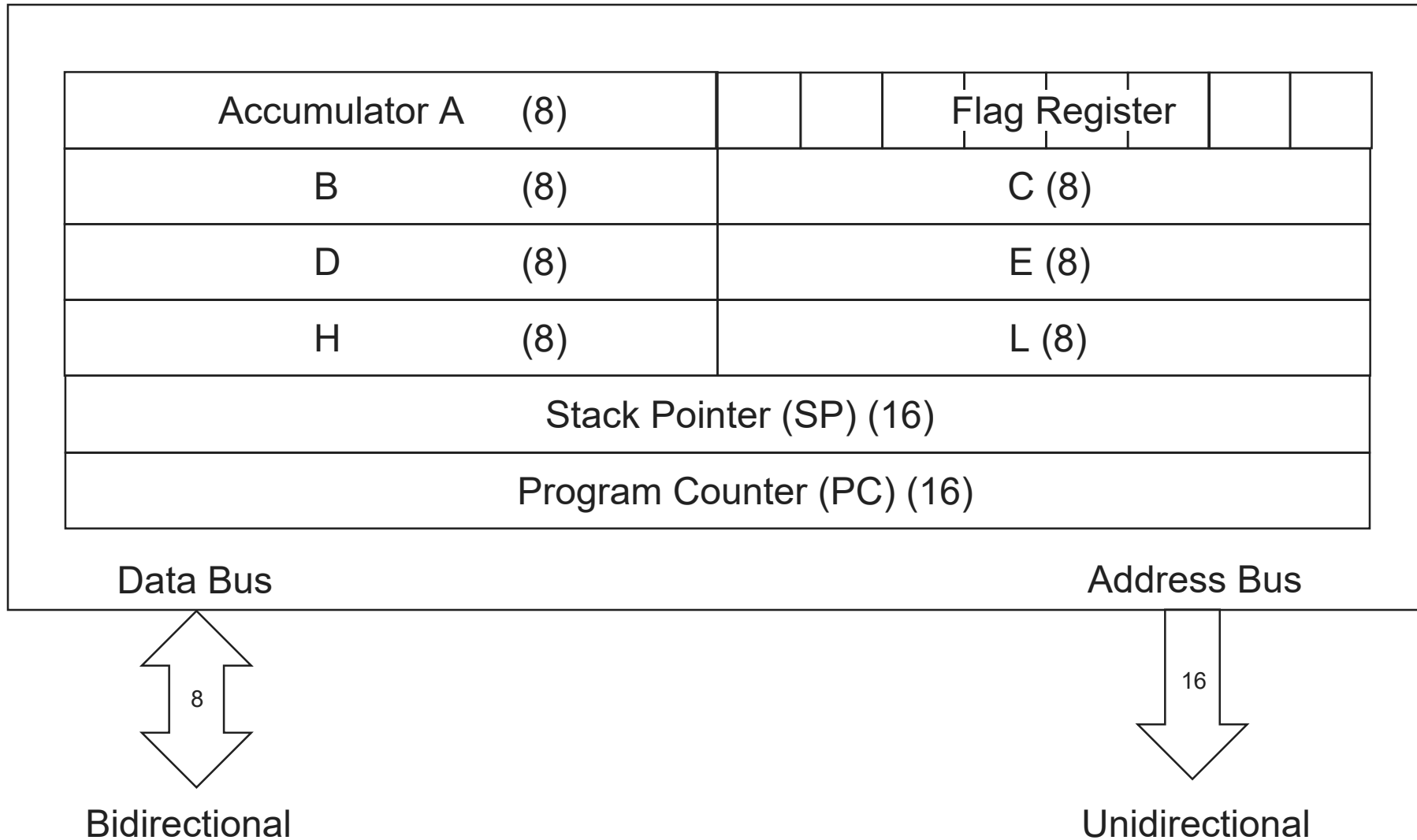
- ▶ ALU has 5 Flag Register that set/reset after an operation according to data conditions of the result in accumulator & other registers
- ▶ Helpful in decision making process of microprocessor
- ▶ Conditions are tested through software instructions

For e.g.

JC (Jump On Carry) is implemented to change the sequence of program when **CY** (Carry Flag) is set (1).



8085 Programming Model



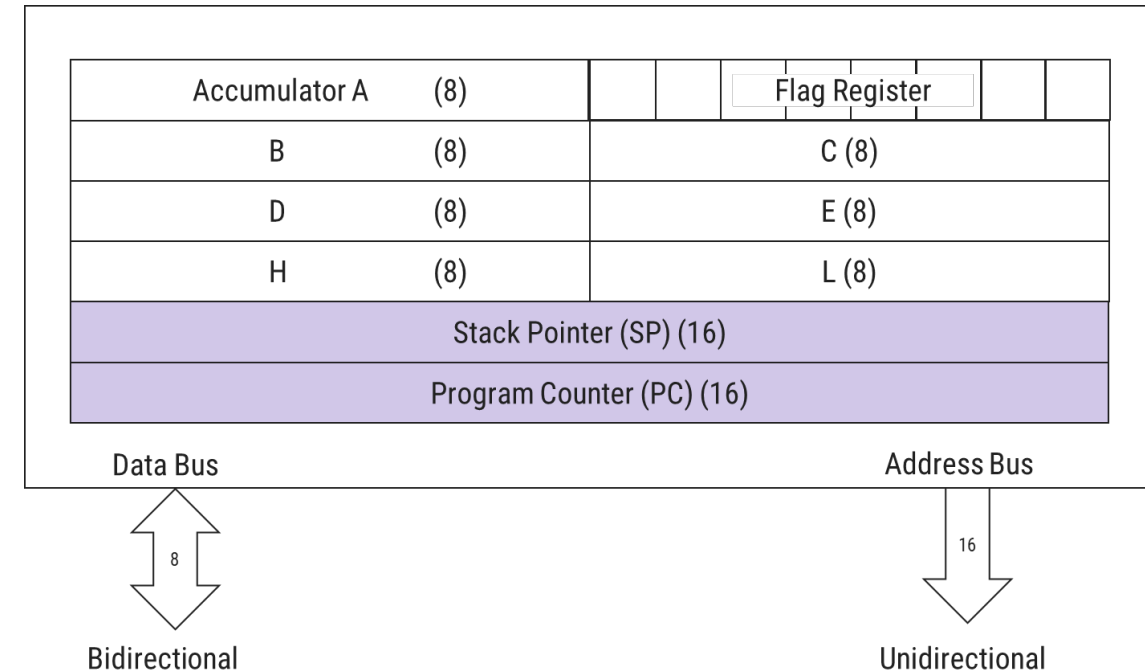
Stack Pointer & Program Counter

StackPointer(SP)

- ▶ Used as **memory pointer**
- ▶ Points to the memory location in R/W memory, called **Stack**
- ▶ Beginning of stack is defined by loading a 16-bit address in the stack pointer

ProgramCounter(PC)

- ▶ Microprocessor uses PC register to **sequence** the execution of instructions
- ▶ Its function is to point to memory address from which **next byte is to be fetched**
- ▶ When a byte is being fetched, PC is **incremented** by **1** to point to next memory location

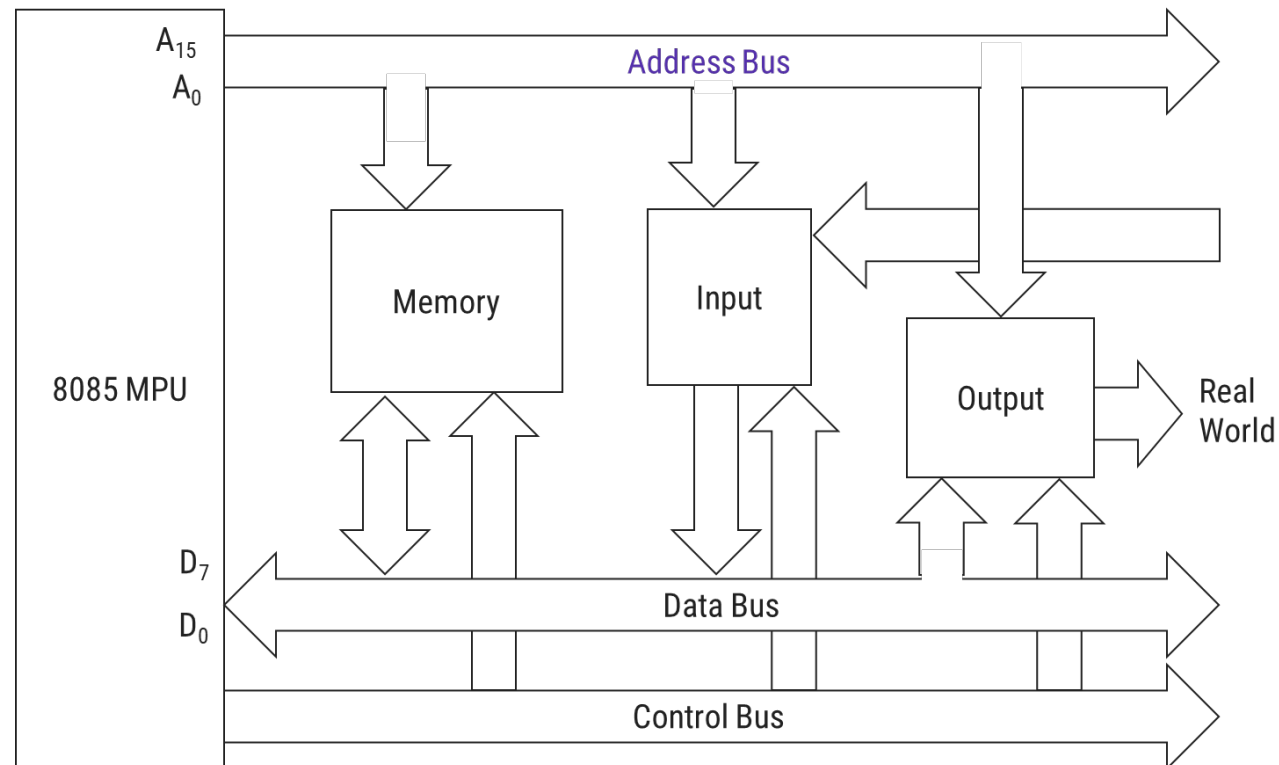


Bus Organization of 8085



Address bus

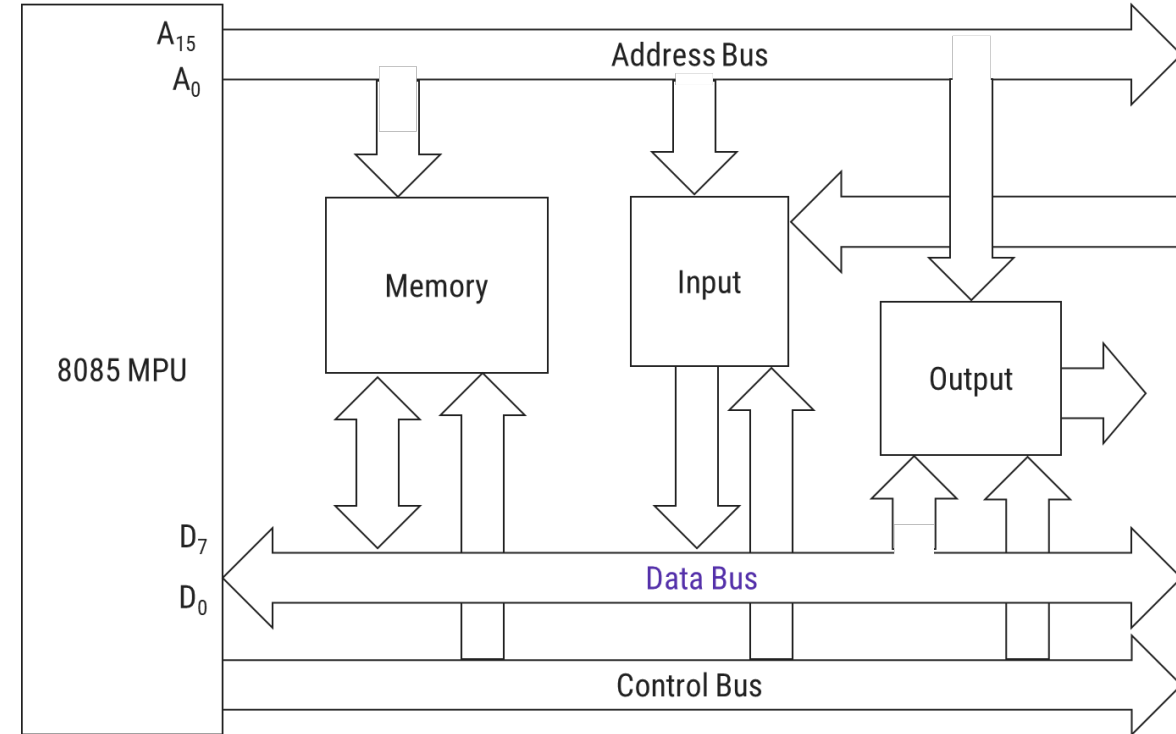
- ▶ Group of 16 **unidirectional** lines generally identified as A_0 to A_{15} .
i.e. bits flow from microprocessor to peripheral devices
- ▶ 16 address lines are capable of addressing **65536** memory locations. So, 8085 has **64K** memory locations





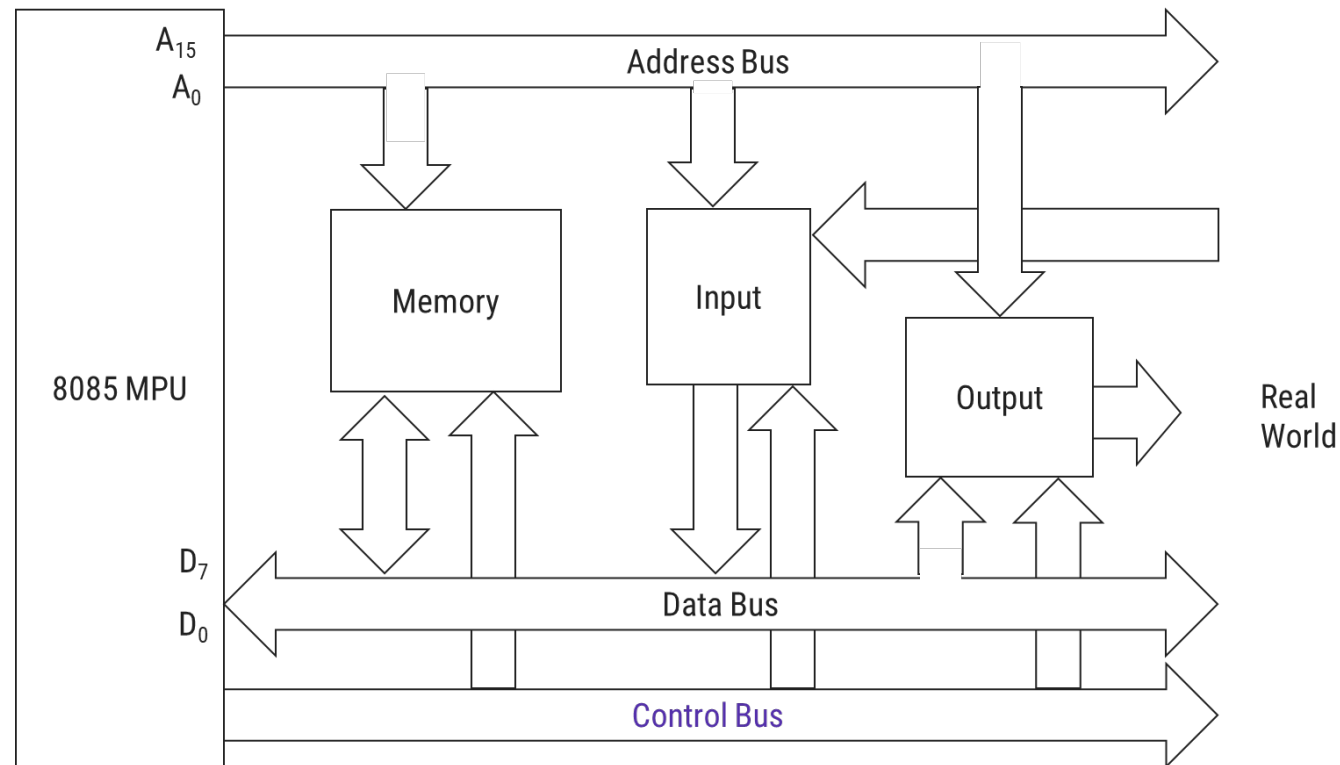
Data bus

- ▶ Group of 8 lines identified as D_0 to D_7 .
- ▶ They are bidirectional i.e. data flow in both directions between microprocessor, memory & peripheral
- ▶ 8 data lines enable microprocessor to manipulate data ranging from 00 H to FF H ($2^8=256$ numbers.)
- ▶ Largest number appear on data bus is 1111
 $1111 \Rightarrow (255)_{10}$.
- ▶ As Data bus is of 8-bit, 8085 is known as 8-bit Microprocessor

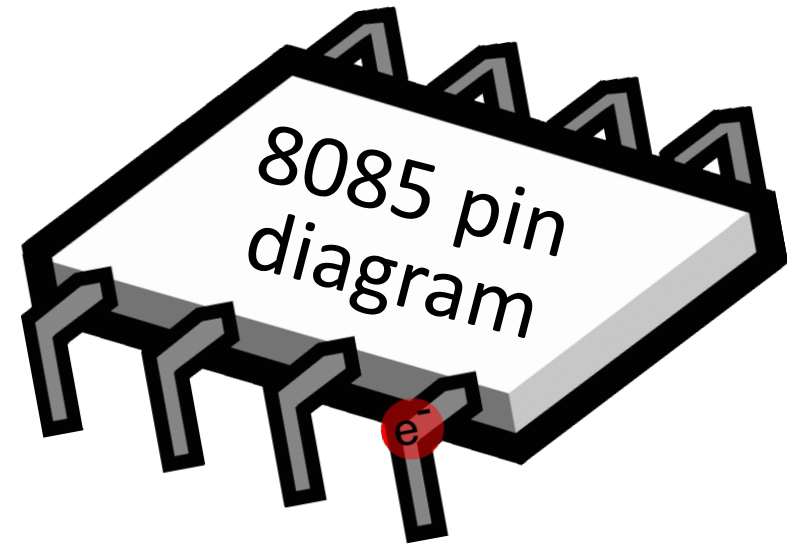


Control bus

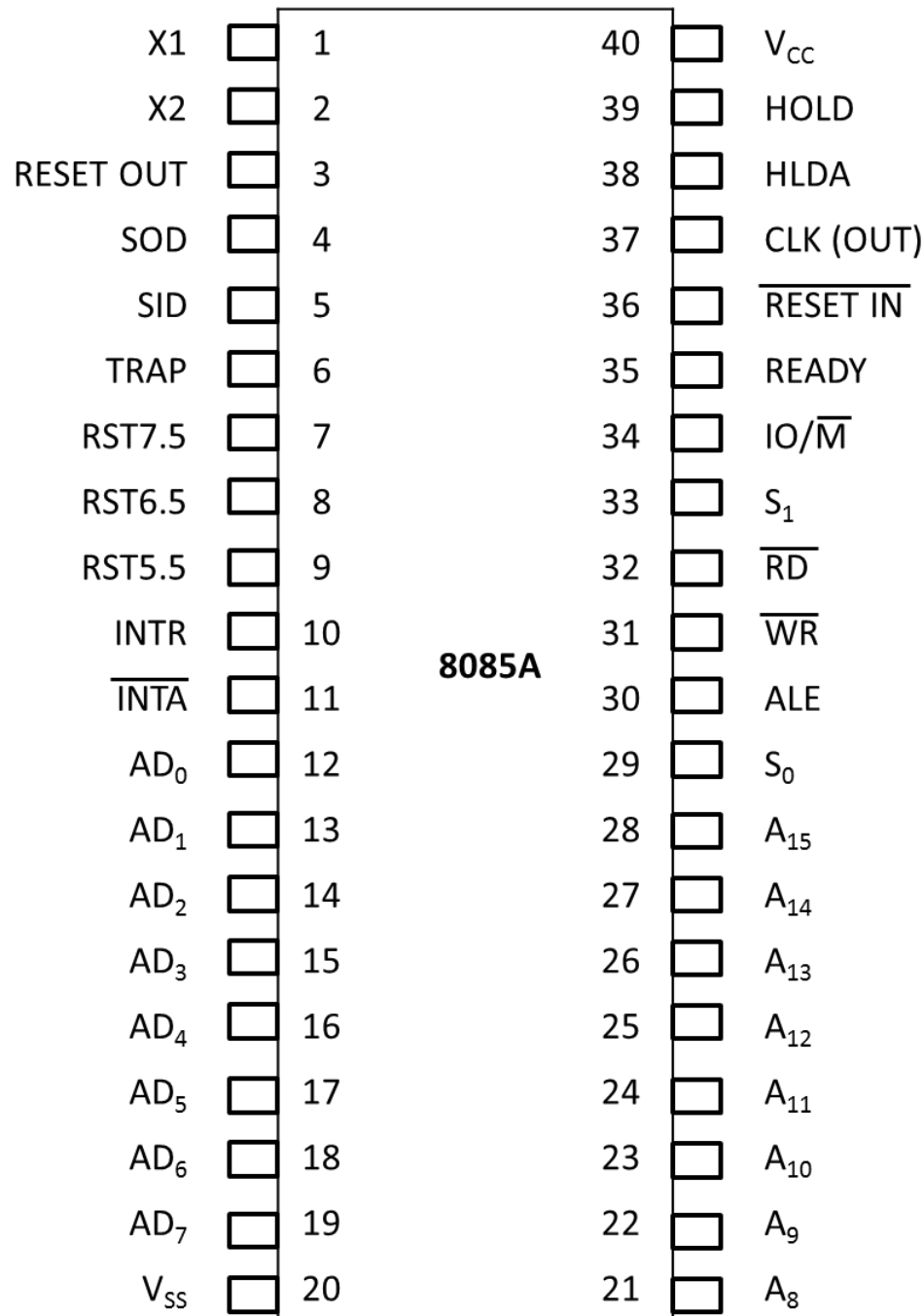
- ▶ It comprises of various single lines that carry **synchronization, timing & control signals**
- ▶ These signals are used to identify a device type with which MPU intend to communicate
- ▶ Some control signals are **Read Write** and **Opcode fetch** etc.



8085 pin diagram



8085 pin diagram

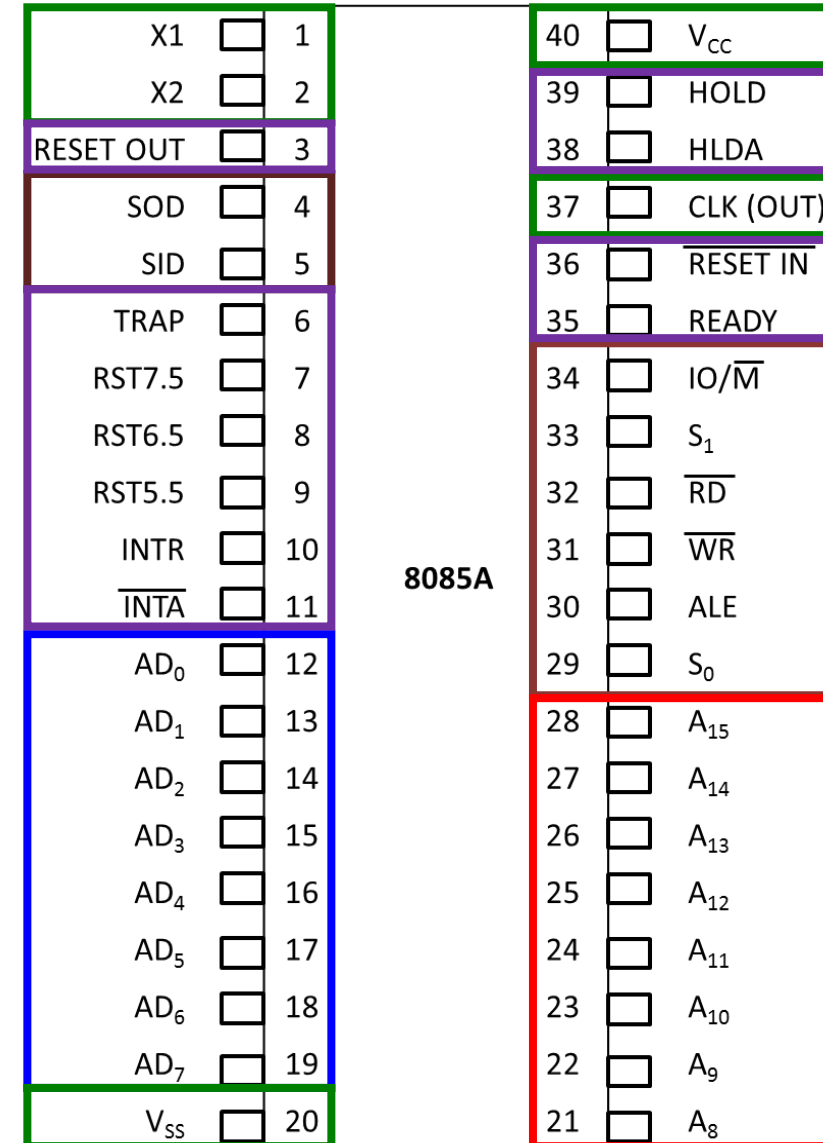


- 8-bit general purpose microprocessor.
- Capable of addressing 64K of memory.
- It has 40 pins.
- Requires +5V single power supply.

8085 pin diagram

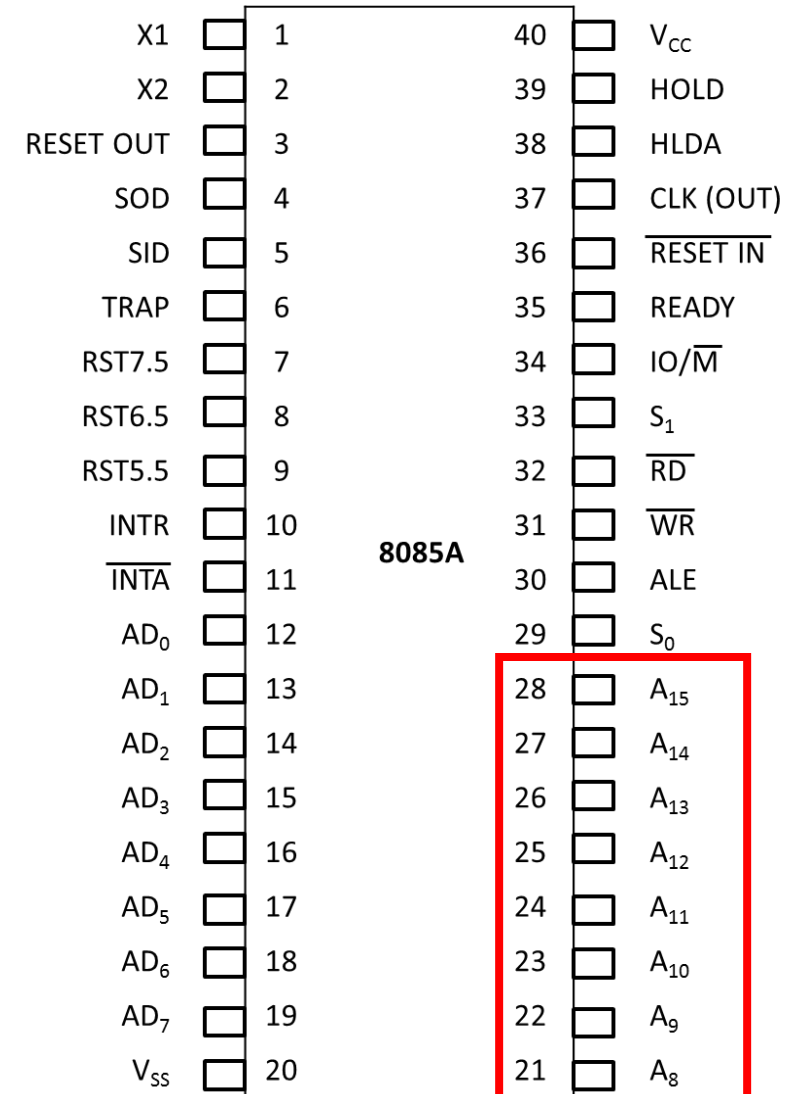
Signals are classified into 6 groups

1. Address bus
2. Multiplexed address/data bus
3. Control & status signals
4. Power supply & frequency signals
5. Externally initiated signals
6. Serial I/O ports



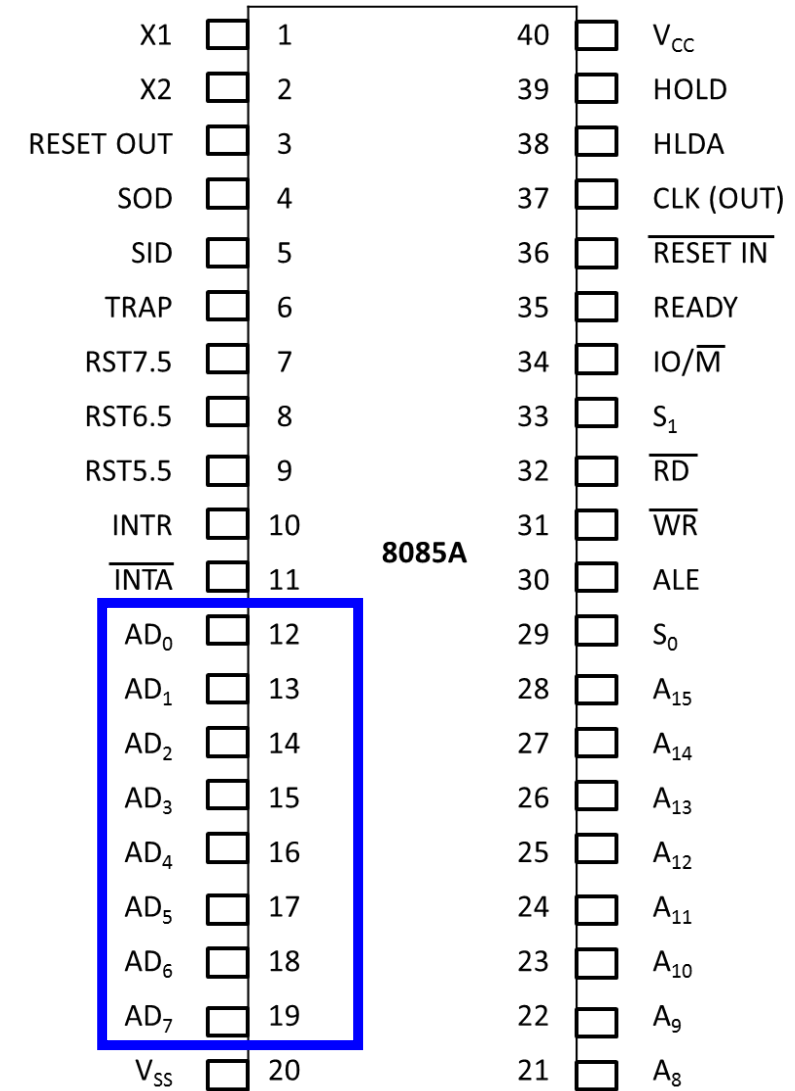
8085 pin diagram: Address Bus

- ▶ 16 signal lines are used as address bus
- ▶ However these lines are split into two segments $A_{15}-A_8$ and AD_7-AD_0
- ▶ $A_{15}-A_8$ are unidirectional and used to carry high-order address of 16-bit address
- ▶ AD_7-AD_0 are used for dual purpose



8085 pin diagram: Multiplexed Address/Data Bus

- ▶ Signal lines AD_7-AD_0 are bidirectional and serve dual purpose
- ▶ They are used as **low-order address bus** as well as **data bus**.
- ▶ The low-order address bus can be separate from these signals by using a latch (**ALE**).



8085 pin diagram: Control & Status Signals

To identify nature of operation

► Two Control Signals

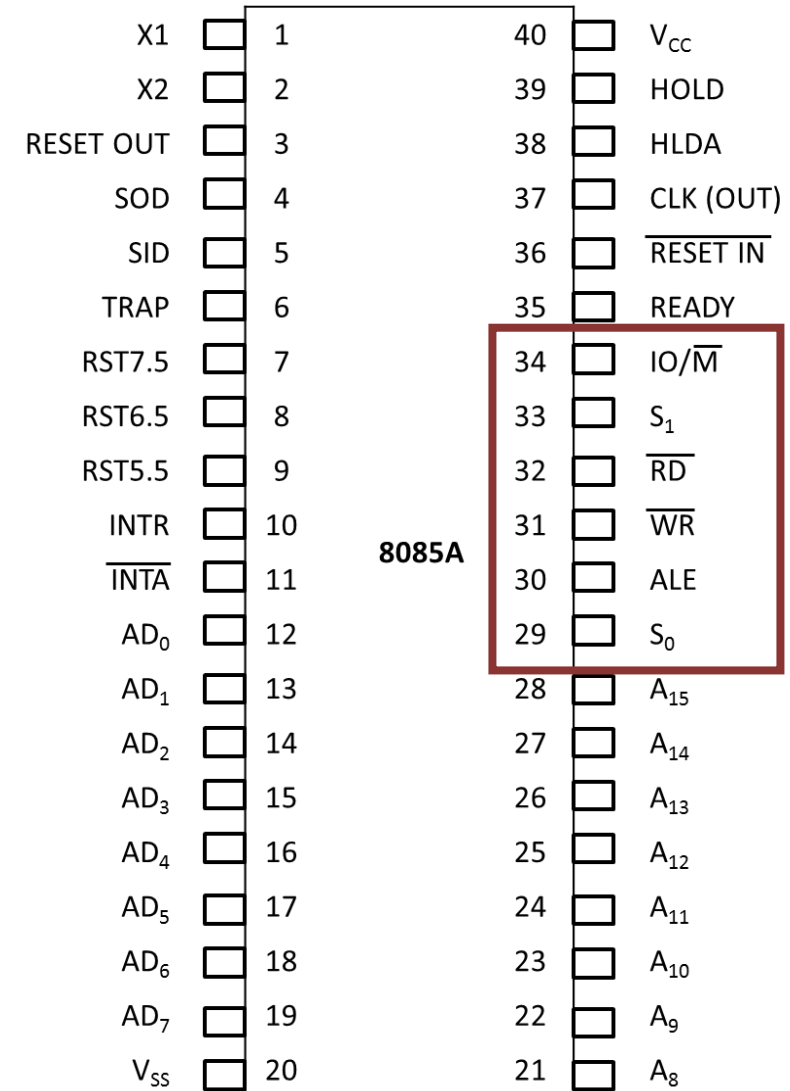
1. \overline{RD} (Read)
2. \overline{WR} (Write)

► Three Status Signals

1. S_1
2. S_0
3. IO/\overline{M}

► To indicate beginning of operation

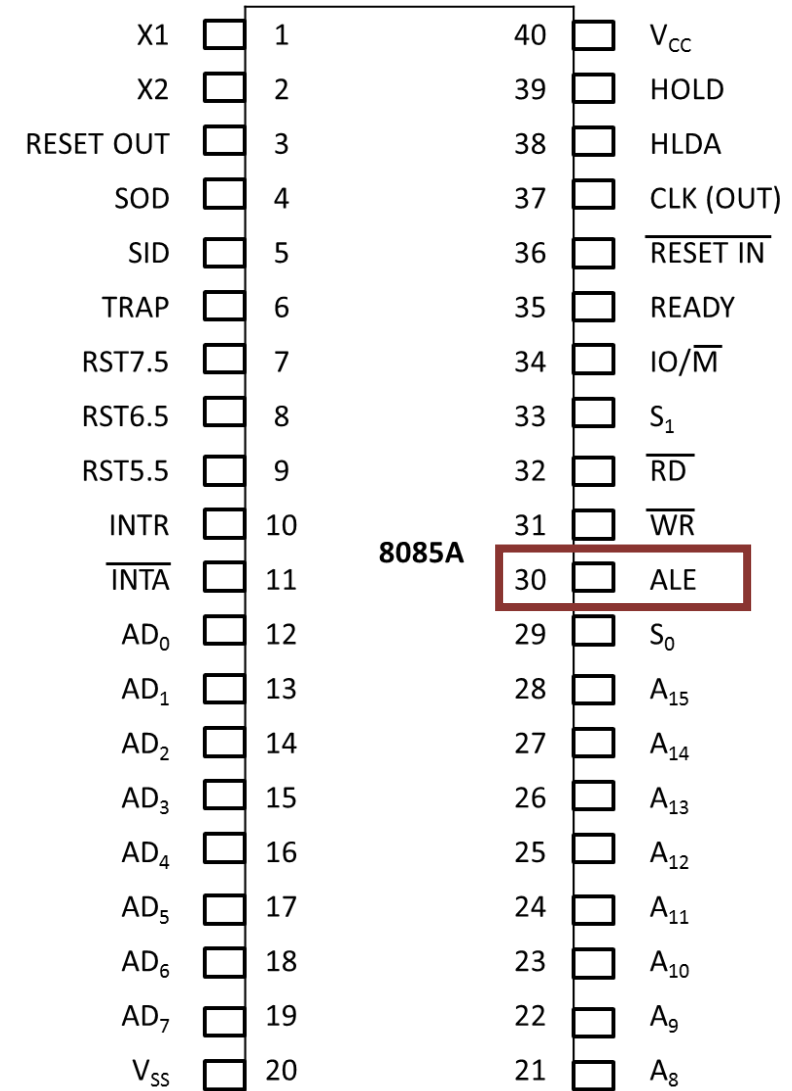
1. ALE (Address Latch Enable)
ALE \leftarrow 1, then Address bus
ALE \leftarrow 0, then Data bus



8085 pin diagram: Control & Status Signals

ALE Pin 30

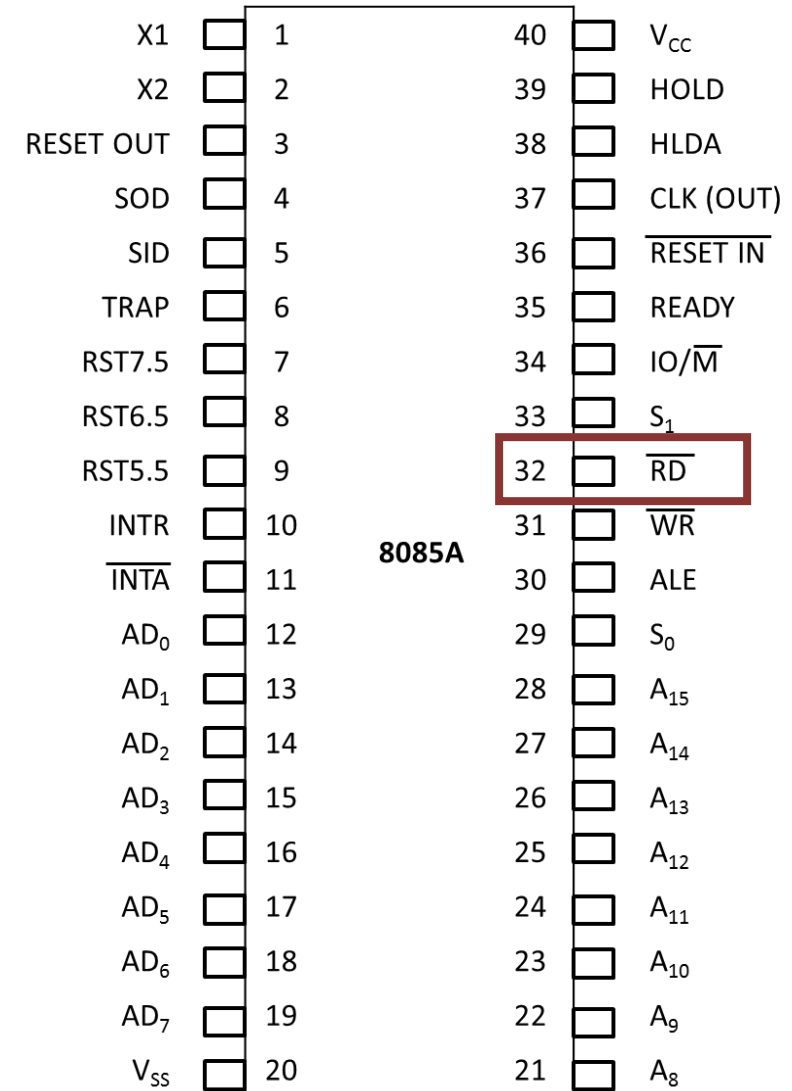
- ▶ This is positive going pulse generated everytime the 8085 begins an operation (machine cycle)
- ▶ It indicates that the bits on AD_7-AD_0 are address bits.
- ▶ This signal is used primarily to latch the low-address from multiplexed bus & generate a separate set of address lines A_7-A_0 .



8085 pin diagram: Control & Status Signals

\overline{RD} (Read) Pin 32

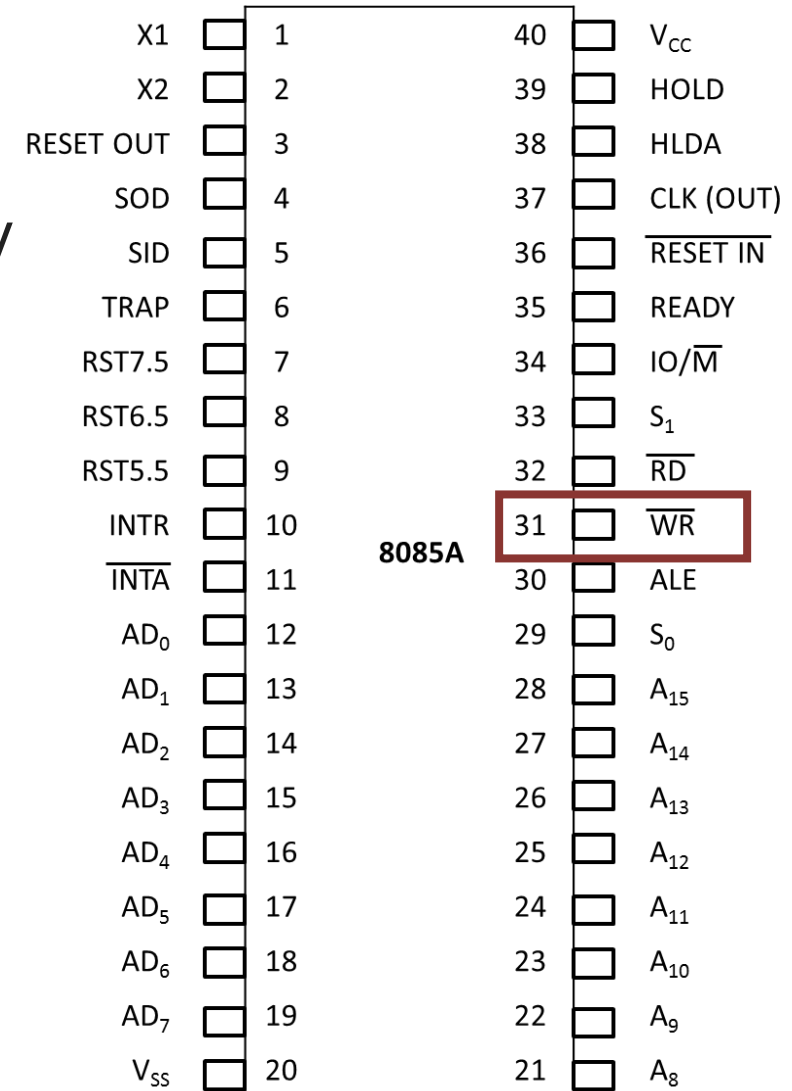
- ▶ This is a read control signal (active low)
- ▶ This signal indicates that the selected I/O or Memory device is to be **read** & data is available on data bus.



8085 pin diagram: Control & Status Signals

WR(Write) Pin 31

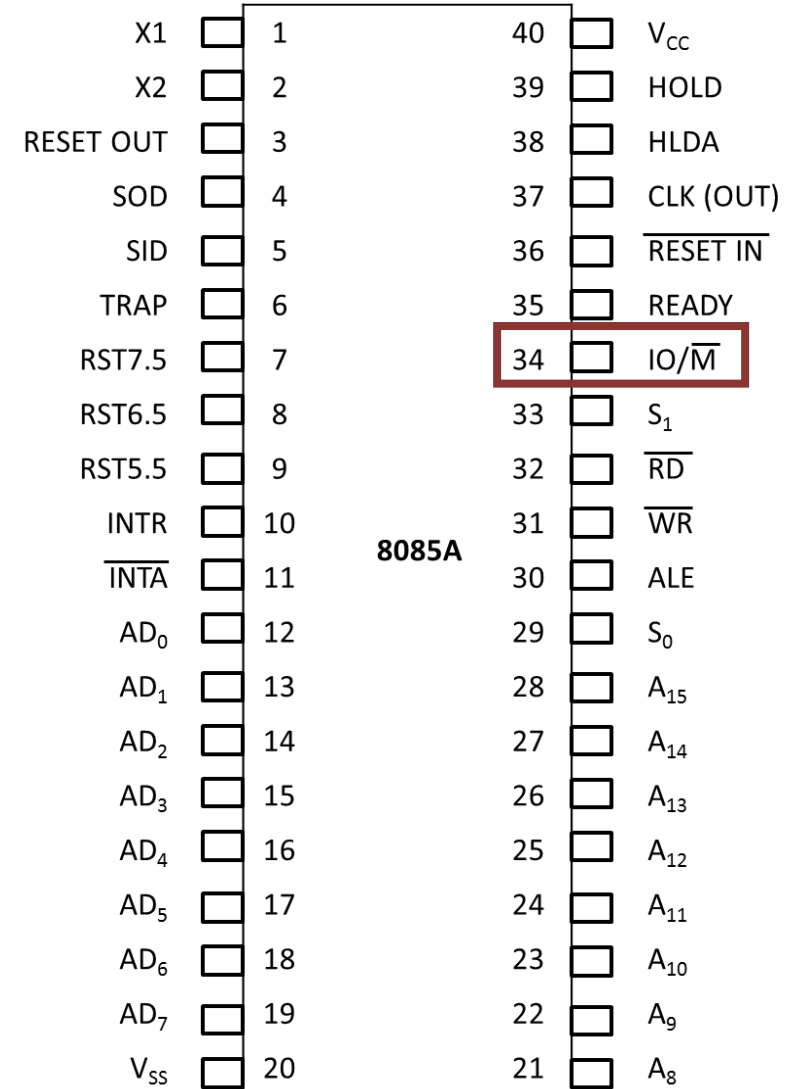
- ▶ This is a write control signal (active low)
- ▶ This signal indicates that the selected I/O or Memory device is to be **write** & data is available on data bus.



8085 pin diagram: Control & Status Signals

$\overline{\text{IO/M}}$ Pin 34

- ▶ This is a status signal used to differentiate **I/O** and **memory operation**
- ▶ When signal is
 - high \rightarrow I/O operation
 - low \rightarrow Memory operation
- ▶ This signal is combined with $\overline{\text{RD}}$ and $\overline{\text{WR}}$ to generate **I/O & memory control signals**.

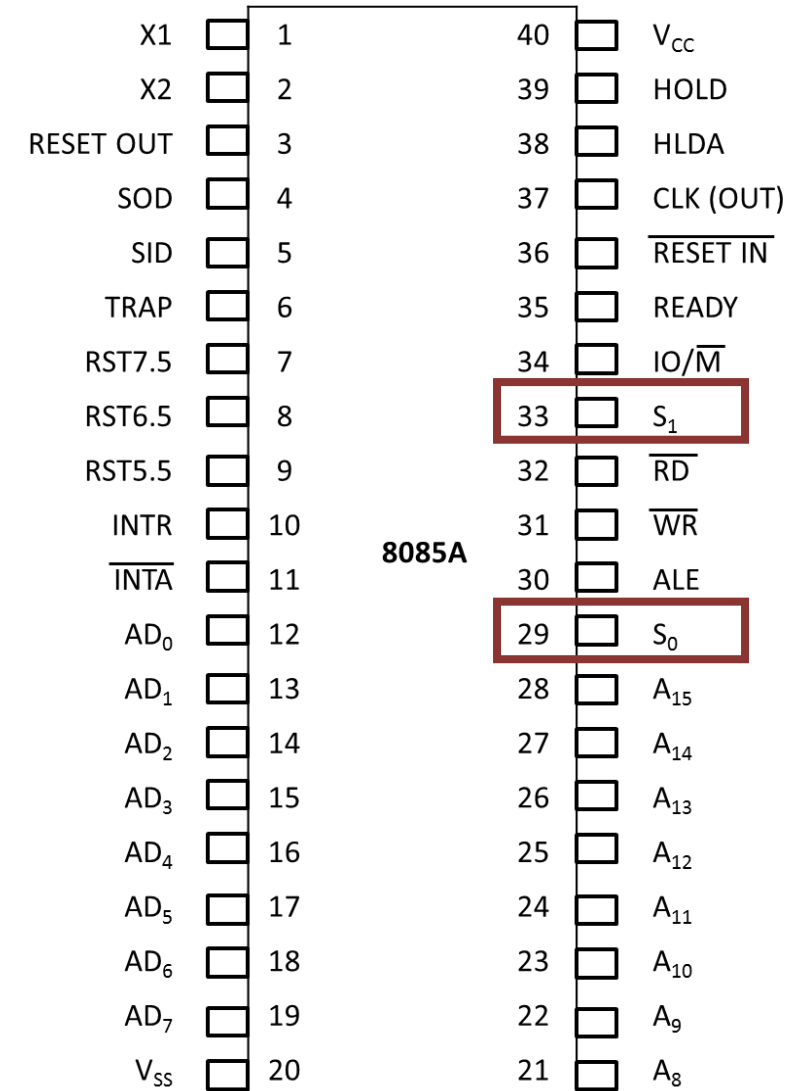


8085 pin diagram: Control & Status Signals

S_1 (Pin33) & S_0 (Pin29)

- These status signals can identify various operations

S_1	S_0	Mode
0	0	HLT
0	1	WRITE
1	0	READ
1	1	OPCODE FETCH

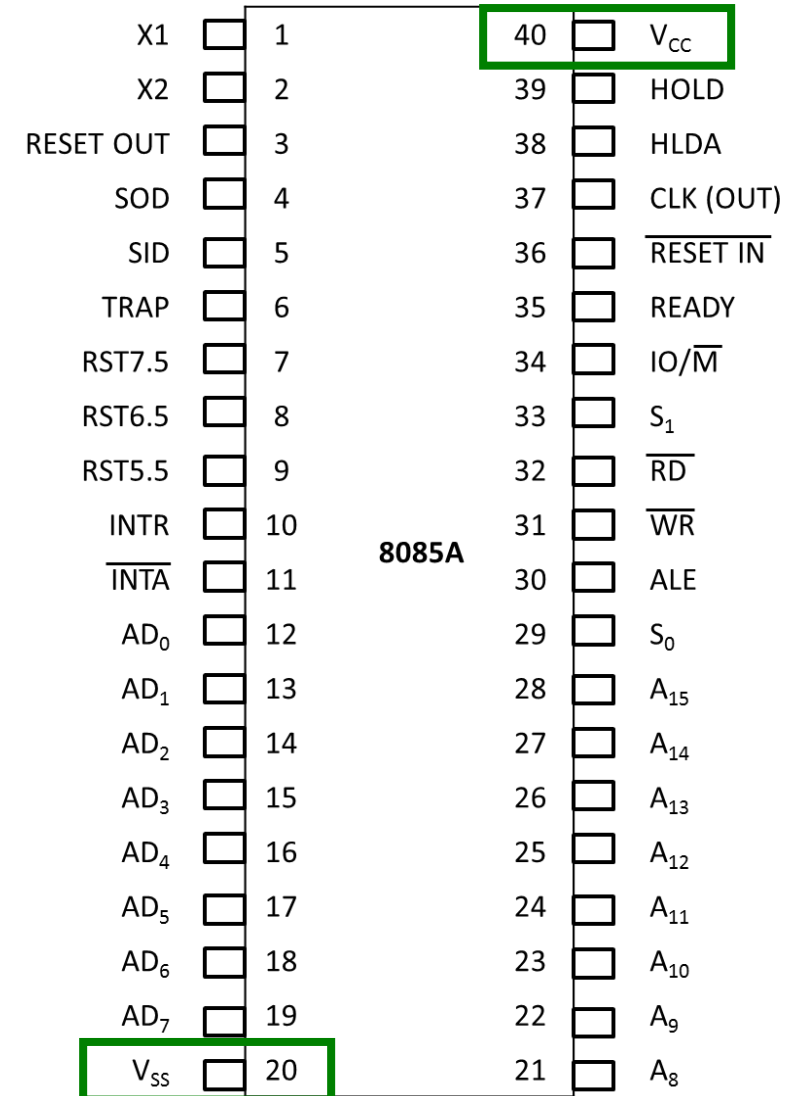


8085 pin diagram

$\overline{IO/\overline{M}}$	\overline{RD}	\overline{WR}	Operation
0	0	0	HLT
0	0	1	\overline{MEMR}
0	1	0	\overline{MEMW}
0	1	1	Opcode Fetch
1	0	0	HLT
1	0	1	\overline{IOR}
1	1	0	\overline{IOW}
1	1	1	NOP

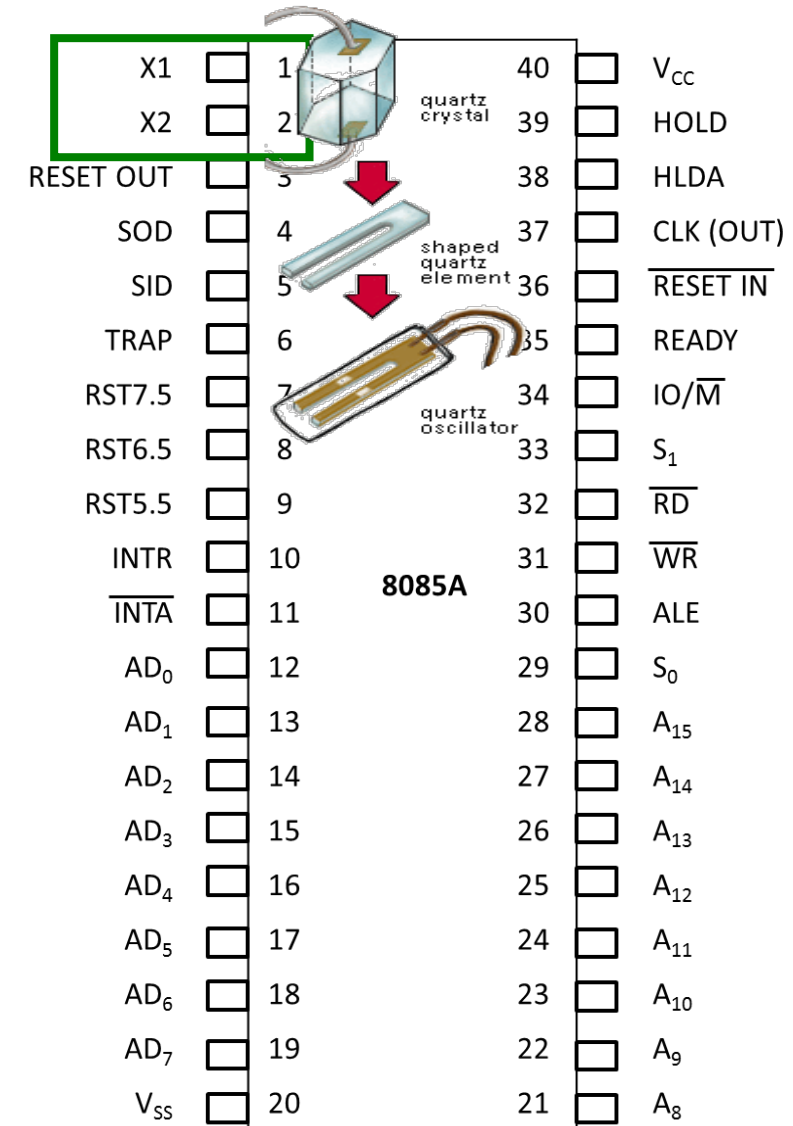
8085 Pin Diagram: Power Supply & Frequency Signal

- ▶ V_{cc} → Pin40, +5V Supply
- ▶ V_{ss} → Pin20, GroundReference



8085 Pin Diagram: Power Supply & Frequency Signal

- ▶ **X1, X2** → Pin 1 & 2, Crystal Oscillator is connected at these two pins
- ▶ The frequency is internally divided by two;
therefore to operate a system at **3MHz**, the crystal should have a frequency of **6MHz**



8085 Pin Diagram: Power Supply & Frequency Signal

- ▶ CLK(OUT) → Clockoutput
- ▶ Pin 37: This signal is used as **system clock** for other **I/O devices** for **synchronization** with **Microprocessor**



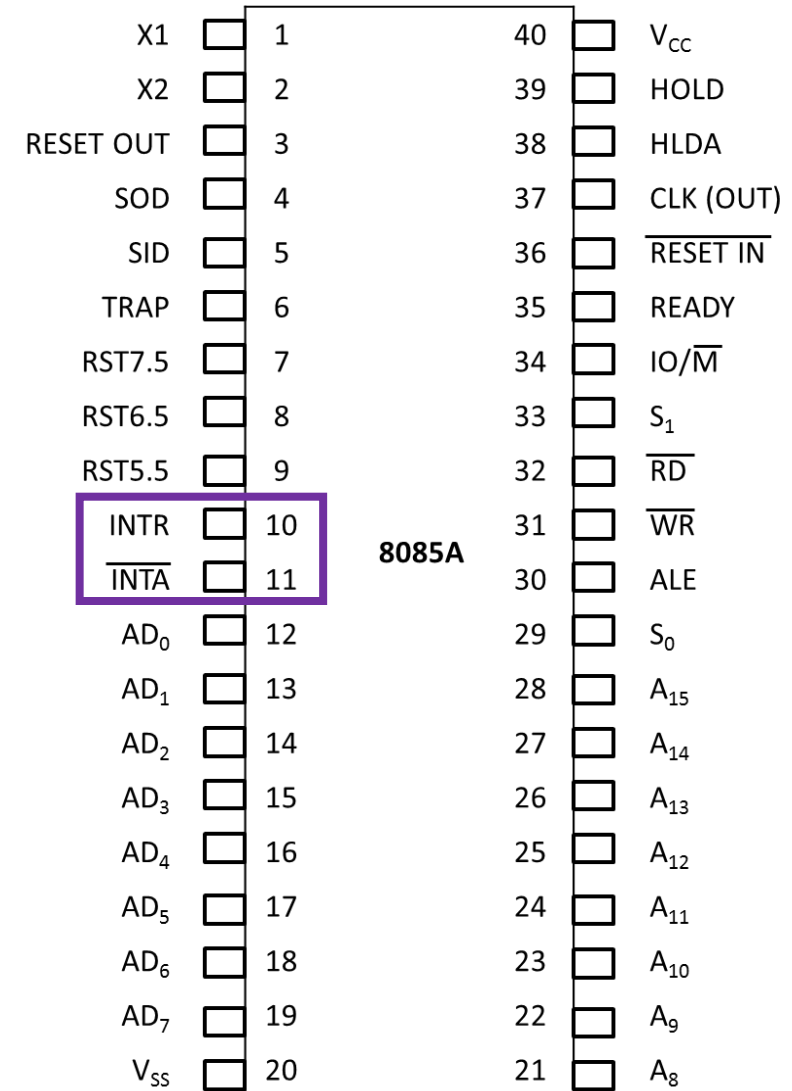
X1	<input type="checkbox"/>	1		40	<input type="checkbox"/>	V _{CC}
X2	<input type="checkbox"/>	2		39	<input type="checkbox"/>	HOLD
RESET OUT	<input type="checkbox"/>	3		38	<input type="checkbox"/>	HLDA
SOD	<input type="checkbox"/>	4		37	<input type="checkbox"/>	CLK (OUT)
SID	<input type="checkbox"/>	5		36	<input type="checkbox"/>	RESET IN
TRAP	<input type="checkbox"/>	6		35	<input type="checkbox"/>	READY
RST7.5	<input type="checkbox"/>	7		34	<input type="checkbox"/>	IO/ \overline{M}
RST6.5	<input type="checkbox"/>	8		33	<input type="checkbox"/>	S ₁
RST5.5	<input type="checkbox"/>	9		32	<input type="checkbox"/>	\overline{RD}
INTR	<input type="checkbox"/>	10		31	<input type="checkbox"/>	\overline{WR}
\overline{INTA}	<input type="checkbox"/>	11	8085A	30	<input type="checkbox"/>	ALE
AD ₀	<input type="checkbox"/>	12		29	<input type="checkbox"/>	S ₀
AD ₁	<input type="checkbox"/>	13		28	<input type="checkbox"/>	A ₁₅
AD ₂	<input type="checkbox"/>	14		27	<input type="checkbox"/>	A ₁₄
AD ₃	<input type="checkbox"/>	15		26	<input type="checkbox"/>	A ₁₃
AD ₄	<input type="checkbox"/>	16		25	<input type="checkbox"/>	A ₁₂
AD ₅	<input type="checkbox"/>	17		24	<input type="checkbox"/>	A ₁₁
AD ₆	<input type="checkbox"/>	18		23	<input type="checkbox"/>	A ₁₀
AD ₇	<input type="checkbox"/>	19		22	<input type="checkbox"/>	A ₉
V _{SS}	<input type="checkbox"/>	20		21	<input type="checkbox"/>	A ₈

8085 Pin Diagram Externally Initiated Signals

- ▶ **INTR**(Input) → Interrupt Request

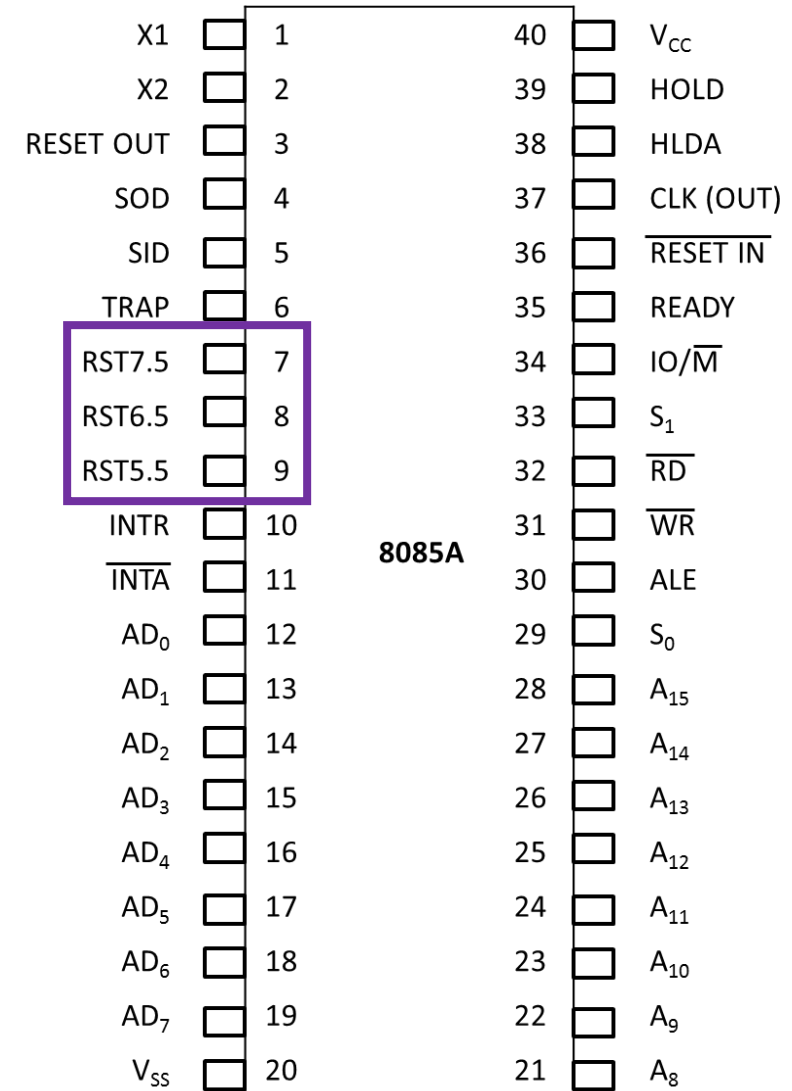
It is used for general purpose interrupt.

- ▶ **$\overline{\text{INTA}}$** (Output) → Interrupt Acknowledge.



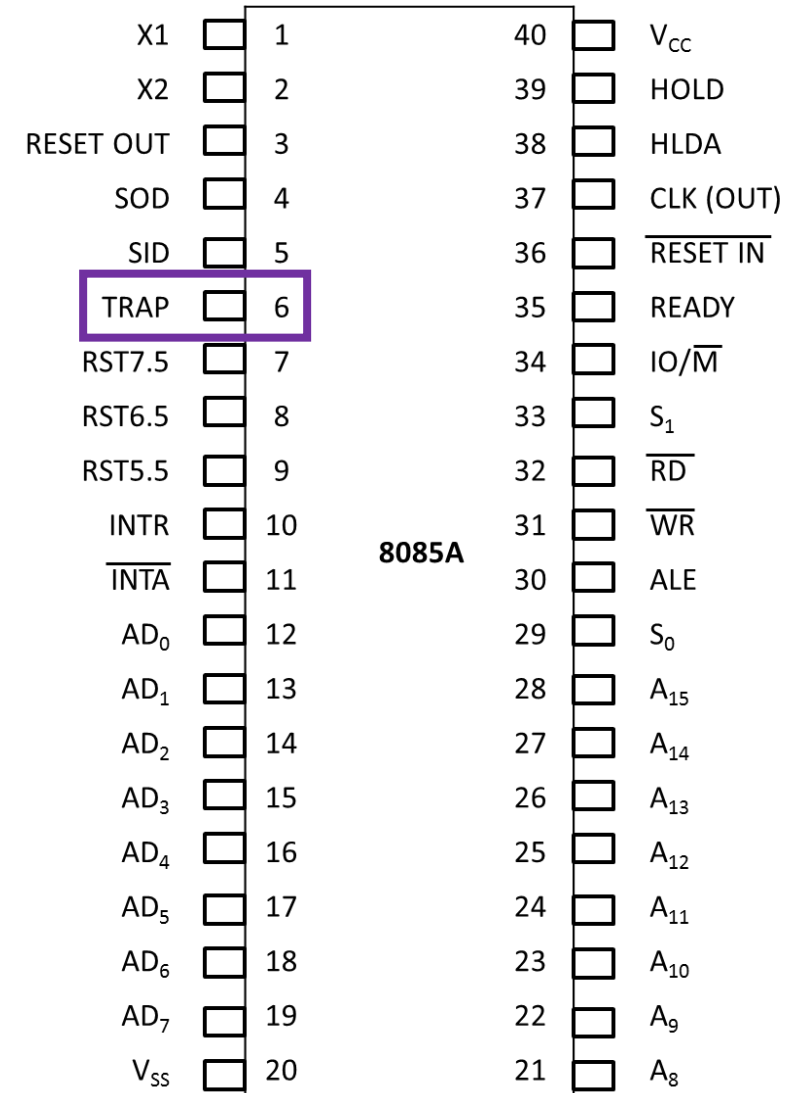
8085 Pin Diagram: Externally Initiated Signals

- ▶ **RST7.5, RST6.5, RST5.5** (Input) → Restart Interrupts.
- ▶ These are **vector interrupts** that transfer the program control to specific **memory locations**.
- ▶ **RST7.5, RST6.5, RST5.5** have higher priorities than **INTR** interrupt.
- ▶ Among these 3 interrupts, the priority order (higher to lower) is **RST7.5, RST6.5, RST5.5** respectively.



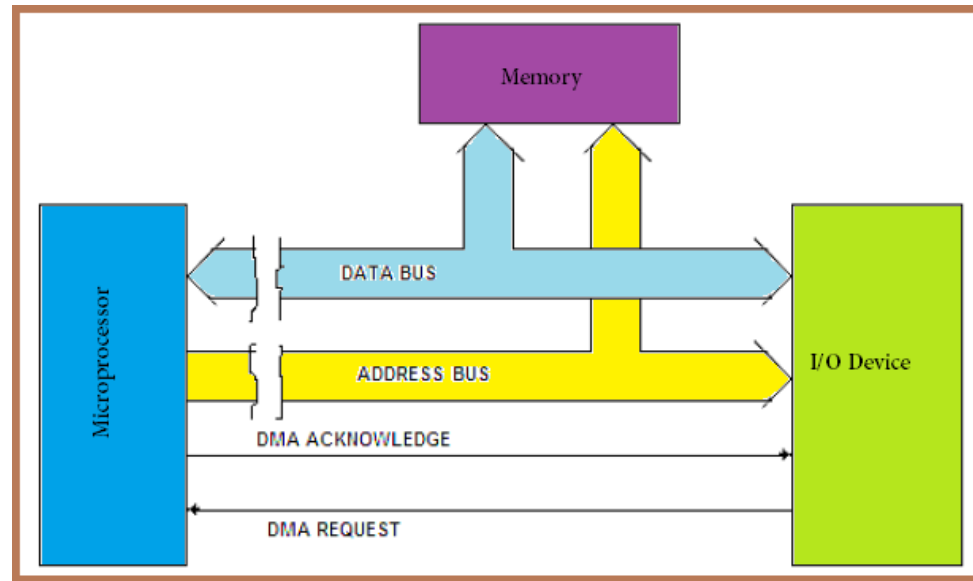
8085 Pin Diagram Externally Initiated Signals

- ▶ TRAP(Input) → This is a **non maskable** interrupt & has the **highest priority**.



8085 Pin Diagram: Externally Initiated Signals

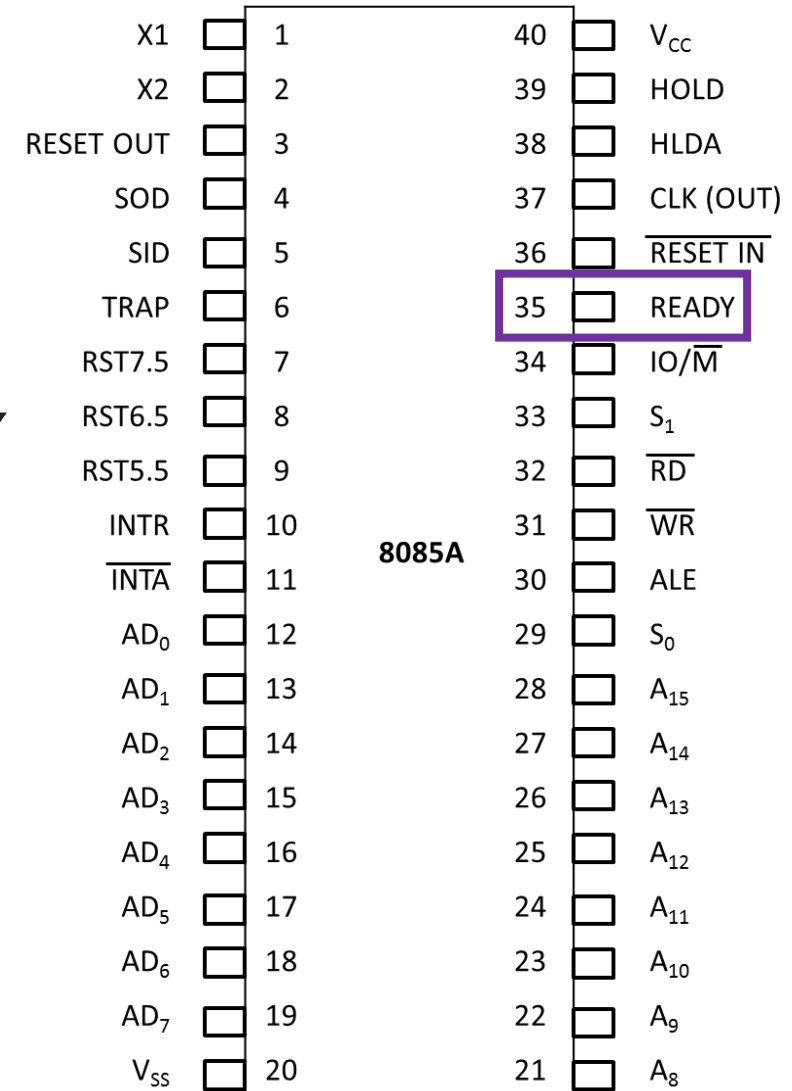
- ▶ **HOLD(Input)** → This signal indicates that a peripheral such as **DMA Controller** is requesting the use of address & data buses
- ▶ **HLDA(Output)** → Hold Acknowledge This signal acknowledges the HOLD request



X1	<input type="checkbox"/>	1	40	<input type="checkbox"/>	V _{CC}
X2	<input type="checkbox"/>	2	39	<input type="checkbox"/>	HOLD
RESET OUT	<input type="checkbox"/>	3	38	<input type="checkbox"/>	HLDA
SOD	<input type="checkbox"/>	4	37	<input type="checkbox"/>	CLK (OUT)
SID	<input type="checkbox"/>	5	36	<input type="checkbox"/>	RESET IN
TRAP	<input type="checkbox"/>	6	35	<input type="checkbox"/>	READY
RST7.5	<input type="checkbox"/>	7	34	<input type="checkbox"/>	IO/ \overline{M}
RST6.5	<input type="checkbox"/>	8	33	<input type="checkbox"/>	S ₁
RST5.5	<input type="checkbox"/>	9	32	<input type="checkbox"/>	\overline{RD}
INTR	<input type="checkbox"/>	10	31	<input type="checkbox"/>	\overline{WR}
\overline{INTA}	<input type="checkbox"/>	11	30	<input type="checkbox"/>	ALE
AD ₀	<input type="checkbox"/>	12	29	<input type="checkbox"/>	S ₀
AD ₁	<input type="checkbox"/>	13	28	<input type="checkbox"/>	A ₁₅
AD ₂	<input type="checkbox"/>	14	27	<input type="checkbox"/>	A ₁₄
AD ₃	<input type="checkbox"/>	15	26	<input type="checkbox"/>	A ₁₃
AD ₄	<input type="checkbox"/>	16	25	<input type="checkbox"/>	A ₁₂
AD ₅	<input type="checkbox"/>	17	24	<input type="checkbox"/>	A ₁₁
AD ₆	<input type="checkbox"/>	18	23	<input type="checkbox"/>	A ₁₀
AD ₇	<input type="checkbox"/>	19	22	<input type="checkbox"/>	A ₉
V _{SS}	<input type="checkbox"/>	20	21	<input type="checkbox"/>	A ₈

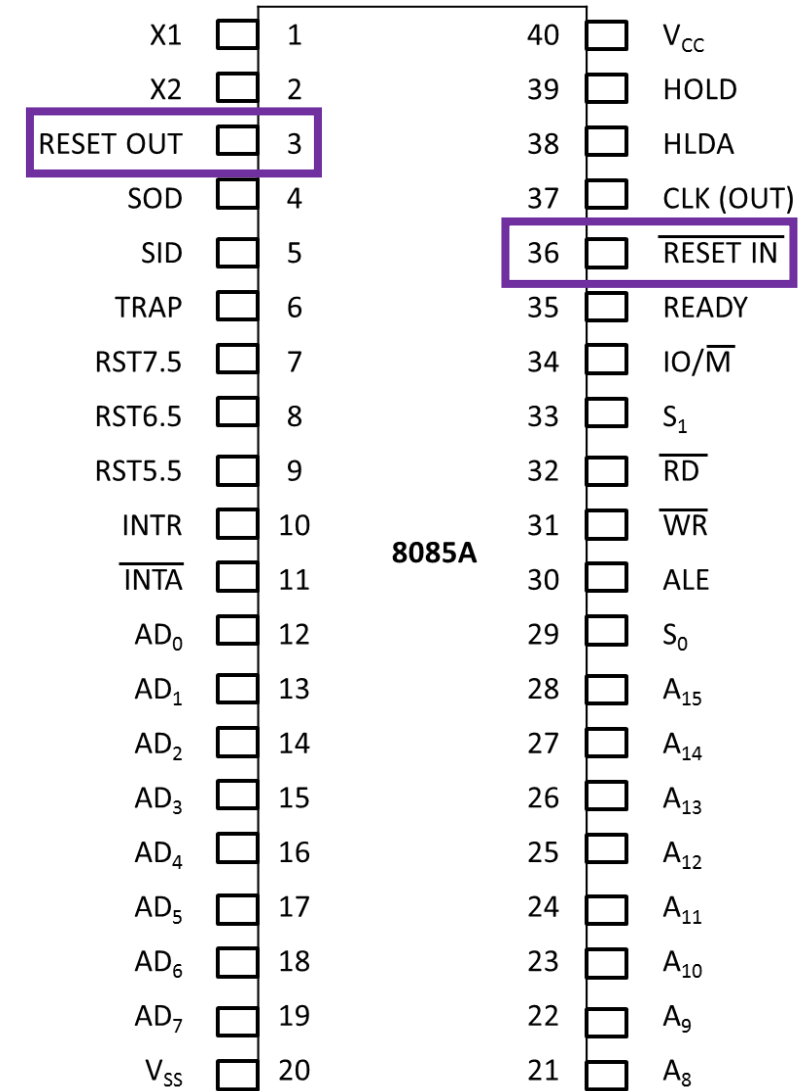
8085 Pin Diagram: Externally Initiated Signals

- ▶ **READY**(Input) → This signal is used to **delay** the microprocessor read or write cycles until low-responding peripheral is ready to send or accept data.
- ▶ When the signal goes low, the microprocessor waits for an integral no. of clock cycles until **READY** signal goes high.



8085 Pin Diagram: Externally Initiated Signals

- ▶ **RESETIN** (Input) → When the signal on this pin goes low, the Program Counter is set to zero, the buses are tri-stated & microprocessor is reset.
- ▶ **RESETOUT** (Output) → This signal indicates that microprocessor is being reset. The signal is also used to reset other devices.

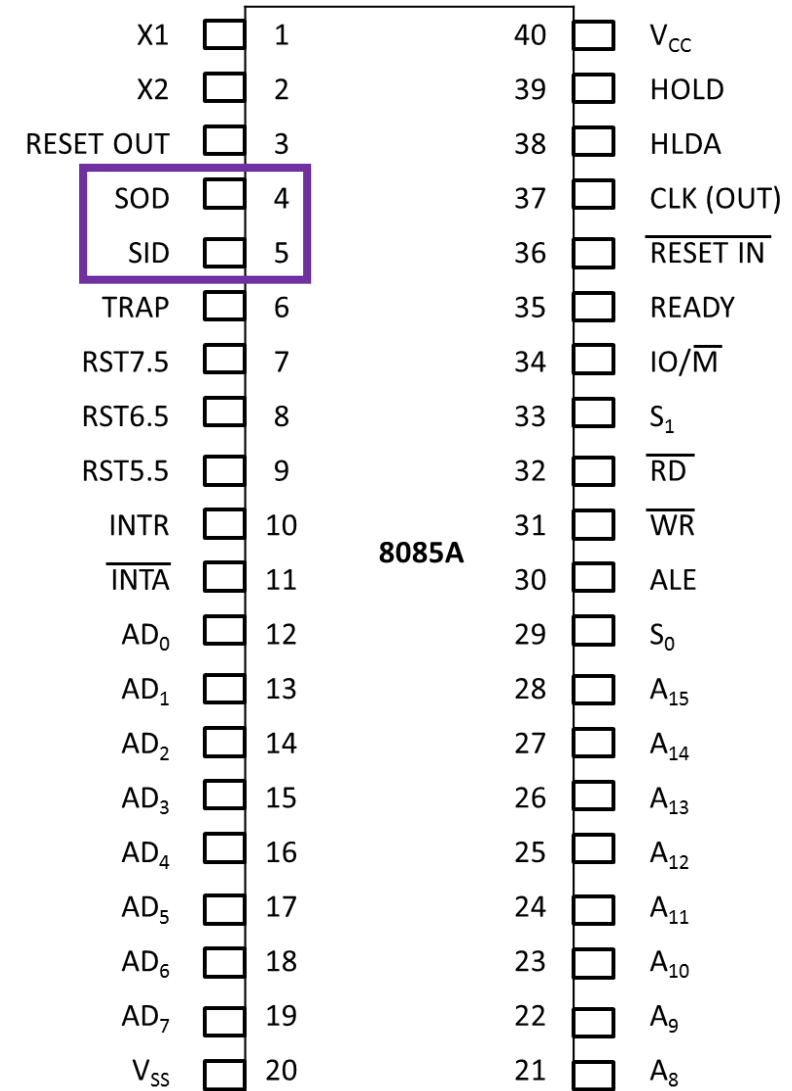


8085 Pin Diagram: Serial I/O Ports

Two pins for serial transmission

1. **SID**(Serial Input Data)
2. **SOD**(Serial Output Data)

► In serial transmission, data bits are sent over a single line, one bit at a time.



8085 Microprocessor signal Groups

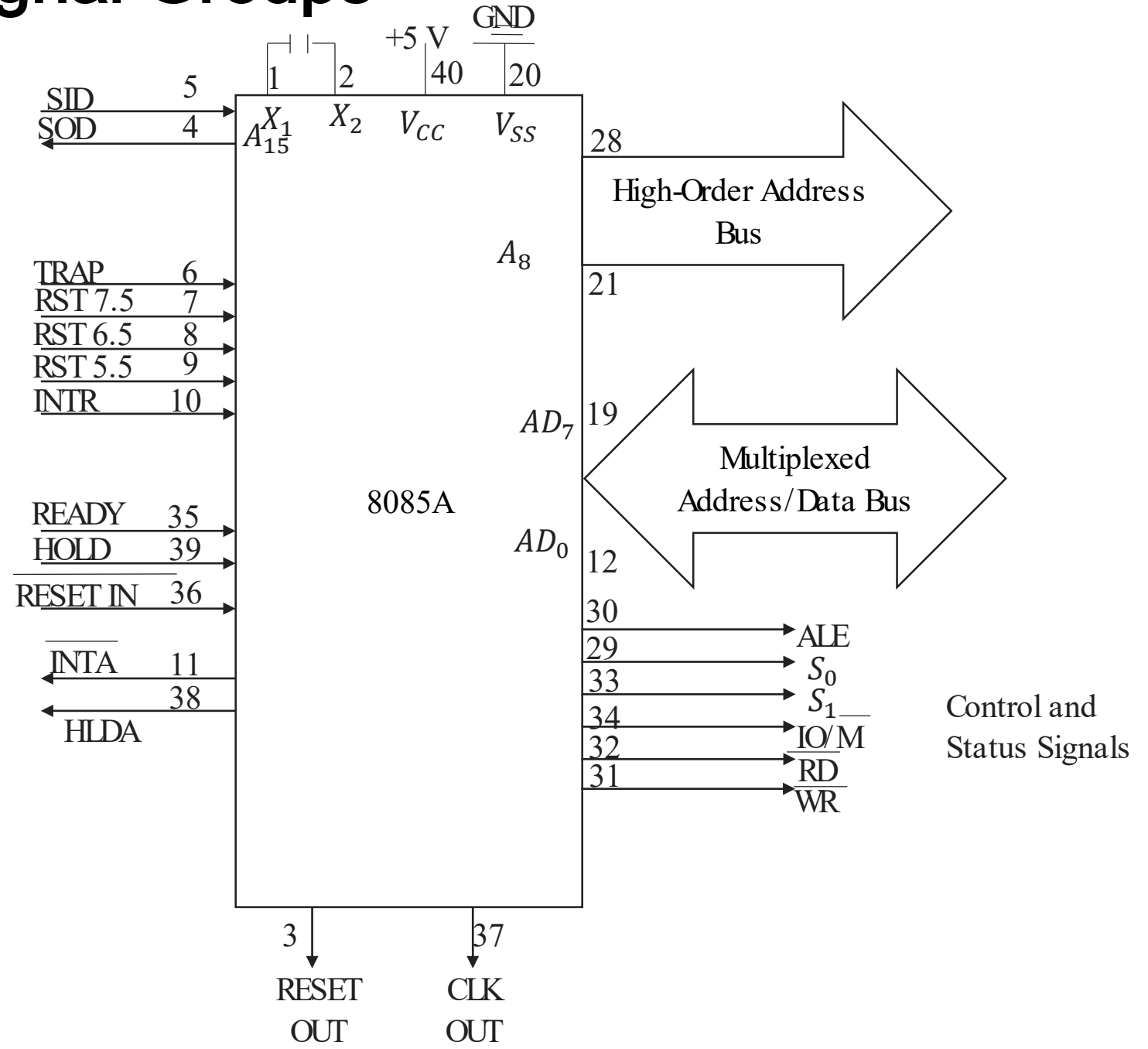
Signals are classified into 6 groups:

1. Address bus
2. Multiplexed address/data bus
3. Control & status signals
4. Power supply & frequency signals
5. Externally initiated signals
6. Serial I/O ports

External Signal
Acknowledgement

Serial
I/O
Ports

Externally
Initiated
Signals



Thank You

