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# Implementation

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- **Slope Based Speed**

```
function out = assign_slope_based_speed( in )  
out = in;  
for i=2:size(in,1)  
out(i,const.COL_SPEED) = 20 - 0.5*out(i,const.COL_SLOPE);  
end  
end
```

- **Segment Time**

```
out(i,const.COL_SEG_TIME) =  
(out(i,const.COL_SEG_DST))/(out(i,const.COL_SPEED));
```

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# Implementation

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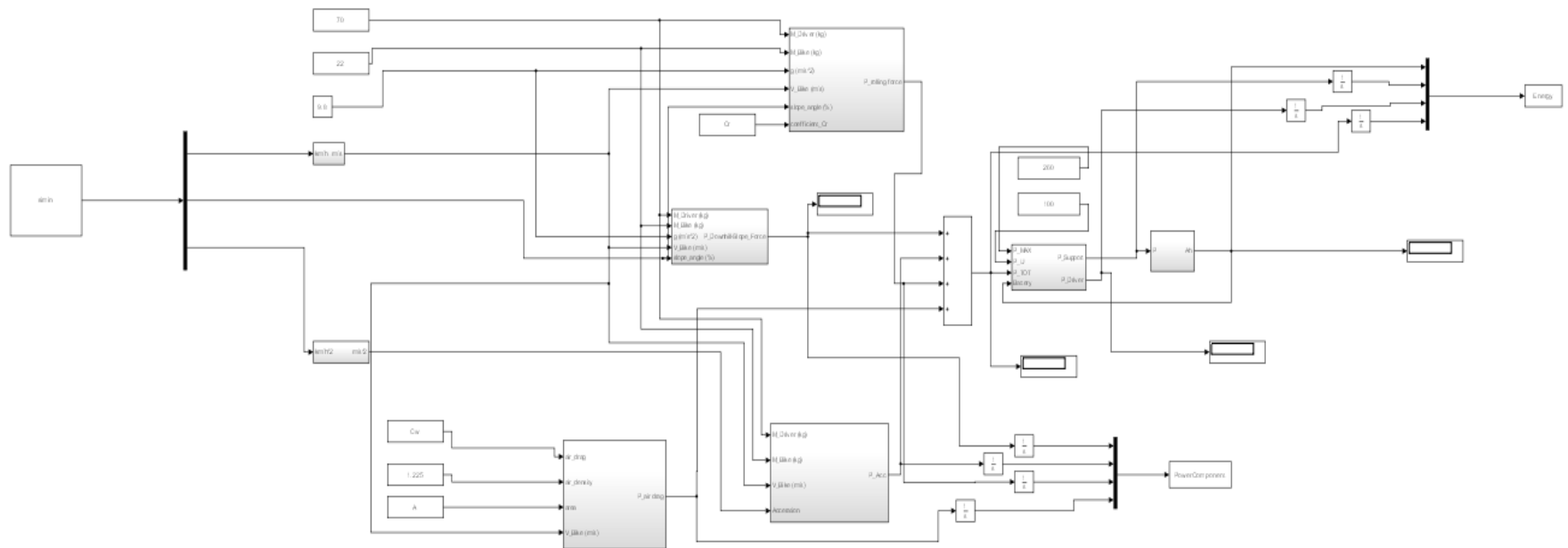
- **Accumulated Time**

`out(:,const.COL_CUM_TIME) = cumsum (out(:,const.COL_SEG_TIME));`

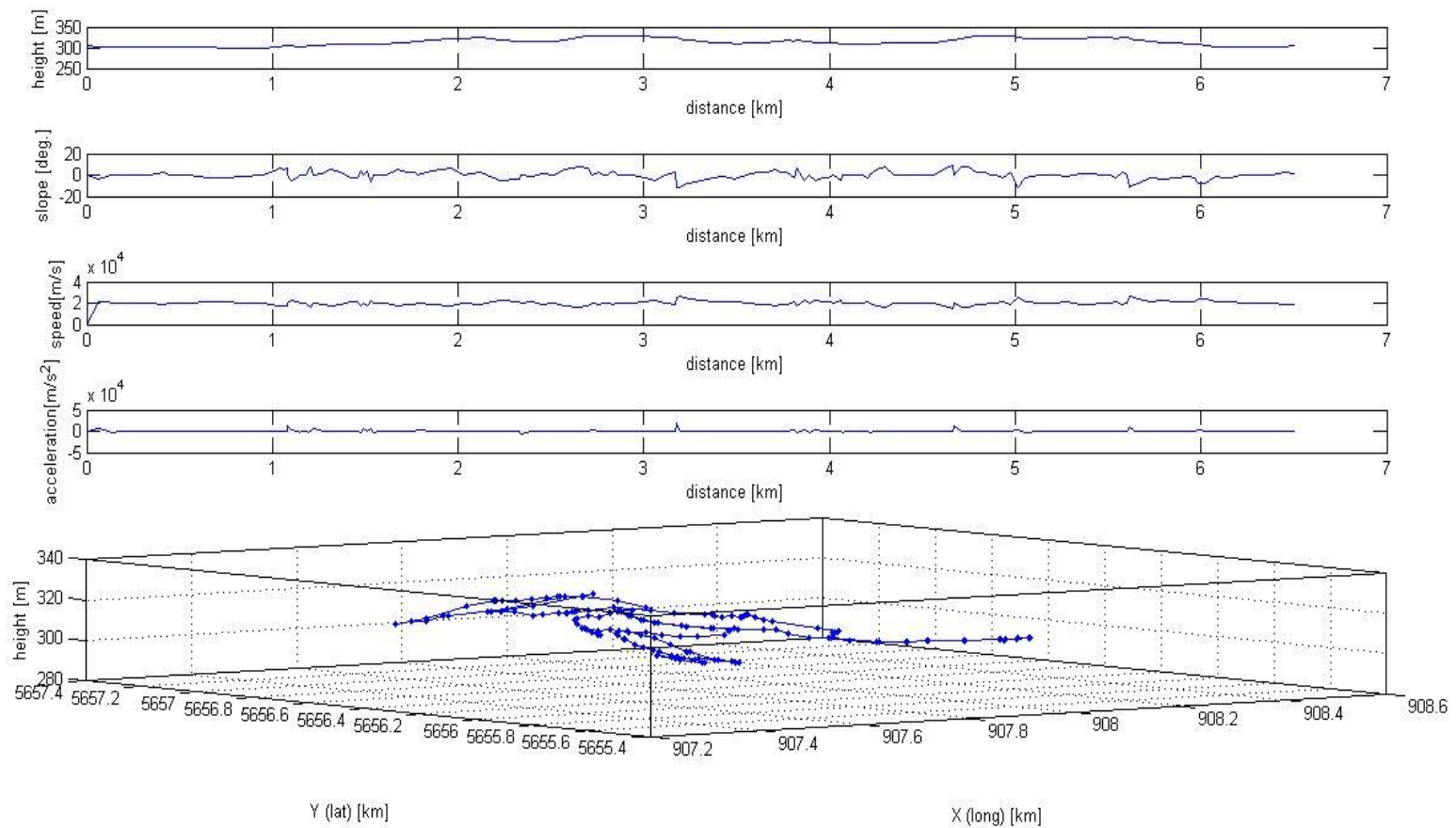
- **Segment Acceleration**

`out(i,const.COL_ACC) = (out(i,const.COL_SPEED)-out((i-1),const.COL_SPEED))  
/out(i,const.COL_SEG_TIME);`

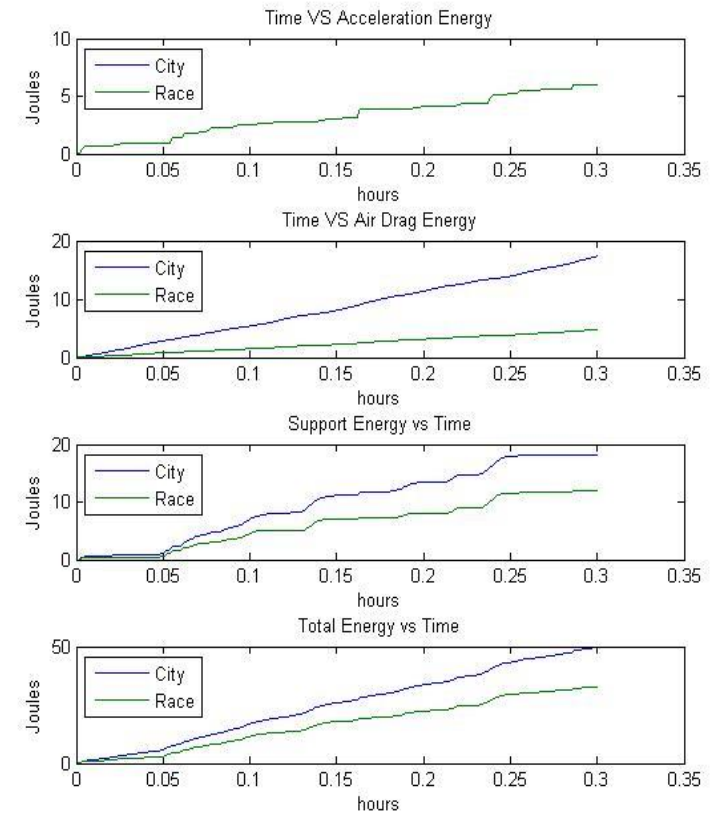
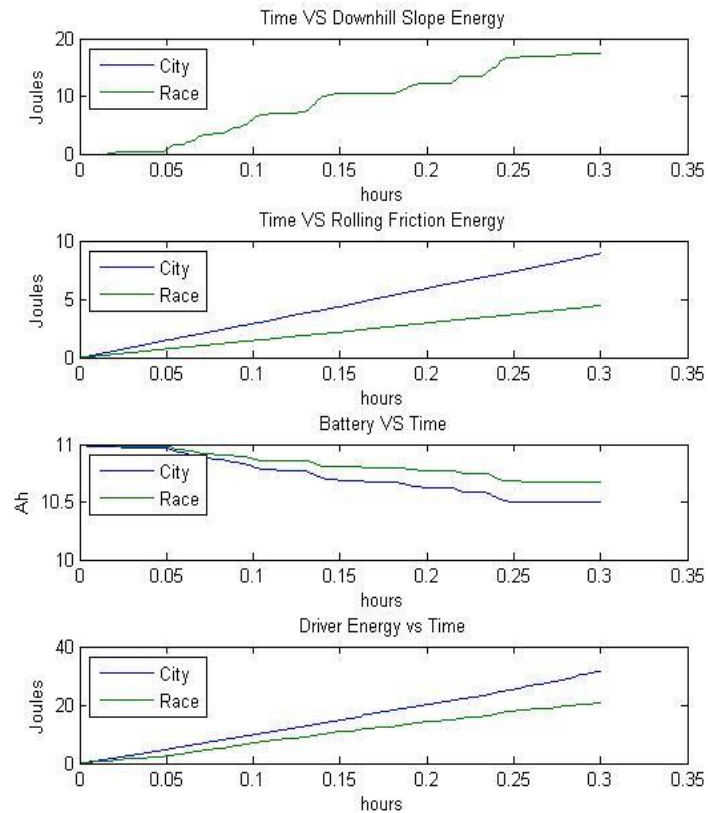
# Implementation



# Results



# Results



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# Result

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## CITY BIKE

Battery and Energy required for City bike at the end:

Battery Support\_Energy Driver\_Energy Total\_Energy  
ans =

10.4982 18.0644 31.5728 49.6373

## RACING BIKE

Battery and Energy required by the Racing bike at the end:

Battery Support\_Energy Driver\_Energy Total\_Energy

ans =

10.6668 11.9936 20.6478 32.6414

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# Result

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