Project Design Phase-4

Date	26 October 2023
Team ID	456
Project Name	4123-Smart Water Management
Team Name	Proj_227234_Team_2
Team Members	5

Adding New Data To The Existing Dataset

Reference: https://wokwi.com/projects/378900005565787137

```
Program Code:
#define PIN_TRIG 26
#define PIN_ECHO 25
#define LOWLED 18
#define MIDLED 19
#define HIGHLED 21
#define MOTOR 27
unsigned int level = 0;

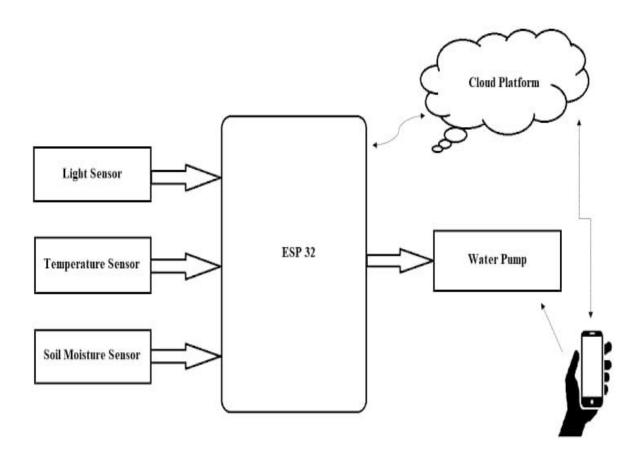
void setup() {
    pinMode(LOWLED, OUTPUT);
    pinMode(MIDLED, OUTPUT);
```

```
pinMode(HIGHLED, OUTPUT);
 pinMode(MOTOR, OUTPUT);
 digitalWrite(LOWLED, HIGH);
 digitalWrite(MIDLED, HIGH);
 digitalWrite(HIGHLED, HIGH);
 digitalWrite(MOTOR, LOW);
 Serial.begin(115200);
 pinMode(PIN_TRIG, OUTPUT);
 pinMode(PIN_ECHO, INPUT);
void loop() {
// Start a new measurement:
 digitalWrite(PIN_TRIG, HIGH);
 delayMicroseconds(10);
 digitalWrite(PIN_TRIG, LOW);
// Read the result:
 int duration = pulseIn(PIN ECHO, HIGH);
```

```
Serial.print("Distance in CM: ");
Serial.println(duration / 58);
Serial.print("Distance in inches: ");
Serial.println(duration / 148);
level = (duration / 10);
if(level < 100)
 digitalWrite(LOWLED, LOW);
 digitalWrite(MOTOR, HIGH);
digitalWrite(HIGHLED, HIGH);
digitalWrite(MIDLED, HIGH);
}
else if ((level > 200 ) && (level < 400))
{
 digitalWrite(LOWLED, HIGH);
 digitalWrite(HIGHLED, HIGH);
digitalWrite(MIDLED, LOW);
```

```
else if (level >= 400 )
{
    digitalWrite(HIGHLED, LOW);
    digitalWrite(MIDLED, HIGH);
    digitalWrite(LOWLED, HIGH);
    digitalWrite(MOTOR, LOW);
}
delay(1000);
}
```

BLOCK DIAGRAM:



Output:

load:0x40080400,len:2972

entry 0x400805dc Distance in CM: 192 Distance in inches: 75 Distance in CM: 192