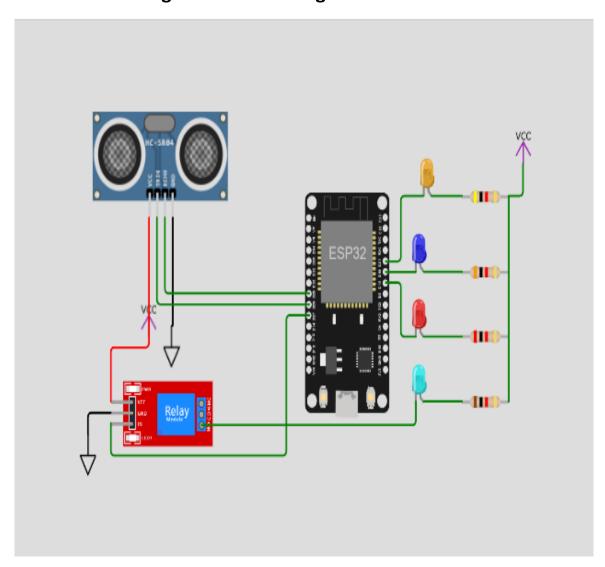
Project Design Phase-3

Date	18 October 2023		
Team ID	456		
Project Name	4123-Smart Water Management		
Team Name	Proj_227234_Team_2		
Team Members	5		

Smart Water Management Block Diagram:

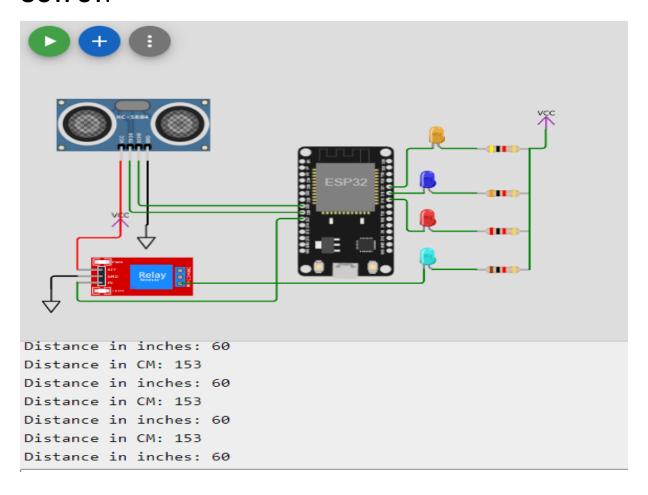


Program code for SWM:

```
sketch.ino
            diagram.json
                          Library Manager
       #define PIN_TRIG 26
  1
       #define PIN ECHO 25
  3
       #define LOWLED 18
  4
       #define MIDLED 19
       #define HIGHLED 21
       #define MOTOR 27
  6
       unsigned int level = 0;
       void setup() {
  9
 10
         pinMode(LOWLED, OUTPUT);
 11
         pinMode(MIDLED, OUTPUT);
 12
 13
         pinMode(HIGHLED, OUTPUT);
 14
        pinMode(MOTOR, OUTPUT);
         digitalWrite(LOWLED, HIGH);
 15
 16
         digitalWrite(MIDLED, HIGH);
         digitalWrite(HIGHLED, HIGH);
 17
        digitalWrite(MOTOR, LOW);
 18
 19
 20
         Serial.begin(115200);
         pinMode(PIN_TRIG, OUTPUT);
 21
 22
         pinMode(PIN_ECHO, INPUT);
 23
 24
 25
       void loop() {
 26
        // Start a new measurement:
 27
 28
         distanting the Corn Total Literal
  27
  28
  29
         digitalWrite(PIN TRIG, HIGH);
  30
         delayMicroseconds(10);
         digitalWrite(PIN_TRIG, LOW);
  31
  32
          // Read the result:
  33
 34
         int duration = pulseIn(PIN_ECHO, HIGH);
         Serial.print("Distance in CM: ");
  35
  36
         Serial.println(duration / 58);
  37
         Serial.print("Distance in inches: ");
  38
         Serial.println(duration / 148);
  39
  40
         level = (duration / 10);
  41
  42
          if(level < 100)
 43
 44
           digitalWrite(LOWLED, LOW);
 45
           digitalWrite(MOTOR, HIGH);
 46
           digitalWrite(HIGHLED, HIGH);
  47
           digitalWrite(MIDLED, HIGH);
 48
  49
  50
          else if ((level > 200 ) && (level < 400))
  51
  52
           digitalWrite(LOWLED, HIGH);
  53
           digitalWrite(HIGHLED, HIGH);
  54
           digitalWrite(MIDLED, LOW);
```

```
49
       else if ((level > 200 ) && (level < 400))
50
51
52
         digitalWrite(LOWLED, HIGH);
53
         digitalWrite(HIGHLED, HIGH);
54
         digitalWrite(MIDLED, LOW);
55
56
57
       else if (level >= 400 )
58
59
         digitalWrite(HIGHLED, LOW);
         digitalWrite(MIDLED, HIGH);
60
         digitalWrite(LOWLED, HIGH);
61
         digitalWrite(MOTOR, LOW);
62
63
64
       delay(1000);
65
66
```

OUTPUT:



Reference: https://wokwi.com/projects/378900005565787137