



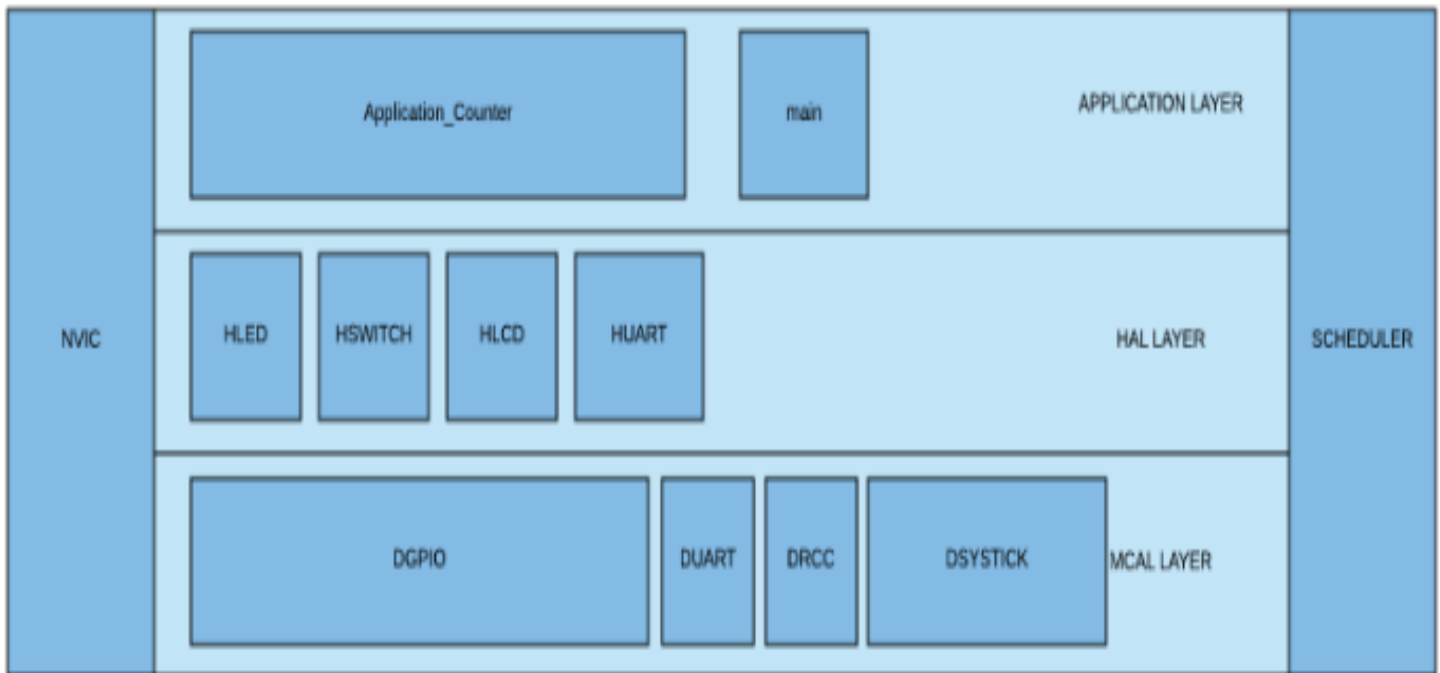
STATIC ARCHITECTURE



Team Members: Mohanad Fawzy
Marcelle Samir
Mostafa Ramadan
Marina Medhat
Mostafa Nader

MARCH 23, 2020

Static Architecture Diagram



DRIVER	DRCC	DESCRIPTION
API's	uint_8t RCC_SetClkStatus (uint_32t Clk,uint_8t Status);	Enables the ready flags of either HSI, HSE or PLL
	uint_8t RCC_SetSystemClk (uint_32t Clk);	Sets HSI, HSE or PLL as the system Clock
	uint_8t RCC_SetPLLConfig (uint_32t Src, uint_8t Mul);	Configures the source to the PLL and the multiplier's Value
	uint_8t RCC_SetPriephralStatus (uint_32t Peripheral,uint_8t Status);	Enables the clock of any peripheral from AHB, APB1 or APB2 Bus
	uint_8t RCC_SetBusPrescale (uint_32t Bus,uint_8t Prescaler);	Set the prescaler value of either AHB, APB1 or APB2 Bus
	uint_8t RCC_GetBusClock (uint_32t Bus,uint_32t *Clk);	Gets the Clock system of either AHB, APB1 or APB2 Bus after prescaling

DRIVER	DGPIO	DESCRIPTION
API's	uint_8t GPIO_Config (GPIO_t * Pins);	Configures one or multiple pins to one or multiple configuration modes at the same port
	uint_8t GPIO_Writee(Port_t *Port,uint_16t Pins ,uint_8t State);	Setting or clearing values to one or multiple pins at the same port
	uint_8t GPIO_ReadPort(Port_t *Port,uint_16t * Value);	Gets the value of an entire port
	uint_8t GPIO_ReadPin (Port_t *Port,uint_16t Pin,uint_8t * Value);	Gets the value of a single pin at a specific port

DRIVER	DSYSTICK	DESCRIPTION
API's	uint_8t SYSTICK_Init (void);	Initializes the interrupt mode and the prescaler of the systick timer
	uint_8t SYSTICK_Start (void);	Enables the systick timer to start counting
	uint_8t SYSTICK_Stop (void);	Disables the systick timer to stop counting
	uint_8t SYSTICK_SetCallback (systickcbf_t Cbf);	Call the function that the user sends when the handler executes
	uint_8t SYSTICK_SetTime (uint_32t Ttimeus,uint_32t Clk);	Receives time from the user in microseconds to star counting it
	uint_8t SYSTICK_SetPrescale (uint_32t Prescaler);	Sets the prescaler of the systick timer to 1 or 8

DRIVER	DUART	DESCRIPTION
API's	uint_8t UART_Init(void);	Enables the UART and initializes the configuration parameters of the UART peripheral(Data length, parity bit, # of stop bits and baud rate) and enables the TC,RXNE interrupts
	uint_8t UART_Send(uint_8t *Buffer, uint_16t Length);	Send a stream of bytes on the transmission line
	uint_8t UART_Receive(uint_8t *Buffer, uint_16t Length);	Receives a stream of bytes on the receiving line
	uint_8t UART_Config(uint_32t BaudRate,uint_32t ParityBits,uint_32t DataSize,uint_32t StopBits);	Configures the configuration parameters of the UART peripheral(Data length, parity bit, # of stop bits and baud rate)
	uint_8t UART_SetTxCbf(TxCbf_t TxCbf);	Function called when the transmission handler is executed
	uint_8t UART_SetRxCbf(RxCbf_t RxCbf);	Function called when the receiving handler is executed

DRIVER	HLED	DESCRIPTION
API's	uint_8t HLED_Init(void);	Initializes the configurations of the LEDs according to the values in the configuration file
	uint_8t HLED_SetLedState(uint_8t Led_Number,uint_8t Led_State);	Setting or Clearing each Led according to the choice of the user in the configuration file

DRIVER	HSWITCH	DESCRIPTION
API's	uint_8t Switch_Init (void);	Initializes the configurations of the Switches according to the values in the configuration file
	uint_8t Switch_GetSwitchState(uint_8t SwitchNum,uint_8t * State);	Gets the values of the switch (High or Low) after checking of five consecutive values

DRIVER	HLCD	DESCRIPTION
API's	uint_8t LCD_Init (void);	Initializes the LCD according to the Datasheet
	uint_8t LCD_WriteData (const uint_8t *data,uint_8t DataLength);	Writing a stream of data bytes on the LCD screen
	uint_8t LCD_ClearLCD (void);	Clears the LCD screen

DRIVER	HUART	DESCRIPTION
API's	uint_8t UART_Init(void);	Initializes the RX & TX Pins configurations and gets the clock's frequency
	uint_8t UART_Send(uint_8t *Buffer, uint_16t Length);	Calls the send function the UART Driver
	uint_8t UART_Receive(uint_8t *Buffer, uint_16t Length);	Calls the Receiving function the UART Driver
	uint_8t HUART_Config(uint_32t BaudRate,uint_32t ParityBits,uint_32t DataSize,uint_32t StopBits);	Send the Baud rate's mantissa and fraction , the StopBits configuration, the ParityBit configuration and the DataLength configuration to the MCAL driver to configure it
	uint_8t HUART_SetTxCbf(TxCbf_t TxCbf);	Calls the Transmitter call back function in the MCAL driver
	uint_8t UART_SetRxCbf(RxCbf_t RxCbf);	Calls the Receiver call back function in the MCAL driver

DRIVER	NVIC	DESCRIPTION
API's	uint_8t DNVIC_EnableIRQ(uint_8t IRQn);	Enables the bit of any peripheral from the 240 external interrupts
	uint_8t DNVIC_DisableIRQ(uint_8t IRQn);	Disables the bit of any peripheral from the 240 external interrupts
	uint_8t DNVIC_SetPendingIRQ (uint_8t IRQn);	Sets the Pending flag of any peripherals from the 240 external interrupts by software
	uint_8t DNVIC_ClearPendingIRQ (uint_8t IRQn);	Clears the Pending flag of any peripherals from the 240 external interrupts by software
	uint_8t DNVIC_GetPendingIRQ (uint_8t IRQn, uint_8t *Val);	Gets the Pending flag value of any peripherals from the 240 external interrupts
	uint_8t DNVIC_GetActive (uint_8t IRQn, uint_8t *Val);	Gets the Active flag Value of any peripherals from the 240 external interrupts
	uint_8t DNVIC_SetPriorityGrouping(uint_32t priority_grouping);	Divides the 4 bits available in ST into preemption and subgroup bits
	uint_8t DNVIC_SetPriority (uint_8t IRQn, uint_8t priority);	Sets the priority of any of the 240 external interrupt from 0->0x0F
	uint_8t DNVIC_GetPriority (uint_8t IRQn, uint_8t *priority);	Gets the priority value of any of the 240 external interrupt
	void DNVIC_voidDisableAllPeripherals(void);	Disables all the interrupts
	void DNVIC_voidEnableAllPeripherals(void);	Enables all the interrupts
	void DNVIC_voidDisableAllFaults(void);	Disables all the interrupts & Faults
	void DNVIC_voidEnableAllFaults(void);	Enables all the interrupts & Faults
	void DNVIC_voidSetBASEPRI(uint_8t priority);	Disable the interrupts of a specific priority or higher

DRIVER	SCHEDULER	DESCRIPTION
API's	uint_8t Sched_Init(void);	Initializes the systick timer with the tick time and initializes the tasks
	uint_8t Sched_Start(void);	Starts the systick timer
	void Sched_Suspend(void);	Suspends a running task