

Learn IN Depth

Be Professional in Embedded System



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Unit: 5 – Project 1

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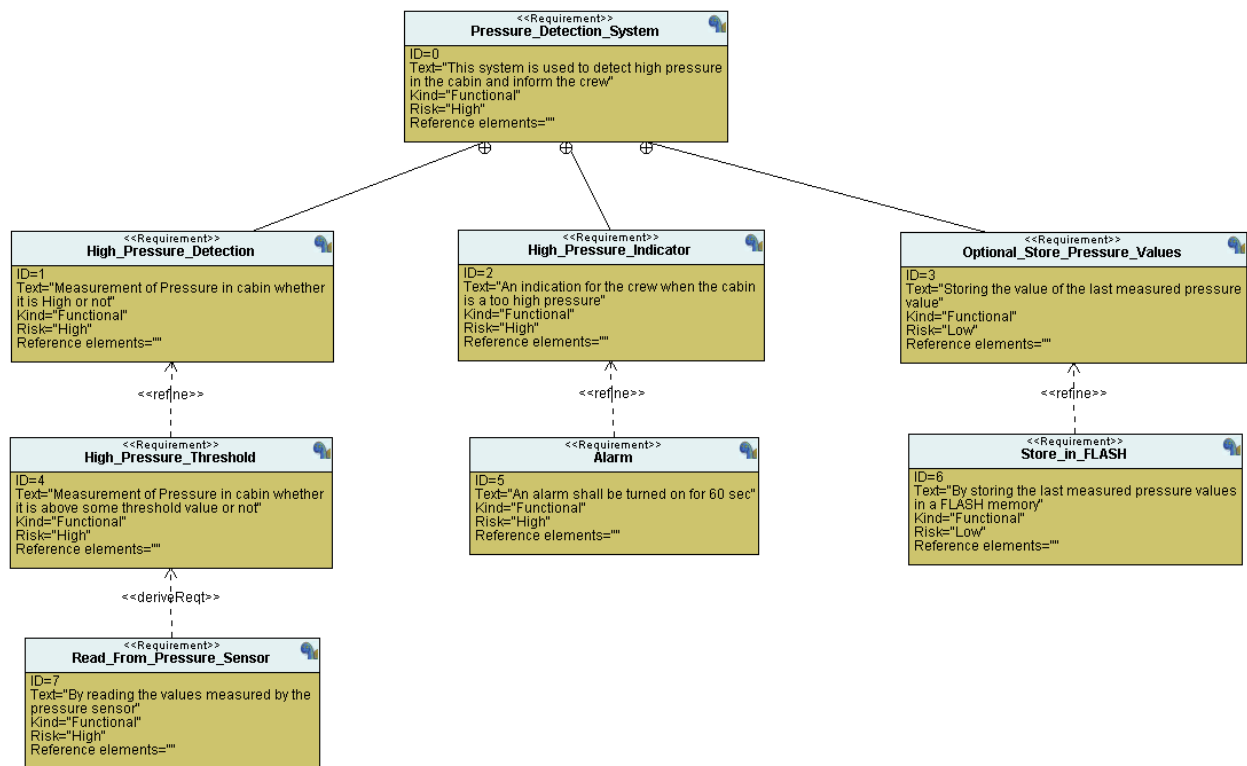
1- Case Study:

A pressure detection system that monitors the value of the pressure in the cabin and sets an alarm on for 60 seconds if the pressure value is greater than or equal to 20 bars.

Assumptions:

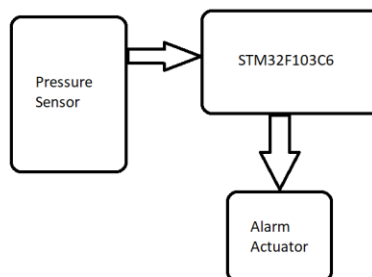
- The pressure sensor never fails
- The alarm actuator never fails
- The system never faces power cuts
- The system maintenance is not modeled

2- Requirements Diagram



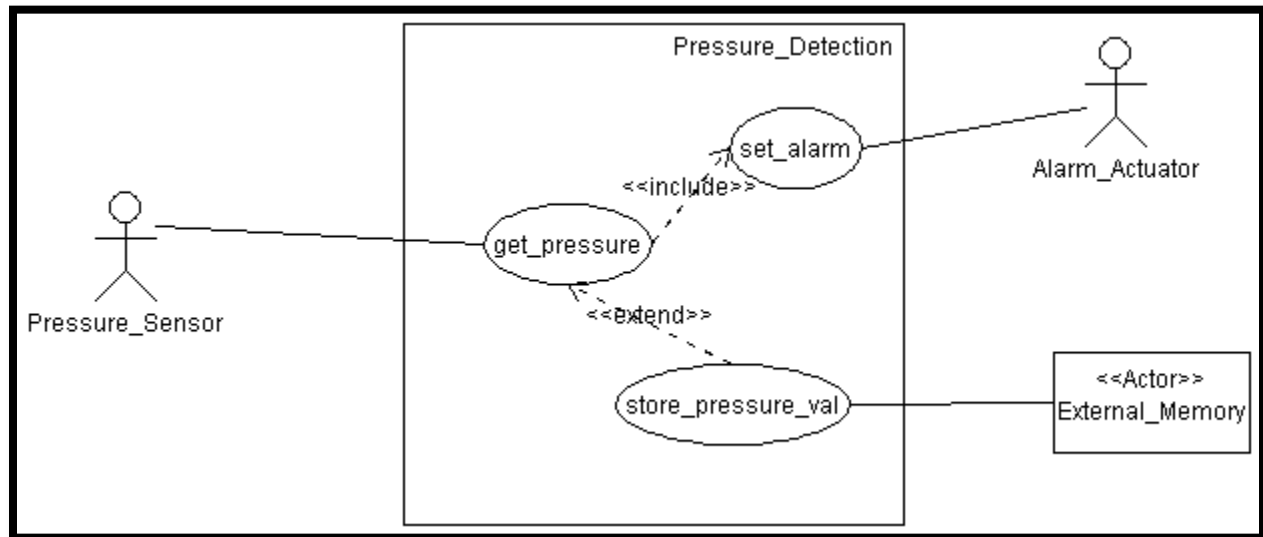
3- Space Exploration

- STM32F103C6 board
- Pressure sensor
- Alarm actuator

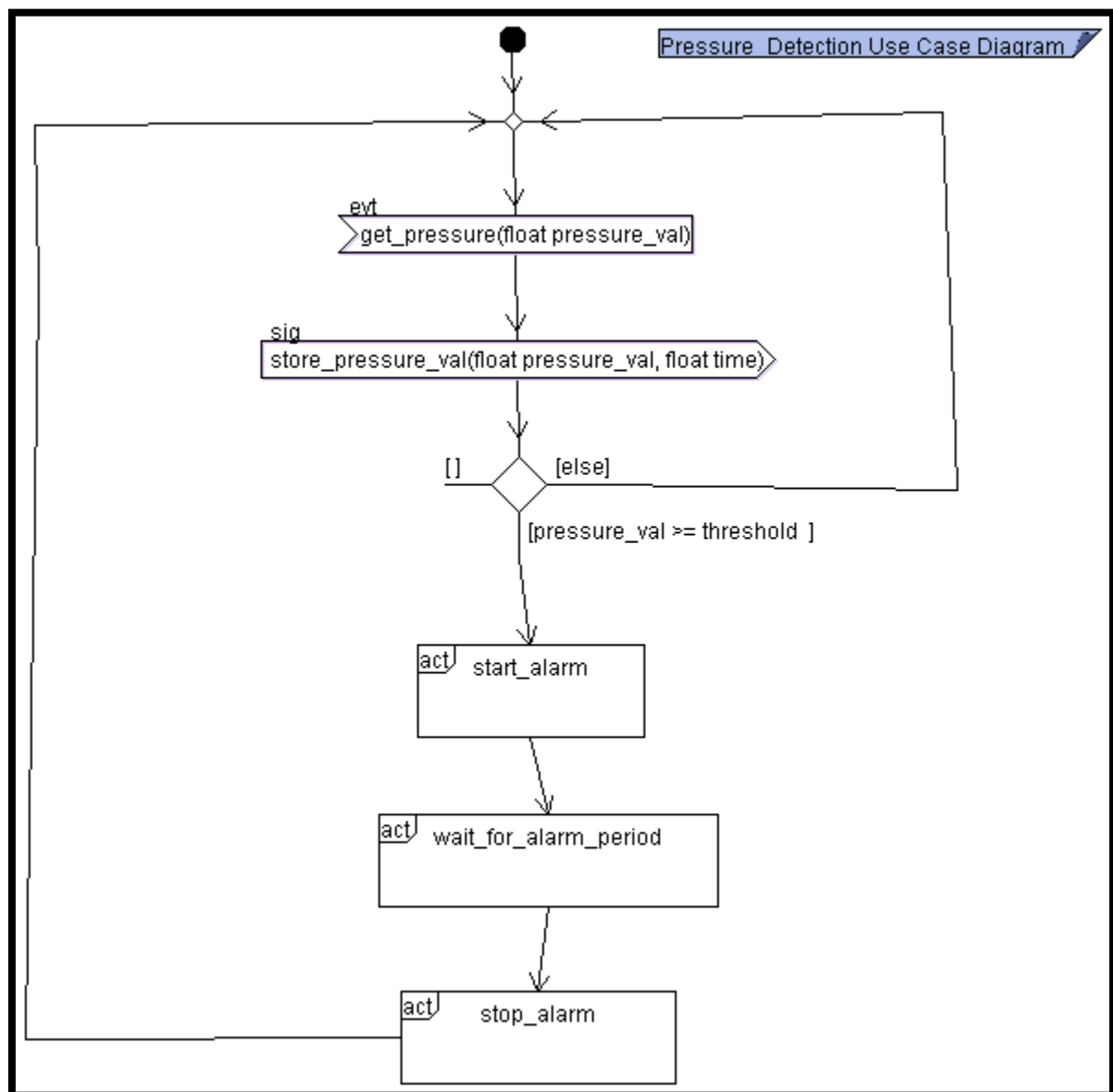


4-System Analysis

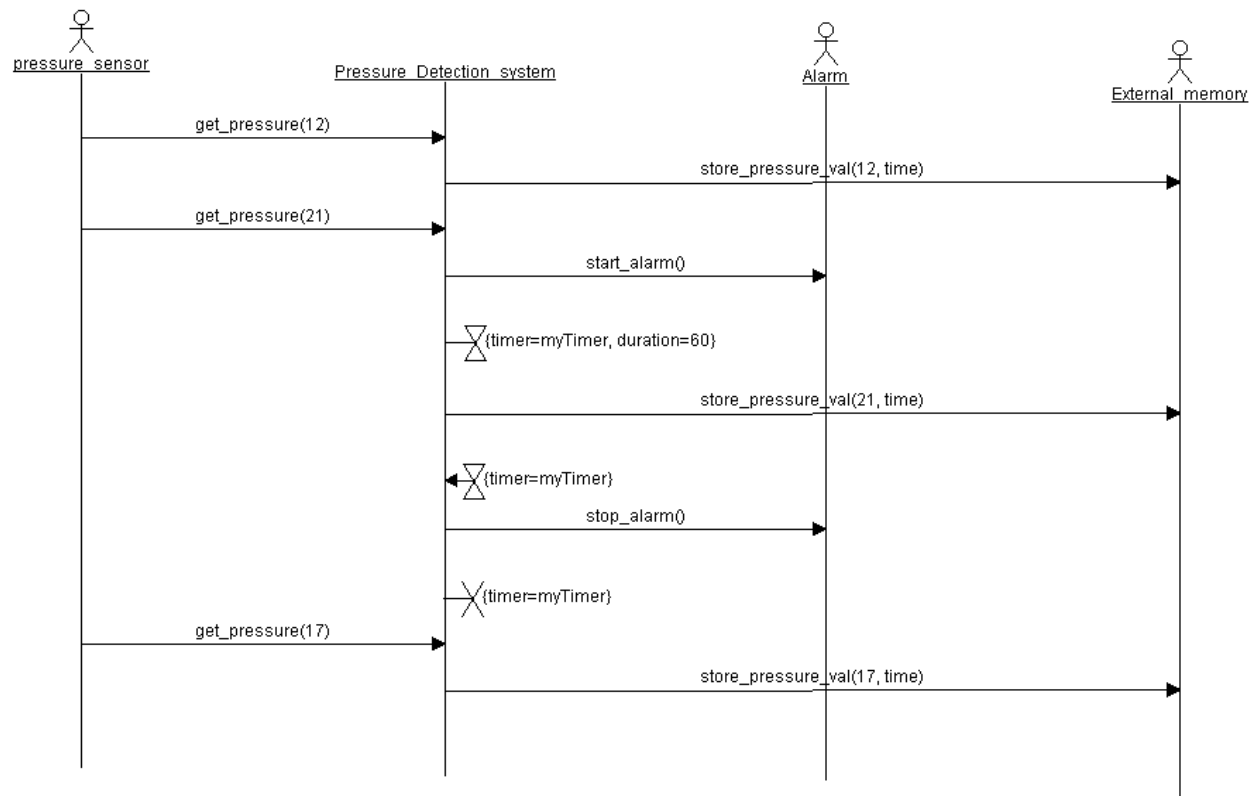
1. Use Case Diagram



2. Activity Diagram

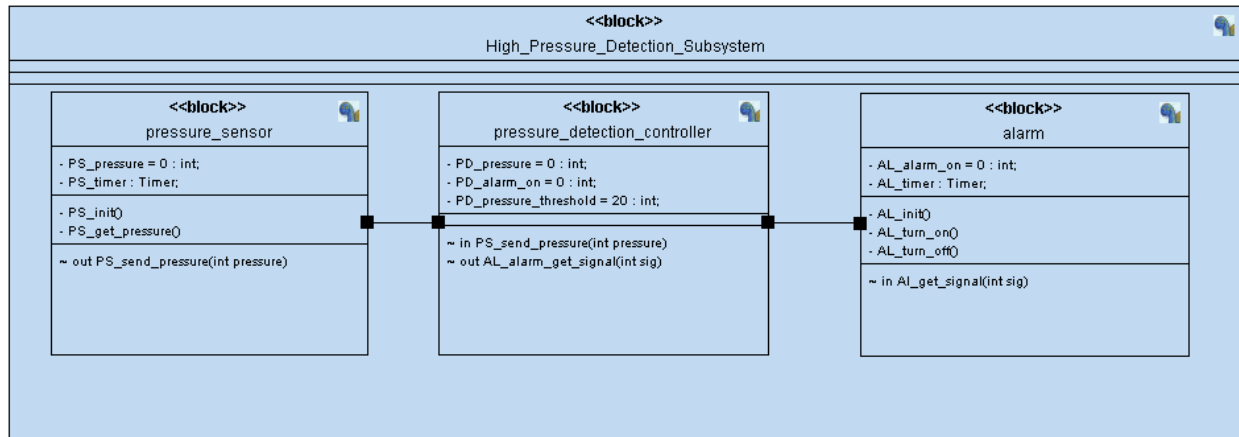


3. Sequence Diagram

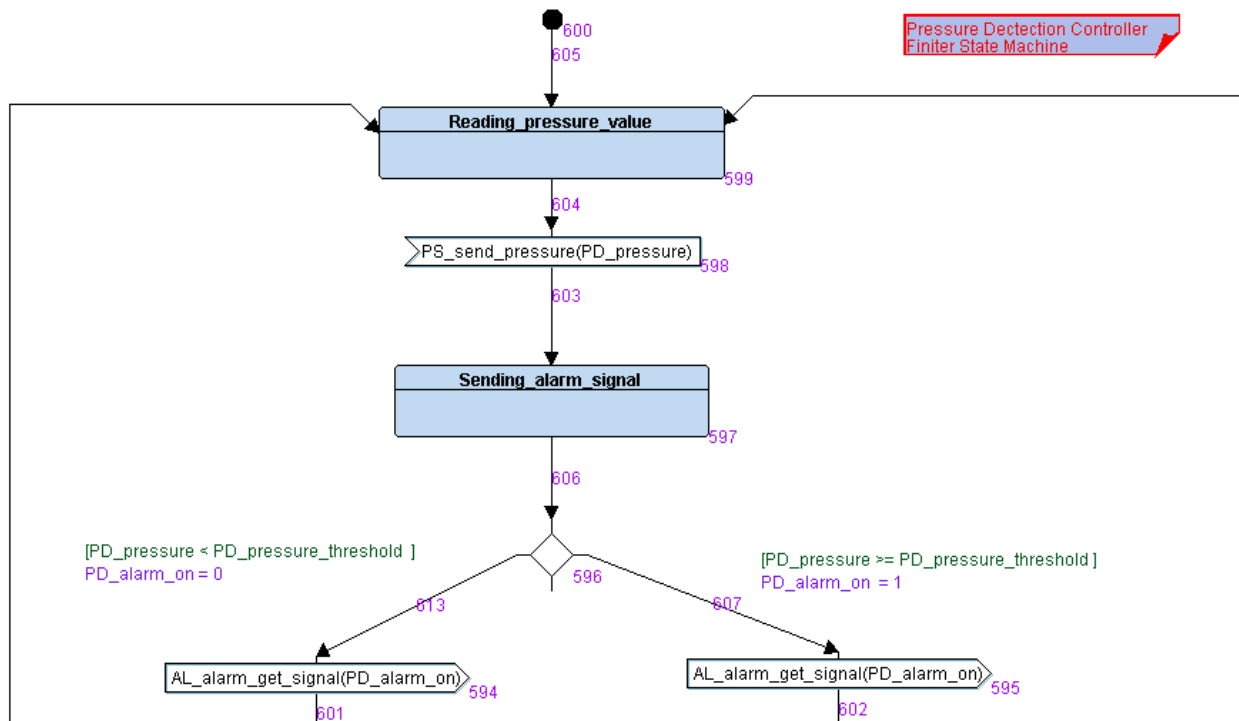


5-System Design

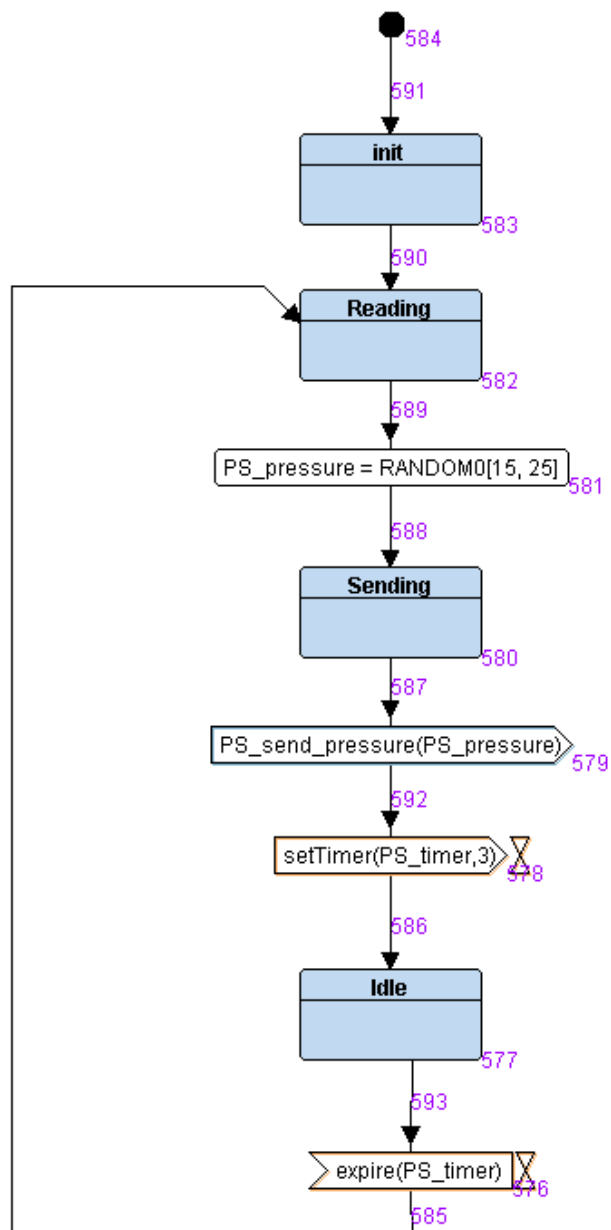
1. Block Diagram



2. Main System FSM



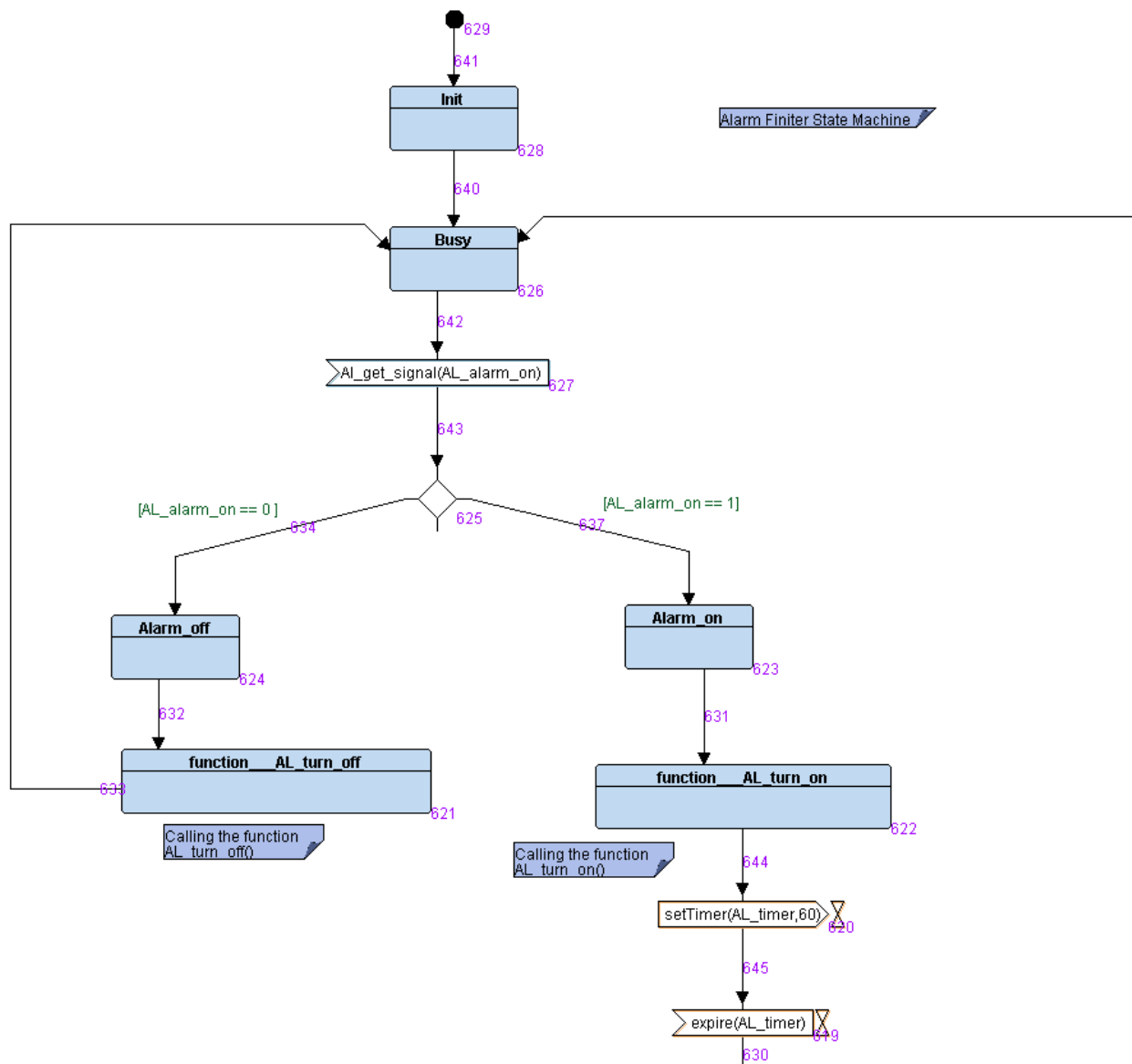
3. Pressure Sensor FSM



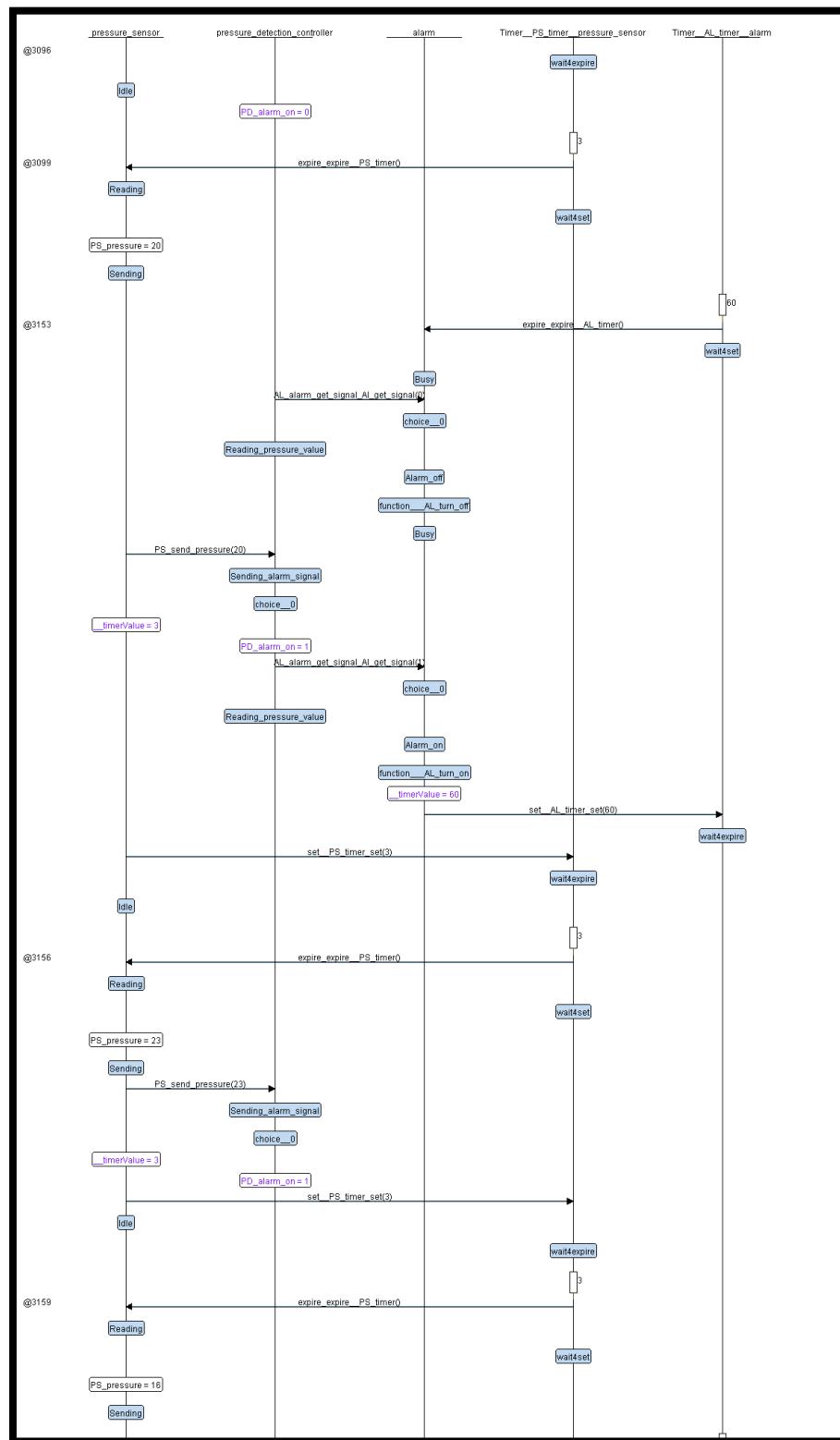
Pressure Sensor Finiter State Machine

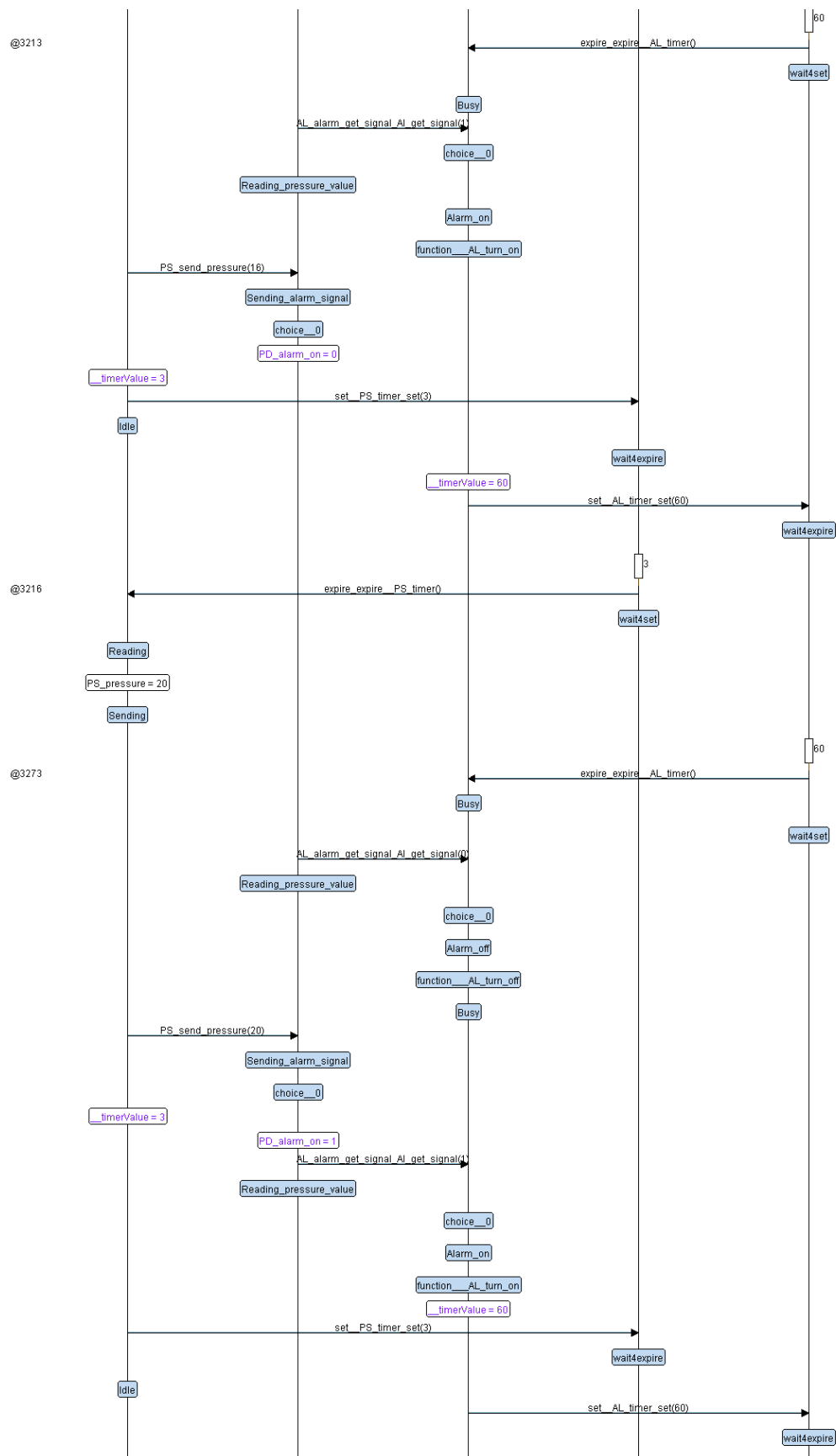
The true value for PS_pressure will be set using
PS_get_pressure()
"PS_pressure = PS_get_pressure();"

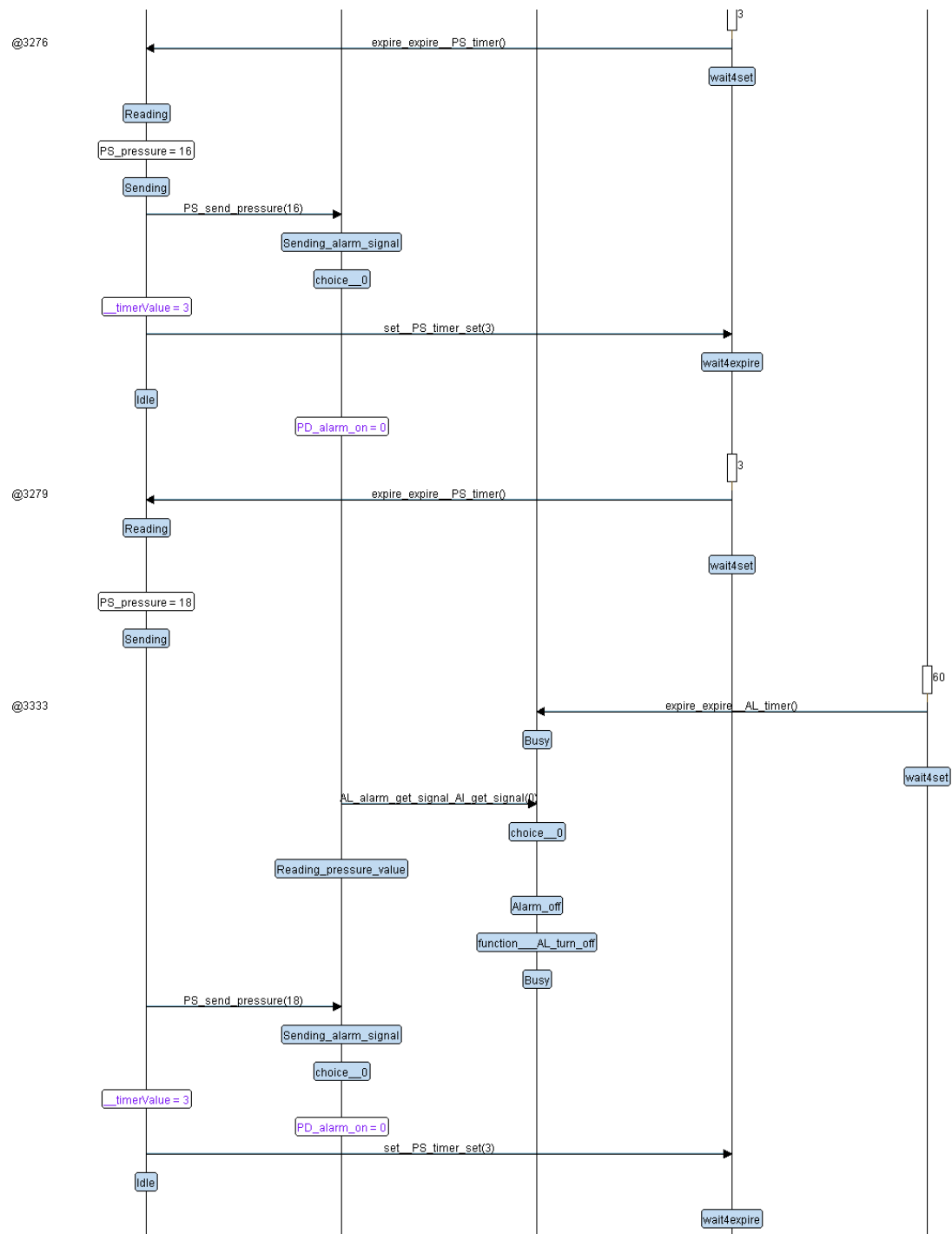
4. Alarm Actuator FSM



6-Verification and Logic

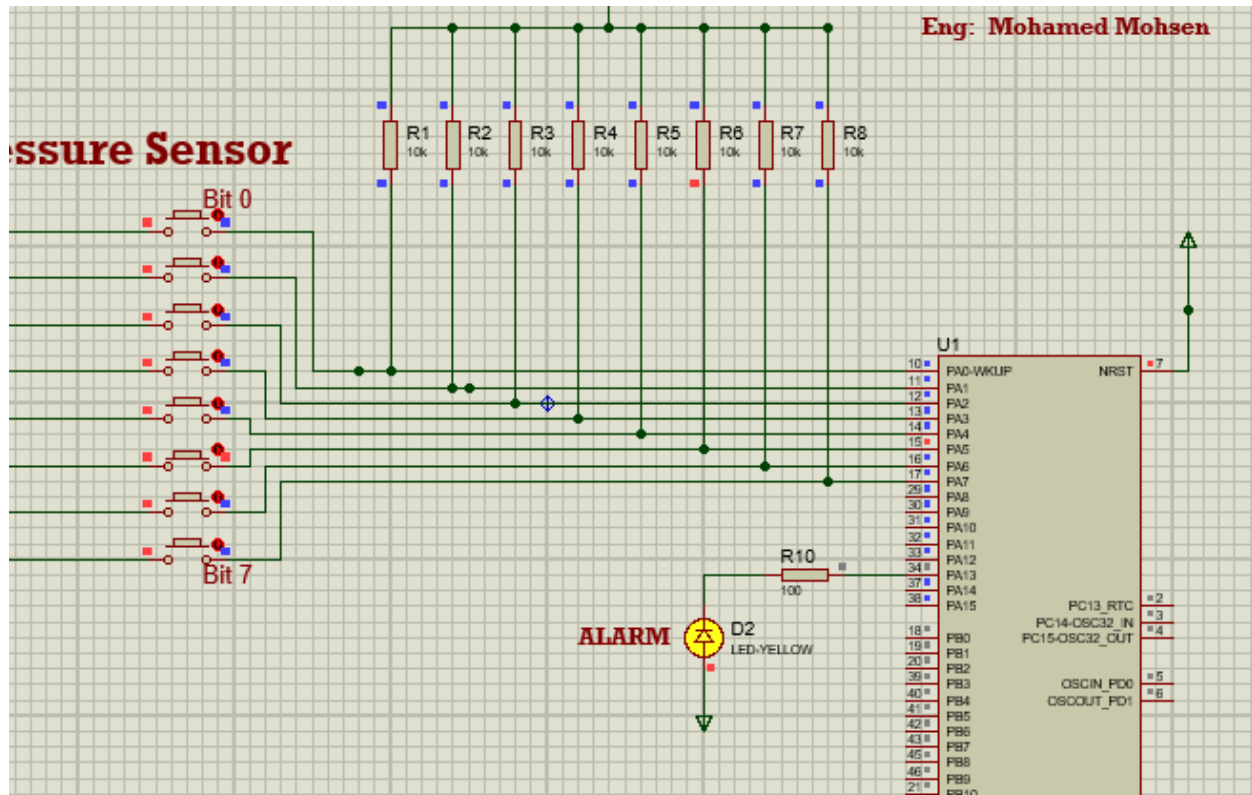




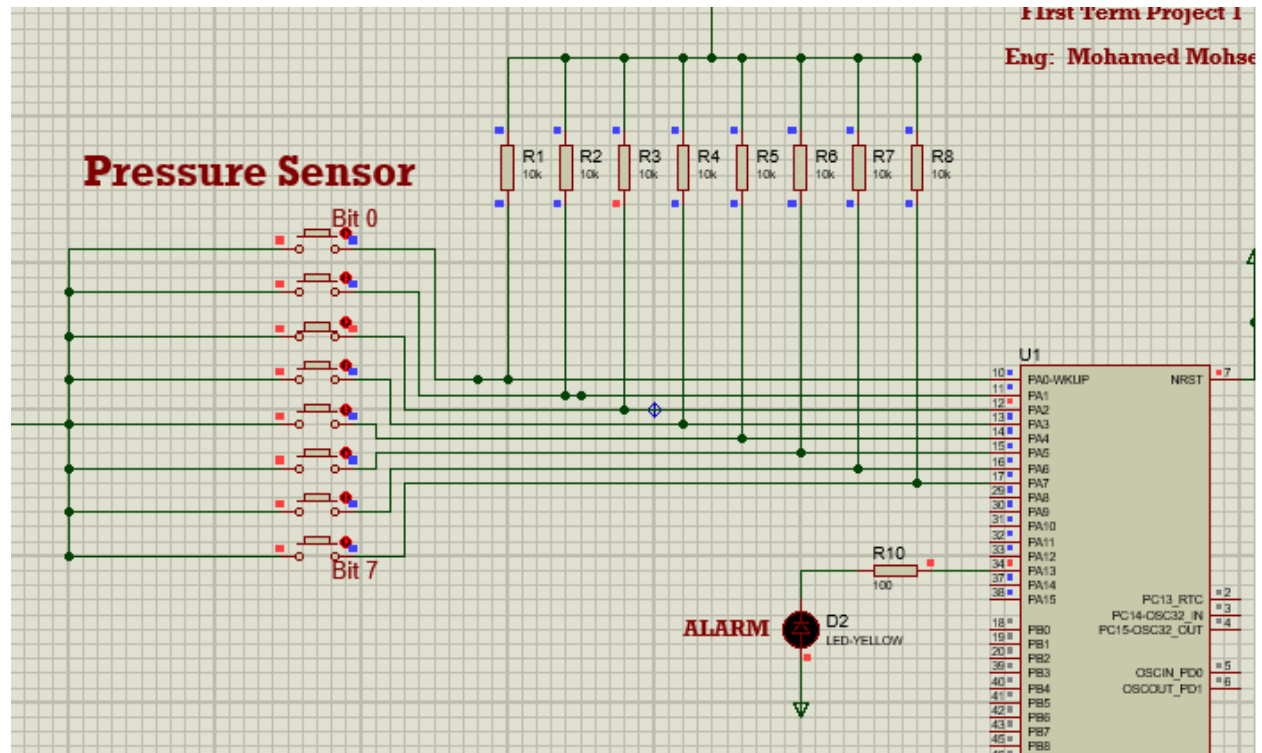


7-Simulation Results

1. Alarm on State



2. Alarm off State



8-Symbols

```
Mohamed@DESKTOP-QJR98KP MINGW64 /g/Git_Repositories/Embedded_Diploma/05_First_Term_Projects/01_Project_1/Code (master)
$ arm-none-eabi-nm alarm.o
00000004 C AL_alarm_sig
00000000 T AL_init
00000004 C AL_state
00000001 C AL_state_id
0000001a T AL_turn_off
0000000c T AL_turn_on
                U Delay
                U Set_Alarm_actuator
0000006c T ST_AL_alarm_off
00000040 T ST_AL_alarm_on
00000028 T ST_AL_busy

Mohamed@DESKTOP-QJR98KP MINGW64 /g/Git_Repositories/Embedded_Diploma/05_First_Term_Projects/01_Project_1/Code (master)
$ arm-none-eabi-nm driver.o
00000000 T Delay
00000020 T getPressureVal
00000074 T GPIO_INITIALIZATION
00000038 T Set_Alarm_actuator

Mohamed@DESKTOP-QJR98KP MINGW64 /g/Git_Repositories/Embedded_Diploma/05_First_Term_Projects/01_Project_1/Code (master)
$ arm-none-eabi-nm pressure_detection_controller.o
00000038 T AL_alarm_get_signal
00000004 C AL_alarm_sig
00000004 C AL_state
00000001 C AL_state_id
00000004 C PD_alarm_sig
00000000 T PD_init
00000004 C PD_pressure
00000004 C PD_pressure_threshold
00000004 C PD_state
00000001 C PD_state_id
0000000c T PS_send_pressure
                U ST_AL_alarm_off
                U ST_AL_alarm_on
00000078 T ST_PD_reading_pressure_value
00000090 T ST_PD_sending_alarm_signal
```



```
Mohamed@DESKTOP-QJR98KP MINGW64 /g/Git_Repositories/Embedded_Diploma/05_First_Term_Projects/01_Project_1/Code (master)
```

```
$ arm-none-eabi-nm pressure_sensor.o
```

```
U Delay
U getPressureVal
00000000 T PS_init
00000004 C PS_pressure
U PS_send_pressure
00000004 C PS_state
00000001 C PS_state_id
00000070 T ST_PS_idle
0000000c T ST_PS_reading
0000003c T ST_PS_sending
```

```
Mohamed@DESKTOP-QJR98KP MINGW64 /g/Git_Repositories/Embedded_Diploma/05_First_Term_Projects/01_Project_1/Code (master)
```

```
$ arm-none-eabi-nm startup.o
```

```
U _E_bss
U _E_data
U _E_text
U _S_bss
U _S_data
U _STACK_TOP
00000000 W Bus_Fault
00000000 T Default_Handler
00000000 W H_fault_Handler
U main
00000000 W MM_Fault_Handler
0000000c T Reset_Handler
00000000 W Usage_Fault_Handler
00000000 D vectors
```