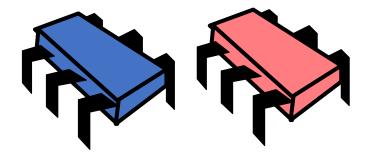
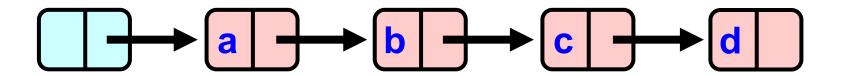
# CSE113: Parallel Programming

#### • Topics:

Concurrent general set





### Announcements

• HW 4 submission by tomorrow.

### Announcements

• HW 5 will be released on this week.

#### Announcements

SETs are out, please do them! It helps us out a lot.

The C++ relaxed memory order provides

- no orderings at all
- orderings only between accesses of the same address
- TSO memory behaviors when run on an x86 system
- o an easy way to accidentally introduce horrible bugs into your program

## Relaxed memory order

language C++11 (sequential consistency)

S

L

S

NO	NO
NO	NO

language C++11 (memory\_order\_relaxed)

. S

different different address

different different address address

basically no orderings except for accesses to the same address

The C++ relaxed memory order provides

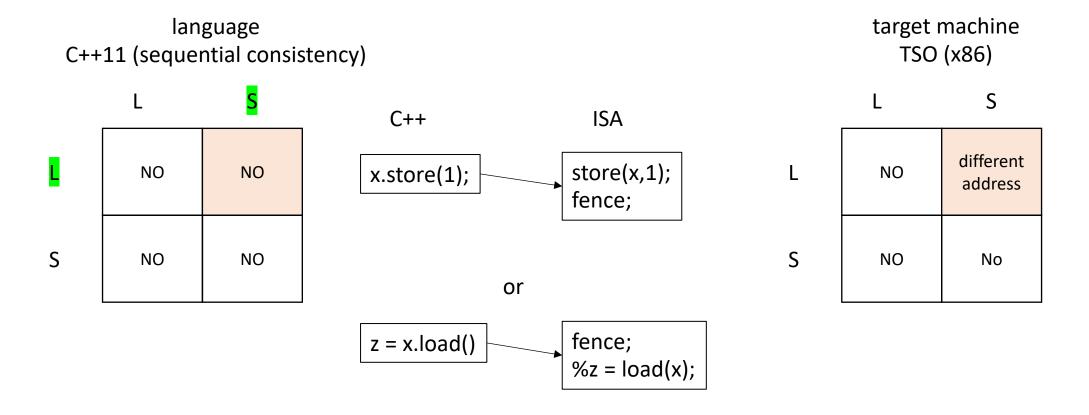
- no orderings at all
- orderings only between accesses of the same address
  - TSO memory behaviors when run on an x86 system
  - o an easy way to accidentally introduce horrible bugs into your program

In terms of memory models, the compiler needs to ensure the following property:

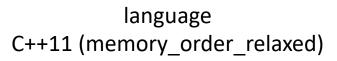
- Any weak behavior allowed in the language is also allowed in the ISA
- O Any weak behaviors that are disallowed in the language need to be disallowed in the ISA
- The compilation ensures that the program has sequentially consistent behavior at the ISA level
- The compiler does not need to reason about relaxed memory

## C++11 atomic operation compilation

start with both of the grids for the two different memory models



# Compiling memory order relaxed



L S

different address address

S different address different address

lots of mismatches!

But language is more relaxed than machine

so no fences are needed

S

target machine TSO (x86)

. S

NO	different address
NO	No

In terms of memory models, the compiler needs to ensure the following property:

- O Any weak behavior allowed in the language is also allowed in the ISA
- -> Any weak behaviors that are disallowed in the language need to be disallowed in the ISA
  - The compilation ensures that the program has sequentially consistent behavior at the ISA level
  - The compiler does not need to reason about relaxed memory

A program that uses mutexes and has no data conflicts does not have weak memory behaviors for which of the following reasons?

- Mutexes prevent memory accesses from happening close enough in time for weak behaviors to occur
- O The OS has built in support for Mutexes that disable architecture features, such as the store buffer
- A correct mutex implementation uses fences in lock and unlock to disallow weak behaviors

A program that uses mutexes and has no data conflicts does not have weak memory behaviors for which of the following reasons?

- Mutexes prevent memory accesses from happening close enough in time for weak behaviors to occur
- O The OS has built in support for Mutexes that disable architecture features, such as the store buffer
- -> A correct mutex implementation uses fences in lock and unlock to disallow weak behaviors

Assuming you had a sequentially consistent processor, any C/++ program you ran on it would also be sequentially consistent, regardless of if there are data-conflicts or not.

○ True

False

Assuming you had a sequentially consistent processor, any C/++ program you ran on it would also be sequentially consistent, regardless of if there are data-conflicts or not.

○ True

-> () False

In addition to processor, the compiler can reorder instruction as well.

If you put a fence after every memory instruction, would that be sufficient to disallow all weak behaviors on a weak architecture? Please write a few sentences explaining your answer.

If you put a fence after every memory instruction, would that be sufficient to disallow all weak behaviors on a weak architecture? Please write a few sentences explaining your answer.

It is sufficient but makes execution slower.

## General Concurrent Set

#### Set Interface

- Unordered collection of items
- No duplicates

• We will implement set as a sorted linked list.

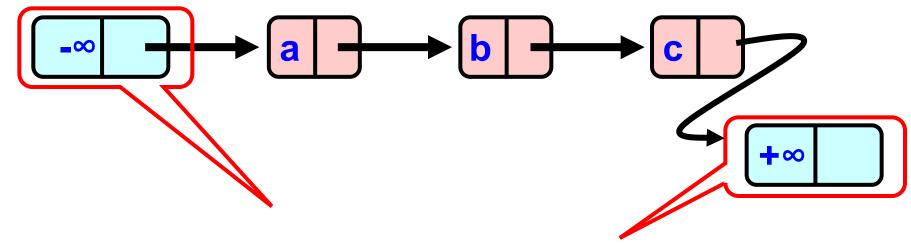
#### Set Interface

- Methods
  - add (x) put x in set
  - remove (x) take x out of set
  - contains (x) tests if x in set

### List Node

```
class Node {
  public:
    Value v;
    int key;
    Node *next;
}
```

#### The List-Based Set



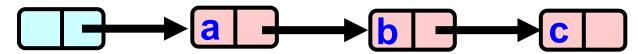
Sorted with Sentinel nodes (min & max possible keys)

# Sequential List Based Set

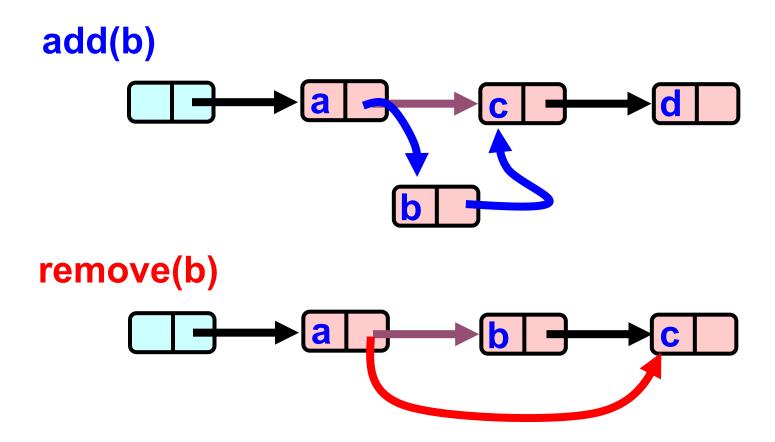
#### add(b)



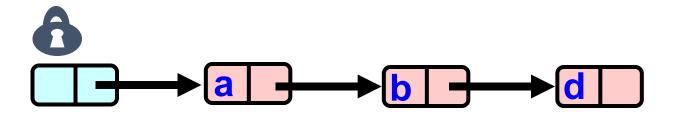
#### remove(b)



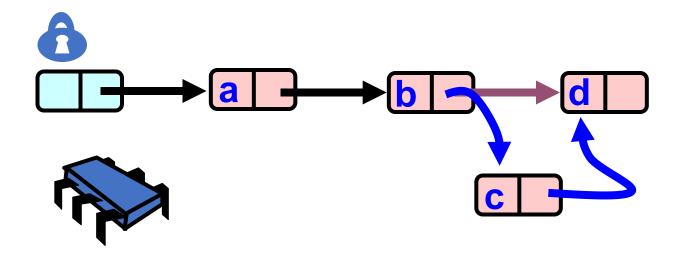
# Sequential List Based Set



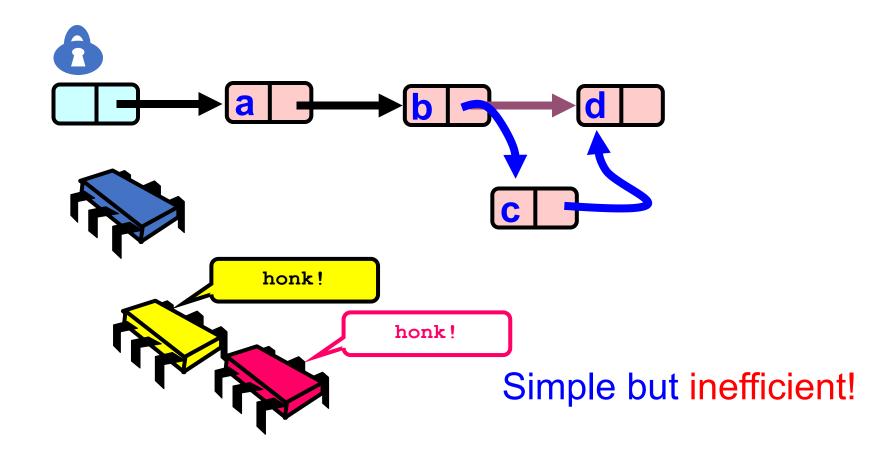
# Coarse-Grained Locking



# Coarse-Grained Locking



# Coarse-Grained Locking

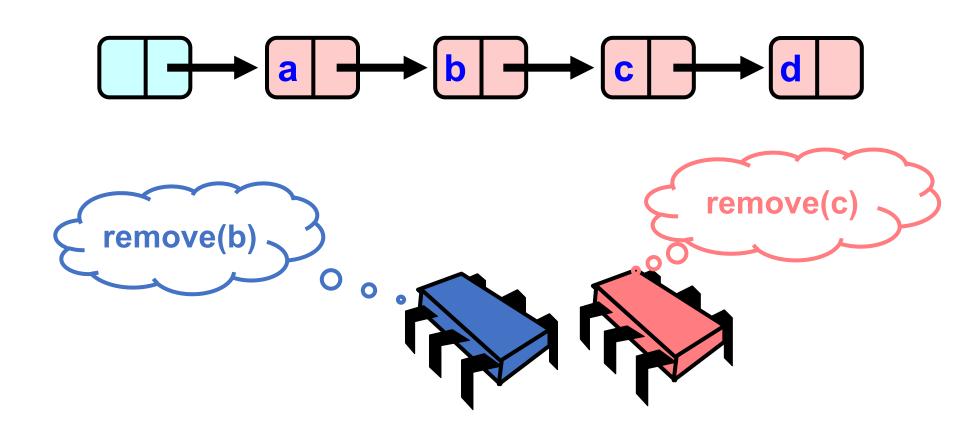


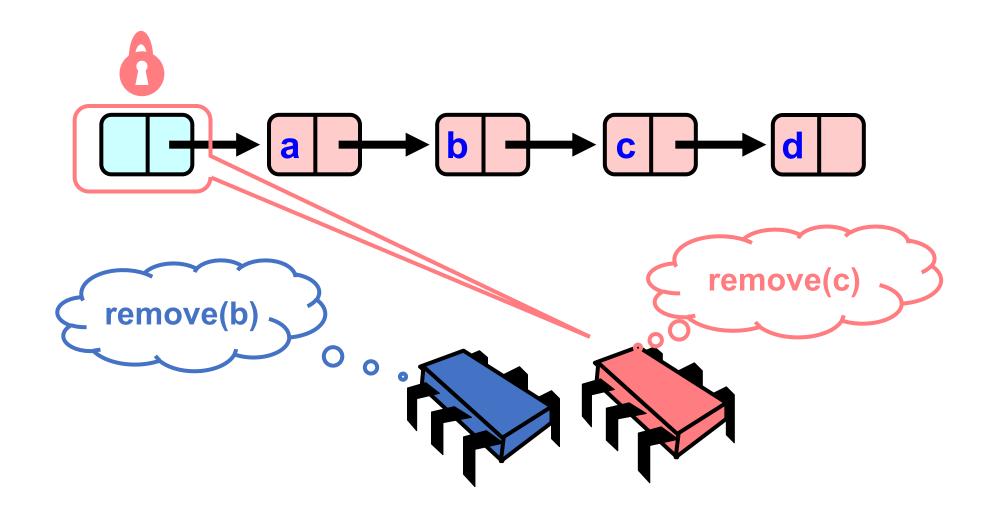
### Schedule

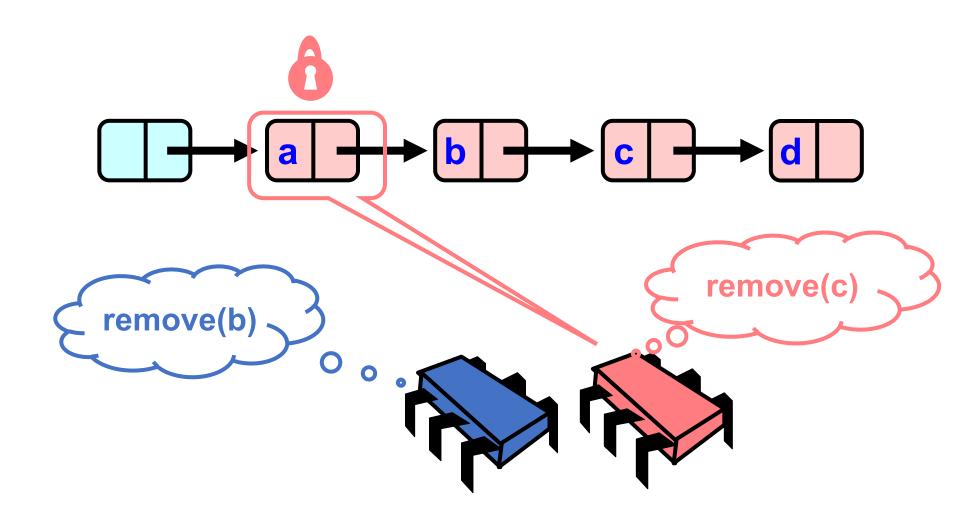
- Concurrent set
  - Coarse-grained lock
  - fine-grained lock
  - optimistic locking

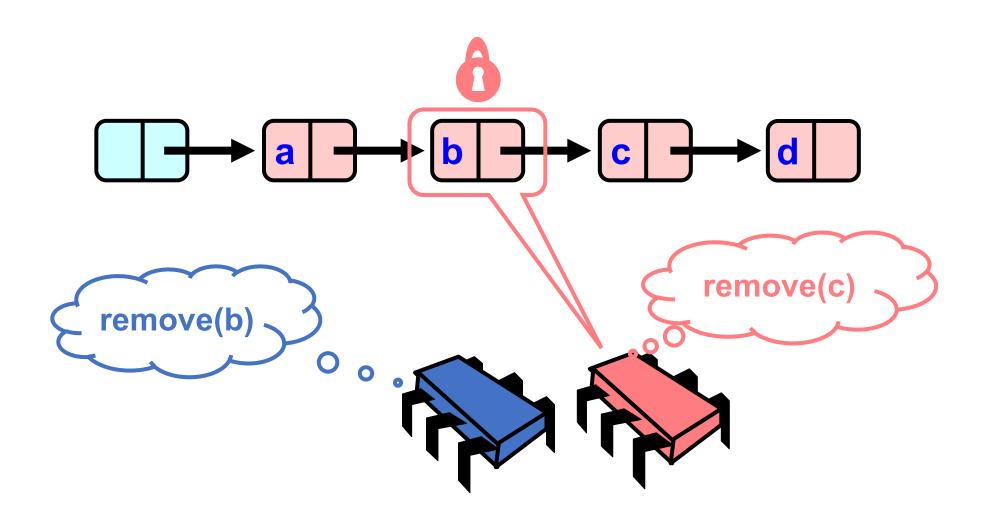
## Fine-grained Locking

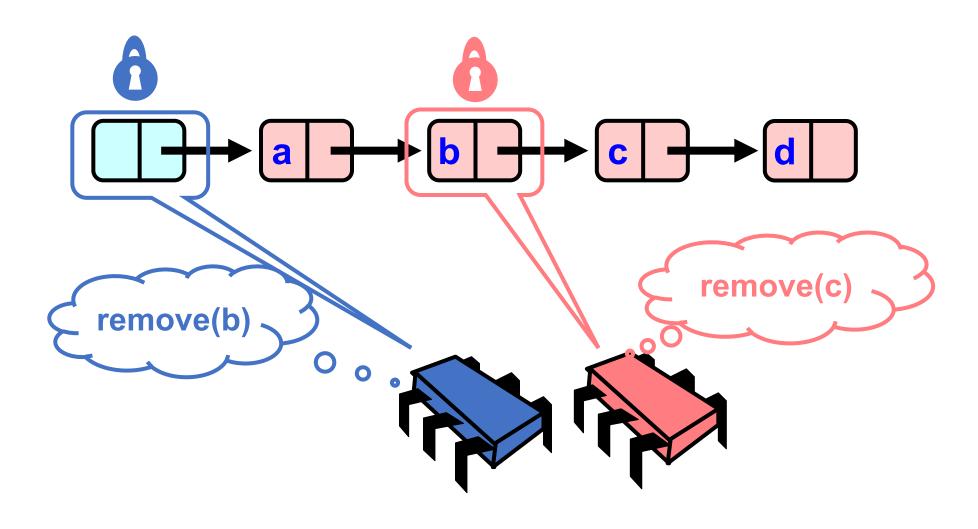
- Split object into pieces
  - Each piece has own lock
  - Methods that work on disjoint pieces need not exclude each other
- Requires careful thought
  - Acquire all required locks
  - Acquire them in the same order

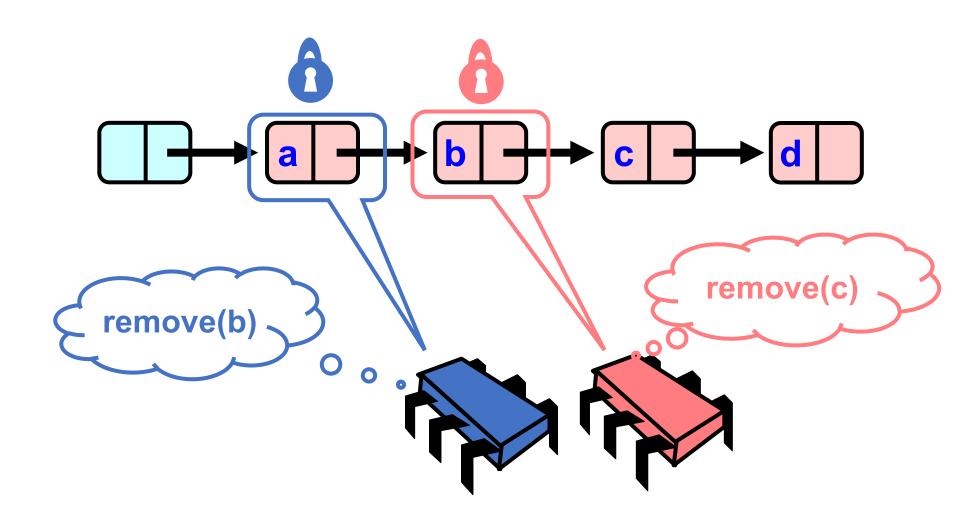




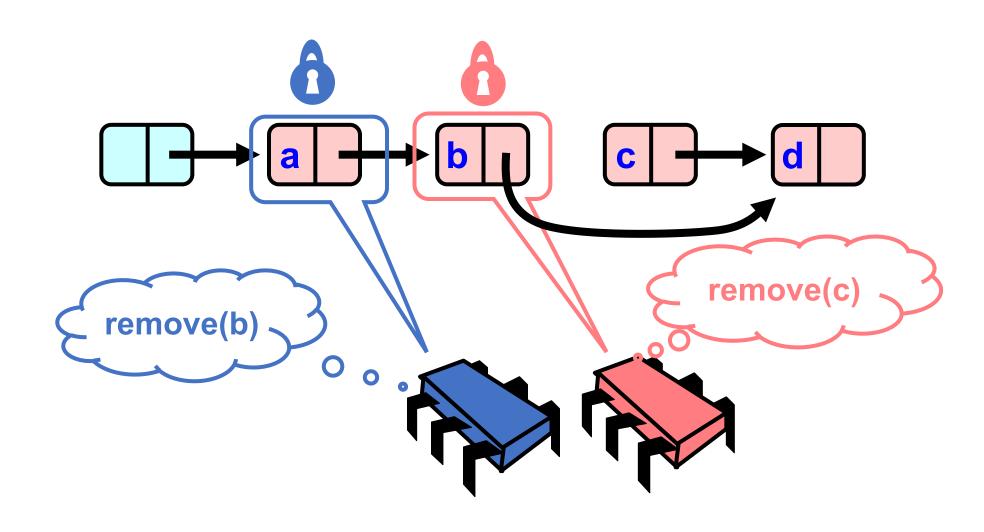




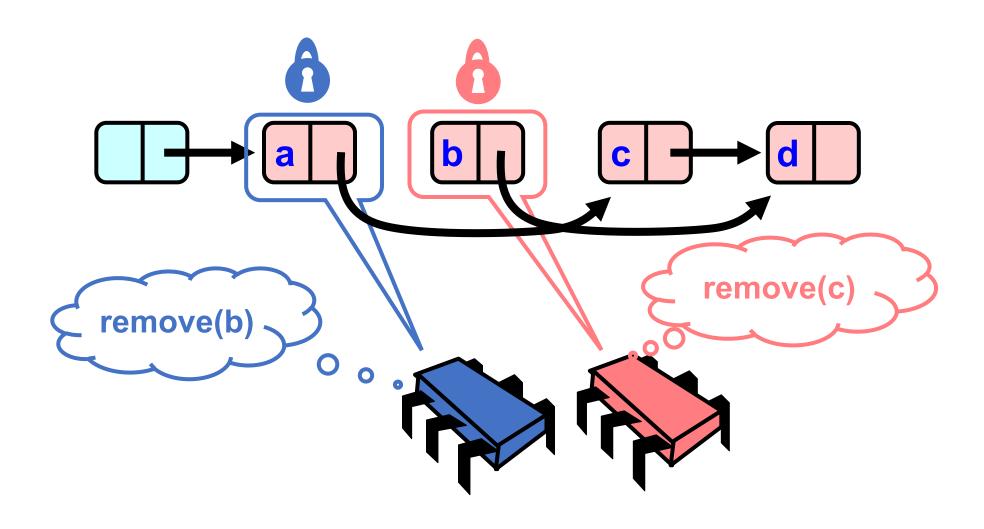




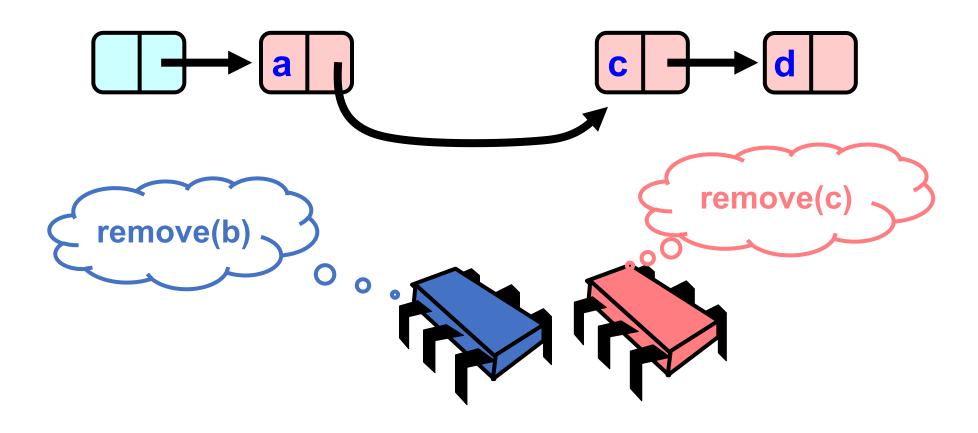
#### Concurrent Removes



#### Concurrent Removes

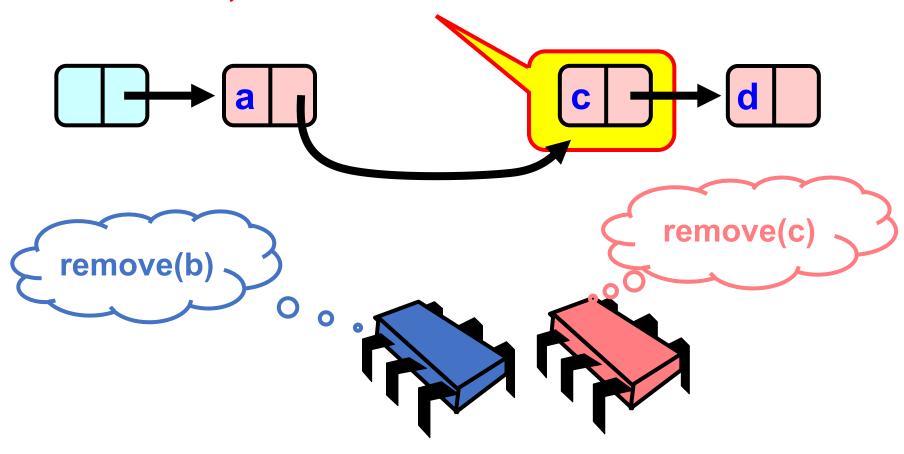


# Uh, Oh



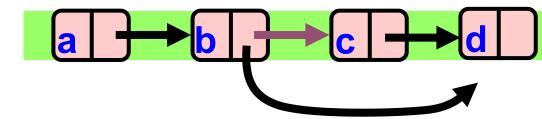
### Uh, Oh

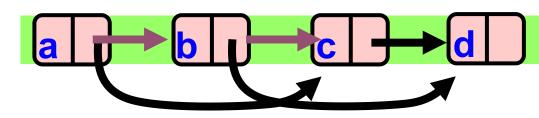
#### Bad news, c not removed

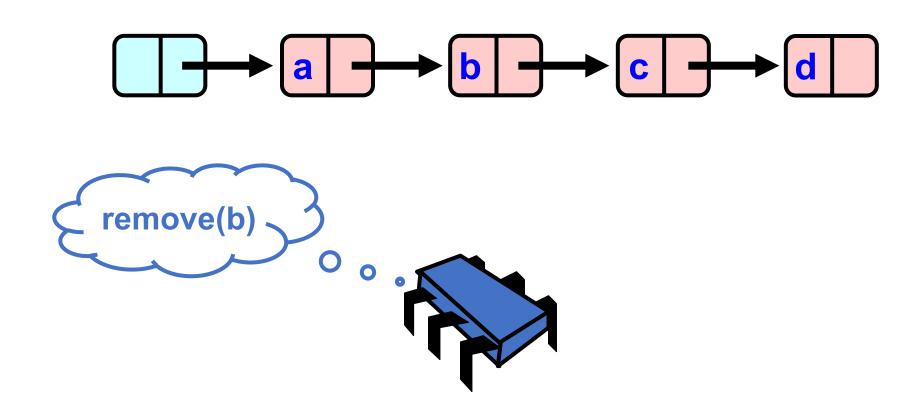


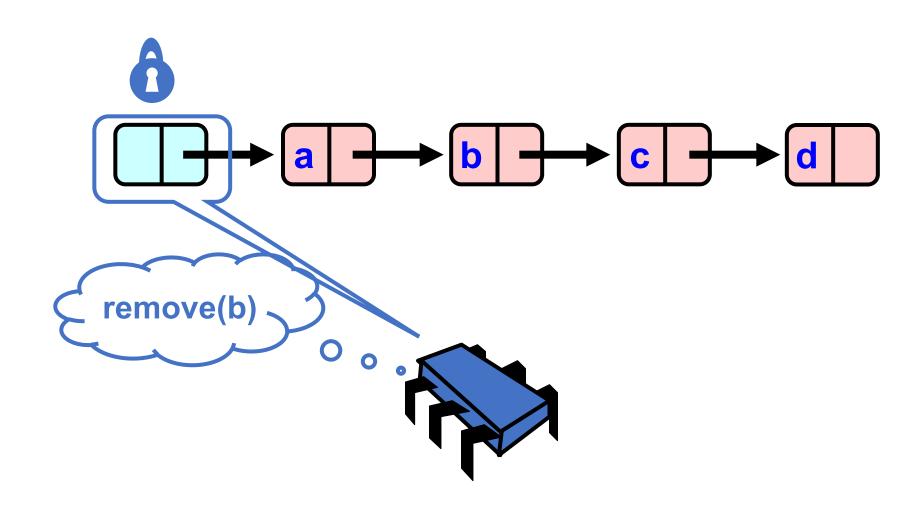
#### Problem

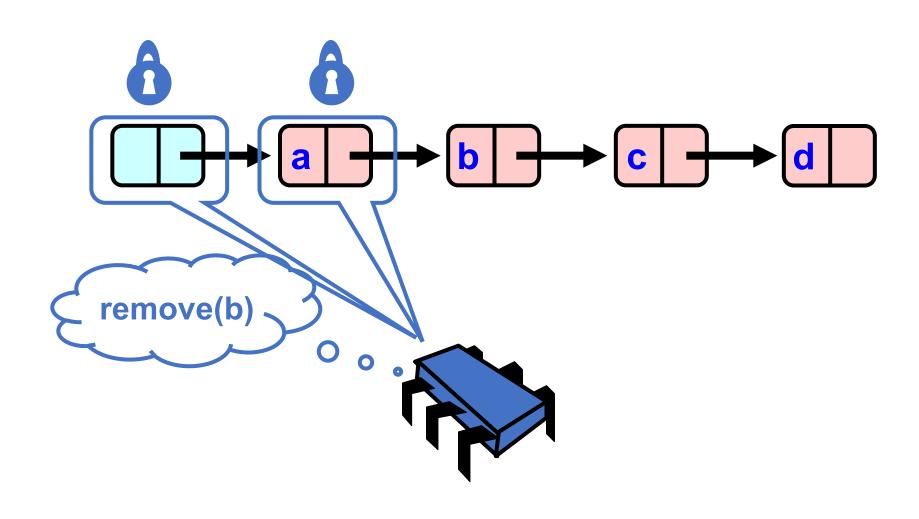
- To delete node c
  - Swing node b's next field to d
- Problem is,
  - Someone deleting b concurrently could direct a pointer to C

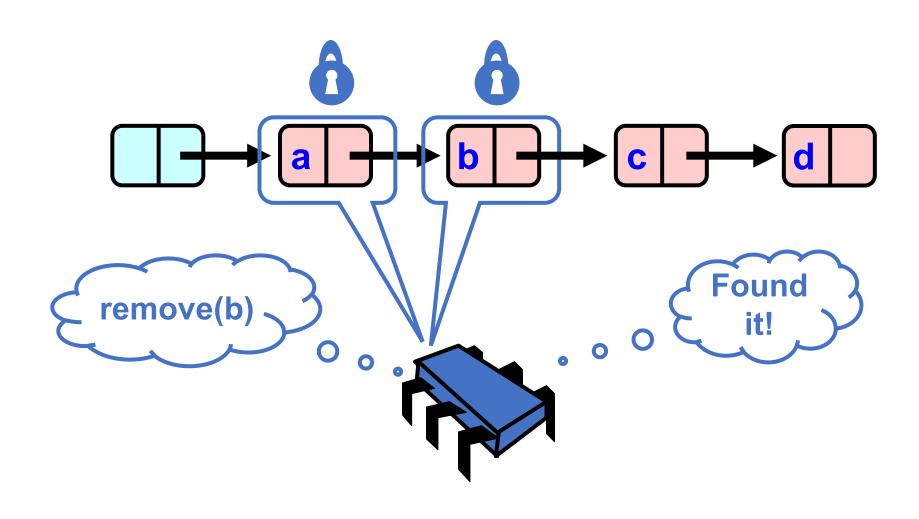


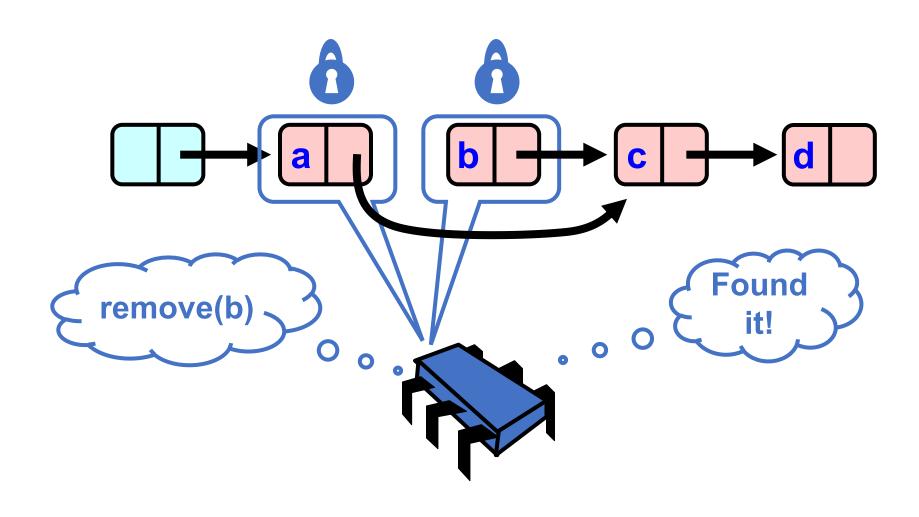


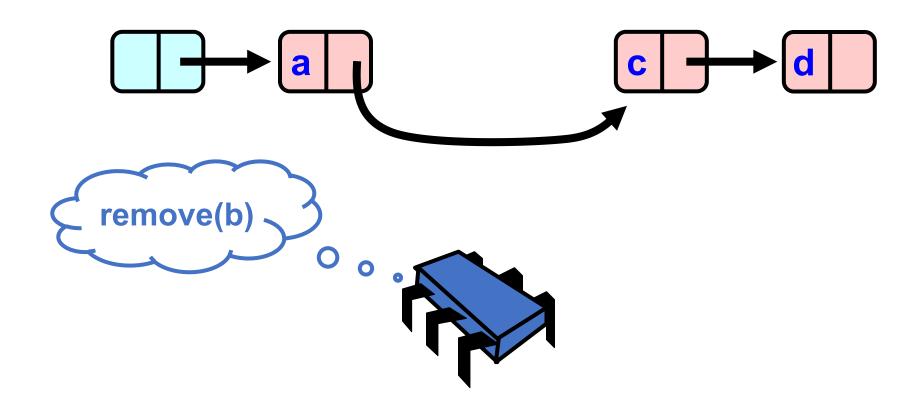


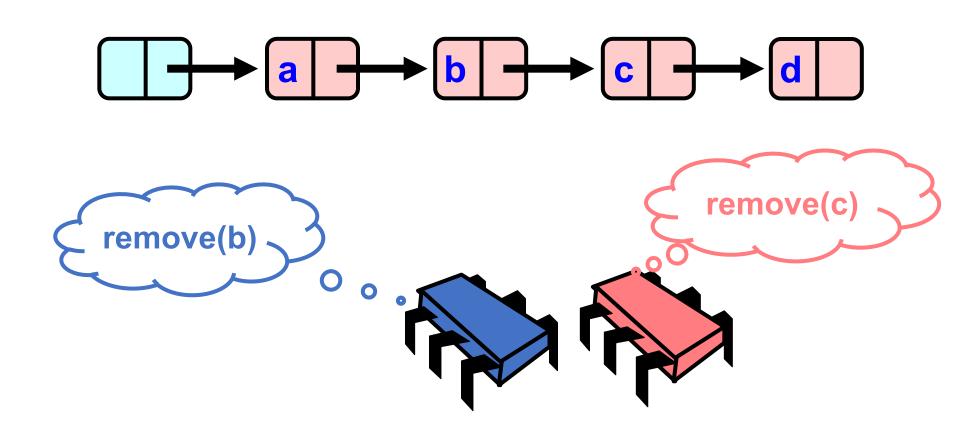


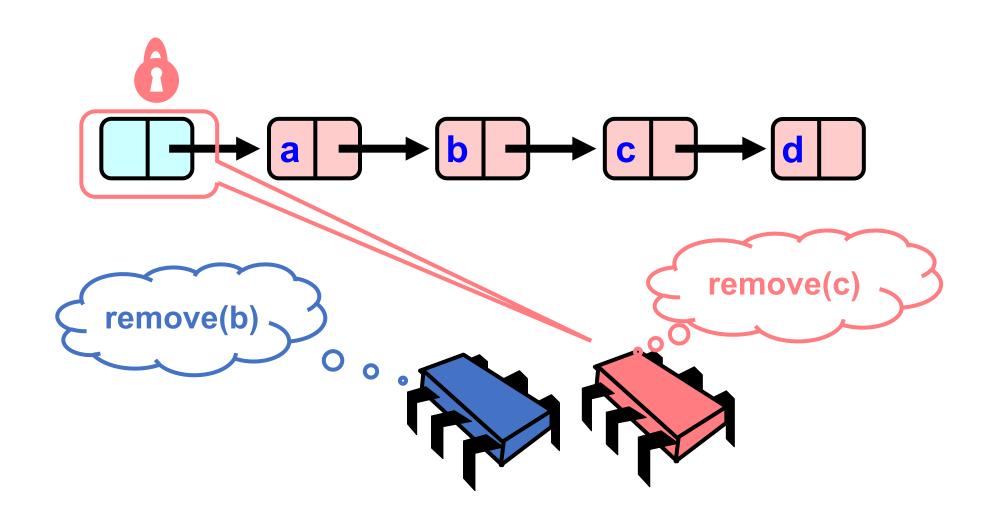


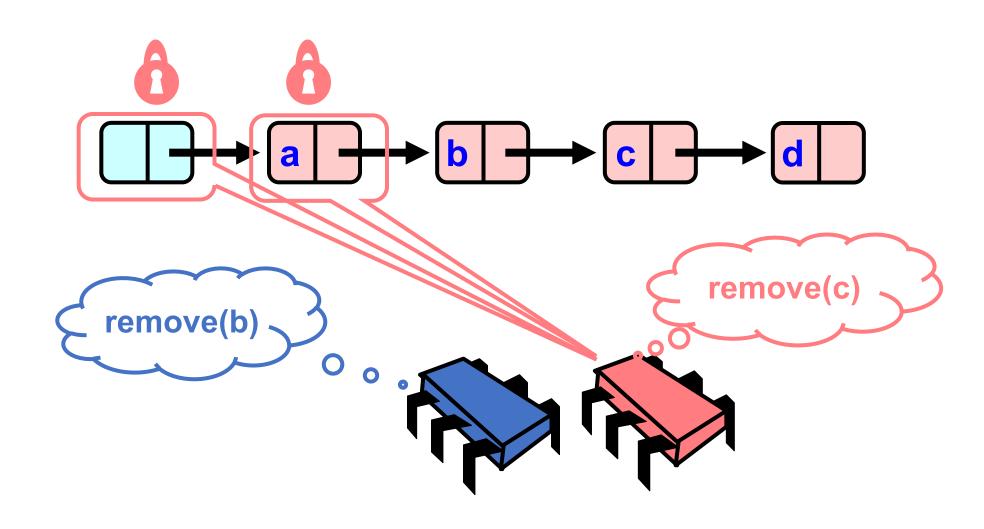


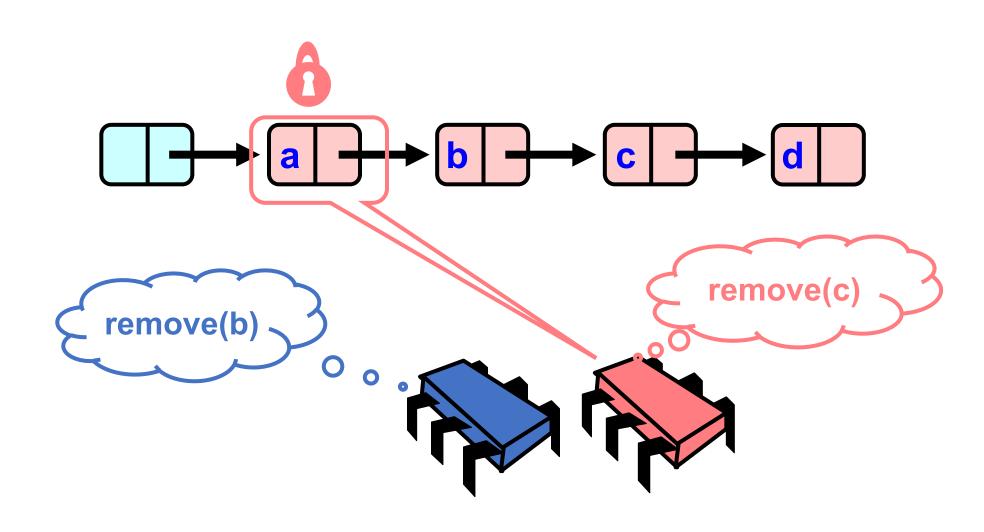


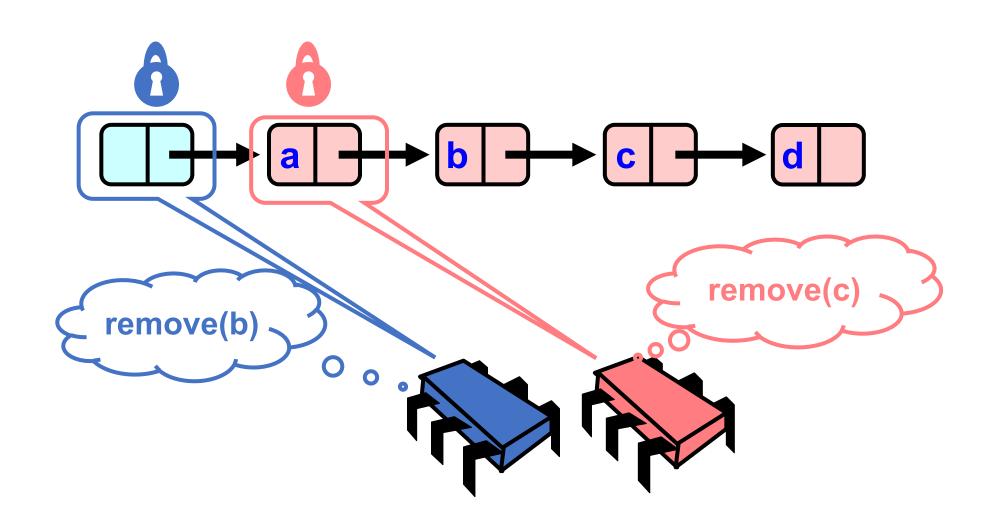


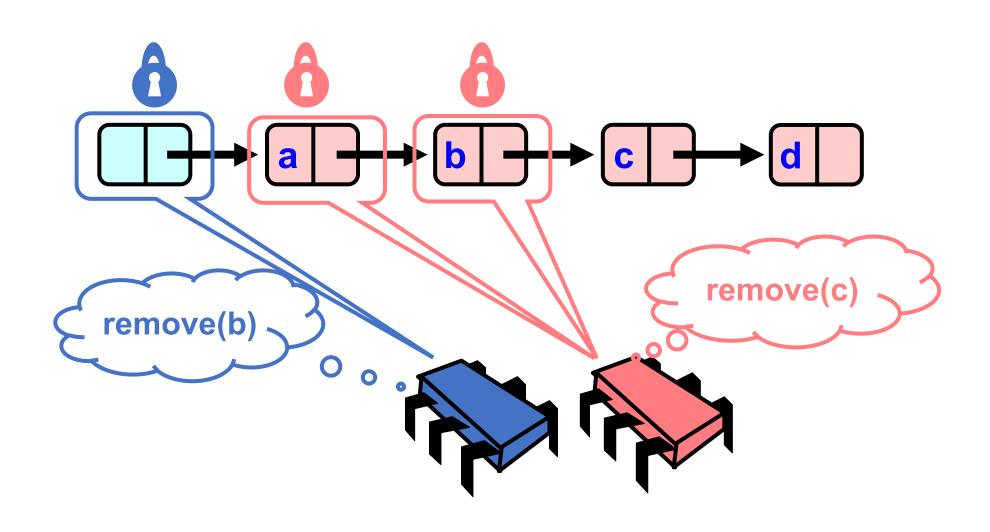


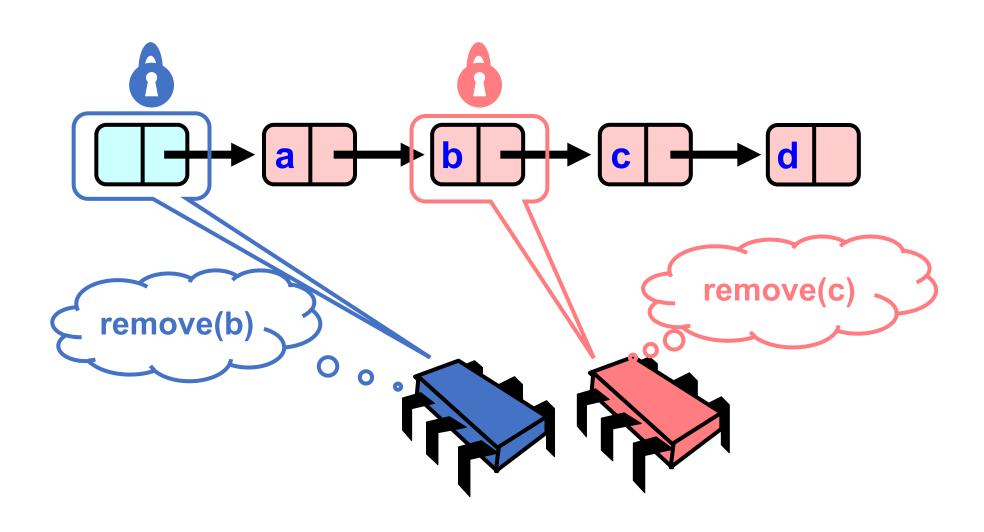


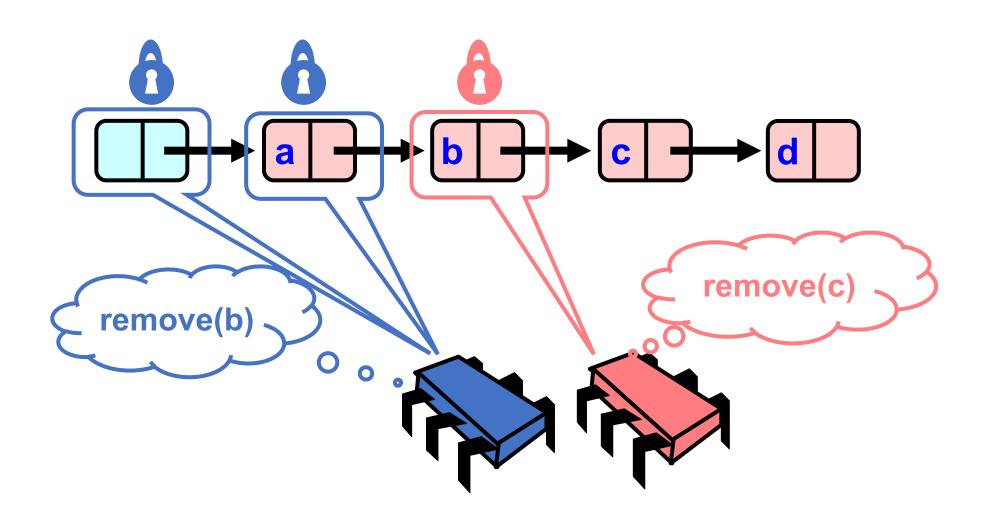


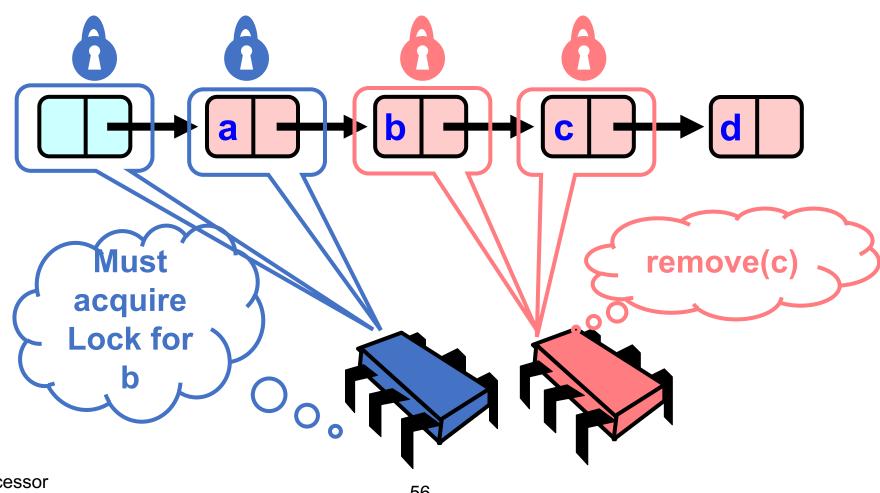




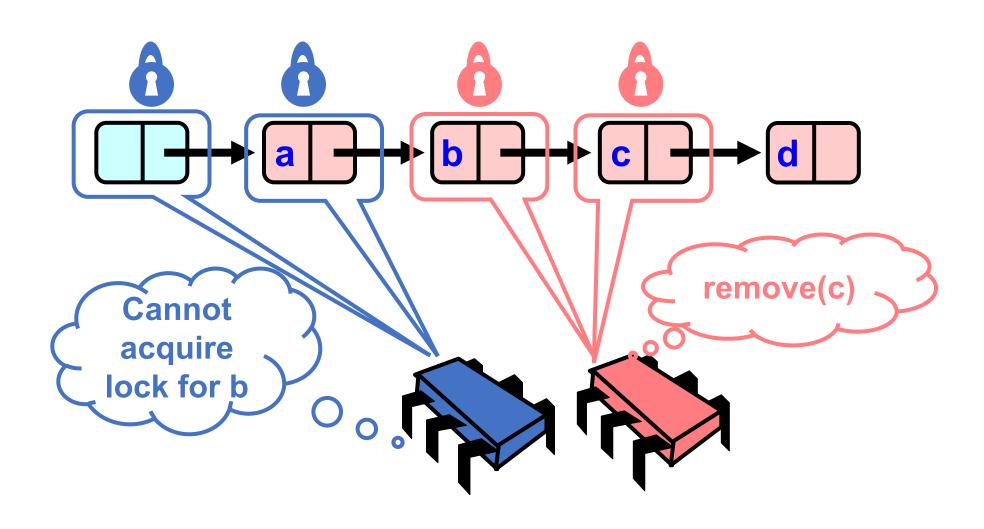


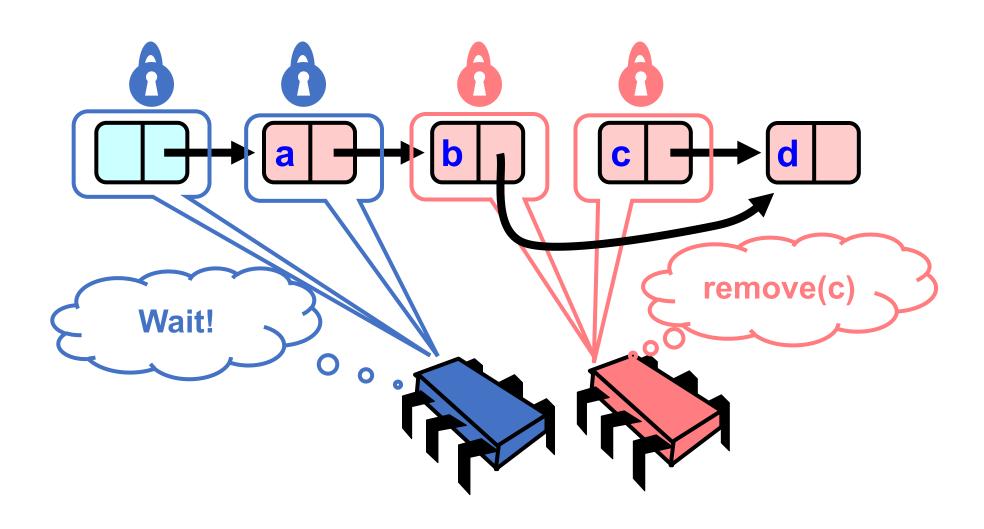


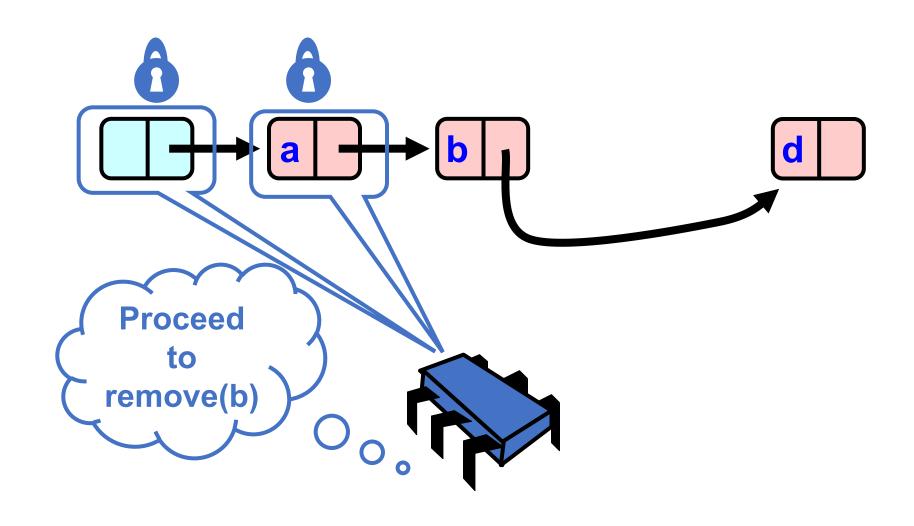


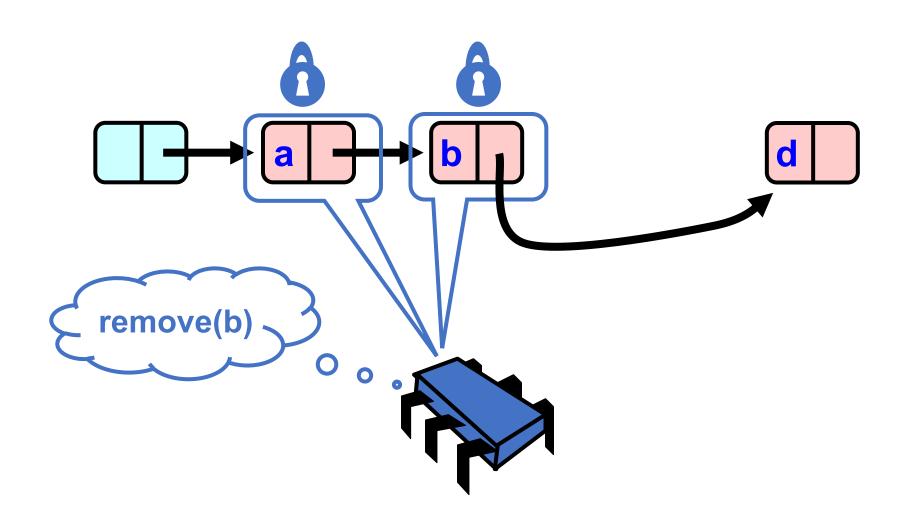


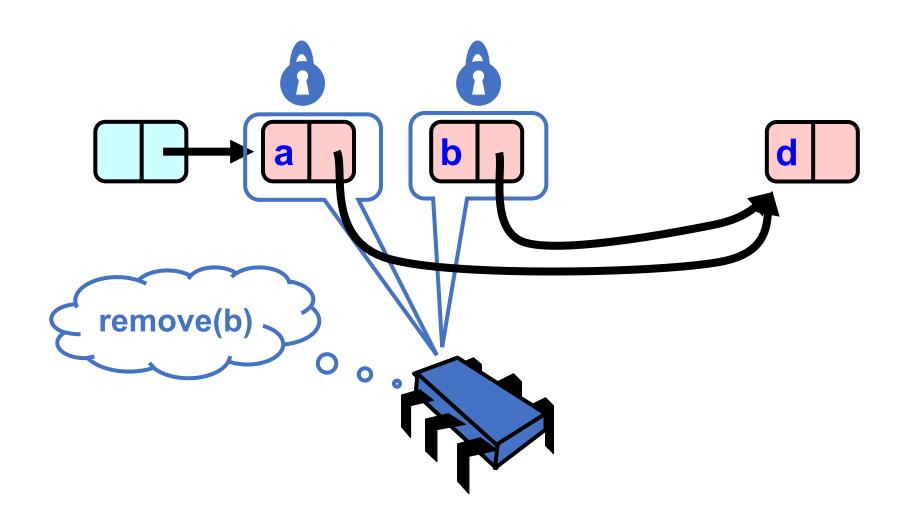
Art of Multiprocessor Programming

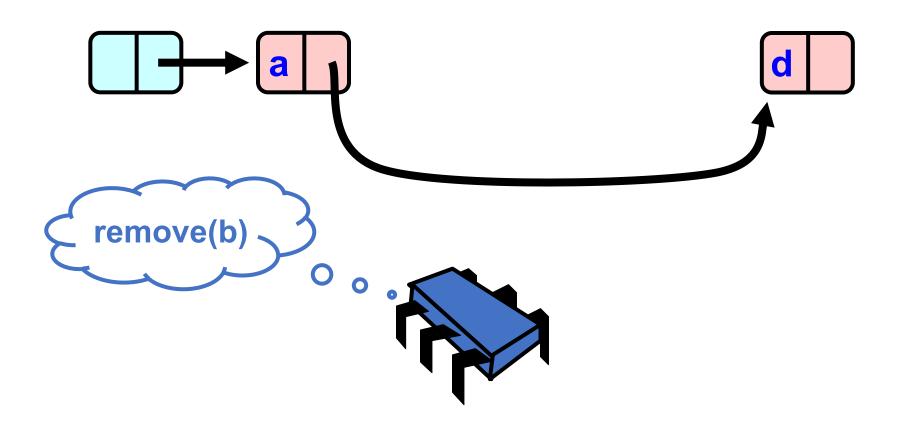


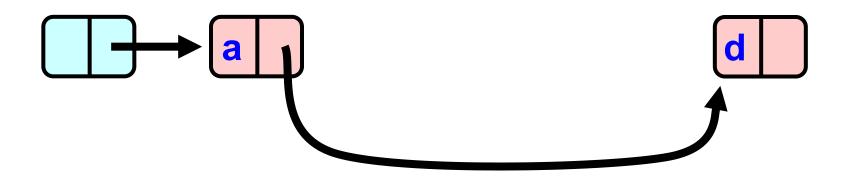












#### Adding Nodes

- Similar hand-over-hand locking
- To add node e
  - Must lock predecessor
  - Must lock successor
- Neither can be deleted

#### Drawbacks of fine-grained locking

- Better than coarse-grained lock
  - Threads can traverse in parallel
- Still not ideal
  - Acquires and releases lock for every node traversed.
     Long chain of acquire/release.
  - Reduces concurrency (traffic jams). Inefficient.

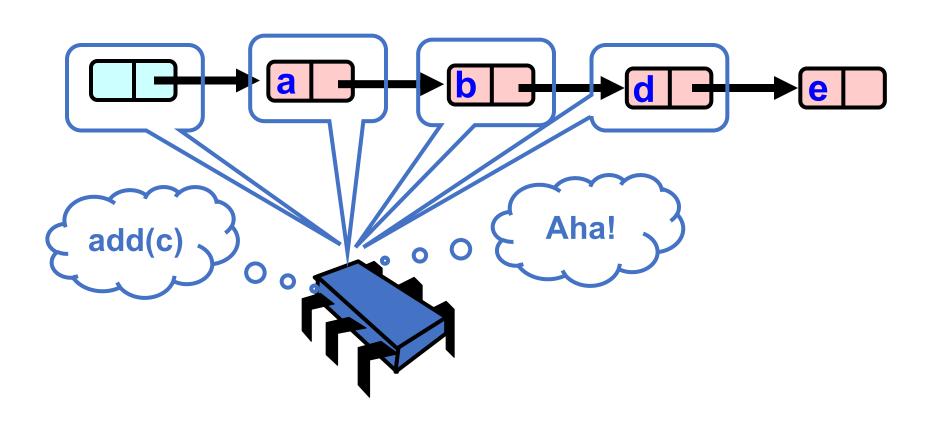
- Assume there will be no conflicts.
- Check before committing.
- If there was a conflict, try again.

• Find nodes without locking. Then, lock the two nodes.

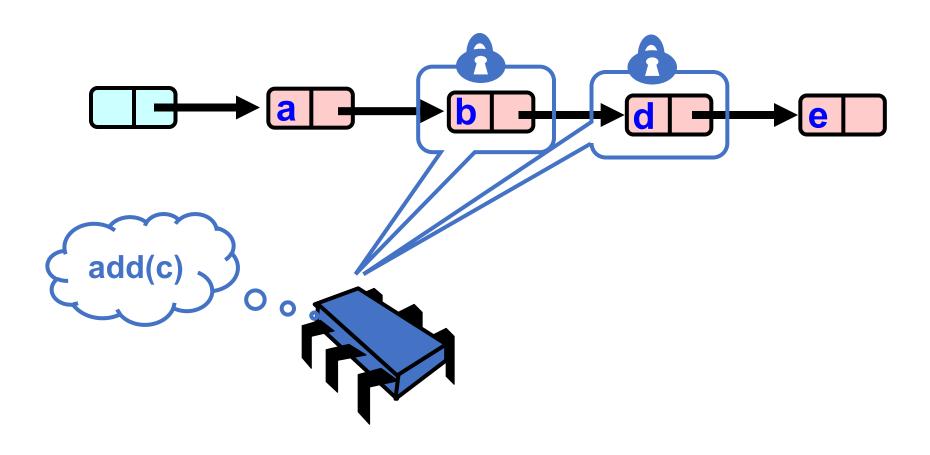
- Find nodes without locking. Then, lock the two nodes.
- Check that the two nodes area still reachable.

- Find nodes without locking. Then, lock the two nodes.
- Check that the two nodes area still reachable.
- If they are not, search again from the beginning of the list.

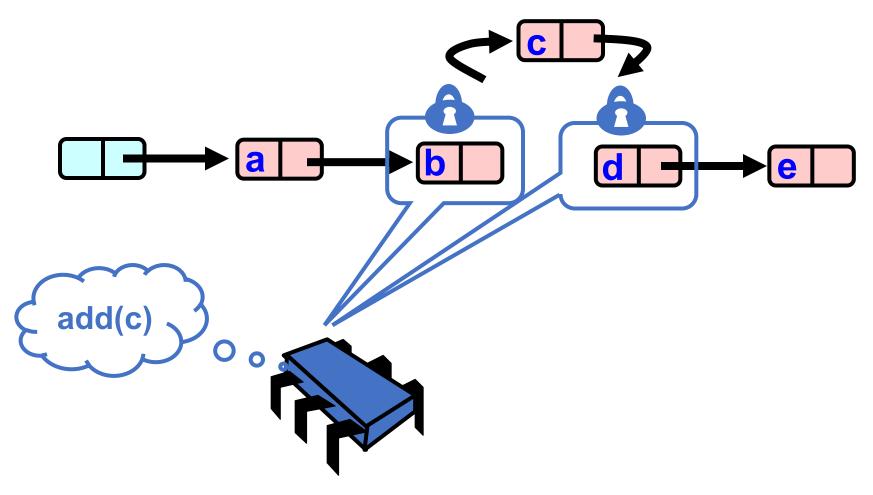
#### Optimistic: Traverse without Locking

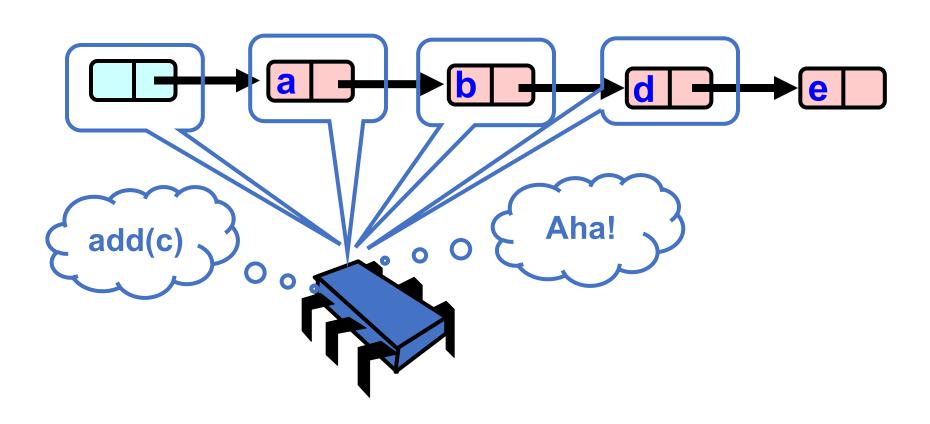


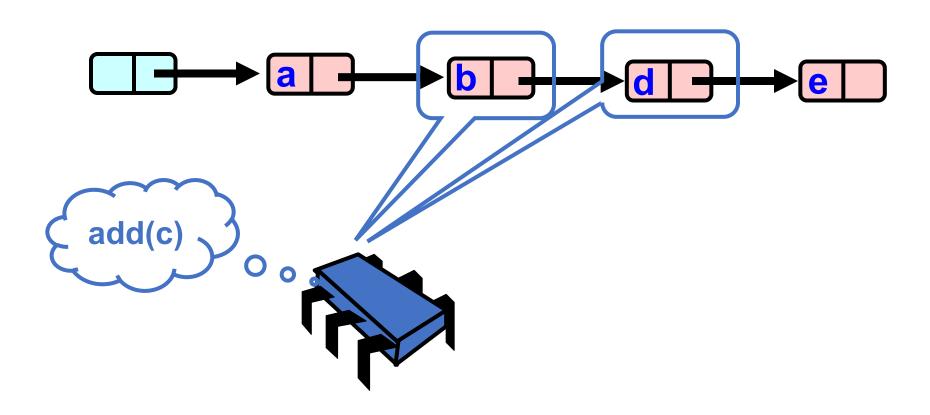
# Optimistic: Lock

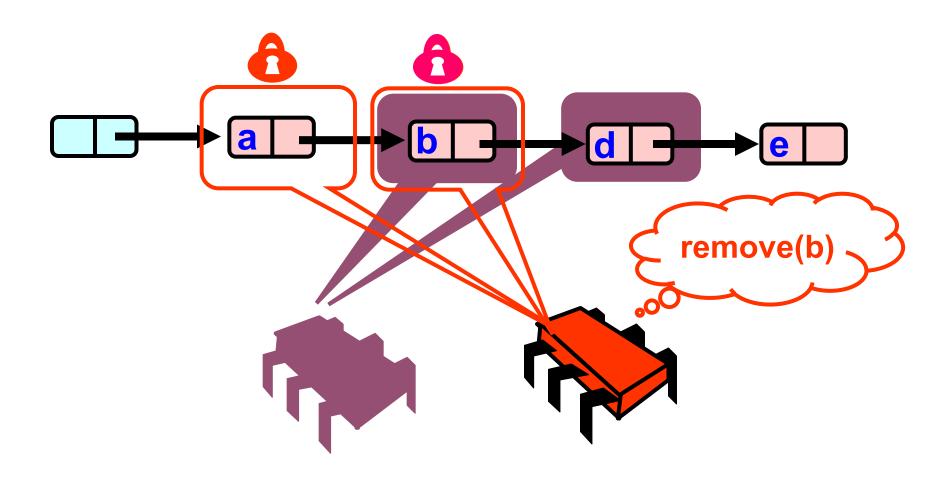


### Optimistic: Insert without checking









# Data conflict (Race)!

- Red thread has the lock on a node (so it can modify the node)
- Blue thread is traversing without locks

• What do we do?

• We can use atomic variables

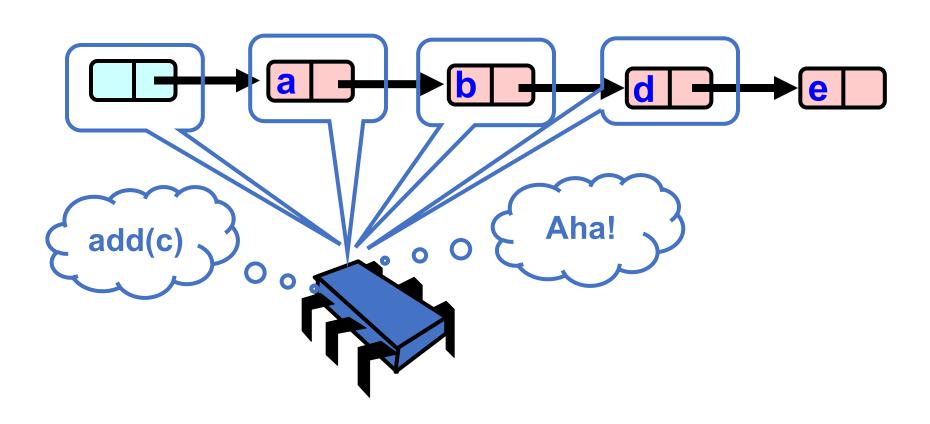
```
class Node {
  public:
    Value v;
    int key;
    Node *next;
}
```

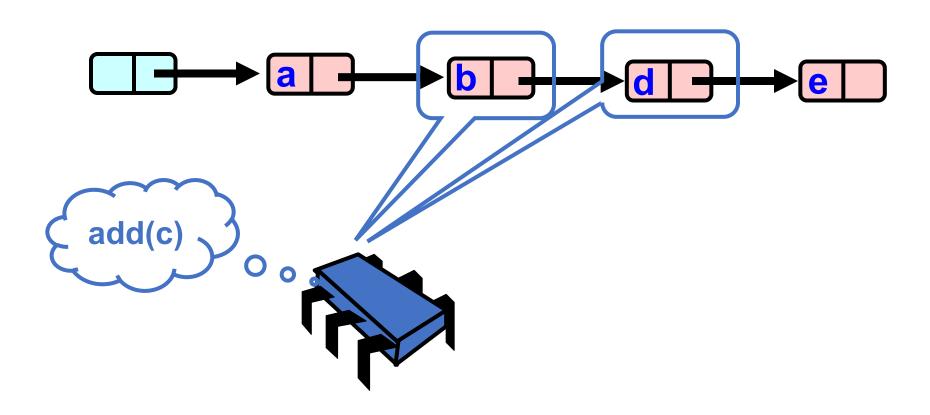
```
class Node {
  public:
    Value v;
    int key;
    atomic<Node*> next;
}
```

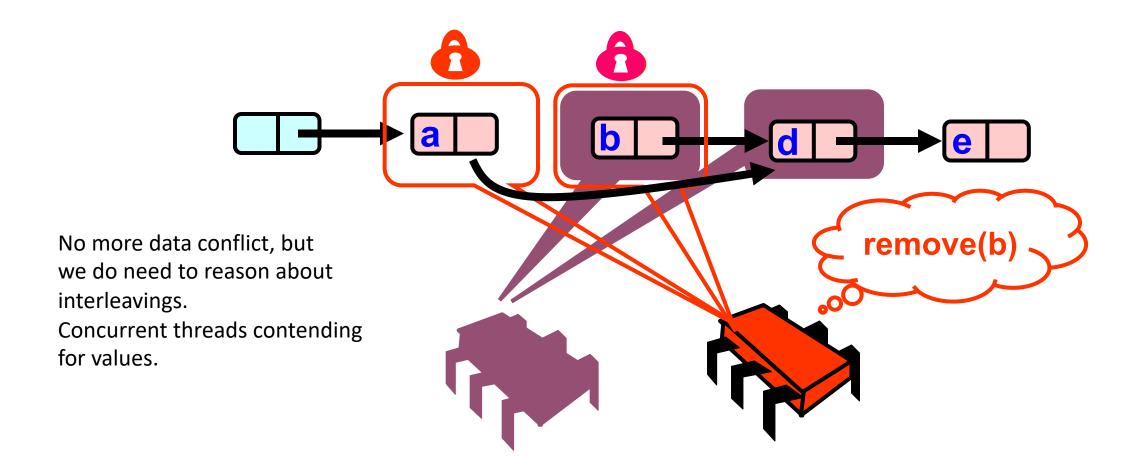
Create an atomic pointer type using C++ templates

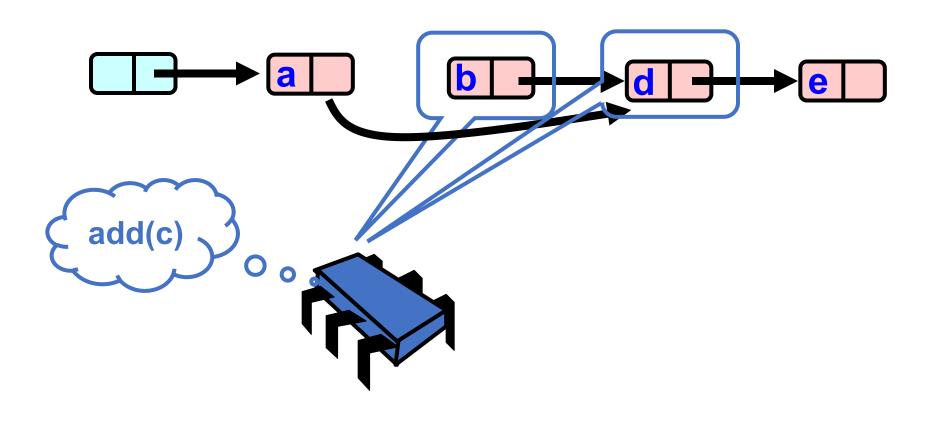
```
void traverse(node *n) {
  while (n->next != NULL) {
    n = n->next;
  }
}
```

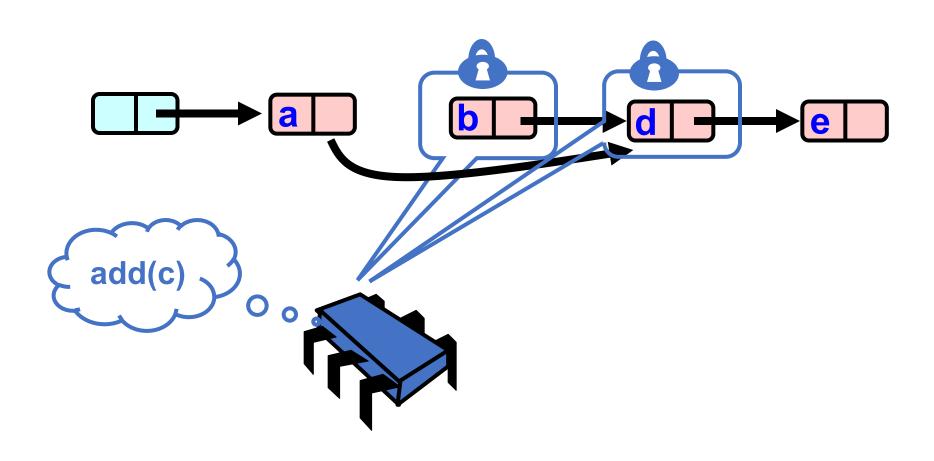
```
void traverse(node *n) {
  while (n->next.load() != NULL) {
    n = n->next.load();
  }
}
```

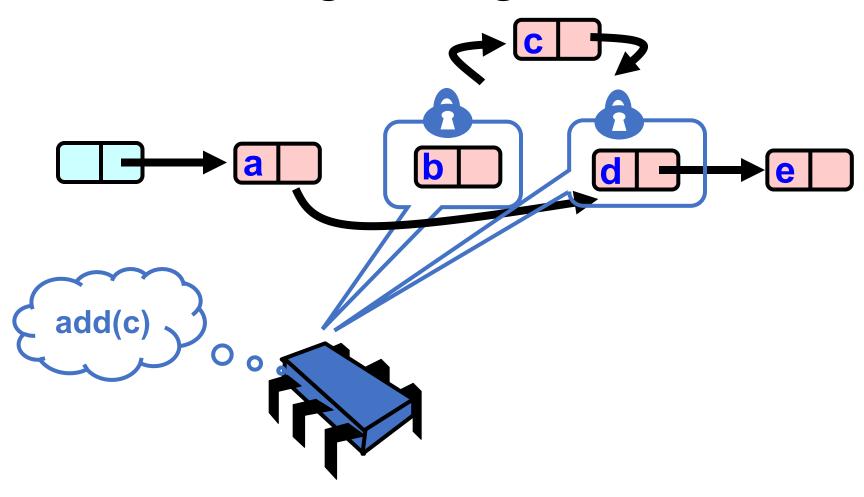


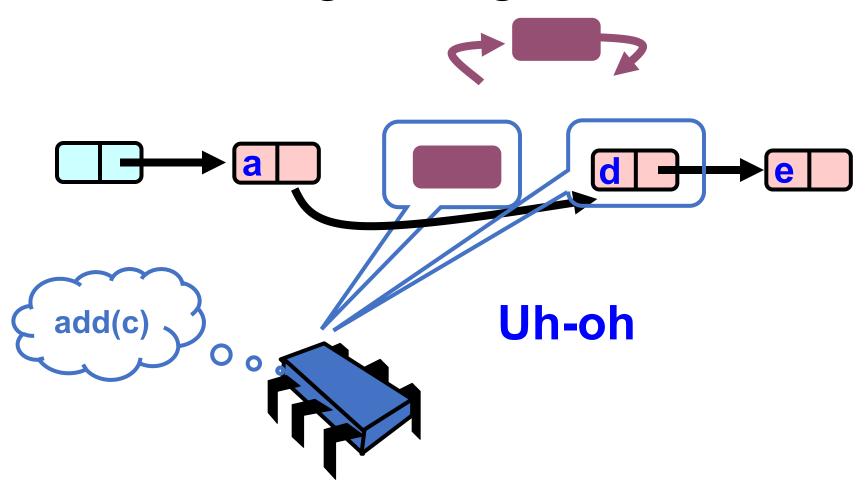




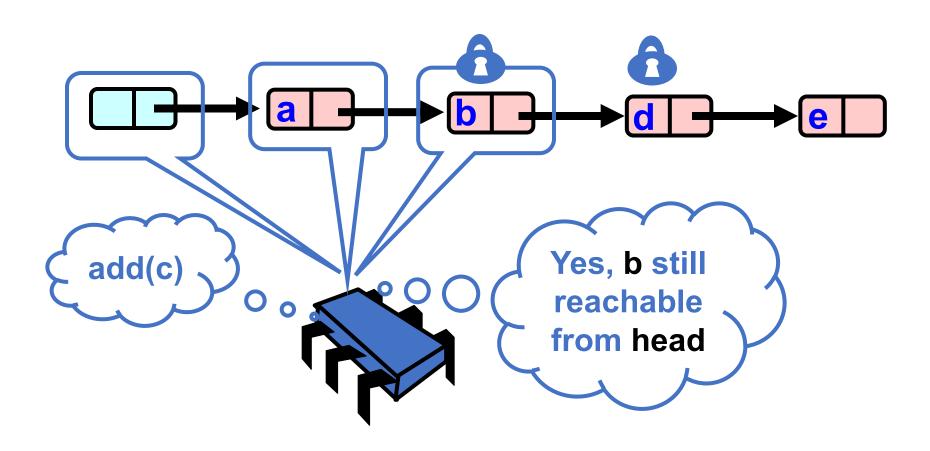








#### Validate – Part 1



# What happens if failure?

• Ideas?

# What happens if failure?

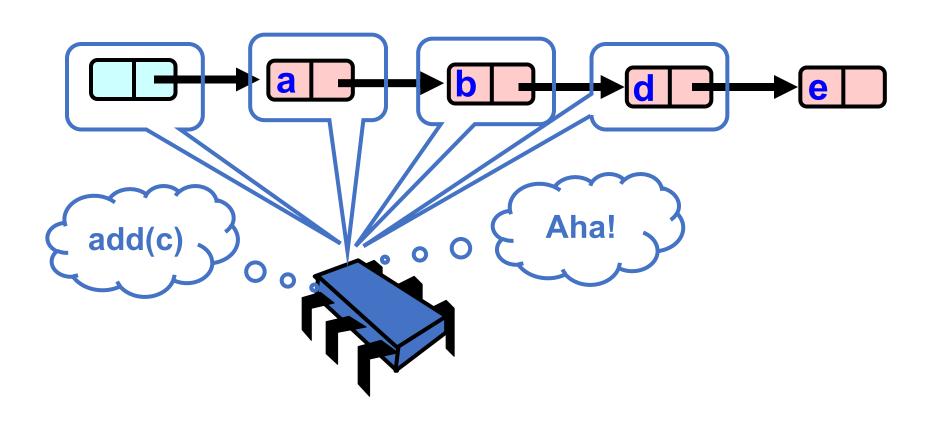
- Could try to recover? Back up a node?
  - Very tricky!
  - Just start over!

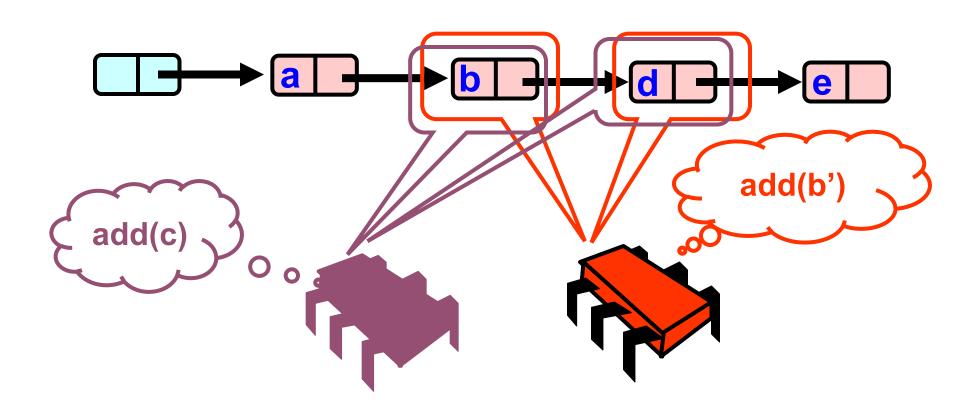
# What happens if failure?

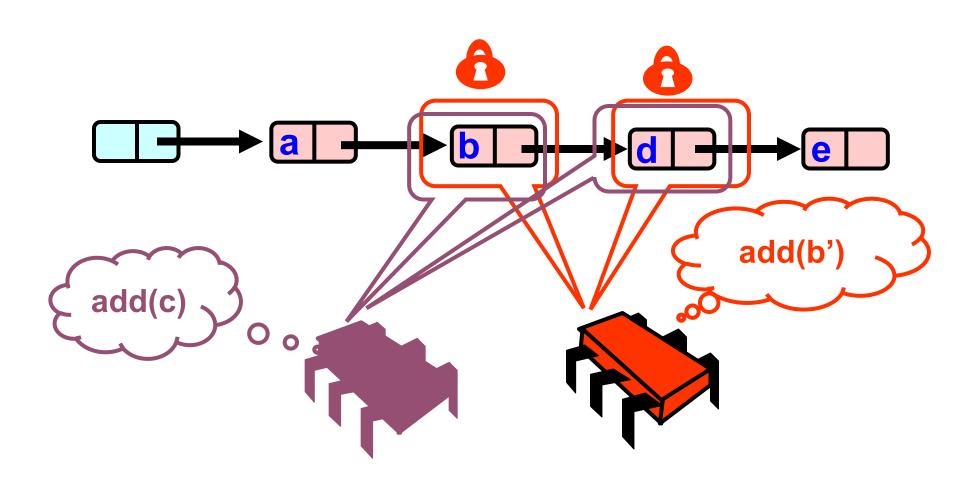
- Could try to recover? Back up a node?
  - Very tricky!
  - Just start over!
- Private method:
  - try\_remove
  - remove loops on try\_remove until it succeeds

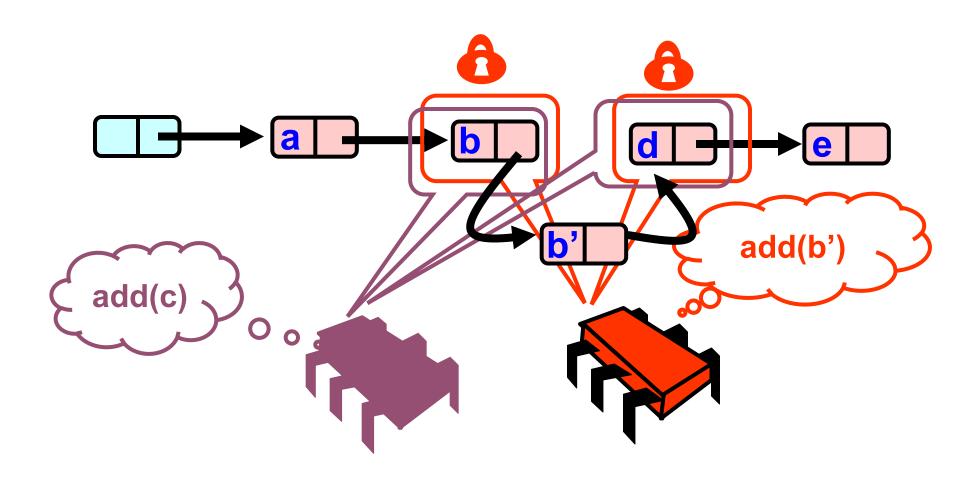
#### What about concurrent adds?

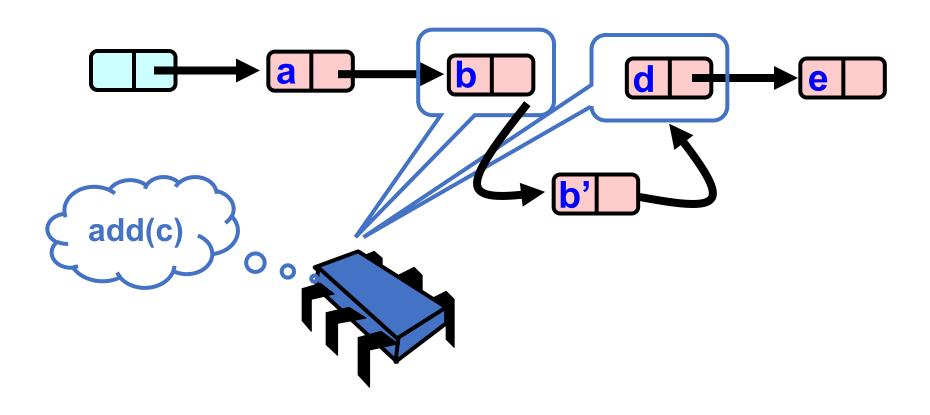
What if 2 threads try to add a node in the same position?

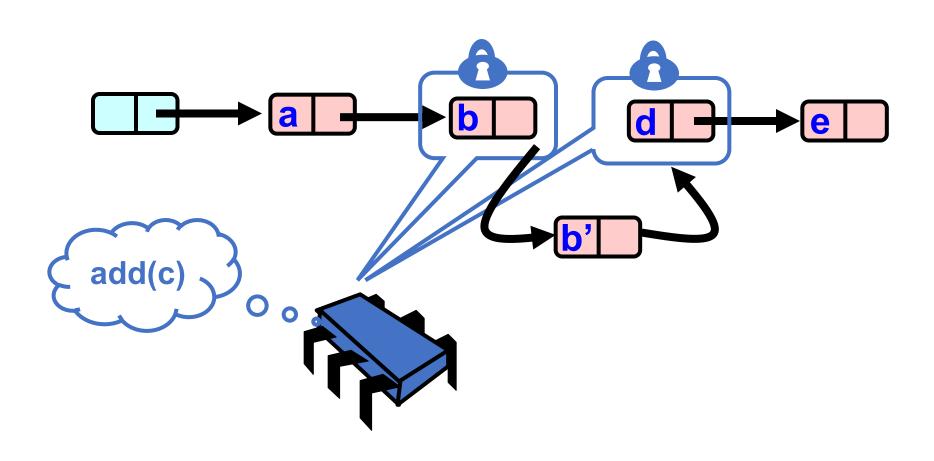


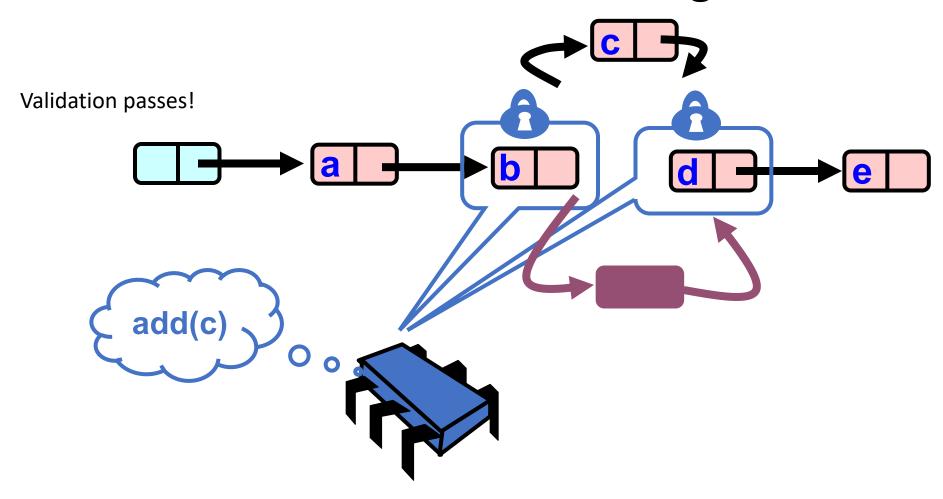




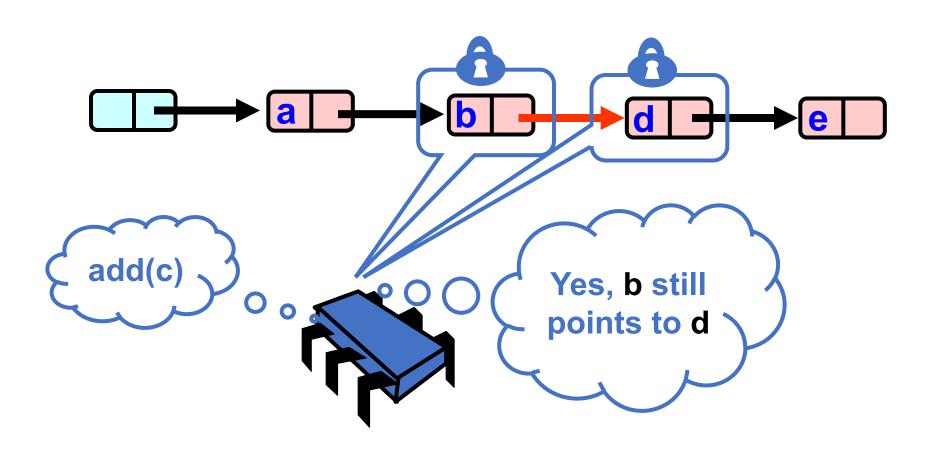


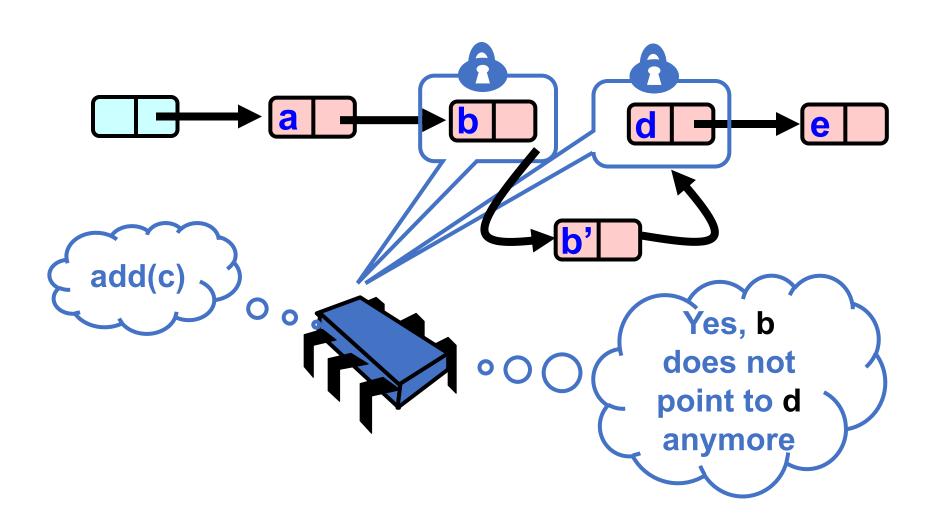




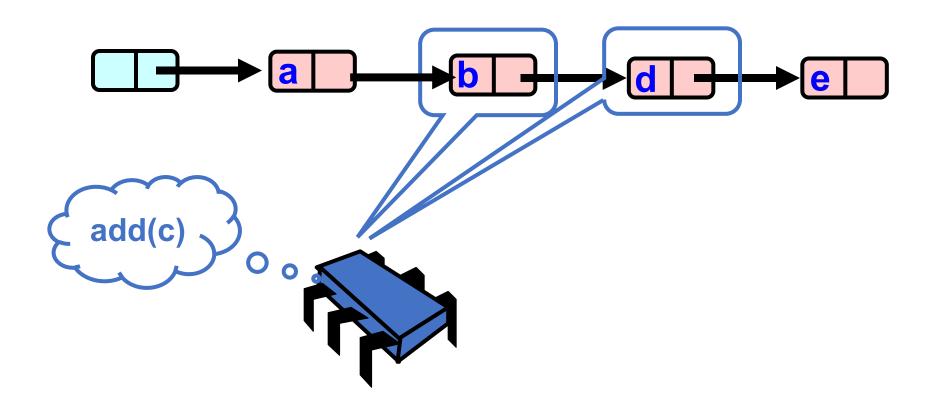


# Validate Part 2 (while holding locks)

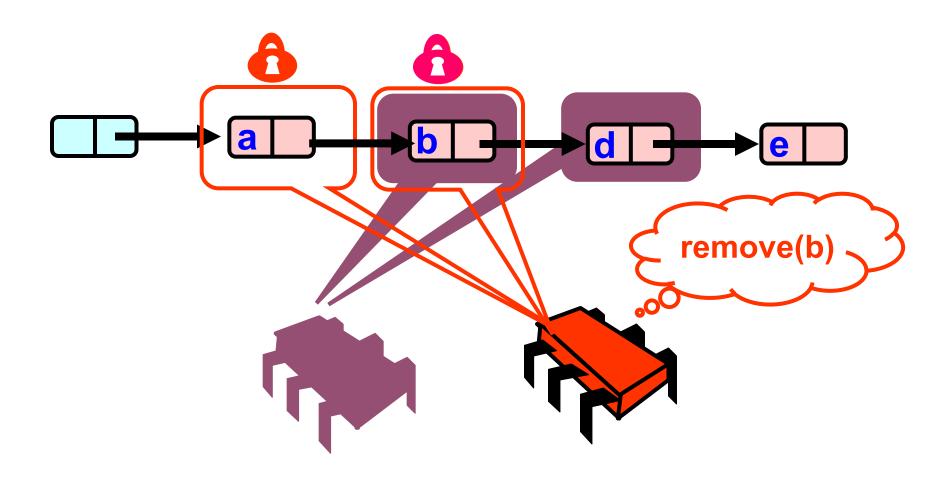




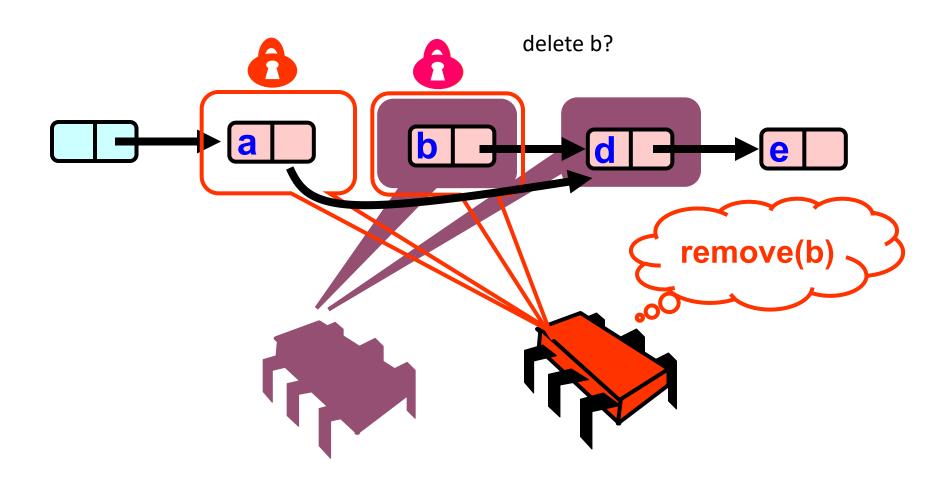
Can threads that remove a node delete (free) it?



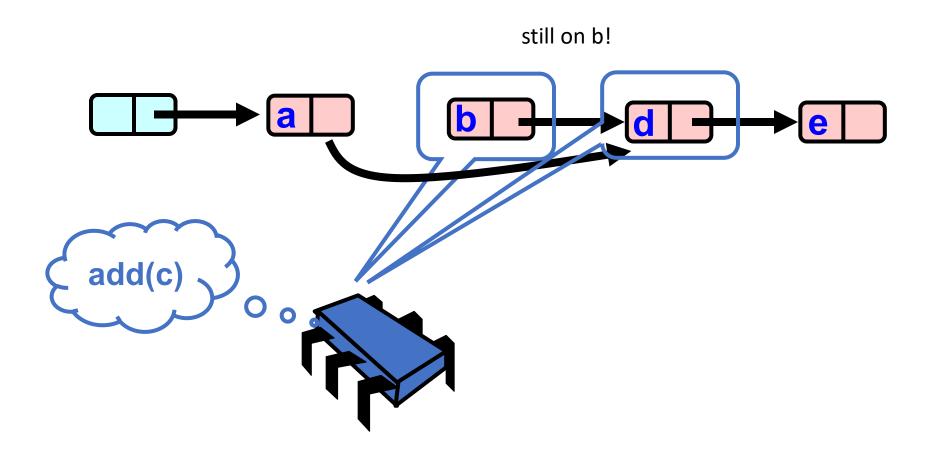
#### Can threads that remove a node delete it?

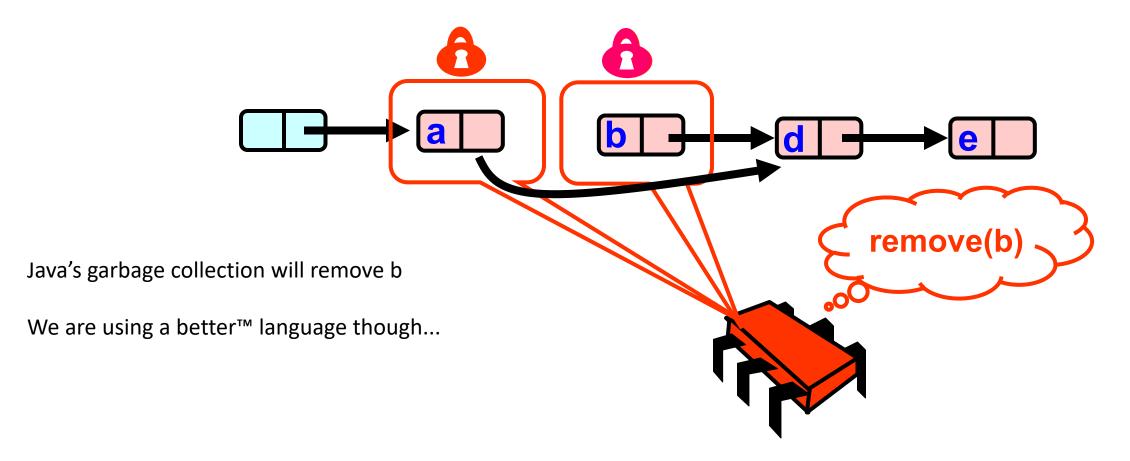


#### Can threads that remove a node delete it?



#### Can threads that remove a node delete it?





maintain a list to delete:



Java's garbage collection will remove b

We are using a better™ language though...

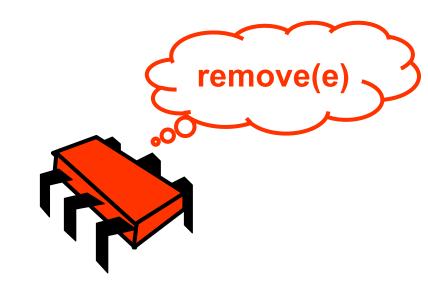
maintain a list to delete:





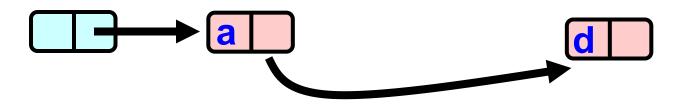
Java's garbage collection will remove b

We are using a better™ language though...



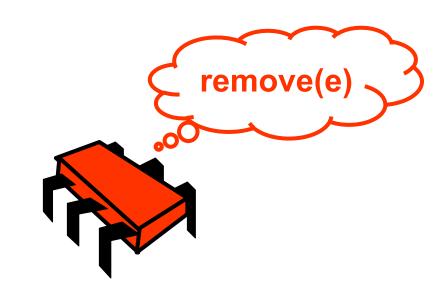
maintain a list to delete: can be thread-local



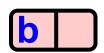


Java's garbage collection will remove b

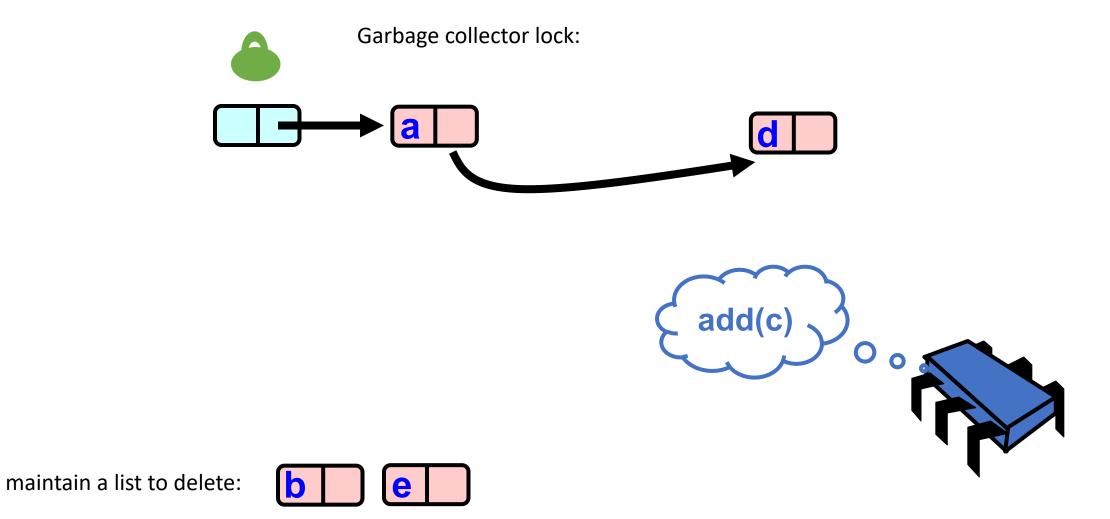
We are using a better™ language though...

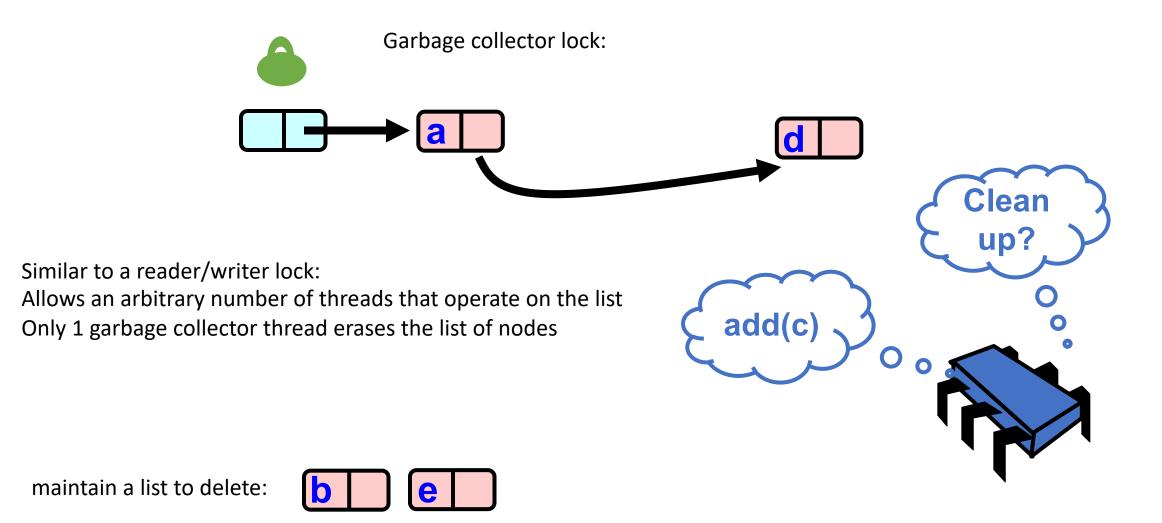


maintain a list to delete:









#### Garbage collector lock

- Many strategies!
  - A big research area ~10 years ago
- **Strat 1:** Threads always try once to take the garbage collector lock:
  - if failed, no worries, the next operation will get a chance
  - can starve garbage collection
- Strat 2: Wait until size grows to a threshold:
  - Wait on the lock
  - Can cause performance spikes

# Summary

- We traverse without lock
  - Traversal may access nodes that are locked
  - Its okay because we have atomic pointers!
- We avoid traversing the old structure
  - We validate after we obtain locks.
    - Our node is still reachable (it was not deleted)
    - Our insertion point is still valid (no thread has inserted in the meantime)
- To free nodes
  - We put them in a list to be freed later.