DVA400 - Assignment

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I. README

The assignment is divided into these 6 files. The "Assignment" files are standalone and no config file is needed to execute any of the scripts.

- Assignment 1
  - $poly\_trajD4.m$
  - $Assignment1\_1.m$
  - $Assignment1\_2.slx$
- Assigment 2
  - $poly\_trajD5.m$
  - $Assigment2\_12.m$
  - $Assigment2\_3.slx$

A. Matlab

The polynomial trajectory generation functions $poly\_trajD4$, $poly\_trajD5$ creates and returns a polynomial of degree 4 and 5 respectively. The example execution of the degree 4 polynomial is located in $Assingment1\_1$. $Assingment2\_12$ for the degree 5 polynomial.

B. Simulink

In $Assignment1\_2$ the example run of the degree 4 polynomial is provided. $Assignment2\_3$ has the execution of the doubly normalized degree 5 polynomial.