## **Erratum discussion**

Bai Q, Xu T, Huang J, Pérez-Sánchez H. Geometric deep learning methods and applications in 3D structure-based drug design. *Drug Discov Today*. 2024;29(7):104024. https://doi.org/10.1016/j.drudis.2024.104024

Due to compatibility issues with the proof system, some formulas are not shown in the above paper, the parts that need to be modified are as follows:

1) The contents below Equation (28) on page 9 in the above paper (Drug Discov Today, 2024;29(7):104024):

$$\begin{split} \tilde{x}^k &= \tilde{x}^{k-1} - \eta \nabla_x E_\theta(\tilde{x}^{k-1}) + \omega \ \underline{(28)} \\ \text{Where } \omega \ \mathcal{N}(0,\sigma) \ \text{and} \ \tilde{x}^K \ q_\theta. \end{split}$$

"where  $\omega \mathcal{N}(0, \sigma)$  and  $\tilde{\chi}^K q_{\theta}$ ." should be **modified** to "where  $\omega \sim \mathcal{N}(0, \sigma)$  and  $\sigma = \delta \epsilon^{\tau}$ .  $\delta$  is the step size,  $\epsilon^{\tau} \sim \mathcal{N}(0, I)$ , and  $\tau$  indexes the time."

For more details, please see reference 1.

## References

1. Gao R, Song Y, Poole B, Wu YN, Kingma DP. Learning energy-based models by diffusion recovery likelihood. arXiv preprint arXiv:201208125. 2020. https://arxiv.org/abs/2012.08125