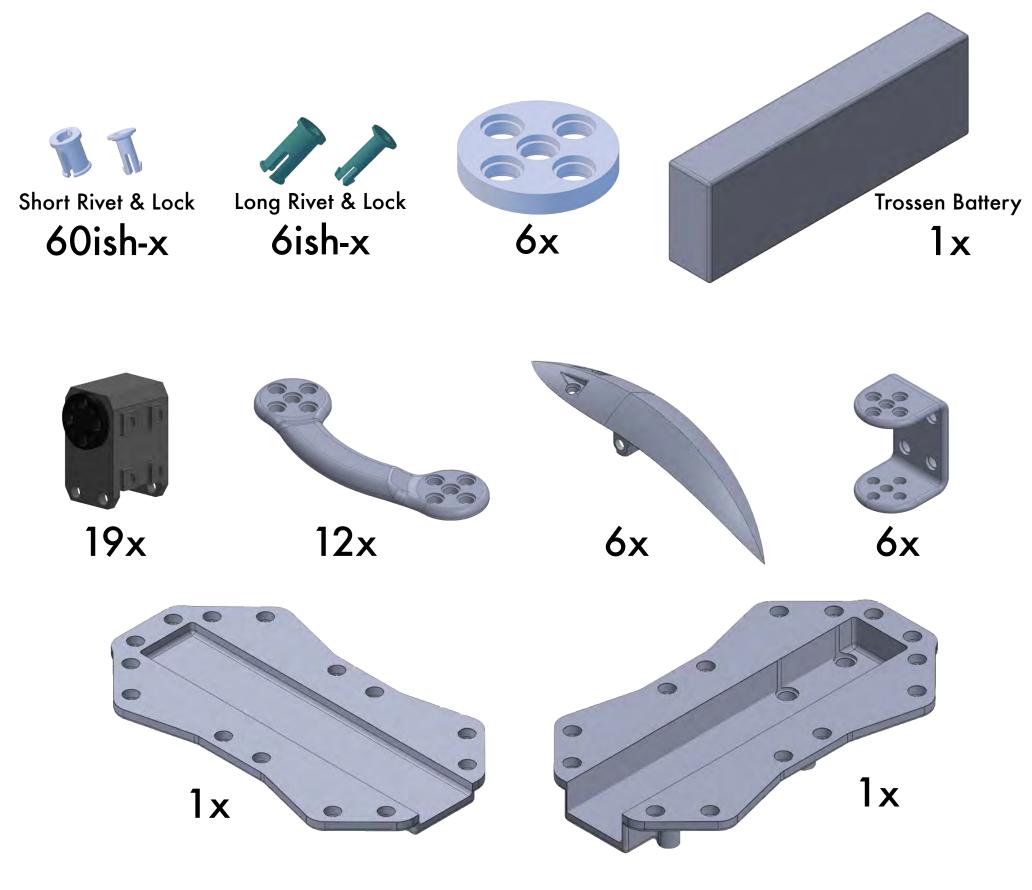
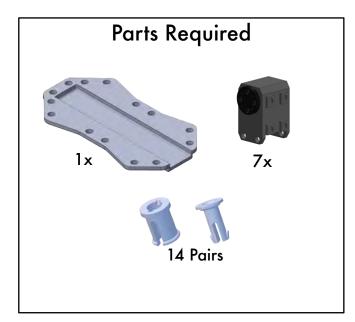
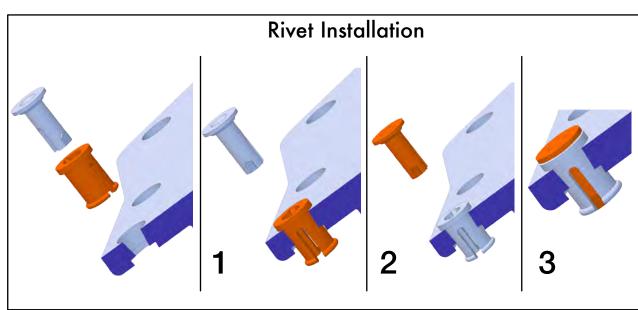
Nico Instruction Manual

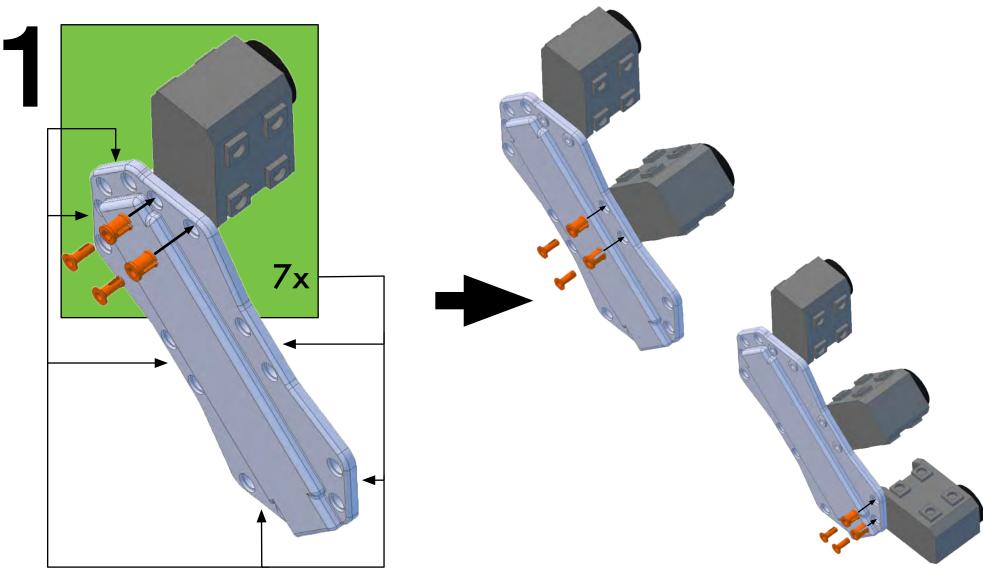


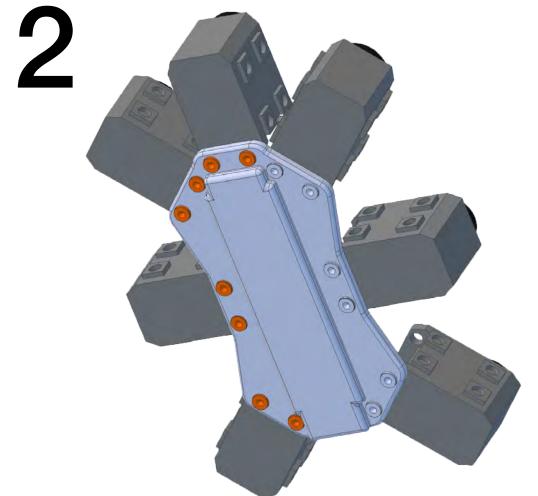
Build of Materials

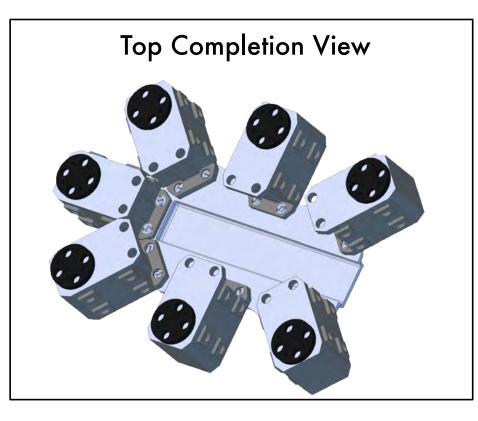


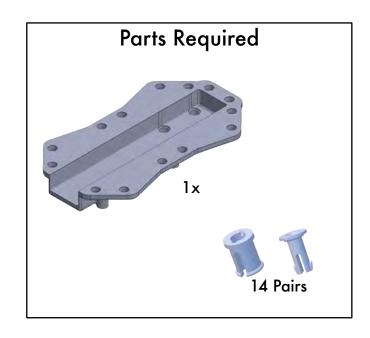


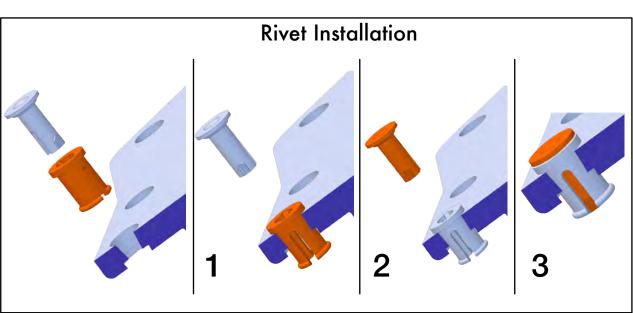


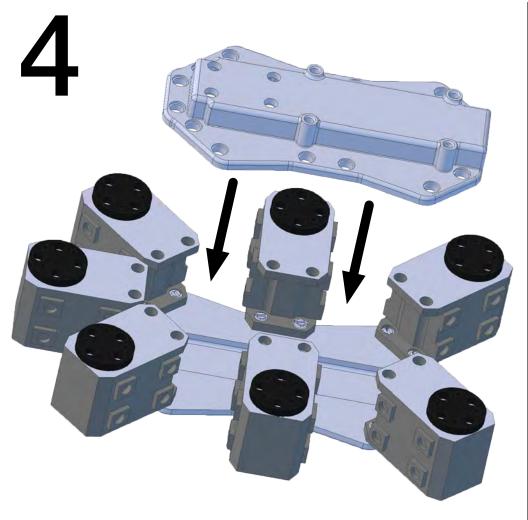


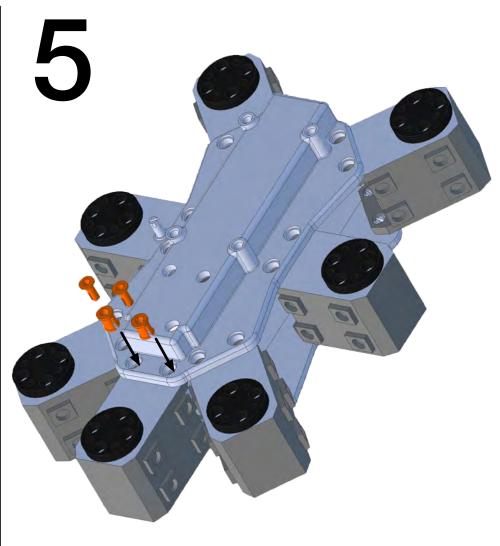


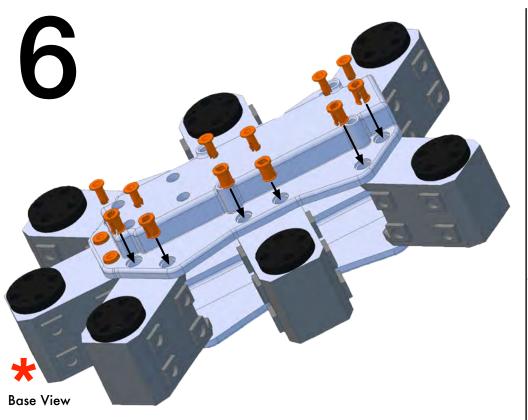


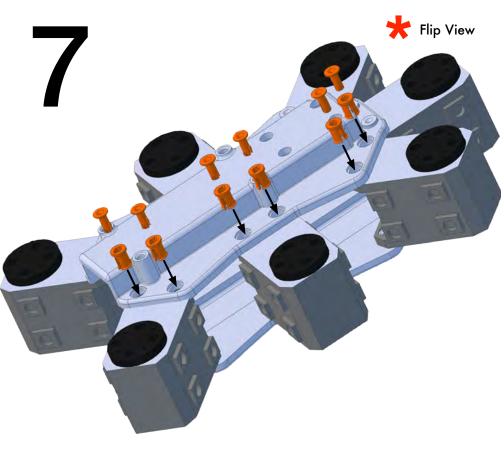


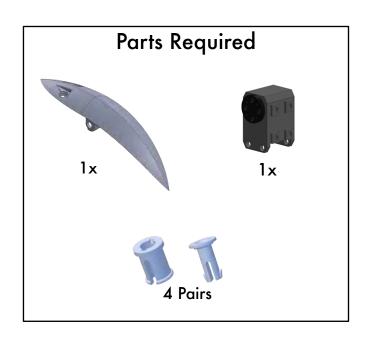


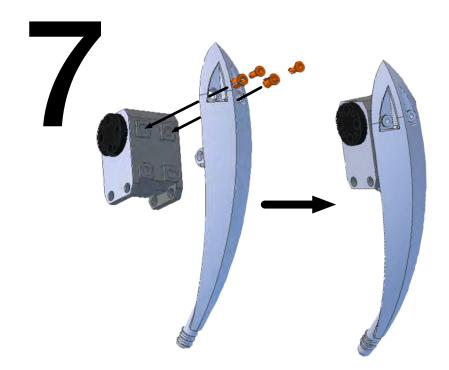


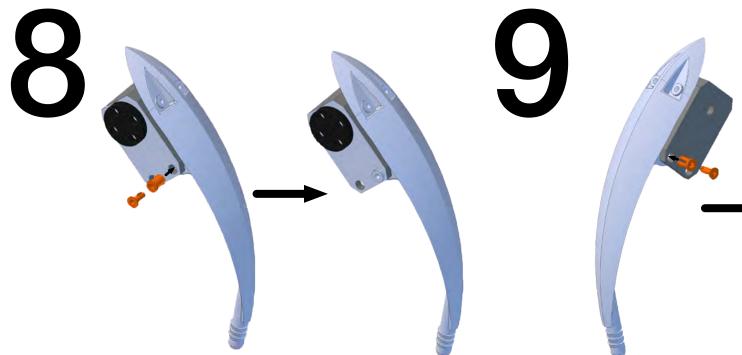


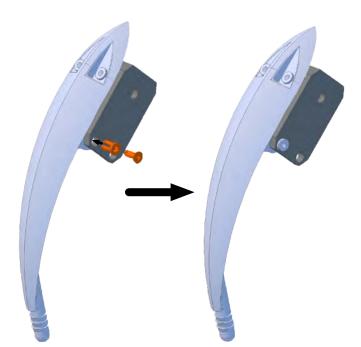




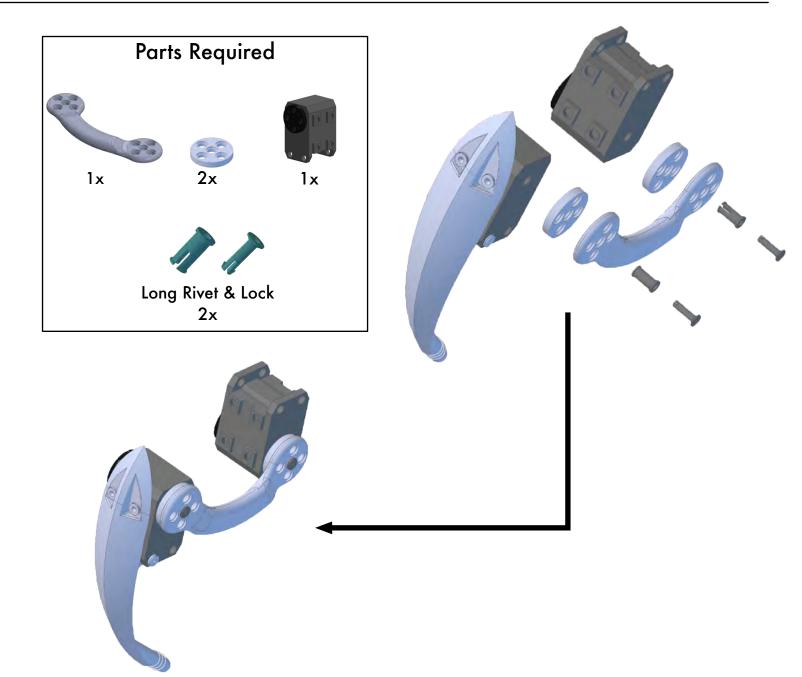


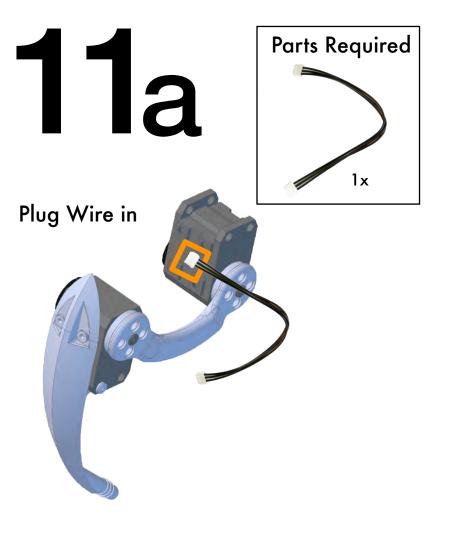




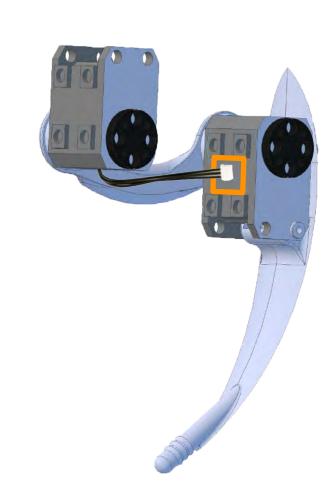








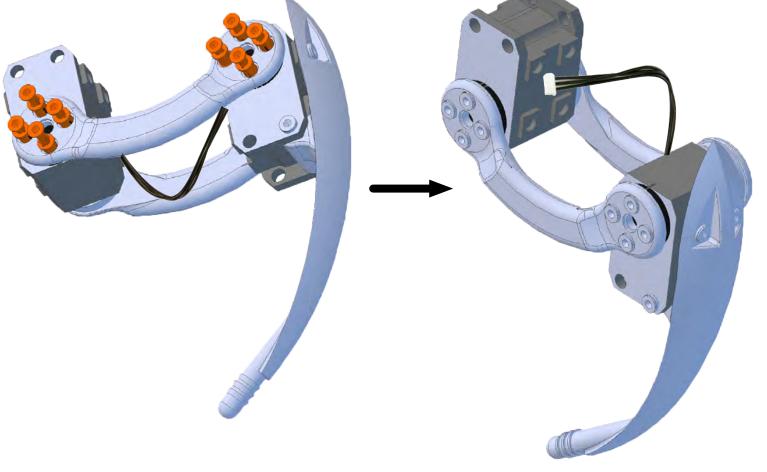
11_b

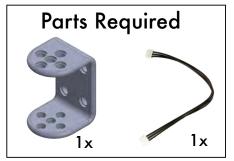


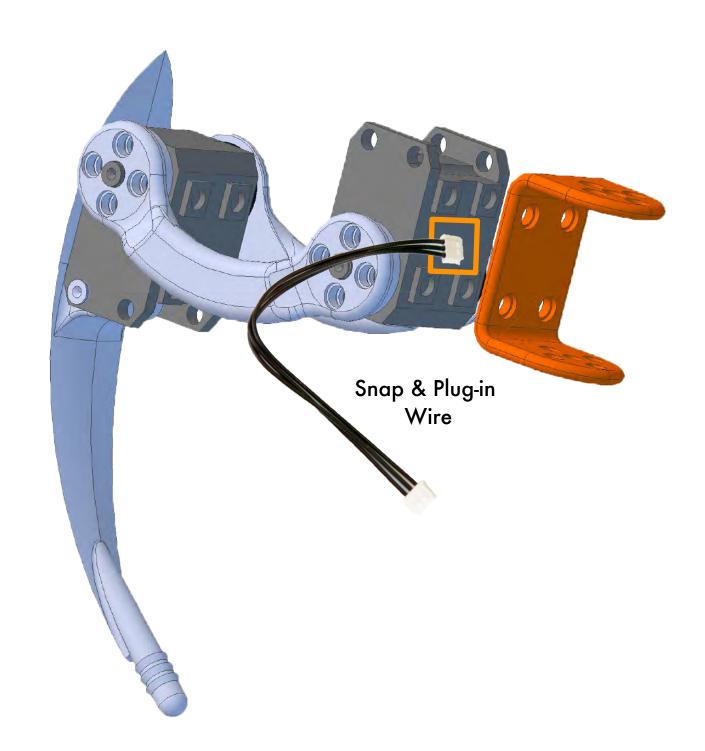
12



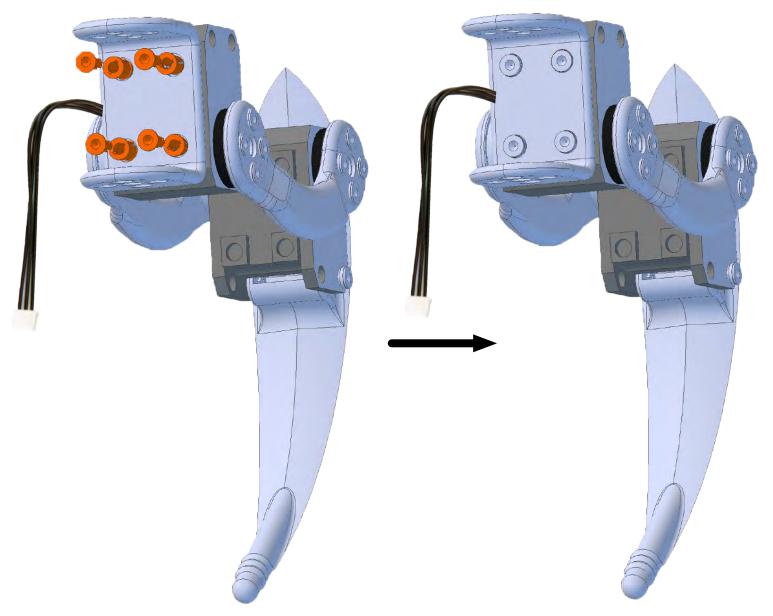




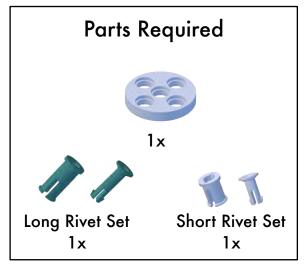




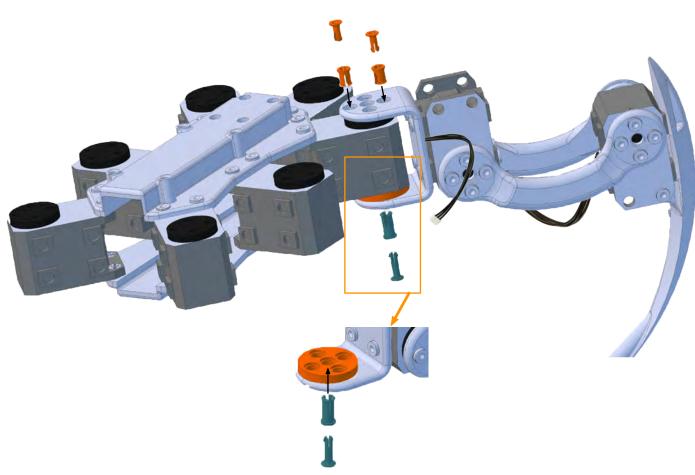


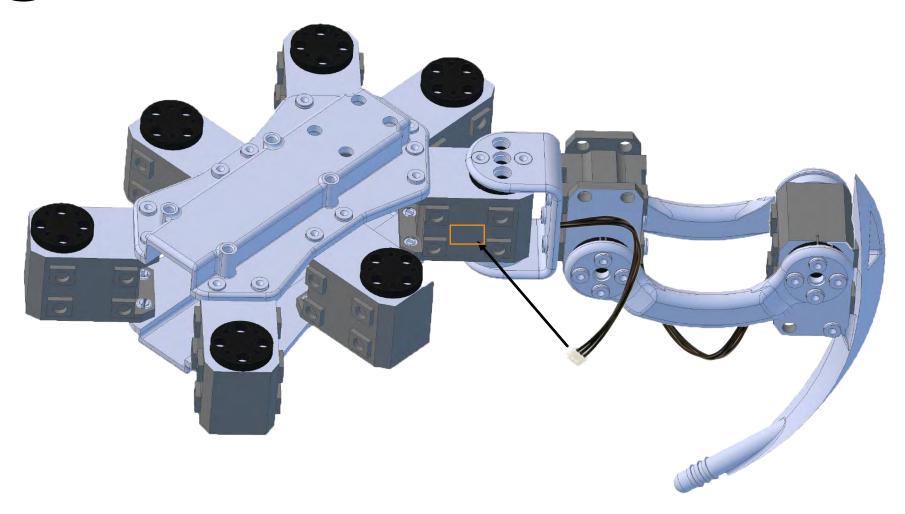


REPEAT STEPS 7-14 UNTIL 6 LEGS CREATED

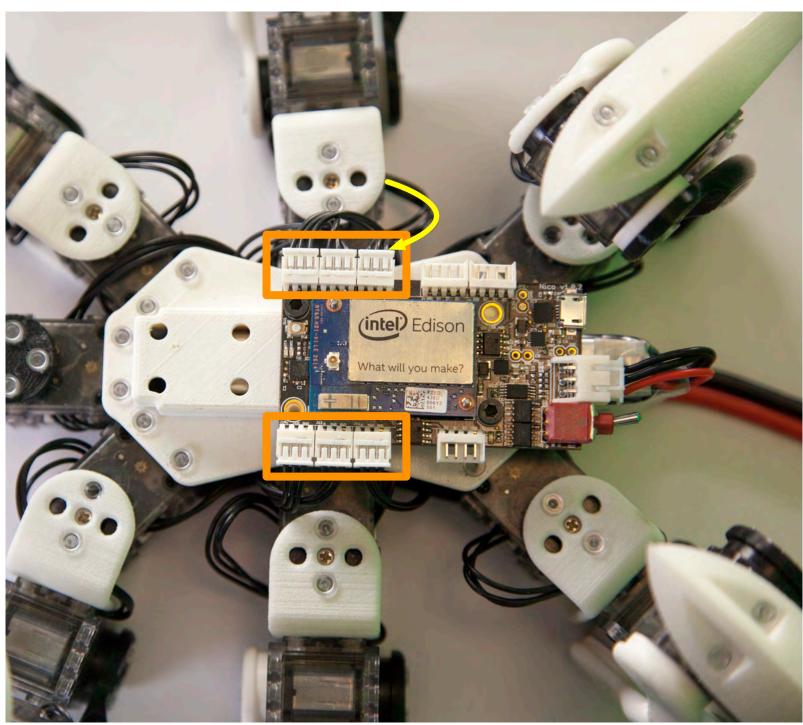








17



Each motor connects to the Printed Circuit Board (PCB).

The orange boxes highlight the connector for all six motors.

The yellow line is an example of the connector cable from motor to PCB.