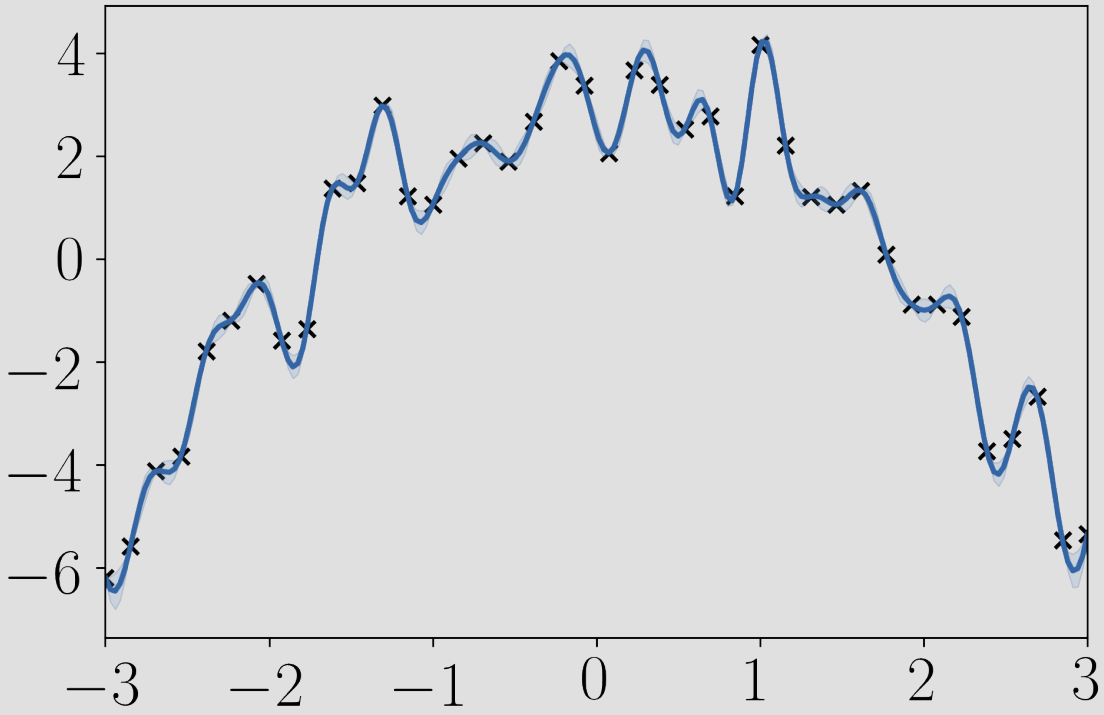
Nuances of GP

Noisy observations



Noisy observations

$$\widehat{f}(x) = f(x) + \epsilon$$

Independent Gaussian noise

$$\epsilon \sim \mathcal{N}(0, s^2)$$

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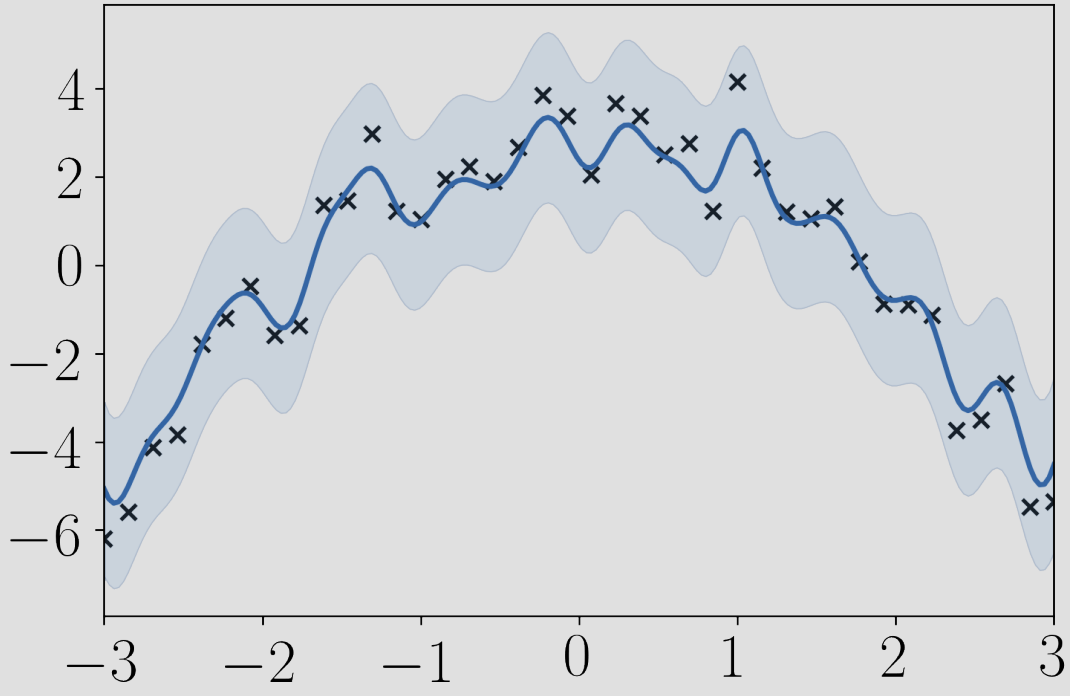
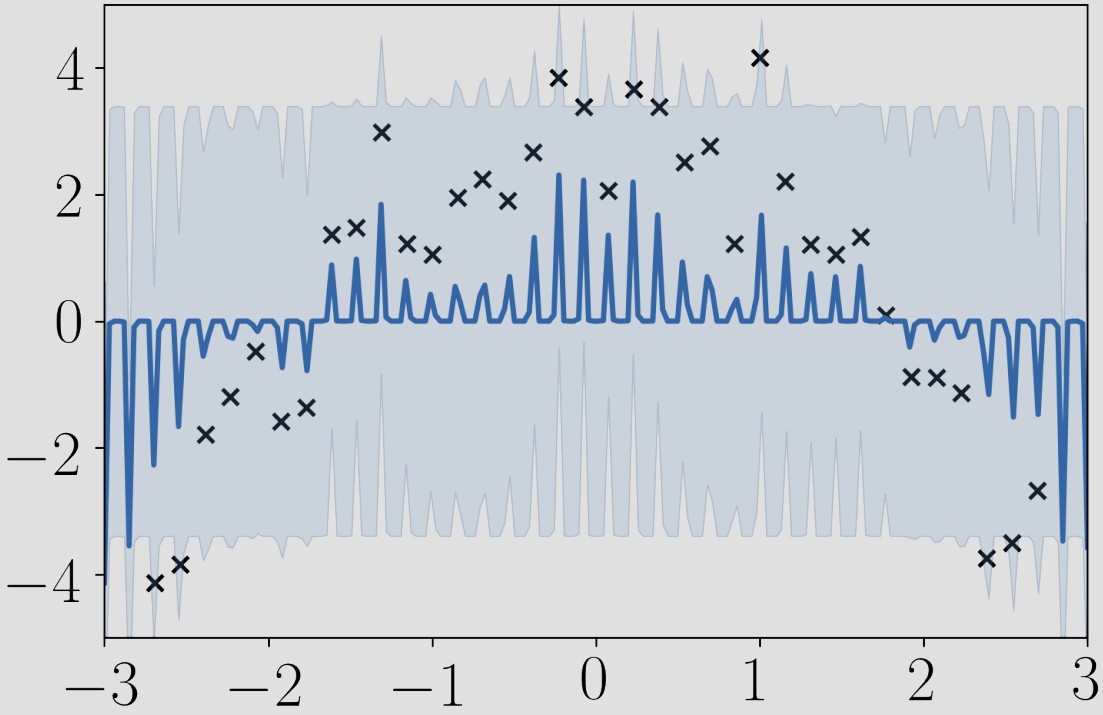


Kernel parameters

$$\widehat{K}(x_1 - x_2) = \sigma^2 \exp\left(-\frac{(x_1 - x_2)^2}{2l^2}\right) + s^2 \mathbb{I}[x_i = x_j]$$

$$l = 0.01$$



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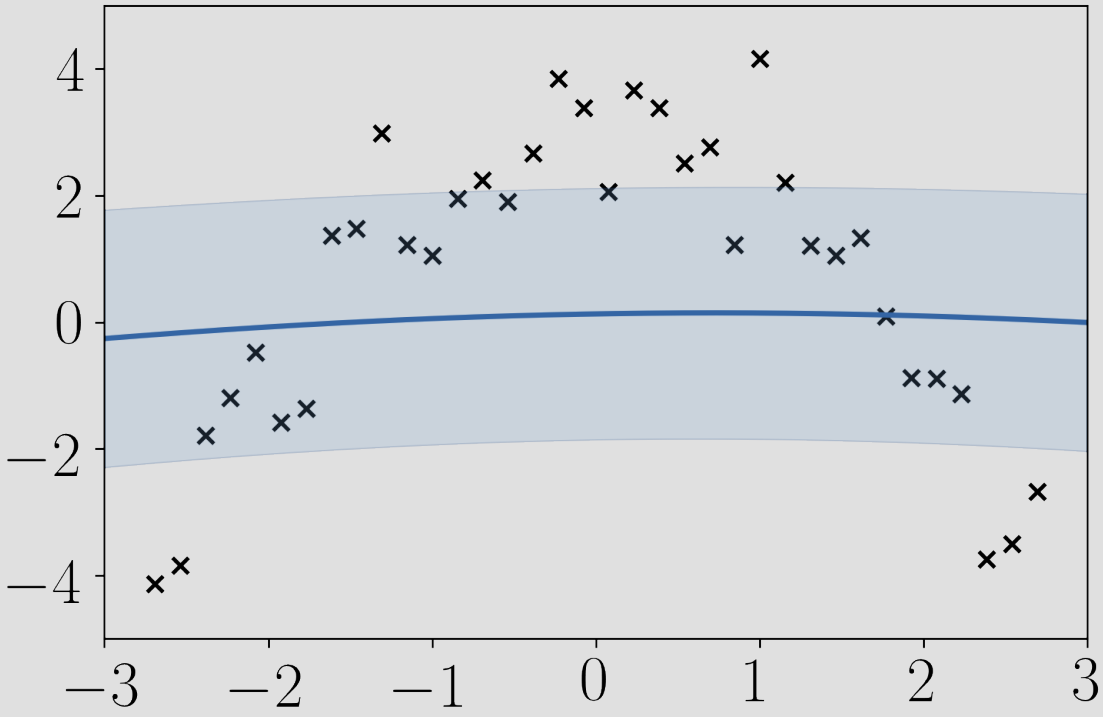
$$l = 10$$



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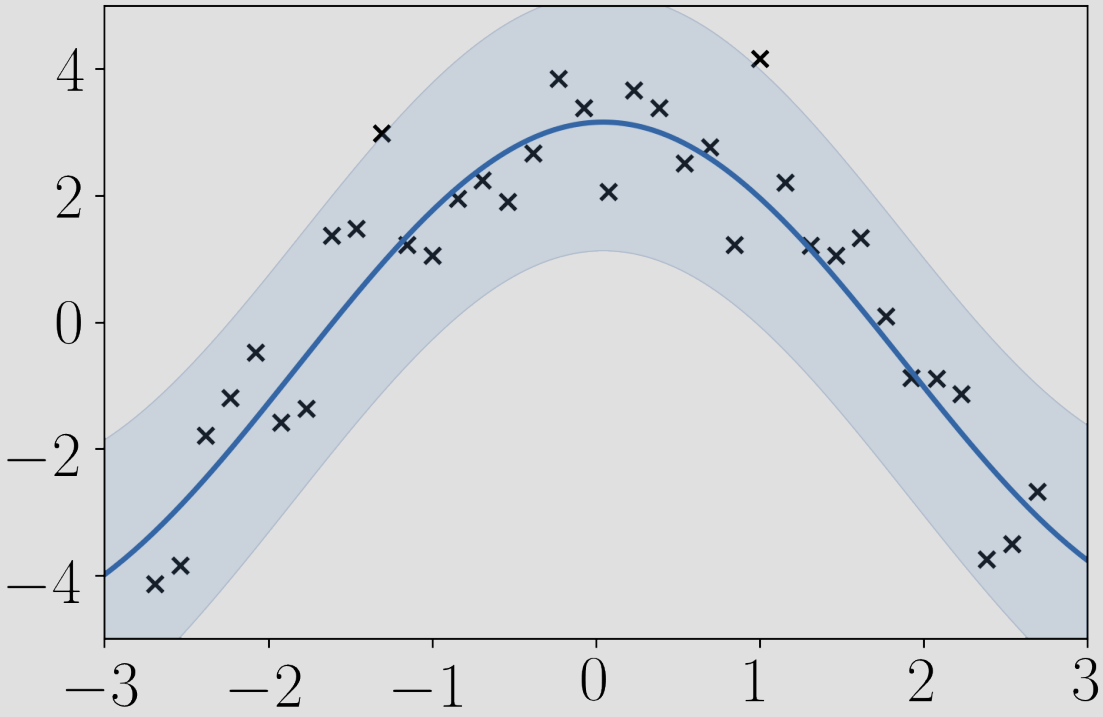
$$l = 2$$



Kernel parameters

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$$p(f(x_1), f(x_2), \ldots, f(x_n) | \sigma^2, l, s^2) \to \max_{\sigma^2, l, s^2}$$

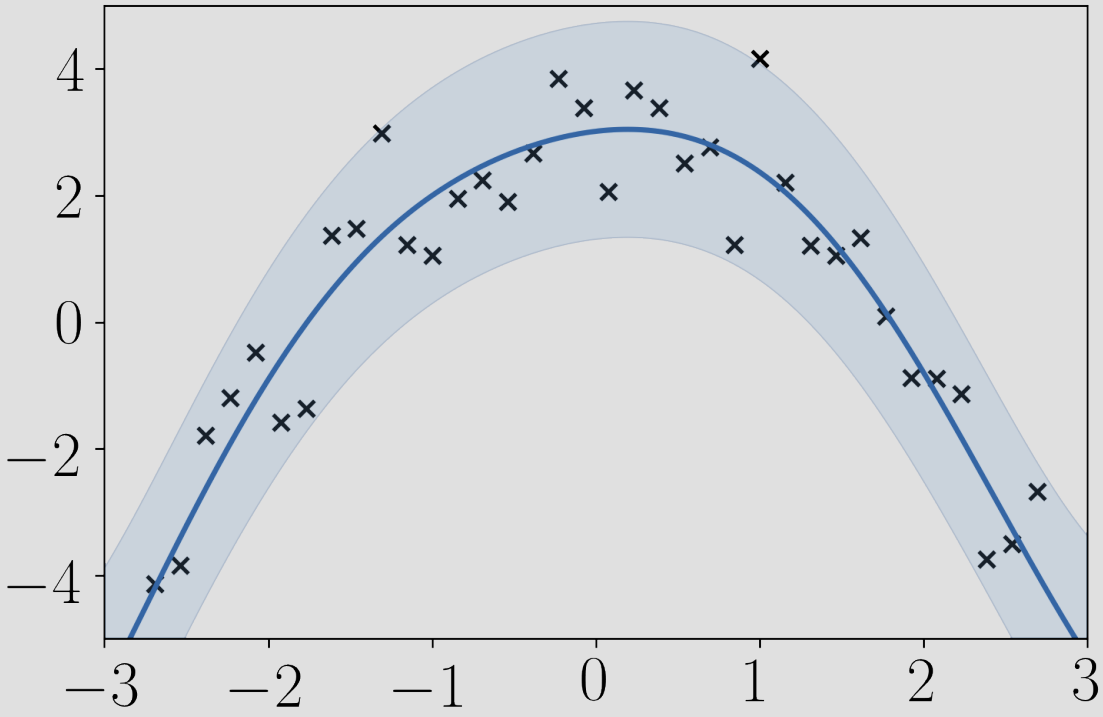
$$\mathcal{N}(f(x_1), f(x_2), \ldots, f(x_n) | 0, C) \to \max_{\sigma^2, l, s^2}$$

Optimize with gradient ascent

Kernel parameters

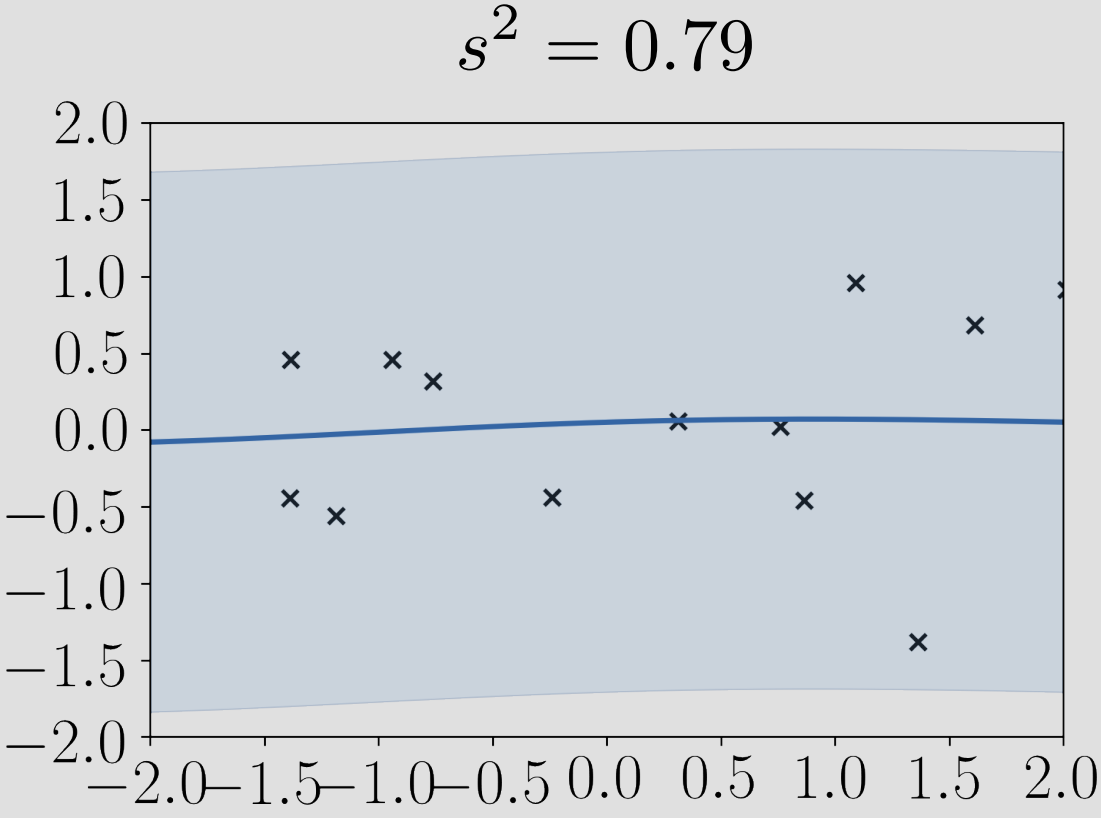
$$\widehat{K}(x_1 - x_2) = \sigma^2 \exp\left(-\frac{(x_1 - x_2)^2}{2l^2}\right) + s^2 \mathbb{I}[x_i = x_j]$$

$$\sigma^2 = 46.4,\ l = 2,\ s^2 = 0.7$$



Kernel parameters

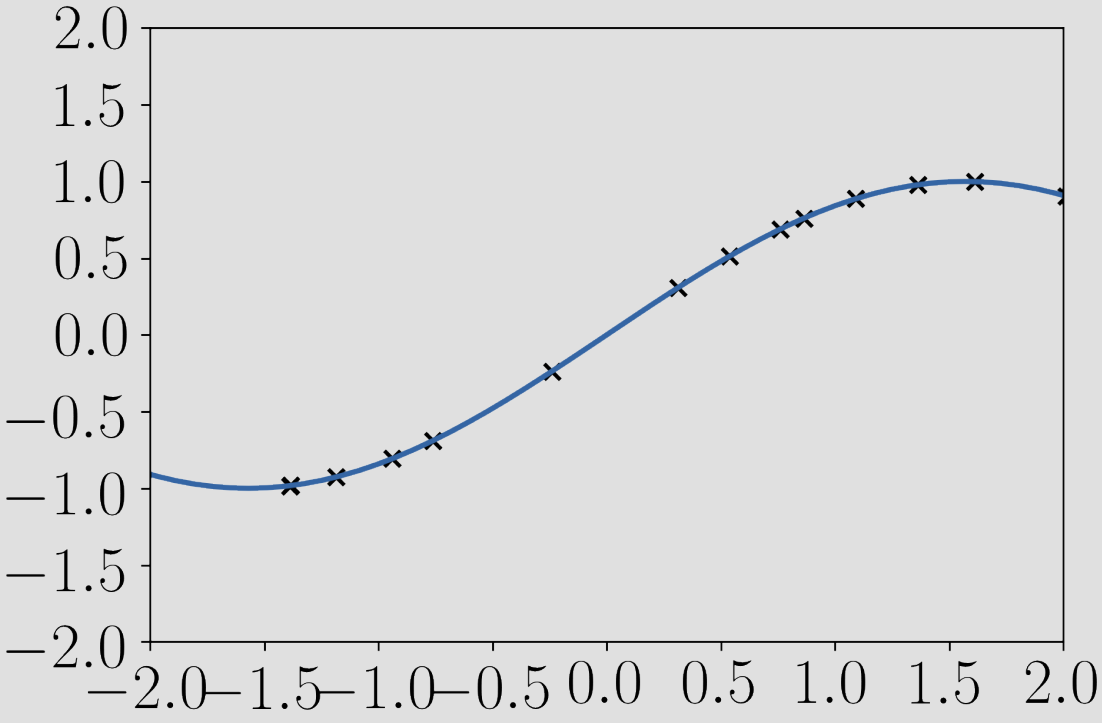
Fitting into **noise**



Kernel parameters

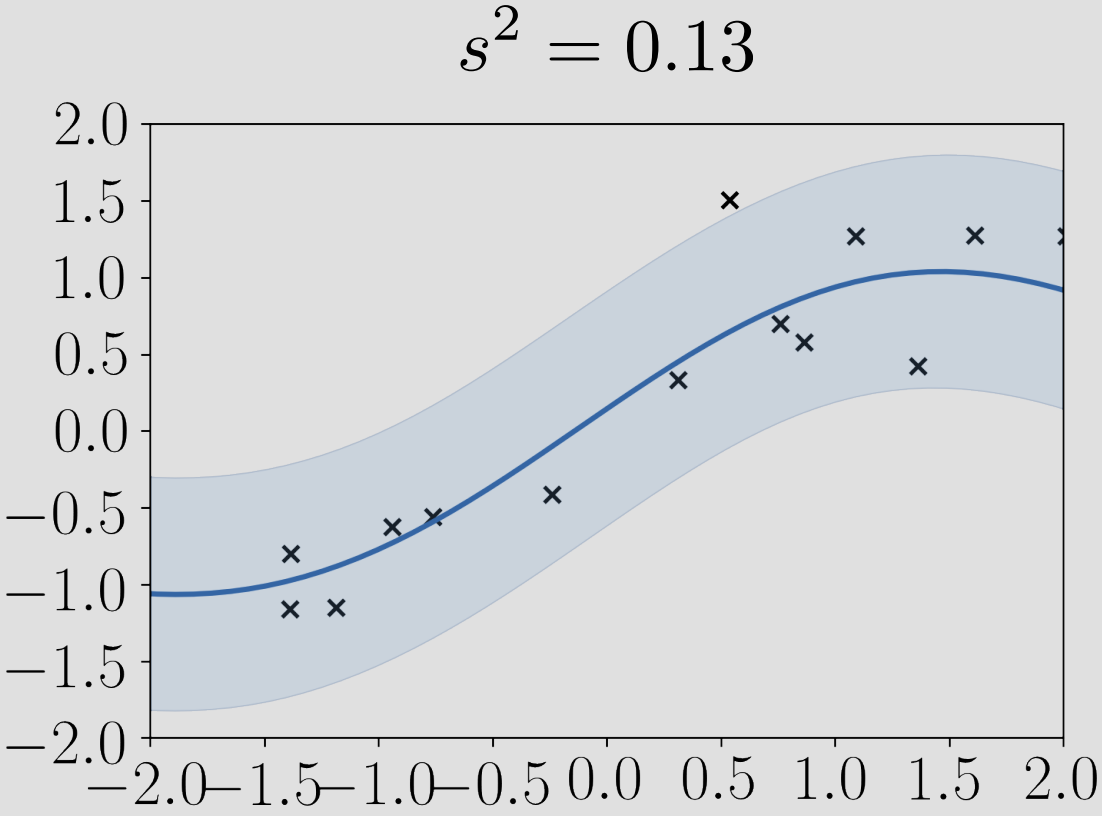
Fitting into signal **without noise**

$$s^2 = 5 \cdot 10^{-17}$$



Kernel parameters

Fitting into **noisy** signal



Classification

$$y \in \{-1, +1\}$$

Latent process: $f(x)$

Class probabilities: $p(y|f) = \dfrac{1}{1 + \exp(-yf)}$

Training:

- Approximate latent process from data

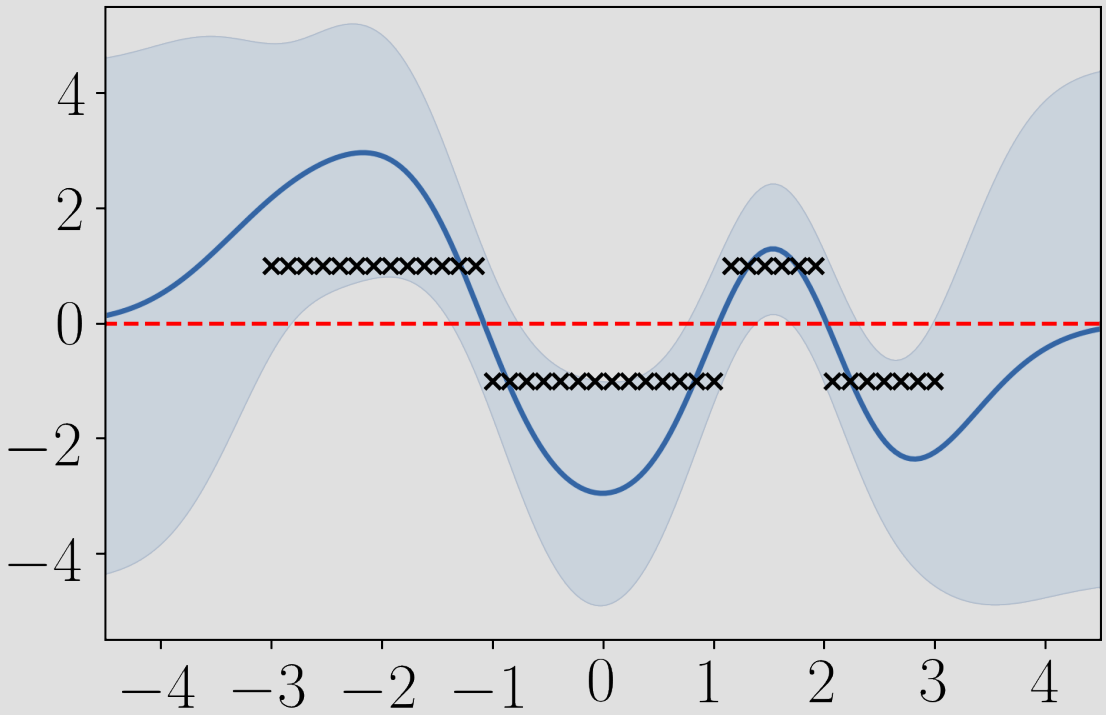
$$p^*(f(x)) = p(f(x) \mid y_1(x_1), \ldots, y_n(x_n))$$

- Compute predictions

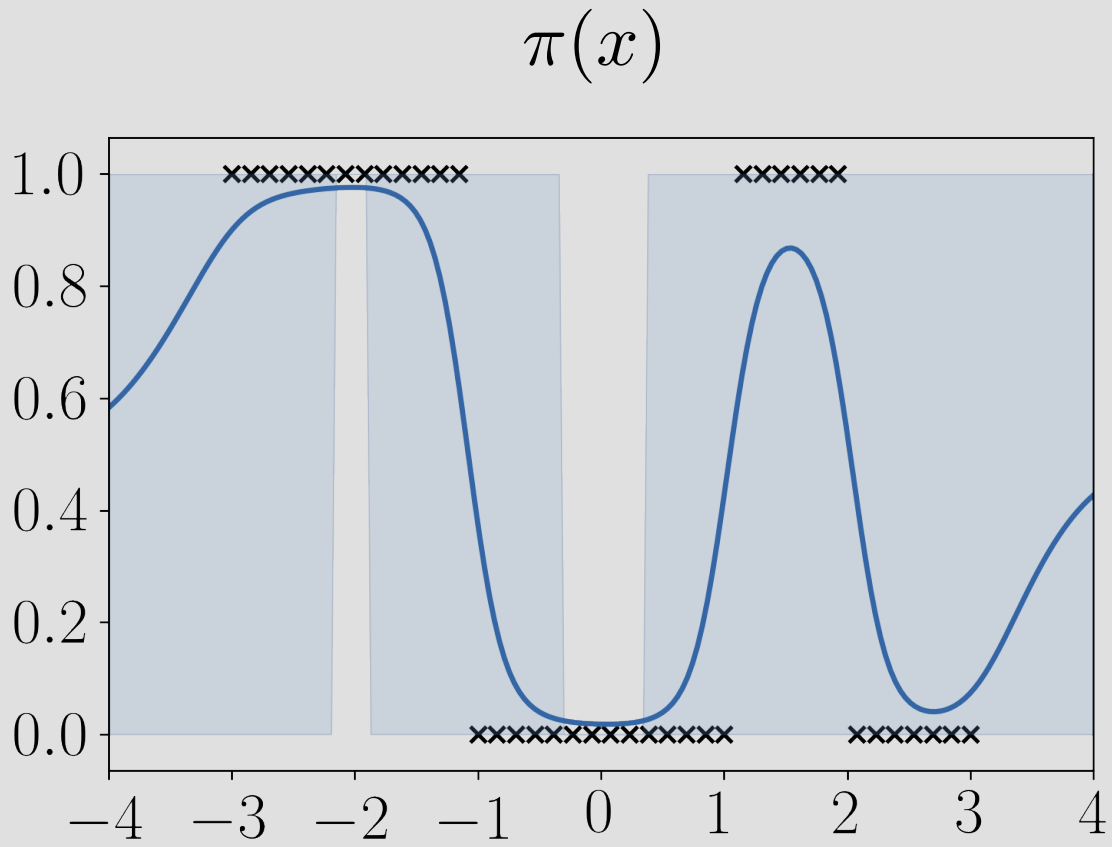
$$\pi(x) = \int p(y(x) \mid f(x)) \cdot p^*(f(x)) df(x)$$

Classification

$$p(f(x) \mid y_1(x_1), \ldots, y_n(x_n))$$



Classification



Inducing inputs

$$\mu = k^T C^{-1} f$$
$$\sigma^2 = K(0) - k^T C^{-1} k$$

$\mathcal{O}(n^3)$

Idea:

- Replace dataset with small number of points (like SVM)
- Predict using those points

Speed:

- Precomputing: $\mathcal{O}(m^2 n)$
- Mean: $\mathcal{O}(m)$
- Variance: $\mathcal{O}(m^2)$

Inducing inputs (ТЕХНИЧЕСКИЙ СЛАЙД)

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$$\mathcal{O}(n^3)$$

Idea:

- Replace dataset with small number of points (like SVM)
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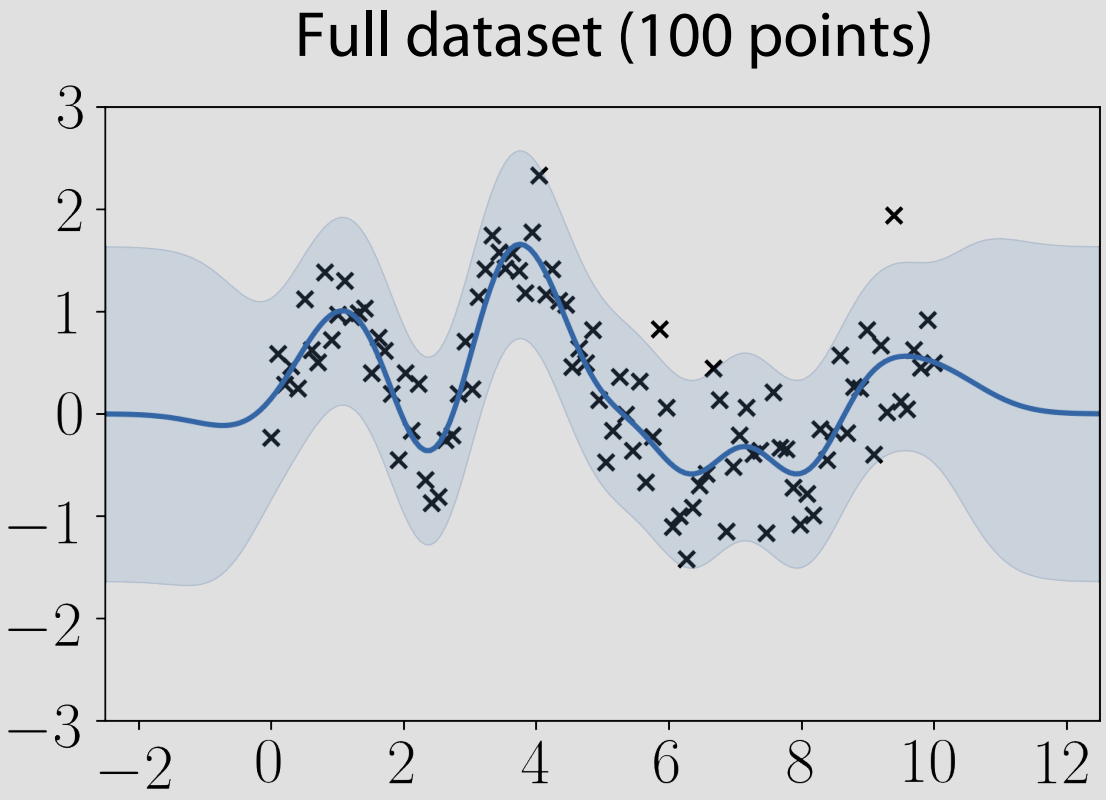
Optimize position & values by MLE

Inducing inputs



Inducing inputs