

## Aplicación del MEF para la 2da ecuación

### Contexto

La empresa de videojuegos desea lanzar el juego de supervivencia más realista que se haya visto jamás y ha prometido tanto los gráficos más reales nunca vistos, también ha prometido las mecánicas más parecidas a la realidad posibles, de modo que se han puesto una gran presión encima y saben que si no logran lo que prometieron los usuarios los cancelaran en cualquier red social existente y por existir, para ello los desarrolladores deben evitar las clásicas cajas de hit box y diseñaron una manera de poder calcular la cantidad de daño que el jugador reciba o ejerza sobre otro jugador u objeto y como no solo se verá afectada la zona donde reciba el impacto sino el resto de partes del cuerpo o del objeto recibirán un porcentaje de daño.

A esta ecuación le llamaron "índice de daño recibido o IDR" la cual es:  $-\epsilon^2 \nabla \cdot (\eta^2 \nabla X) = \eta^2 + \eta$

Modelo

$$-\epsilon^2 \nabla \cdot (\eta^2 \nabla X) = \eta^2 + \eta$$

Paso 1: Localización

$$N_1 = 1 - \epsilon - \eta - \phi$$

$$N_2 = \epsilon$$

$$N_3 = \eta$$

$$N_4 = \phi$$

Paso 2: Interpolación

$$X \approx N_1 X_1 + N_2 X_2 + N_3 X_3 + N_4 X_4$$

$$= [N_1 \ N_2 \ N_3 \ N_4] \begin{bmatrix} X_1 \\ X_2 \\ X_3 \\ X_4 \end{bmatrix} = NX \quad X \approx NX$$

Paso 3: Aproximación del modelo

$$-\epsilon^2 \nabla \cdot (\eta^2 \nabla X) = \eta^2 + \eta$$

$$-\epsilon^2 \nabla \cdot (\eta^2 \nabla (NX)) = \eta^2 + \eta$$

$$R = \eta^2 + \eta + \epsilon^2 \nabla \cdot (\eta^2 \nabla (NX))$$

Paso 4: Método de los Residuos Ponderados

$$R = \eta^2 + \eta + \epsilon^2 \nabla \cdot (\eta^2 \nabla (NX))$$

$$\int_V W R dV = 0$$

$$\int_V W (\eta^2 + \eta + \epsilon^2 \nabla \cdot (\eta^2 \nabla (NX))) dV = 0$$

Paso 5: Método de Galerkin

$$W = N^T$$

$$\int_V N^T (\eta^2 + \eta + \epsilon^2 \nabla \cdot (\eta^2 \nabla (NX))) dV = 0$$

Interludio y "formatos" de los términos

$$\int_V (N^T \eta^2 + N^T \eta + N^T \epsilon^2 \nabla \cdot (\eta^2 \nabla (NX))) dV = 0$$

$$\int_V N^T \eta^2 dV + \int_V N^T \eta dV + \int_V N^T \epsilon^2 \nabla \cdot (\eta^2 \nabla (NX)) dV = 0$$

$$\int_V N^T \eta^2 dV + \int_V N^T \eta dV + \left( \int_V N^T \epsilon^2 \nabla \cdot (\eta^2 \nabla N) dV \right) X = 0$$

$$- \left( \int_V N^T \epsilon^2 \nabla \cdot (\eta^2 \nabla N) dV \right) X = \int_V N^T \eta^2 dV + \int_V N^T \eta dV$$

# Paso 6: Resolución de integrales

hacer directo

$$\int_V N^T \eta^2 dV + \int_V N^T \eta dV$$

$$\int_V \begin{bmatrix} 1-\epsilon-\eta-\phi \\ \epsilon \\ \eta \\ \phi \end{bmatrix} \eta^2 dV + \int_V \begin{bmatrix} 1-\epsilon-\eta-\phi \\ \epsilon \\ \eta \\ \phi \end{bmatrix} \eta dV$$

$$\int_V \begin{bmatrix} \eta^2 - \epsilon \eta^2 - \eta^3 - \phi \eta^2 \\ \epsilon \eta^2 \\ \eta^3 \\ \phi \eta^2 \end{bmatrix} dV + \int_V \begin{bmatrix} \eta - \epsilon \eta - \eta^2 - \phi \eta \\ \epsilon \eta \\ \eta^2 \\ \phi \eta \end{bmatrix} dV \quad dV = dx dy dz$$

$$\int_V \begin{bmatrix} \eta^2 - \epsilon \eta^2 - \eta^3 - \phi \eta^2 \\ \epsilon \eta^2 \\ \eta^3 \\ \phi \eta^2 \end{bmatrix} dx dy dz + \int_V \begin{bmatrix} \eta - \epsilon \eta - \eta^2 - \phi \eta \\ \epsilon \eta \\ \eta^2 \\ \phi \eta \end{bmatrix} dx dy dz$$

$$dx dy dz = J d\epsilon d\eta d\phi$$

$$\int_V \begin{bmatrix} \eta^2 - \epsilon \eta^2 - \eta^3 - \phi \eta^2 \\ \epsilon \eta^2 \\ \eta^3 \\ \phi \eta^2 \end{bmatrix} J d\epsilon d\eta d\phi + \int_V \begin{bmatrix} \eta - \epsilon \eta - \eta^2 - \phi \eta \\ \epsilon \eta \\ \eta^2 \\ \phi \eta \end{bmatrix} J d\epsilon d\eta d\phi$$

$$J \left( \int_V \begin{bmatrix} \eta^2 - \epsilon \eta^2 - \eta^3 - \phi \eta^2 \\ \epsilon \eta^2 \\ \eta^3 \\ \phi \eta^2 \end{bmatrix} d\epsilon d\eta d\phi + \int_V \begin{bmatrix} \eta - \epsilon \eta - \eta^2 - \phi \eta \\ \epsilon \eta \\ \eta^2 \\ \phi \eta \end{bmatrix} d\epsilon d\eta d\phi \right)$$



Resolviendo la  
primer integral

$$\int_V \begin{bmatrix} \eta^2 - \epsilon \eta^2 - \eta^3 - \phi \eta^2 \\ \epsilon \eta^2 \\ \eta^3 \\ \phi \eta^2 \end{bmatrix} d\epsilon d\eta d\phi$$

$$\int_0^1 \int_0^{1-\phi} \int_0^{1-\eta-\phi} \begin{bmatrix} \eta^2 - \epsilon \eta^2 - \eta^3 - \phi \eta^2 \\ \epsilon \eta^2 \\ \eta^3 \\ \phi \eta^2 \end{bmatrix} d\epsilon d\eta d\phi$$

$$\begin{bmatrix} \int_0^1 \int_0^{1-\phi} \int_0^{1-\eta-\phi} (\eta^2 - \epsilon \eta^2 - \eta^3 - \phi \eta^2) d\epsilon d\eta d\phi \\ \int_0^1 \int_0^{1-\phi} \int_0^{1-\eta-\phi} \epsilon \eta^2 d\epsilon d\eta d\phi \\ \int_0^1 \int_0^{1-\phi} \int_0^{1-\eta-\phi} \eta^3 d\epsilon d\eta d\phi \\ \int_0^1 \int_0^{1-\phi} \int_0^{1-\eta-\phi} \phi \eta^2 d\epsilon d\eta d\phi \end{bmatrix}$$

$$\int_0^1 \int_0^{1-\phi} \int_0^{1-\eta-\phi} \epsilon \eta^2 d\epsilon d\eta d\phi$$

$$\int_0^{1-\eta-\phi} \epsilon \eta^2 d\epsilon \Rightarrow \eta^2 \int_0^{1-\eta-\phi} \epsilon d\epsilon$$

$$= \eta^2 \left( \frac{1 - 2\eta - 2\phi + \eta^2 + 2\eta\phi + \phi^2}{2} \right) = \frac{\eta^2 - 2\eta^3 - 2\eta^2\phi + \eta^4 + 2\eta^3\phi + \eta^2\phi^2}{2}$$

$$\int_0^{1-\phi} \frac{\eta^2 - 2\eta^3 - 2\eta^2\phi + \eta^4 + 2\eta^3\phi + \eta^2\phi^2}{2} d\eta$$

$$= \frac{2 - 7\phi + 8\phi^2 - 2\phi^3 - 2\phi^2 + \phi^3 - 3(1-\phi)^4}{12} + \frac{(1-\phi)^5}{10}$$

$$\int_0^1 \frac{2-7\phi+8\phi^2-2\phi^3-2\phi^4+\phi^5-3(1-\phi)^4}{12} + \frac{(1-\phi)^5}{10} d\phi$$

$$= \frac{1}{360}$$

$$\int_0^1 \int_0^{1-\phi} \int_0^{1-\eta-\phi} \eta^3 d\epsilon d\eta d\phi$$

$$\int_0^{1-\eta-\phi} \eta^3 d\epsilon \Rightarrow \eta^3 \int_0^{1-\eta-\phi} d\epsilon = \eta^3(1-\eta-\phi) = \eta^3 - \eta^4 - \eta^2\phi$$

$$\int_0^{1-\phi} \eta^3 - \eta^4 - \eta^2\phi d\eta$$

$$= \frac{(1-\phi)^4 - (1-\phi)^4\phi}{4} - \frac{(1-\phi)^5}{5}$$

$$\int_0^1 \frac{(1-\phi)^4 - (1-\phi)^4\phi}{4} - \frac{(1-\phi)^5}{5} d\phi$$

$$= \frac{1}{120}$$

$$\int_0^1 \int_0^{1-\phi} \int_0^{1-\eta-\phi} \phi \eta^2 d\epsilon d\eta d\phi \xrightarrow[\text{al reordenar la integral}]{\int_0^1 \int_0^{1-\phi} \int_0^{1-\eta-\phi} \phi \eta^2 d\phi d\eta d\epsilon} \begin{matrix} \text{tiene la misma forma que} \\ \text{la primera integral} \end{matrix}$$

$$= \frac{1}{360}$$

$$\int_0^1 \int_0^{1-\phi} \int_0^{1-\eta-\phi} (\eta^2 - \epsilon \eta^2 - \eta^3 - \phi \eta^2) d\epsilon d\eta d\phi$$

$$= \int_0^1 \int_0^{1-\phi} \int_0^{1-\eta-\phi} \eta^2 d\epsilon d\eta d\phi - \int_0^1 \int_0^{1-\phi} \int_0^{1-\eta-\phi} \epsilon \eta^2 d\epsilon d\eta d\phi$$

$$- \int_0^1 \int_0^{1-\phi} \int_0^{1-\eta-\phi} \eta^3 d\epsilon d\eta d\phi - \int_0^1 \int_0^{1-\phi} \int_0^{1-\eta-\phi} \eta^2 \phi d\epsilon d\eta d\phi$$

$$= \int_0^1 \int_0^{1-\phi} \int_0^{1-\eta-\phi} \eta^2 d\epsilon d\eta d\phi - \frac{1}{360} - \frac{1}{120} - \frac{1}{360}$$

$$\int_0^{1-\eta-\phi} \eta^2 d\theta \Rightarrow \eta^2 \int_0^{1-\eta-\phi} d\theta = \eta^2(1-\eta-\phi) \\ = \eta^2 - \eta^3 - \eta^2\phi$$

$$\int_0^{1-\phi} \eta^2 - \eta^3 - \eta^2\phi d\eta \\ = \frac{\phi^4 - 4\phi^3 + 6\phi^2 - 4\phi + 1}{3} - \frac{(1-\phi)^4}{4}$$

$$\int_0^1 \frac{\phi^4 - 4\phi^3 + 6\phi^2 - 4\phi + 1}{3} - \frac{(1-\phi)^4}{4} d\phi \\ = \frac{1}{60}$$

$$= \int_0^1 \int_0^{1-\phi} \int_0^{1-\eta-\phi} \eta^2 d\theta d\eta d\phi = \frac{1}{360} - \frac{1}{120} - \frac{1}{360} \\ = \frac{1}{60} - \frac{1}{360} - \frac{1}{120} - \frac{1}{360} \\ = \frac{1}{360}$$

$$\begin{bmatrix} \frac{1}{360} \\ \frac{1}{360} \\ \frac{1}{120} \\ \frac{1}{360} \end{bmatrix}$$



Resolviendo la segunda integral

$$\int_V \begin{bmatrix} \eta - \epsilon\eta - \eta^2 - \phi\eta \\ \epsilon\eta \\ \eta^2 \\ \phi\eta \end{bmatrix} d\epsilon d\eta d\phi$$

$$\int_0^1 \int_0^{1-\phi} \int_0^{1-\eta-\phi} \begin{bmatrix} \eta - \epsilon\eta - \eta^2 - \phi\eta \\ \epsilon\eta \\ \eta^2 \\ \phi\eta \end{bmatrix} d\epsilon d\eta d\phi$$

$$\left[ \begin{aligned} &\int_0^1 \int_0^{1-\phi} \int_0^{1-\eta-\phi} (\eta - \epsilon\eta - \eta^2 - \phi\eta) d\epsilon d\eta d\phi \\ &\int_0^1 \int_0^{1-\phi} \int_0^{1-\eta-\phi} \epsilon\eta d\epsilon d\eta d\phi \\ &\int_0^1 \int_0^{1-\phi} \int_0^{1-\eta-\phi} \eta^2 d\epsilon d\eta d\phi \\ &\int_0^1 \int_0^{1-\phi} \int_0^{1-\eta-\phi} \phi\eta d\epsilon d\eta d\phi \end{aligned} \right]$$

$$\int_0^1 \int_0^{1-\phi} \int_0^{1-\eta-\phi} \epsilon\eta d\epsilon d\eta d\phi$$

$$\int_0^{1-\eta-\phi} \epsilon\eta d\epsilon \Rightarrow \eta \int_0^{1-\eta-\phi} \epsilon d\epsilon$$

$$= \eta \left( \frac{1 - 2\eta - 2\phi + \eta^2 + 2\eta\phi + \phi^2}{2} \right) = \frac{\eta - 2\eta^2 - 2\eta\phi + \eta^3 + 2\eta^2\phi + \eta\phi^2}{2}$$

$$\int_0^{1-\phi} \frac{\eta - 2\eta^2 - 2\eta\phi + \eta^3 + 2\eta^2\phi + \eta\phi^2}{2} d\eta$$

$$= \frac{-\phi^4 + 4\phi^3 - 6\phi^2 + 4\phi - 1}{8} + \frac{(1-\phi)^4}{8}$$

$$\int_0^1 \frac{-\phi^4 + 4\phi^3 - 6\phi^2 + 4\phi - 1}{12} + \frac{(1-\phi)^4}{8} d\phi$$

$$= \frac{1}{120}$$

$$\int_0^1 \int_0^{1-\phi} \int_0^{1-\eta-\phi} \eta^2 d\epsilon d\eta d\phi \quad \text{Esta integral se resolvió anteriormente}$$

$$= \frac{1}{60}$$

$$\int_0^1 \int_0^{1-\phi} \int_0^{1-\eta-\phi} \phi \eta d\epsilon d\eta d\phi \Rightarrow \int_0^1 \int_0^{1-\phi} \int_0^{1-\eta-\phi} \phi \eta d\phi d\eta d\epsilon$$

al intercambiar la integral Tiene la misma forma de la primera integral

$$= \frac{1}{120}$$

$$\int_0^1 \int_0^{1-\phi} \int_0^{1-\eta-\phi} (\eta - \epsilon \eta - \eta^2 - \phi \eta) d\epsilon d\eta d\phi$$

$$= \int_0^1 \int_0^{1-\phi} \int_0^{1-\eta-\phi} \eta d\epsilon d\eta d\phi - \int_0^1 \int_0^{1-\phi} \int_0^{1-\eta-\phi} \epsilon \eta d\epsilon d\eta d\phi$$

$$- \int_0^1 \int_0^{1-\phi} \int_0^{1-\eta-\phi} \eta^2 d\epsilon d\eta d\phi - \int_0^1 \int_0^{1-\phi} \int_0^{1-\eta-\phi} \phi \eta d\epsilon d\eta d\phi$$

$$= \int_0^1 \int_0^{1-\phi} \int_0^{1-\eta-\phi} \eta d\epsilon d\eta d\phi - \frac{1}{120} - \frac{1}{60} - \frac{1}{120}$$

$$\int_0^1 \int_0^{1-\phi} \int_0^{1-\eta-\phi} \eta d\epsilon d\eta d\phi$$

$$\int_0^{1-\eta-\phi} \eta d\epsilon \Rightarrow \eta \int_0^{1-\eta-\phi} d\epsilon = \eta(1-\eta-\phi)$$

$$= \eta - \eta^2 - \phi \eta$$

$$\int_0^{1-\phi} \eta - \eta^2 - \phi \eta d\eta$$

$$= \frac{-\phi^3 + 3\phi^2 - 3\phi + 1}{6}$$

$$\int_0^1 \frac{-\phi^3 + 3\phi^2 - 3\phi + 1}{6} d\phi$$

$$= \frac{1}{24}$$



$$\begin{aligned}
 &= \int_0^1 \int_0^{1-\phi} \int_0^{1-\eta-\phi} \eta \, d\phi \, d\eta \, d\phi = \frac{1}{120} - \frac{1}{60} - \frac{1}{120} \\
 &= \frac{1}{24} - \frac{1}{120} - \frac{1}{60} - \frac{1}{120} \\
 &= \frac{1}{120}
 \end{aligned}$$

$$\begin{bmatrix} \frac{1}{120} \\ \frac{1}{120} \\ \frac{1}{60} \\ \frac{1}{120} \end{bmatrix}$$

$$J \left( \int_V \begin{bmatrix} \eta^2 - \epsilon \eta^2 - \eta^3 - \phi \eta^2 \\ \epsilon \eta^2 \\ \eta^2 \\ \phi \eta^2 \end{bmatrix} d\epsilon \, d\eta \, d\phi + \int_V \begin{bmatrix} \eta - \epsilon \eta - \eta^2 - \phi \eta \\ \epsilon \eta \\ \eta^2 \\ \phi \eta^2 \end{bmatrix} d\epsilon \, d\eta \, d\phi \right)$$

$$J \left( \begin{bmatrix} \frac{1}{360} \\ \frac{1}{360} \\ \frac{1}{120} \\ \frac{1}{360} \end{bmatrix} + \begin{bmatrix} \frac{1}{120} \\ \frac{1}{120} \\ \frac{1}{60} \\ \frac{1}{120} \end{bmatrix} \right) = J \left( \begin{bmatrix} \frac{1}{90} \\ \frac{1}{90} \\ \frac{1}{40} \\ \frac{1}{90} \end{bmatrix} \right) = b$$

Locho izquierdo

$$-\int_V N^T \epsilon^z \nabla \cdot (\eta^2 \nabla N) dV$$

$$\int_V u dV = [uV]_V - \int_V d u V$$

$$u = N^T \epsilon^z \quad dV = \nabla \cdot (\eta^2 \nabla N)$$

$$d u = \nabla N^T \epsilon^z \quad V = \eta^2 \nabla N$$

$$-([N^T \epsilon^z \eta^2 \nabla N]_V - \int_V \nabla N^T \epsilon^z \eta^2 \nabla N dV)$$

$$-[N^T \epsilon^z \eta^2 \nabla N]_V + \int_V \nabla N^T \epsilon^z \eta^2 \nabla N dV,$$

$$\int_V \nabla N^T \epsilon^z \eta^2 \nabla N dV$$

$$\nabla N = \begin{bmatrix} \frac{\delta}{\delta x} \\ \frac{\delta}{\delta y} \\ \frac{\delta}{\delta z} \end{bmatrix} N = \begin{bmatrix} \frac{\delta}{\delta x} \\ \frac{\delta}{\delta y} \\ \frac{\delta}{\delta z} \end{bmatrix} [N_1 \ N_2 \ N_3 \ N_4]$$

$$= \begin{bmatrix} \frac{\delta}{\delta x} \\ \frac{\delta}{\delta y} \\ \frac{\delta}{\delta z} \end{bmatrix} [1 - \theta - \eta - \phi \quad \epsilon \quad \eta \quad \phi]$$



$$\begin{bmatrix} \frac{\partial}{\partial \epsilon} \\ \frac{\partial}{\partial \eta} \\ \frac{\partial}{\partial \phi} \end{bmatrix} = J \begin{bmatrix} \frac{\partial}{\partial x} \\ \frac{\partial}{\partial y} \\ \frac{\partial}{\partial z} \end{bmatrix} \Rightarrow \begin{bmatrix} \frac{\partial}{\partial x} \\ \frac{\partial}{\partial y} \\ \frac{\partial}{\partial z} \end{bmatrix} = J^{-1} \begin{bmatrix} \frac{\partial}{\partial \epsilon} \\ \frac{\partial}{\partial \eta} \\ \frac{\partial}{\partial \phi} \end{bmatrix}$$

$$\nabla N = J^{-1} \begin{bmatrix} \frac{\partial}{\partial \epsilon} \\ \frac{\partial}{\partial \eta} \\ \frac{\partial}{\partial \phi} \end{bmatrix} [1 - \epsilon - \eta - \phi \quad \epsilon \quad \eta \quad \phi]$$

$$= J^{-1} \begin{bmatrix} \frac{\partial}{\partial \epsilon} (1 - \epsilon - \eta - \phi) & \frac{\partial}{\partial \epsilon} \epsilon & \frac{\partial}{\partial \epsilon} \eta & \frac{\partial}{\partial \epsilon} \phi \\ \frac{\partial}{\partial \eta} (1 - \epsilon - \eta - \phi) & \frac{\partial}{\partial \eta} \epsilon & \frac{\partial}{\partial \eta} \eta & \frac{\partial}{\partial \eta} \phi \\ \frac{\partial}{\partial \phi} (1 - \epsilon - \eta - \phi) & \frac{\partial}{\partial \phi} \epsilon & \frac{\partial}{\partial \phi} \eta & \frac{\partial}{\partial \phi} \phi \end{bmatrix}$$

$$= J^{-1} \begin{bmatrix} -1 & 1 & 0 & 0 \\ -1 & 0 & 1 & 0 \\ -1 & 0 & 0 & 1 \end{bmatrix} = J^{-1} B$$

$$J^{-1} = \frac{1}{J} A$$

$$\nabla N = \frac{1}{J} A B$$



$$\nabla N^T = \left(\frac{1}{J} AB\right)^T \Rightarrow \frac{1}{J} (AB)^T$$

$$\nabla N^T = \frac{1}{J} B^T A^T$$

$$\int_V \nabla N^T \epsilon^z \eta^2 \nabla N dV$$

$$= \int_V \frac{1}{J} B^T A^T \epsilon^z \eta^2 \frac{1}{J} AB dV$$

$$= \frac{1}{J^2} B^T A^T AB \int_V \epsilon^z \eta^2 dV$$

$$= \frac{1}{J^2} B^T A^T AB \int_V \epsilon^z \eta^2 dx dy dz = \frac{1}{J^2} B^T A^T AB \int_V \epsilon^z \eta^2 J d\epsilon d\eta d\phi$$

$$= \frac{1}{J^2} B^T A^T AB J \int_V \epsilon^z \eta^2 d\epsilon d\eta d\phi = \frac{1}{J} B^T A^T AB \int_V \epsilon^z \eta^2 d\epsilon d\eta d\phi$$

$$\int_V \epsilon^z \eta^2 d\epsilon d\eta d\phi$$

$$\int_0^1 \int_0^{1-\phi} \int_0^{1-\eta-\phi} \epsilon^z \eta^2 d\epsilon d\eta d\phi$$

$$\int_0^{1-\eta-\phi} \epsilon^z \eta^2 d\epsilon$$

$$= \frac{\eta^2 - \eta^5 - \eta^2 \phi^3 - 3\eta^3 - 3\eta^2 \phi + 3\eta^4 - 3\eta \phi + 3\eta^2 \phi^2 - 3\eta^3 \phi^2 + 6\eta^3 \phi}{3}$$

$$\int_0^{1-\phi} \frac{\eta^2 - \eta^5 - \eta^2 \phi^3 - 3\eta^3 - 3\eta^2 \phi + 3\eta^4 - 3\eta \phi + 3\eta^2 \phi^2 - 3\eta^3 \phi^2 + 6\eta^3 \phi}{3} d\eta$$

$$= \frac{(\phi-1)^6}{180}$$

$$\int_0^1 \frac{(\phi-1)^6}{180} d\phi$$

$$= \frac{1}{1260}$$

$$= \frac{1}{J} B^T A^T A B \int_V \epsilon^* \eta^2 d\epsilon d\eta d\phi$$

$$= \frac{1}{J} B^T A^T A B \left( \frac{1}{1260} \right)$$

$$= \frac{1}{1260 J} B^T A^T A B$$

$$- [N^T \epsilon^* \eta^2 \nabla N] |_V + \left( \frac{1}{1260 J} B^T A^T A B \right) X = J \begin{bmatrix} \frac{1}{90} \\ \frac{1}{90} \\ \frac{1}{40} \\ \frac{1}{90} \end{bmatrix}$$

$$\left( \frac{1}{1260 J} B^T A^T A B \right) X = J \begin{bmatrix} \frac{1}{90} \\ \frac{1}{90} \\ \frac{1}{40} \\ \frac{1}{90} \end{bmatrix}$$

$$KX = b$$