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IT - I

ML ASSIGNMENT - II

## unit - V Advanced learning

### 1) K-mean clustering:-

K-mean is a partitional clustering algorithm that divides a dataset into K-clusters based on similarity.

steps:-

- 1) choose no of clusters K
- 2) Randomly initialize K centroids
- 3) Assign each data points to nearest centroid
- 4) Recompute centroids as mean of points in each clusters.
- 5) Repeat steps 3-4 until centroids do not change significantly.

$$\text{Objective : Minimize } J = \sum_{i=1}^k \sum_{x \in C_i} \|x - \mu_i\|^2$$

where,  $C_i = \text{cluster}_i$

$\mu_i = \text{centroid of cluster}_i$

Application:-

- => customer segmentation
- => Image compression.

## 2) principal component analysis (PCA)

PCA is a dimensionality reduction technique used to transform high-dimensional data into fewer dimensions while preserving maximum variance

steps:

- 1) Standardize the data
- 2) Compute covariance matrix
- 3) Find eigenvalues, eigenvectors
- 4) Select top  $k$  eigenvectors (principal components)
- 5) Transform data into new reduced feature space.

Example:-

Dataset with 2 feature

$x_1$	$x_2$
2	0
0	2
3	1
1	3

step 1: standardize (mean = 1.5)

step 2: covariance matrix

$$\Sigma = \begin{bmatrix} 1.67 & -1.0 \\ -1.0 & 1.67 \end{bmatrix}$$

first principal component aligns along direction

$[1, -1]$ ;

data can be represented along one axis ( $x_1, -x_2$ ) capturing most of variance.

Advantages:-

- => Remove noise & redundancy.
- => Reduce computation
- => Improve visualization

Applications:-

- => Face and handwriting recognition
- => Image compression
- => Exploratory data analysis

### 3) Gaussian mixture model (GMM)

Introduction:-

A Gaussian mixture model (GMM) is a probabilistic model for representing normally distributed subpopulation within an overall population unlike k-means, it allows clusters of different shapes.

Model definition:-

$$P(x) = \sum_{i=1}^k \pi_i \cdot N(x | \mu_i, \Sigma_i)$$

\*  $\pi_i$  = mixing coefficient

\*  $\mu_i$  = mean vector

\*  $\Sigma_i$  = covariance matrix

Learning parameter:-

expectation - Maximization (EM) algo:-

- 1) Initialize mean ( $\mu$ ), covariance ( $\Sigma$ ) and weight ( $\pi$ ).
- 2) E-step : compute probability each point belongs to each gaussian.
- 3) M-step : Update  $\mu, \Sigma, \pi$  based on these probabilities.
- 4) Repeat : Until log-likelihood converges.

example:-

consider 1D data : [1.0, 1.2, 1.4, 5.0, 5.2, 5.4]

we assume 2 gaussians

- \* Initial mean  $M_1 = 1.0, M_2 = 5.0$
- \* EM will adjust  $M_1 = 1.2, M_2 = 5.2$  and compute
- \* result: two overlapping normal curves fit two clusters better than k-means circles.

Advantages:-

- => handle overlapping clusters
- => provide probability of membership

Application:-

- => Speaker recognition
- => Object detection.
- => Animals detection.

#### 4. Q - learning algorithm:-

reinforcement learning (RL) is learning through interaction. An agent learns to make sequence of decisions, by receiving rewards from the environment. Q-learning is model-free off policy RL algorithm that learn optimal action-value function.

components:-

- > state: environment's situation
- > action: what agent can do
- > reward: numerical feedback
- > policy: mapping from state to action
- > Q-value: expected feature rewards for  $(s, a)$

Q - learning update equation.

$$Q(s, a) \leftarrow Q(s, a) + \alpha [r + \gamma \cdot \max_a Q(s', a') - Q(s, a)]$$

example:-

grid world:

agent starts at bottom-left and must reach top-right goal

action: [up, down, left, right]

reward: +10 for goal, -1 for step.

Initially  $Q(s, a) = 0$

When agent moves and gets reward  $r$ , Q-table update using formula.

After many episode, agent learn optimal action

Advantage:-

- ⇒ Learn without environment model
- ⇒ Work for stochastic task.

Application:-

- ⇒ Game AI ( chess, Go )
- ⇒ Robotic navigation
- ⇒ Traffic signal optimisation.

Problem based on K-means clustering:-

cluster these points into  $k=2$  clusters.

(2,3), (3,3), (6,6), (8,7)

Step 1: Initialize centroid.

$$C_1 = (2,3), C_2 = (6,6)$$

Step 2: Assign points

point	$d(C_1)$	$d(C_2)$	assigned.
(2,3)	0	5	$C_1$
(3,3)	1	4.24	$C_1$
(6,6)	4.24	0	$C_2$
(8,7)	6.4	2.24	$C_2$

$$\text{cluster: } C_1 = [(2,3), (3,3)]$$

$$C_2 = [(6,6), (8,7)]$$

Step 3: Recompute centroid

$$C_1 = (2.5, 3.0)$$

$$C_2 = (7.0, 6.6)$$

Step 4: Assign points  $\rightarrow$  same cluster.

$$C_1 = [(2, 3), (3, 3)]$$

$$C_2 = [(6, 6), (8, 7)]$$