

New Idea: No computing $\frac{d^m f}{dt^m}$
Use only $= f(t, x)$

$$x' = f(t, x)$$

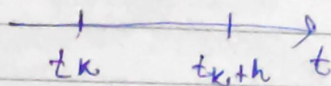
Runge-Kutta Method

1st order $x_{k+1} = x_k + h \cdot f(t_k, x_k)$

2nd order $x_{k+1} = x_k + \frac{1}{2} K_1 + \frac{1}{2} K_2$

where $\begin{cases} K_1 = h \cdot f(t_k, x_k) \\ K_2 = h \cdot f(t_k + h, x_k + K_1) \end{cases} \quad x' = f$

Heun's method.



Theorem: Heun's Method is 2nd order.

pf: It suffices to show local error is $O(h^3)$

Taylor series for $f(t_k + h, x_k + K_1)$ expanded at (t_k, x_k)

$$f(t_k + h, x_k + K_1) = f(t_k, x_k) + h \cdot f_t(t_k, x_k) + K_1 f_x(t_k, x_k) + \underbrace{O(h^2, K_1^2)}_{O(h^2)}$$

$$\Rightarrow K_2 = h \cdot (f + h f_t + h f \cdot f_x + O(h^2))$$

Multi-variable Taylor Series

$f(t_k + h, x_k + K_1)$ expanded at (t_k, x_k)

$$f(t_k + h, x_k + K_1) = f(t_k, x_k) + h f_t(t_k, x_k) + K_1 f_x(t_k, x_k) + \underbrace{O(h^2, K_1^2)}_{O(h^2)}$$

$$\Rightarrow K_2 = h(f + h f_t + h f \cdot f_x + O(h^2))$$

$$x_{k+1} = x_k + \frac{1}{2} h \cdot f + \frac{1}{2} h (f + h f_t + h f \cdot f_x + O(h^2))$$

$$\Rightarrow x_k + \frac{1}{2} h \cdot f + \frac{1}{2} h \cdot f + \frac{h^2}{2} f_t + \frac{h^2}{2} f f_x + O(h^3)$$

$$\Rightarrow x_k + h \cdot f + \frac{h^2}{2} (f_t + f f_x) + O(h^3)$$

Exact soln. $x(t) = \quad x'(t) = f(x, t) \quad x(t_k) = x_k$

Exact solution $x(t_k+h)$

using Taylor Series $\Rightarrow x(t_k) + h \cdot x'(t_k) + \frac{h^2}{2} x''(t_k) + O(h^3)$

$$\Rightarrow x(t_k) + h \cdot f + \frac{h^2}{2} [f_t + f_x \cdot x'] + O(h^3)$$

$$\Rightarrow x_k + h \cdot f + \frac{h^2}{2} [f_t + f_x \cdot f] + O(h^3)$$

$$\text{Local Error} \Rightarrow |x_{k+1} - x(t_{k+1})| = O(h^3)$$

local Error is third order.

general form of m th order Runge Kutta

$$x_{k+1} = x_k + w_1 k_1 + w_2 k_2 + \dots + w_m k_m$$

$$\text{where } k_1 = h \cdot f(t_k, x_k)$$

$$k_2 = h \cdot f(t_k + a_2 \cdot h, x_k + b_2 k_1)$$

$$k_3 = h \cdot f(t_k + a_3 h, x_k + b_3 k_1 + c_3 k_2)$$

\vdots

Classical Runge-Kutta 4

$$x_{k+1} = x_k + \frac{1}{6} [k_1 + 2k_2 + 2k_3 + k_4]$$

$$k_1 = h \cdot f(t_k, x_k) \quad k_2 = h \cdot f(t_k + \frac{1}{2}h, x_k + \frac{1}{2}k_1)$$

$$k_3 = h \cdot f(t_k + \frac{1}{2}h, x_k + \frac{1}{2}k_2) \quad k_4 = h \cdot f(t_k + h, x_k + k_3)$$

Simpson's method

→ Adaptive Methods

Observation

- ① Small $h \rightarrow$ smaller error
- ② Higher order \rightarrow smaller error
- ③ Uniform grid, gives varying local error

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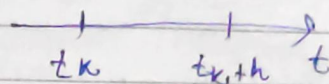
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⋮

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idea: $\rightarrow x_{k+1}$
 $\rightarrow \tilde{x}_{k+1}$ (better method)

$|x_{k+1} - \tilde{x}_{k+1}|$: error measurement

- if $\text{error} \gg \text{tolerance}$, reject, half the step size (h)
- if $\text{error} \ll \text{tolerance}$, accept, double the step size (h)
- if $\text{error} \approx \text{tolerance}$, accept, continue

① Method 1 : take RK4, one step w/ h

Method 2 : take RK4, two steps w/ $h/2$

Use RK4, RK5 \rightarrow Runge-Kutta-Fehlberg
 $m_1 \quad m_2$