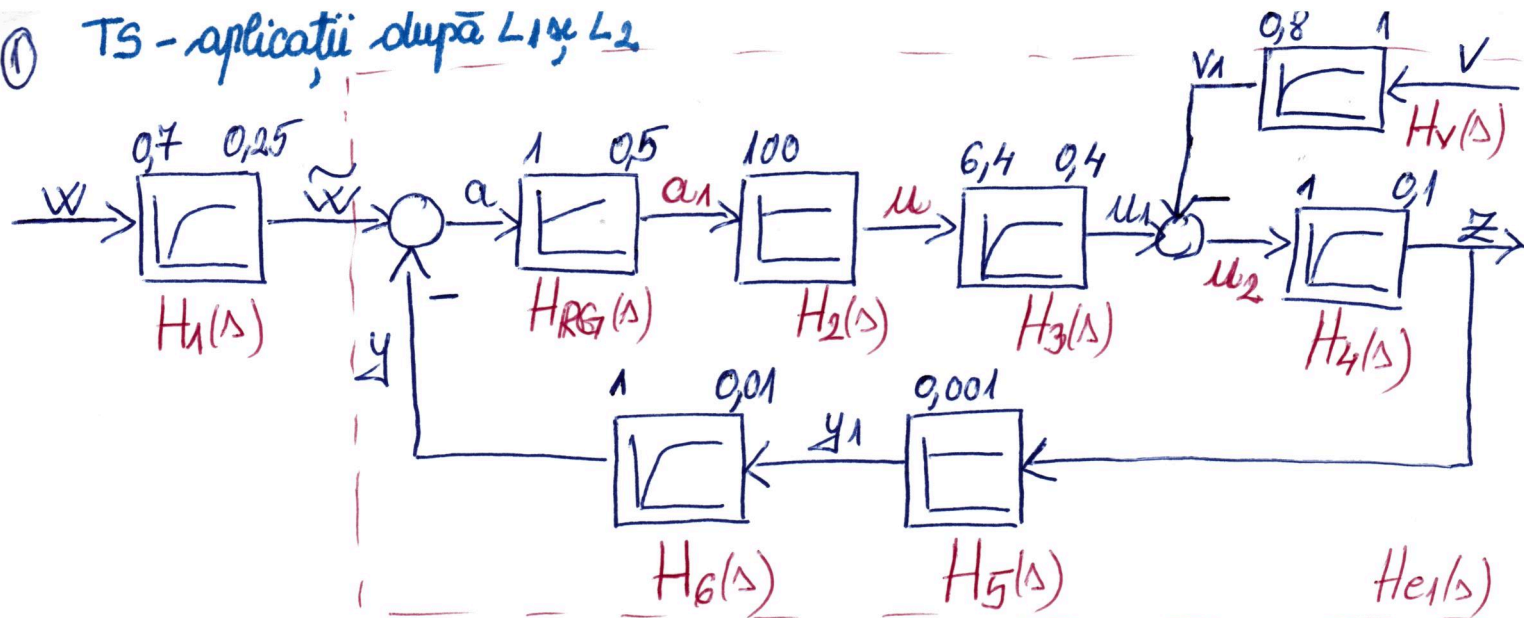


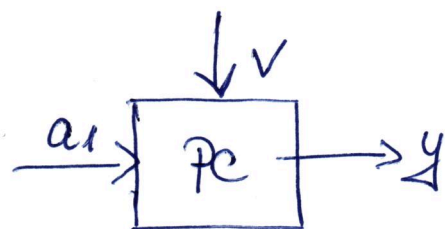
# ① TS - aplicații după $L1$ & $L2$



Să se determine funcțiile de transfer:

$$H_{y a_1}(s) = ? \quad \left. \begin{array}{l} H_{y v}(s) = ? \end{array} \right\} \begin{array}{l} \text{afărate PC} \\ \text{(bucă deschisă)} \end{array}$$

$$H_{z w}(s) = ? \quad \left. \begin{array}{l} H_{z v}(s) = ? \end{array} \right\} \begin{array}{l} \text{afărate SRA} \\ \text{(bucă închisă)} \end{array}$$



$$H_1(s) = \frac{0,7}{1+0,25s} (ET-PT_1)$$

$$H_2(s) = 100 (ET-P)$$

$$H_3(s) = \frac{6,4}{1+0,4s} (ET-PT_1)$$

$$H_4(s) = \frac{1}{1+0,1s} (ET-PT_1)$$

$$H_5(s) = 0,001 (ET-P)$$

$$H_6(s) = \frac{1}{1+0,01s} (ET-PT_1)$$

$$H_{RG}(s) = \frac{k(1+sT)}{sT} = \frac{1 \cdot (1+0,5s)}{0,5s}$$

$$\Rightarrow H_{RG}(s) = \frac{1+0,5s}{0,5s} (ET-Pi)$$

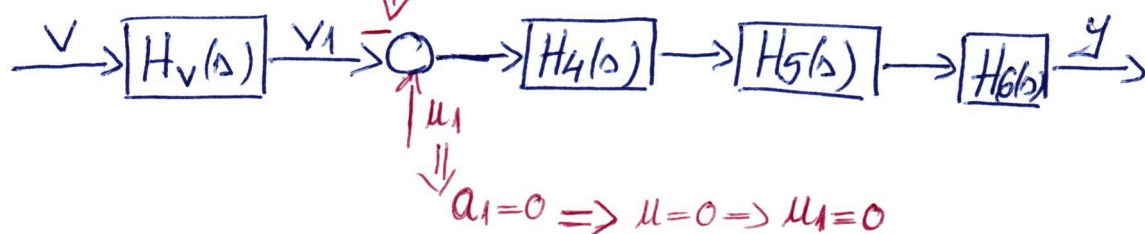
$$H_v(s) = \frac{0,8}{1+s} (ET-PT_1)$$

$$H_{y a_1}(s) = \left. \frac{y(s)}{a_1(s)} \right|_{v=0} = H_2(s) \cdot H_3(s) \cdot H_4(s) \cdot H_5(s) H_6(s) =$$

$$= 100 \cdot \frac{6,4}{1+0,4s} \cdot \frac{1}{1+0,1s} \cdot 0,001 \cdot \frac{1}{1+0,01s} = \frac{0,64}{(1+0,4s)(1+0,1s)(1+0,01s)}$$

$$\Rightarrow H_{y a_1}(\Delta) = \frac{0,64}{(1+0,01\Delta)(1+0,1\Delta)(1+0,4\Delta)}$$

$$H_{y v}(\Delta) = \left. \frac{y(\Delta)}{v(\Delta)} \right|_{a_1=0} = -H_v(\Delta) \cdot H_4(\Delta) \cdot H_5(\Delta) \cdot H_6(\Delta) \Rightarrow$$



$$H_{y v}(\Delta) = - \frac{0,8}{1+\Delta} \cdot \frac{1}{1+0,1\Delta} \cdot 0,001 \cdot \frac{1}{1+0,01\Delta} \Rightarrow H_{y v}(\Delta) = - \frac{0,0008}{(1+\Delta)(1+0,1\Delta)(1+0,01\Delta)}$$

$$H_{zw}(\Delta) = \left. \frac{z(\Delta)}{w(\Delta)} \right|_{v=0} = H_1(\Delta) \cdot H_{e_1}(\Delta) = H_1(\Delta) \cdot \frac{H_{R6}(\Delta) \cdot H_2(\Delta) \cdot H_3(\Delta) \cdot H_4(\Delta)}{1 + H_{R6}(\Delta) H_2(\Delta) H_3(\Delta) H_4(\Delta) [H_5(\Delta) + H_6(\Delta)]}$$

$$= \frac{0,7}{1+0,25\Delta} \cdot \frac{\frac{1+0,5\Delta}{0,5\Delta} \cdot 100 \cdot \frac{6,4}{1+0,4\Delta} \cdot \frac{1}{1+0,1\Delta}}{1 + \frac{640(1+0,5\Delta)}{0,5\Delta(1+0,4\Delta)(1+0,1\Delta)} \cdot 0,001 \cdot \frac{1}{1+0,01\Delta}} =$$

$$= \frac{0,7}{1+0,25\Delta} \cdot \frac{\frac{1280(1+0,5\Delta)}{\Delta(1+0,4\Delta)(1+0,1\Delta)}}{1 + \frac{1,28(1+0,5\Delta)}{\Delta(1+0,4\Delta)(1+0,1\Delta)(1+0,01\Delta)}} = \frac{0,7}{1+0,25\Delta} \cdot \frac{\frac{1280(1+0,5\Delta)}{\Delta(1+0,4\Delta)(1+0,1\Delta)}}{\frac{\Delta(1+0,4\Delta)(1+0,1\Delta)(1+0,01\Delta) + 1,28(1+0,5\Delta)}{\Delta(1+0,4\Delta)(1+0,1\Delta)(1+0,01\Delta)}}$$

$$= \frac{0,7}{1+0,25\Delta} \cdot \frac{1280(1+0,01\Delta)(1+0,5\Delta)}{\Delta(1+0,4\Delta)(1+0,1\Delta)(1+0,01\Delta) + 1,28(1+0,5\Delta)} =$$

$$= \frac{0,7}{1+0,25\Delta} \cdot \frac{1280(1+0,01\Delta)(1+0,5\Delta)}{(0,4\Delta^2 + \Delta)(0,001\Delta^2 + 0,11\Delta + 1) + 1,28 + 0,64\Delta} =$$

$$= \frac{0,7}{1+0,25\Delta} \cdot \frac{1280(1+0,01\Delta) \cdot 1}{0,0004\Delta^4 + 0,044\Delta^3 + 0,4\Delta^2 + 0,001\Delta^3 + 0,11\Delta^2 + \Delta + 1,28 + 0,64\Delta}$$

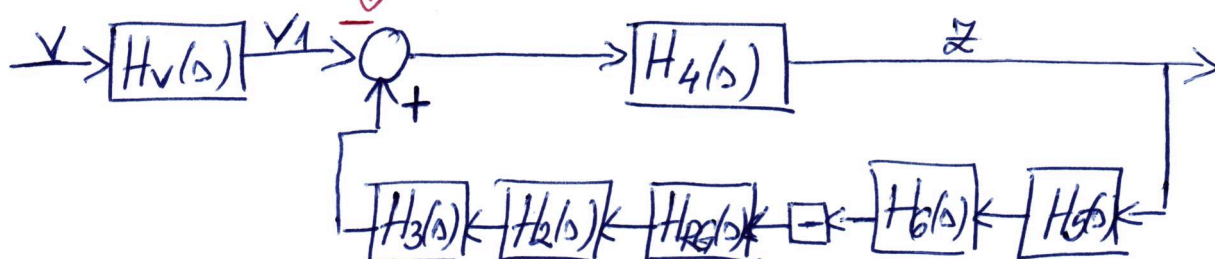
$$= \frac{896(1+0,01\Delta)(1+0,5\Delta)}{(1+0,25\Delta)(0,0004\Delta^4 + 0,045\Delta^3 + 0,51\Delta^2 + 1,64\Delta + 1,28)}$$



$$H_{zw}(s) = \frac{896(1+0,01s)(1+0,5s)}{(1+0,25s)(0,0004s^4+0,045s^3+0,51s^2+1,64s+1,28)}$$

$$H_{zv}(s) = \left. \frac{z(s)}{v(s)} \right|_{w=0} = -H_v(s) \cdot H_{e2}(s) = -H_v \cdot \frac{H_4(s)}{1-H_4(s)[H_5(s)H_6(s)(-H_{RG}(s)H_2(s)H_3(s))]}$$

$$1+H_{RG}(s)H_2(s)H_3(s)H_4(s)H_5(s)H_6(s)}$$

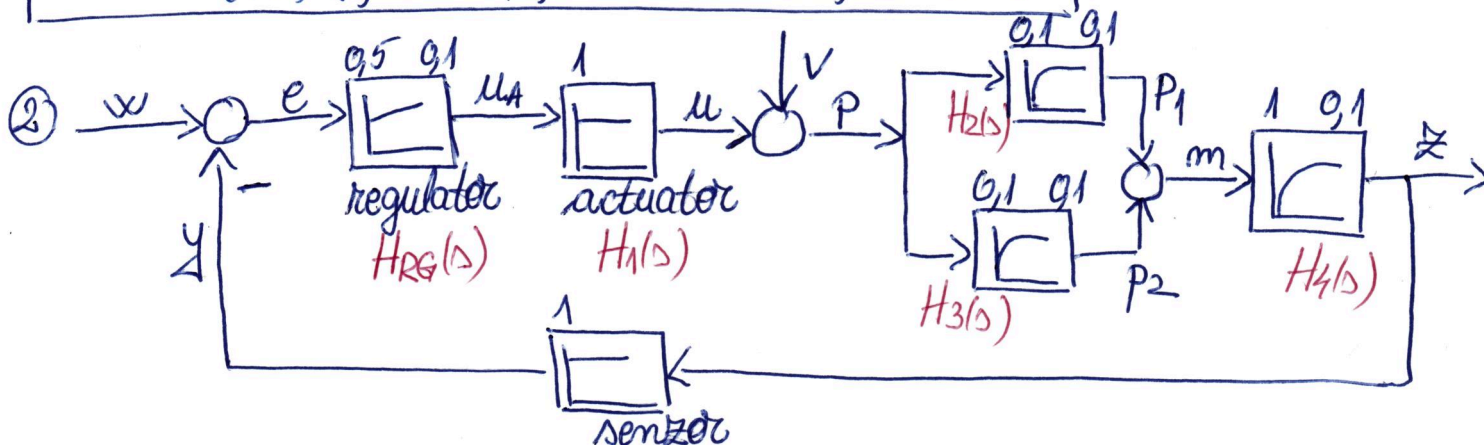


$$H_{zv}(s) = - \frac{0,8}{1+s} \cdot \frac{\frac{1}{1+0,1s}}{0,0004s^4+0,045s^3+0,51s^2+1,64s+1,28} =$$

$$\frac{\Delta(1+0,01s)(1+0,4s)}{0,0004s^4+0,045s^3+0,51s^2+1,64s+1,28}$$

$$= - \frac{0,8}{1+s} \cdot \frac{\Delta(1+0,01s)(1+0,4s)}{0,0004s^4+0,045s^3+0,51s^2+1,64s+1,28} \Rightarrow$$

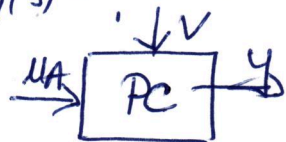
$$H_{zv}(s) = \frac{0,8s(1+0,01s)(1+0,4s)}{(1+s)(0,0004s^4+0,045s^3+0,51s^2+1,64s+1,28)}$$



Să se determine funcțiile de transfer:

$$\left. \begin{aligned} H_{yu_A}(s) &= ? \\ H_{yv}(s) &= ? \end{aligned} \right\} \text{ aferente PC}$$

(bucă deschisă)



$$\left. \begin{aligned} H_{zw}(s) &= ? \\ H_{zv}(s) &= ? \end{aligned} \right\} \text{ aferente SRA}$$

(bucă închisă)



$$H_{RG}(s) = \frac{k(1+\Delta T)}{\Delta T} = \frac{0,5(1+0,1\Delta)}{0,1\Delta} = \frac{5(1+0,1\Delta)}{\Delta} (ET-P_i^o)$$

$$H_1(s) = 1(ET-P)$$

$$\left. \begin{aligned} H_2(s) &= \frac{0,1}{1+0,1\Delta} (ET-PT_1) \\ H_3(s) &= \frac{0,1}{1+0,1\Delta} (ET-PT_1) \end{aligned} \right\} \Rightarrow H_{23}(s) = H_2(s) + H_3(s) = \frac{0,2}{1+0,1\Delta} (ET-PT_1)$$

$$H_4(s) = \frac{1}{1+0,1\Delta} (ET-PT_1)$$

$$H_5(s) = 1 (ET-P)$$

$$H_{y_{uA}}(s) = \left. \frac{y(s)}{u_A(s)} \right|_{v=0} = H_1(s) \cdot H_{23}(s) \cdot H_4(s) \cdot H_5(s) = 1 \cdot \frac{0,2}{1+0,1\Delta} \cdot \frac{1}{1+0,1\Delta} \quad (1 \Rightarrow)$$

$$\boxed{H_{y_{uA}}(s) = \frac{0,2}{(1+0,1\Delta)(1+0,1\Delta)}}$$

$$H_{y_v}(s) = \left. \frac{y(s)}{v(s)} \right|_{u_A=0} = H_{23}(s) \cdot H_4(s) \cdot H_5(s) = \frac{0,2}{1+0,1\Delta} \cdot \frac{1}{1+0,1\Delta} \cdot 1 \Rightarrow$$

$$\boxed{H_{y_v}(s) = \frac{0,2}{(1+0,1\Delta)(1+0,1\Delta)}}$$

$$H_{zw}(s) = \left. \frac{z(s)}{w(s)} \right|_{v=0} = \frac{H_{RG}(s) \cdot H_1(s) \cdot H_{23}(s) \cdot H_4(s)}{1 + H_{RG}(s) \cdot H_1(s) \cdot H_{23}(s) \cdot H_4(s) \cdot H_5(s)} =$$

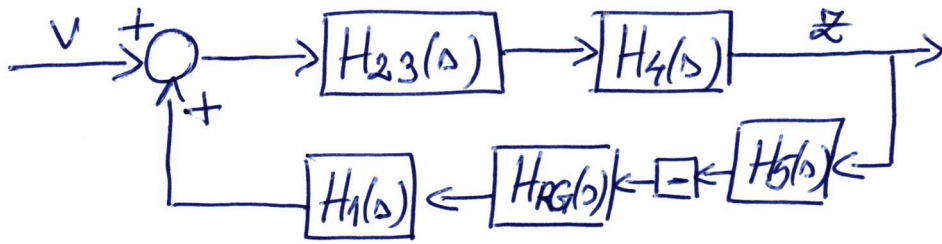
$$= \frac{\frac{5(1+0,1\Delta)}{\Delta} \cdot 1 \cdot \frac{0,2}{1+0,1\Delta} \cdot \frac{1}{1+0,1\Delta}}{1 + \frac{(1+0,1\Delta)}{\Delta(1+0,1\Delta)(1+0,1\Delta)} \cdot 1} = \frac{\frac{(1+0,1\Delta)}{\Delta(1+0,1\Delta)(1+0,1\Delta)}}{\frac{\Delta(1+0,1\Delta)^2 + (1+0,1\Delta)}{\Delta(1+0,1\Delta)(1+0,1\Delta)}} =$$

$$= \frac{1+0,1\Delta}{(1+0,1\Delta)(\Delta(1+0,1\Delta) + 1)} = \frac{1+0,1\Delta}{(1+0,1\Delta)(0,1\Delta^2 + \Delta + 1)} \Rightarrow$$

$$\boxed{H_{zw}(s) = \frac{1+0,1\Delta}{(1+0,1\Delta)(0,1\Delta^2 + \Delta + 1)}}$$



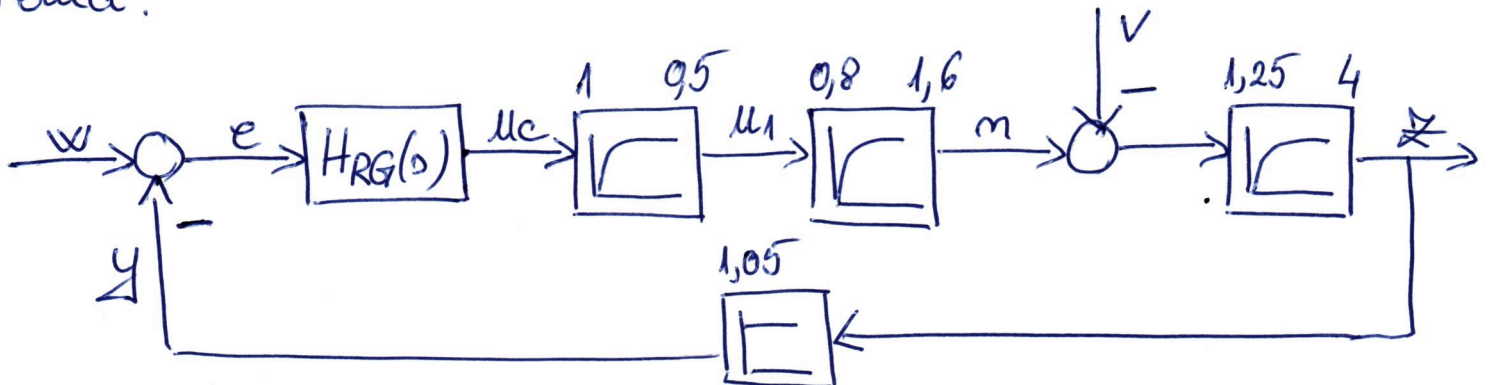
$$H_{zv}(s) = \left. \frac{z(s)}{v(s)} \right|_{w=0} = \frac{H_{23}(s)H_4(s)}{1 - H_{23}(s)H_4(s)[(-)H_{RG}(s)H_1(s)H_5(s)]} \Rightarrow$$



$$H_{zv}(s) = \frac{H_{23}(s)H_4(s)}{1 + H_{RG}(s)H_1(s)H_{23}(s)H_4(s)H_5(s)} = \frac{\frac{0,2}{(1+0,1s)} \cdot \frac{1}{(1+0,1s)}}{\frac{(1+0,1s)(0,1s^2 + s + 1)}{s(1+0,1s)(1+0,1s)}}$$

$$\Rightarrow \boxed{H_{zv}(s) = \frac{0,2s}{(1+0,1s)(0,1s^2 + s + 1)}}$$

Temă:



Să se determine f.d.t:  $H_{yuc}(s) = ?$

$H_{yv}(s) = ?$

$H_{zw}(s) = ?$

$H_{zv}(s) = ?$

Funcția de transfer a regulatorului este:  $H_{RG}(s) = \frac{2(1+2s)}{1+0,1s} (ET-PAT)$