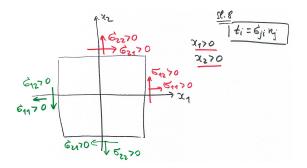
$$\sigma_{allow} \le \frac{\sigma_{ultimate}}{n}$$

$$\sigma' = A \cdot \sigma \cdot A^{\mathrm{T}}, a_{ij} = \cos(x'_i, x_j)$$



$$\varepsilon_{ij} = \frac{1}{2} \left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right)$$

$$\begin{cases} \varepsilon_{11} = \frac{1}{E}\sigma_{11} - \frac{v}{E}\sigma_{22} - \frac{v}{E}\sigma_{33} \\ \varepsilon_{22} = -\frac{v}{E}\sigma_{11} + \frac{1}{E}\sigma_{22} - \frac{v}{E}\sigma_{33} \\ \varepsilon_{33} = -\frac{v}{E}\sigma_{11} - \frac{v}{E}\sigma_{22} + \frac{1}{E}\sigma_{33} \\ \varepsilon_{12} = \frac{1+v}{E}\sigma_{12}, \, \varepsilon_{23} = \frac{1+v}{E}\sigma_{23}, \, \varepsilon_{13} = \frac{1+v}{E}\sigma_{13} \end{cases}$$

$$G = \frac{E}{2(1+v)}$$

$$\delta = \sum_{i} \frac{P_i \ L_i}{A_i E_i}$$

$$\varphi = \sum_{i} \frac{T_i \ L_i}{J_i G_i}$$

$$J = \frac{1}{2}\pi c^4$$

$$\varepsilon_{xx} = -\frac{y}{\rho}$$

$$\sigma_{xx} = -\frac{M_z y}{I_-}$$

 $\sigma_{xx} = (\sigma_{xx})_{centric} + (\sigma_{xx})_{bending}$

$$\sigma_{xx} = -\frac{M_z y}{I_z} + \frac{M_y z}{I_y}$$
$$I_z = \frac{1}{12}bh^3$$





$$q = rac{VQ_z}{I_z}, \qquad au_{ave} = rac{VQ_z}{I_z t}$$
 $- au xy \max = rac{3}{2} rac{V}{A}$

$$M(x) = EI \frac{d^2y}{dx^2}$$

$$\det(\boldsymbol{\sigma} - \boldsymbol{I}\tilde{\sigma}) = 0$$

$$C_I = \frac{\sigma_{II} + \sigma_{III}}{2}, \qquad R_I = \frac{\sigma_{II} - \sigma_{III}}{2}$$