

Dynamics 2

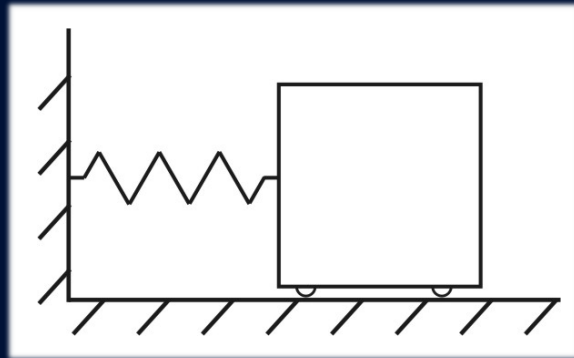
Introduction to Oscillations (Oscillatory Motion)

Oscillatory Motion

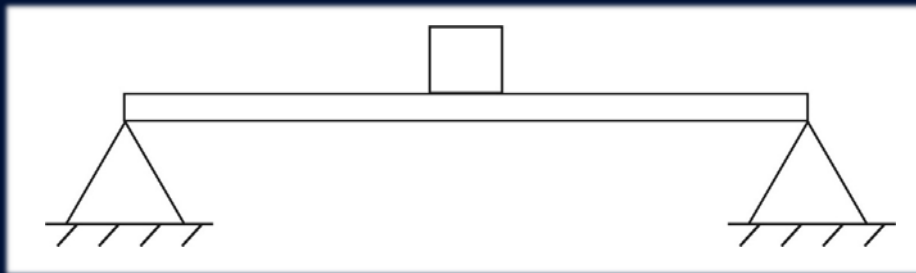
- Dynamics problems have involved steadily accelerating particles and bodies.
- Large problem areas in Dynamics involve non-steady acceleration
 - ie oscillatory motion
- A consequence of the interaction of two basic properties of material bodies

Mass + Elasticity → Oscillations

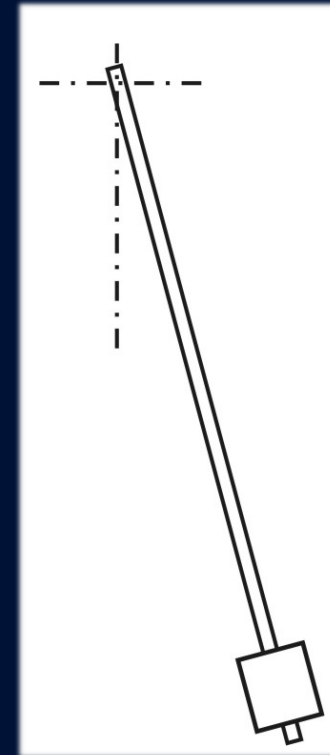
Basic Mechanical Oscillators



mass + spring



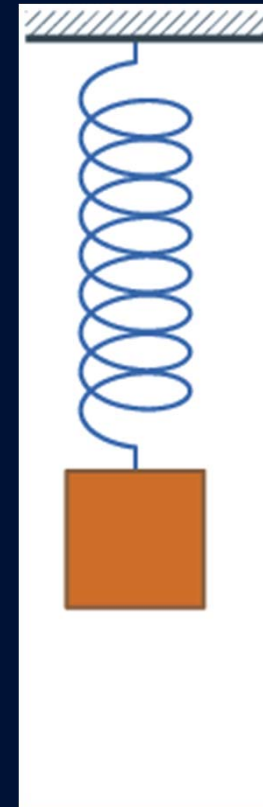
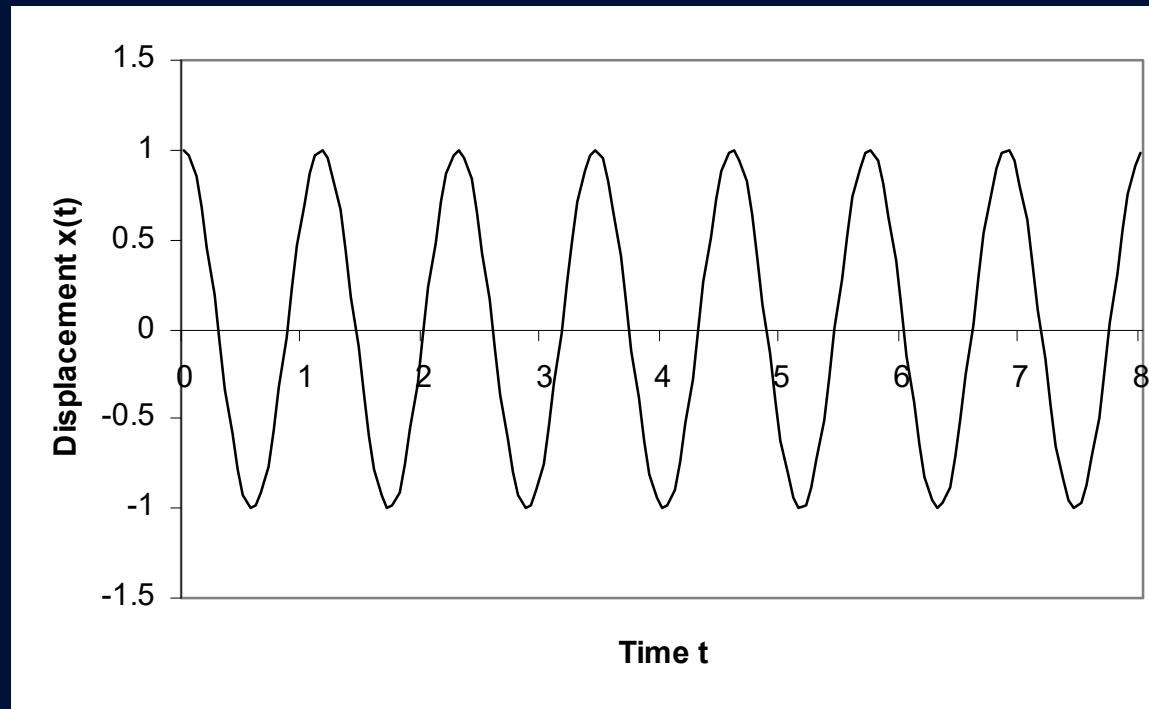
mass on beam



pendulum

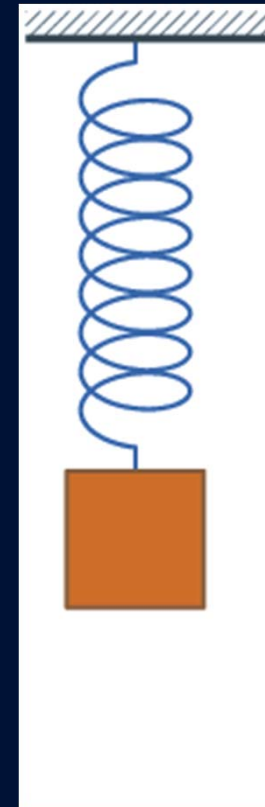
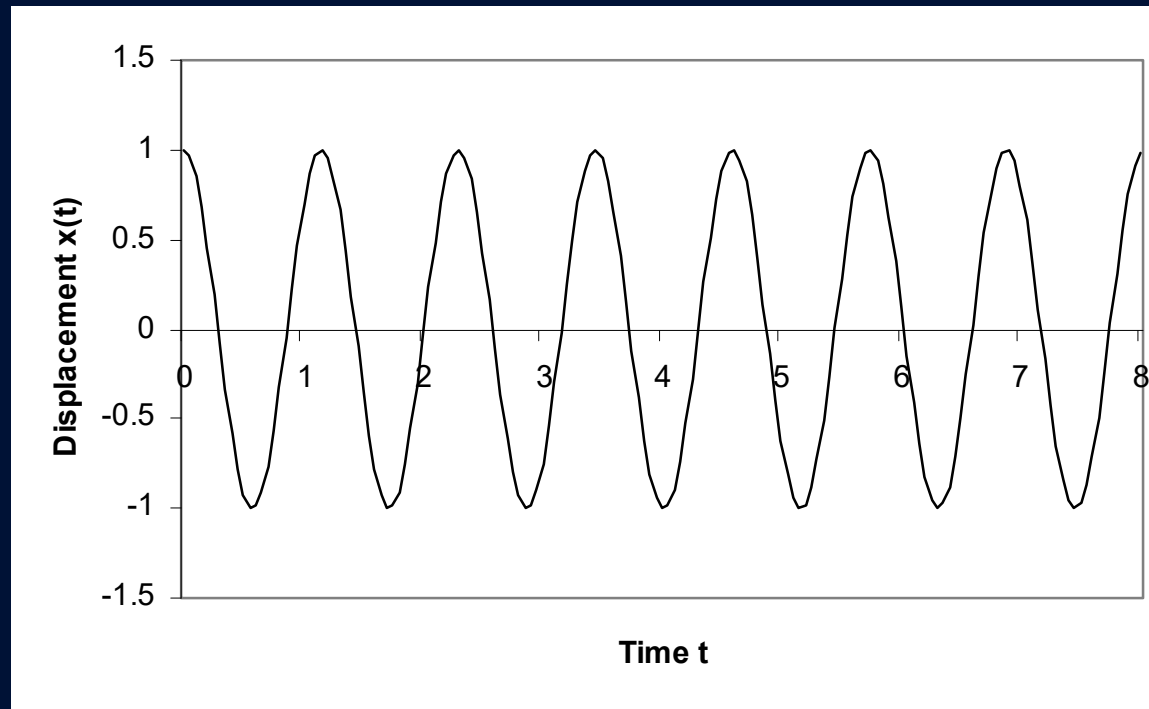
Basic Mechanical Oscillators

- Disturbances cause oscillations
 - Simple Harmonic Motion (SHM)



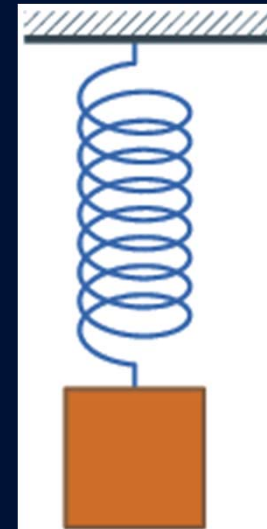
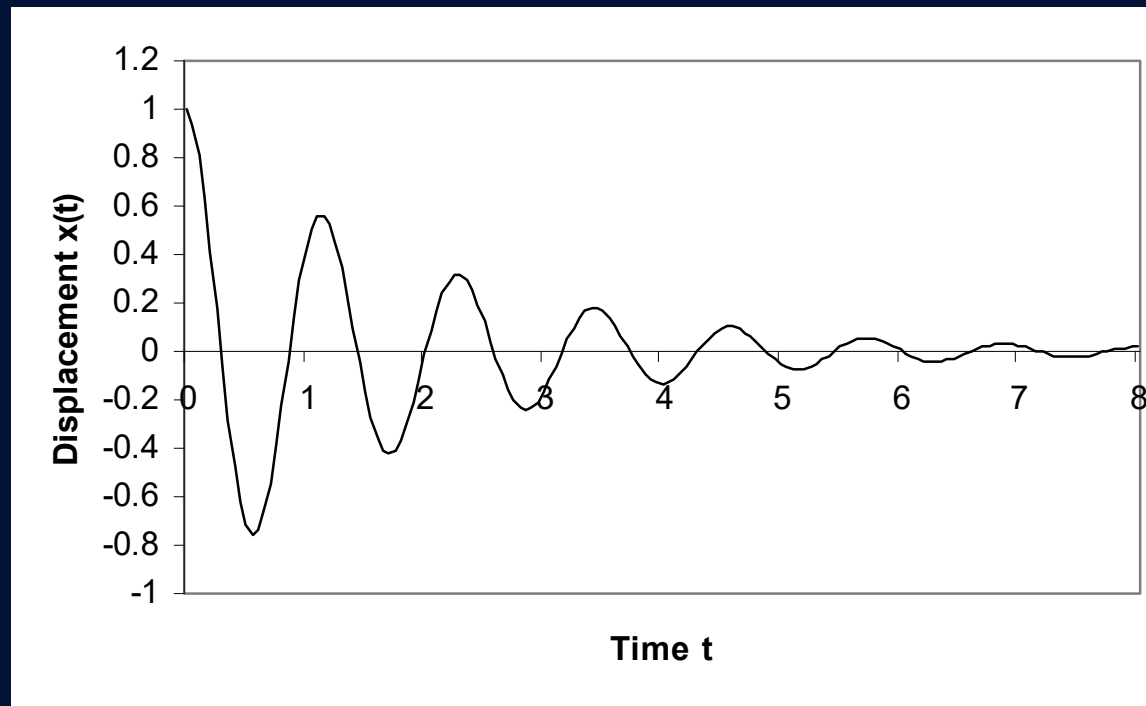
Basic Mechanical Oscillators

- 'Free vibration' in response to initial disturbance
 - In ideal case, oscillations last indefinitely



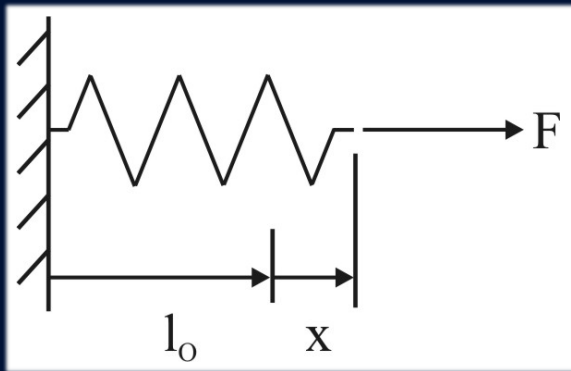
Basic Mechanical Oscillators

- In reality, energy lost by friction
 - oscillations decay due to damping!

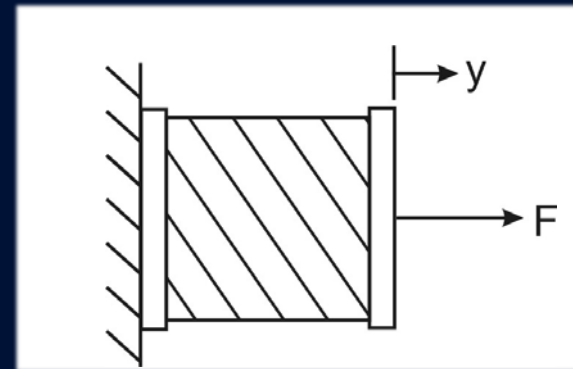


Elasticity and Spring Elements

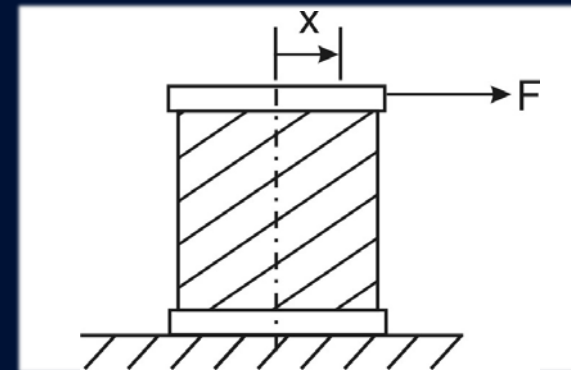
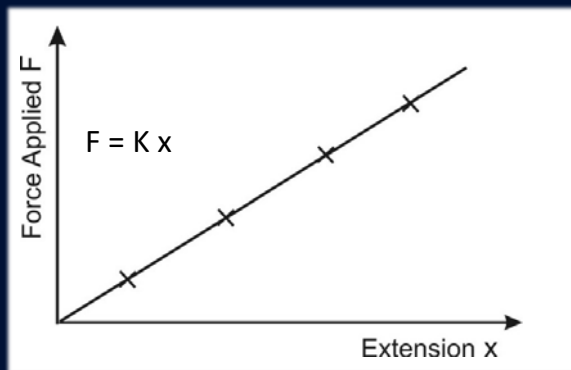
- Coil spring



- Rubber bush

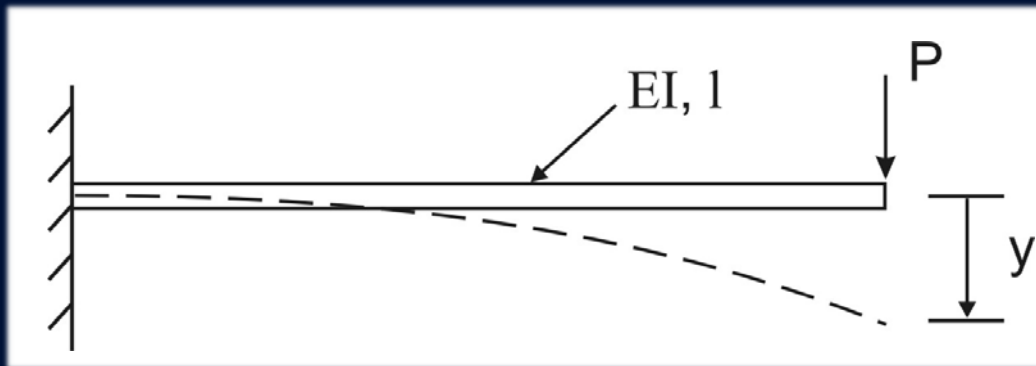


- Hookes Law



Elasticity and Spring Elements

- Beams – Cantilever



$$\text{Flexural Rigidity} = \frac{3EI}{l^3}$$

E = Young's modulus (N/m^2)

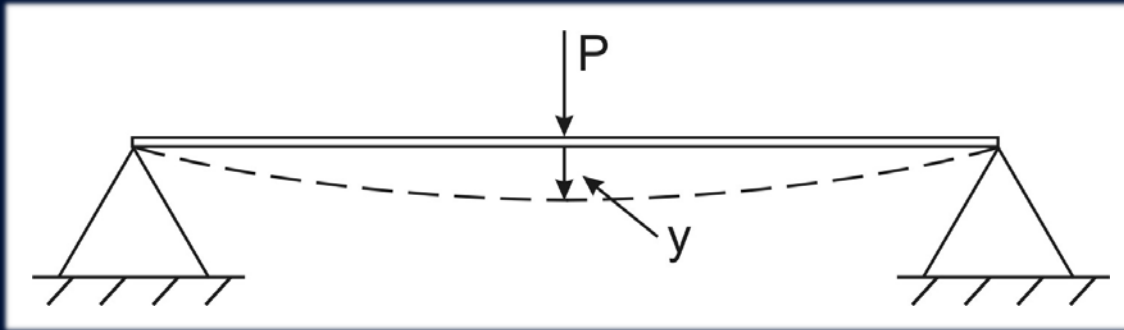
I = Second moment of area (m^4)

$$y = \frac{Pl^3}{3EI}$$

$$P = \left(\frac{3EI}{l^3} \right) y$$

Elasticity and Spring Elements

- Beams – Simply supported



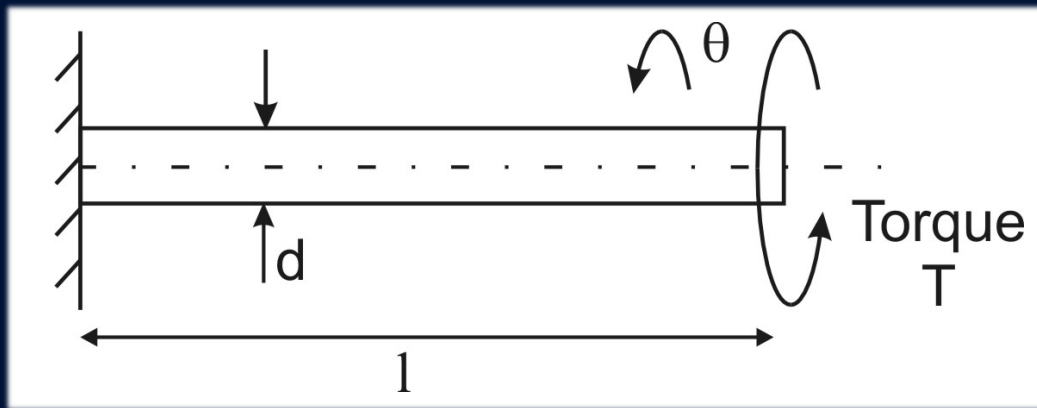
$$y = \frac{Pl^3}{48EI}$$

$$P = \left(\frac{48EI}{l^3} \right) y$$

$$\text{Flexural Rigidity} = \frac{48EI}{l^3}$$

Elasticity and Spring Elements

- Beams – Torsion Bar



$$T = \frac{GI_p}{l} \theta$$

$$T = \left(\frac{G\pi d^4}{32l} \right) \theta$$

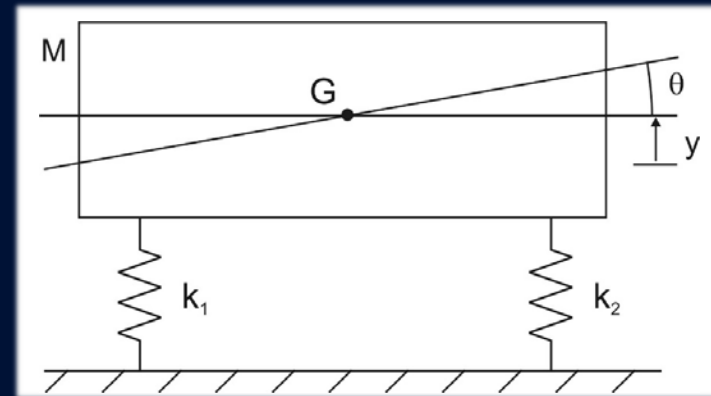
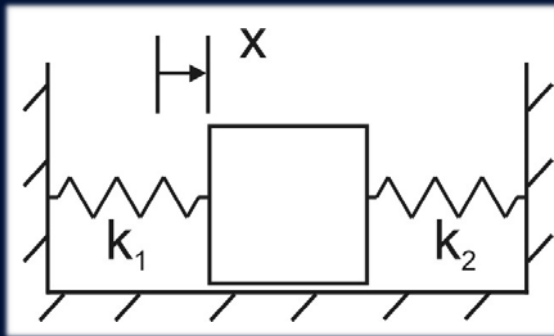
$$\text{Torsional Stiffness} = \frac{G\pi d^4}{32l}$$

G = modulus of rigidity (N/m^2)

I_p = polar second moment of area (m^4)

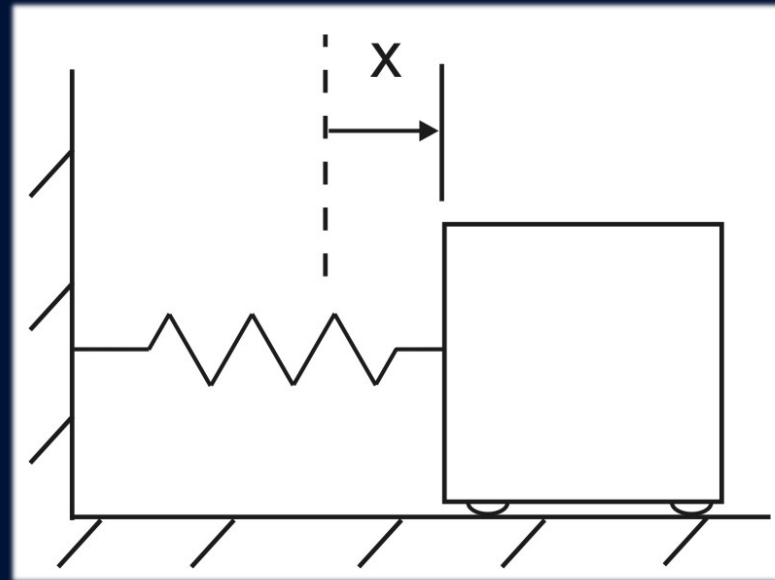
Degrees of Freedom (DoF)

- DoF is the number of coordinates needed to fully specify the instantaneous position of body in motion
- and number of natural frequencies system possesses
 - corresponding ‘mode’ of oscillation
- Only single DoF systems used in this course
- Examples of 1 (left) and 2 DoF (right) systems



Differential Equation of Free Oscillations

- Simplest mechanical oscillator
- $x(t)$ is instantaneous position of the mass from its equilibrium point (i.e. with the spring unstretched)



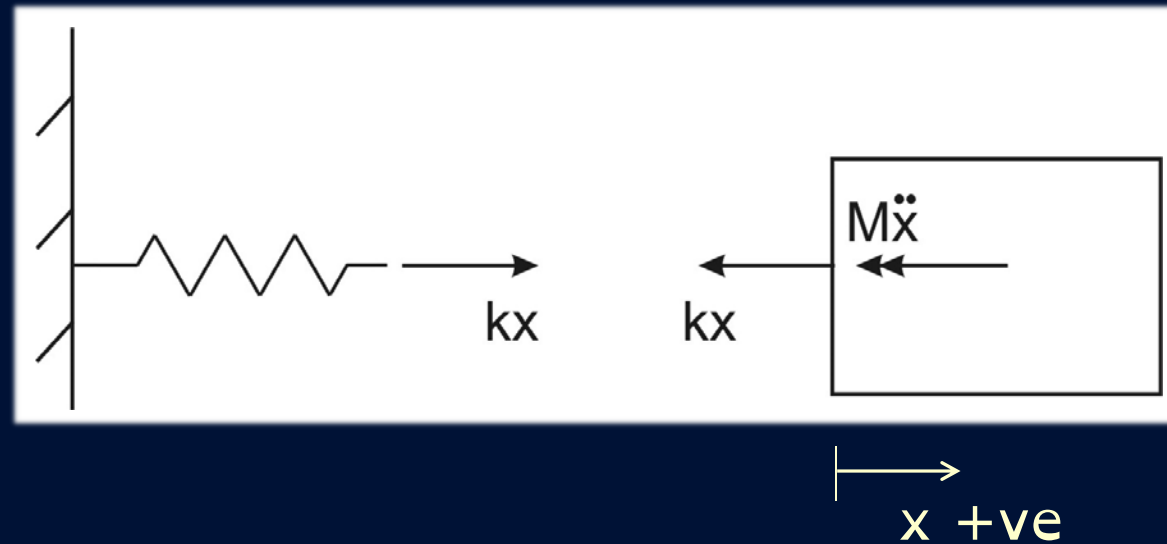
Differential Equation of Free Oscillations

- FBD

$$M\ddot{x} + Kx = 0$$

$$\ddot{x} + \frac{K}{M}x = 0$$

$$\ddot{x} + \omega_0^2 x = 0$$



$$\omega_0 = \sqrt{\frac{K}{M}}$$

Differential Equation of Free Oscillations

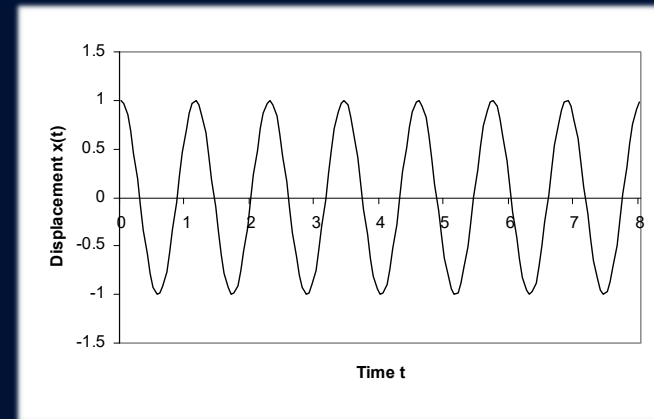
- Second order DE

$$\ddot{x} + \omega_0^2 x = 0$$

- General Solution

$$x(t) = C_1 \cos \omega_0 t + C_2 \sin \omega_0 t$$

- Simple Harmonic Motion
 - natural frequency (in Hz)
 - Period (in seconds)



$$f_0 = \frac{\omega_0}{2\pi}$$

$$T_0 = \frac{2\pi}{\omega_0}$$

Differential Equation of Free Oscillations

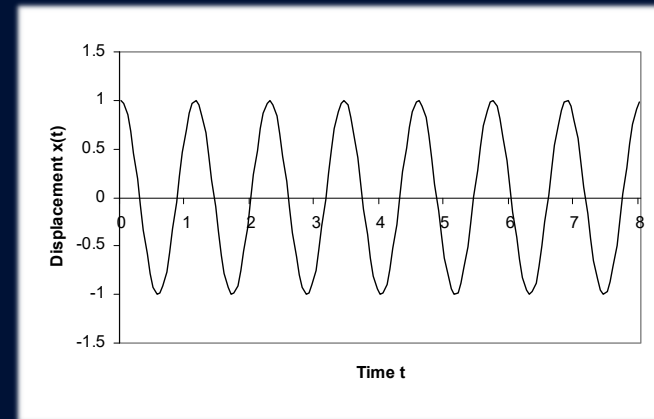
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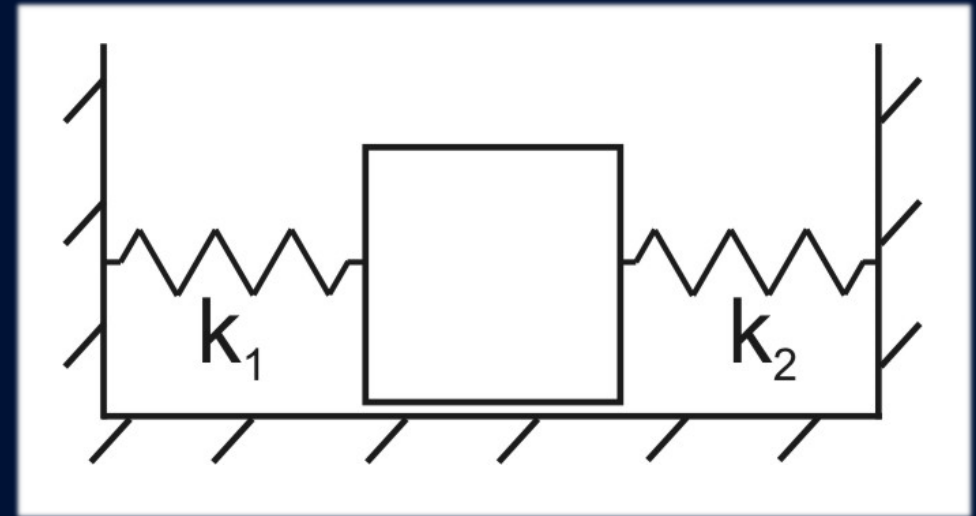
$$x(t) = C_1 \cos \omega_0 t + C_2 \sin \omega_0 t$$

- Magnitude of oscillation determined by the constants C_1 and C_2 which are fixed by the boundary conditions
 - eg, the initial displacement and/or velocity of the mass at $t = 0$.



Example 4.1

- Find
 - system DE
 - natural frequency of oscillation in Hz, if the system is disturbed
- Data
 - $M = 0.5 \text{ kg}$
 - $k_1 = 80 \text{ N/m}$
 - $k_2 = 140 \text{ N/m}$

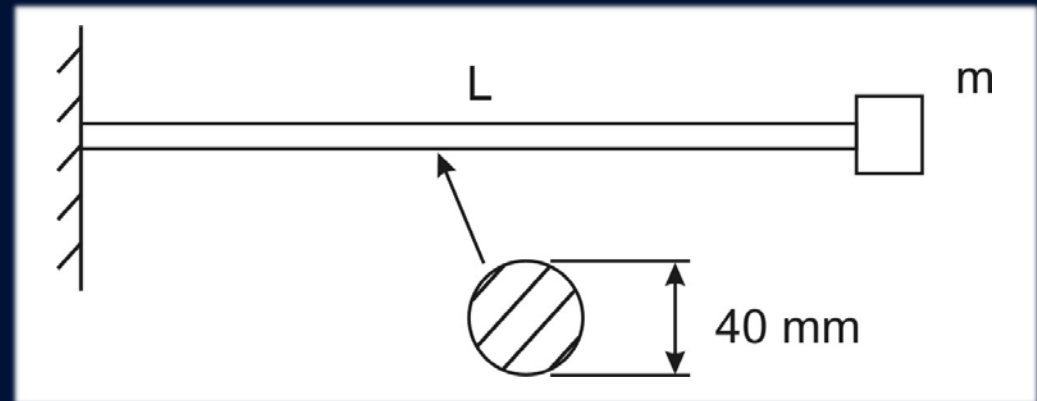


Dynamics 2

Introduction to Oscillations
(Oscillatory Motion)
Worked Example: Cantilever

Example 4.2

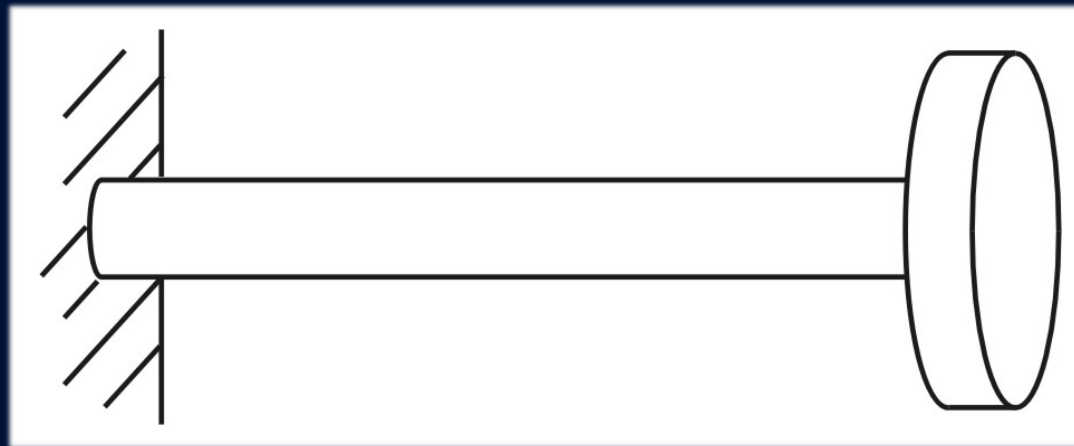
- Mass m (12 kg) is attached to the end of a cantilevered beam.
- Find the system natural frequency of free vibration if disturbed.
- Steel beam
 - $E = 20.7 \times 10^{10} \text{ N/m}^2$
 - $L = 1.2 \text{ m}$
 - cross section shown.



- What approximations are used?
- What is the effect of gravity?

Example 4.6

- Determine the frequency of torsional oscillations of a uniform disc connected to a solid circular steel bar
- Disc details: $R = 0.4 \text{ m}$; mass = 20 kg
- Steel bar details: 1 m; $\varnothing = 0.1$; $G = 80 \text{ GPa}$



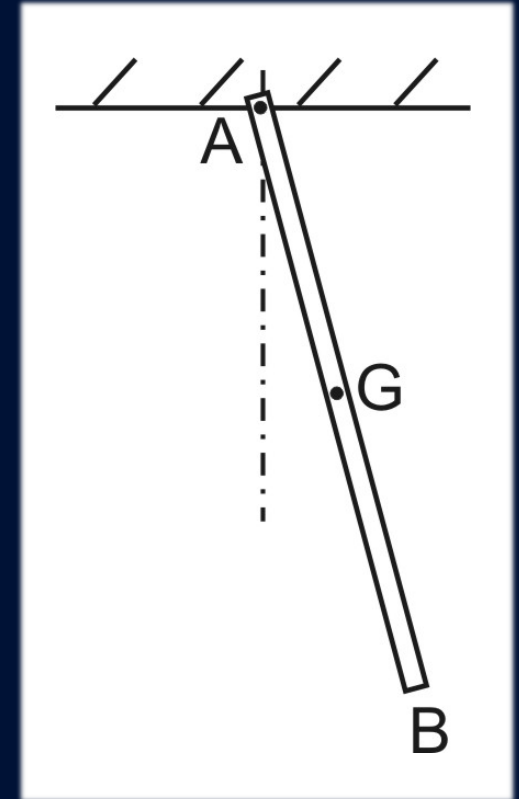
Dynamics 2

Introduction to Oscillations
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Worked Example: Hinged Pendulum

Example 4.5

- Find an expression for the frequency of small oscillations of the uniform pendulum bar AB
- What would be the effect if the pivot was attached to a lift accelerating upwards?

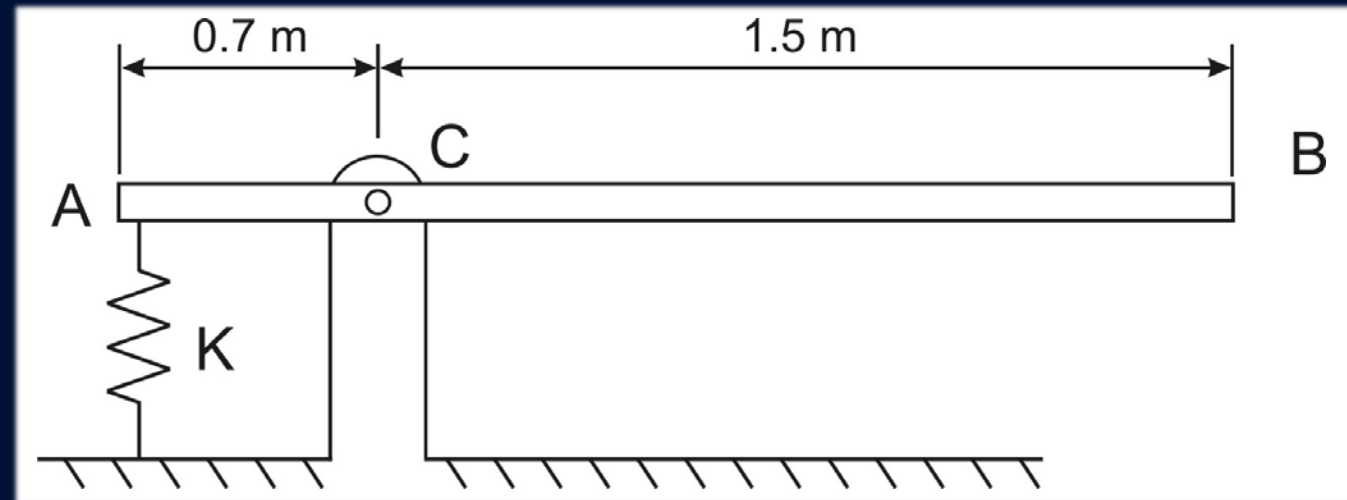


Summary

- Worked example of oscillatory motion in a hinged pendulum with small amplitude of oscillation.

Example 4.4

- Equipment shown is for a childrens' playground
- AB is a 65 kg pivoted steel beam
- Find the stiffness of spring K to give a system frequency of oscillation of 0.8 Hz when a 30 kg child is sitting at B



Example 4.3

- A is a 25 kg crate moving along roller track at 3.5 m/s
- It is stopped by B, a spring loaded buffer
 - B is rigid 32 kg mass restrained by four 90 N/m stiffness springs
- Find
 - maximum displacement of the buffer
 - maximum load transmitted to the wall

