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Algebraic dynamics is “dynamics in the setting of algebraic geometry”.

The base field is an algebraically closed field \mathbf{k} with characteristic 0, usually \mathbb{C} or $\overline{\mathbb{Q}}$.

An *algebraic dynamical system* is a pair (X, f) where X is a variety over \mathbf{k} and $f : X \dashrightarrow X$ is a dominant rational self-map.

Here we focus on the case that X is smooth and projective, and f is an endomorphism.

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First we introduce some basic invariants of algebraic dynamical systems.

Definition 1 ((The first) dynamical degree).

Definition 2 (Arithmetic degree).

Note that dynamical degree is a global invariant of the map f , while arithmetic degree is a local invariant at the point x . Therefore, it is natural to ask about the relation between these two invariants. Kawaguchi-Silverman conjectured the following.

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Suppose that this point x has a Zariski dense (forward) orbit. Somehow this means that x can reflect the global dynamics of f on X . Then we expect that the arithmetic degree at x equals to the dynamical degree of f .

Conjecture 3 (Kawaguchi-Silverman Conjecture = KSC).

So far KSC is still wide open in general. A useful method to study KSC is to use equivariant fibrations. That is, we have a dominant rational map $\pi : X \dashrightarrow Y$ and a dominant rational map $g : Y \dashrightarrow Y$ such that the following diagram commutes:

$$\begin{array}{ccc} X & \xrightarrow{f} & X \\ \downarrow \pi & & \downarrow \pi \\ Y & \xrightarrow{g} & Y. \end{array}$$

Suppose further that $\delta_f = \delta_g$. Then KSC for (X, f) can be reduced to KSC for (Y, g) . Therefore, it is important to study when such fibrations exist.

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A fibration $\pi : X \dashrightarrow Y$ is said to be *f-equivariant* if there is a dominant rational map $g : Y \dashrightarrow Y$ such that $\pi \circ f = g \circ \pi$.

Given a fibration $\pi : X \rightarrow Y$ induced by a semiample divisor D . Suppose that $f^*D \equiv qD$ for some $q > 0$, then by rigidity lemma and elementary intersection theory, π is *f*-equivariant.

In algebraic geometry, Iitaka fibration is a very important fibration associated to an effective divisor. Therefore, it is natural to ask how to give a dynamical analogue of Iitaka fibration.

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Professor Meng and Zhang recently developed a dynamical analogue of Iitaka theory. Here I will briefly introduce some main results in their paper [MZ23].

First we need to extend the definition of Iitaka dimension to the setting of algebraic dynamics.

Definition 4 (Dynamical Iitaka dimension).

Then we have the following result about the existence of dynamical Iitaka fibration.

Theorem 5 (ref. [MZ23, Theorem 4.6]).

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Using dynamical Iitaka fibration, we can try to classify algebraic dynamical systems (X, f) . In classical theory, varieties are classified according to the Kodaira dimension, i.e., Iitaka dimension of the canonical divisor K_X . In the dynamical setting, we will consider the dynamical Iitaka dimension of the ramification divisor $R_f = K_X - f^*K_X$. It is always effective. Hence we have the following three cases.

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- $\kappa_f(X, R_f) = 0$. (log étale case)
- $0 < \kappa_f(X, R_f) < \dim X$. (intermediate case)
- $\kappa_f(X, R_f) = \dim X$. (big case)

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We consider the case the (X, f) has admitted an f -equivariant extremal Fano contraction $\pi : X \rightarrow Y$ such that $\delta_f > \delta_{f|_Y}$.

Since π is of relative Picard number 1, the general fiber X_Y is Fano and $\delta_f > \delta_{f|_Y} \geq 1$, the ramification divisor R_f is non-trivial and π -ample.

Hence we want to use the dynamical Iitaka fibration associated to R_f to get another f -equivariant fibration.

Further assume that the base Y is either an abelian variety or a smooth projective variety of Picard number one, we get our main results.

Theorem 6 (Main Theorem 1).

Theorem 7 (Main Theorem 2).

As a direct application of our main results, we can prove KSC for such varieties.