```
vars, n, a, x, y, z, w, m, o
 ivar, i, k, j, l
 const, b
 A, B, C
                                           В
                                                                                                   Base type
                                          Unit
                                                                                                   Unit
                                          A\otimes B
                                                                                                   Non-commutative tensor
                                          A \rightharpoonup B
                                                                                                   Left implication
                                          A \leftarrow B
                                                                                                   Right implication
                                          \mathsf{w} A
                                           \mathsf{c} A
                                           eA
                                ::=
                                          \boldsymbol{x}
                                          b
                                          unit
                                          let t_1: A be t_2 in t_3
                                          let t_1 be t_2 in t_3
                                                                                     S
                                          t_1 \otimes t_2
                                          \lambda_l x : A.t
                                          \lambda_r x : A.t
                                           app_l t_1 t_2
                                          app_r t_1 t_2
                                           \mathbf{W} t
                                           e t
                                          \mathbf{C}\,t
                                          \text{weak}_l t_1 \text{ in } t_2
                                          \operatorname{weak}_r t_1 \operatorname{in} t_2
                                           con_l x, y to t_1 in t_2
                                           con_r x, y to t_1 in t_2
                                           \operatorname{ex} x_1, x_2 \operatorname{with} t_1, t_2 \operatorname{in} t_3
 Γ, Δ, Φ, Ψ
                                          \Gamma_1, \Gamma_2
                                          x : A
                                          (Γ)
                                                                                     S
\Gamma; \Psi; \Phi; \Delta \vdash t : A
                                                                                                Lax
                                                              \overline{\cdot;\cdot;\cdot;x:A\vdash x:A}
                                                                                                W_{\!AX}
                                                              \overline{\cdot;\cdot;x:A;\cdot\vdash x:A}
                                                                                                Cax
                                                              \overline{\cdot;x:A;\cdot;\cdot\vdash x:A}
                                                                                                Eax
                                                              \overline{x:A;\cdot;\cdot;\cdot\vdash x:A}
```

```
\frac{}{\cdot;\cdot;\cdot;\cdot\vdash b:B} Const
                                                            \overline{\cdot;\cdot;\cdot;\cdot} + unit : Unit
                        \Gamma_1; \Psi_1; \Phi_1; \Delta_1 \vdash t_1 : \mathsf{Unit} \quad \Gamma_2; \Psi_2; \Phi_1; \Delta_2 \vdash t_2 : C
                                                                                                                                                          UNITE
             \overline{(\Gamma_1,\Gamma_2);(\Psi_1,\Psi_2);(\Phi_1,\Phi_2);(\Delta_1,\Delta_2)} \vdash \mathsf{let}\,\mathsf{unit}\,\mathsf{be}\,t_1\,\mathsf{in}\,t_2:C
                         \Gamma_1; \Psi_1; \Phi_1; \Delta_1 \vdash t_1 : A \quad \Gamma_2; \Psi_2; \Phi_1; \Delta_2 \vdash t_2 : B
                                                                                                                                                   TENSORI
                   \overline{(\Gamma_1, \Gamma_2); (\Psi_1, \Psi_2); (\Phi_1, \Phi_2); (\Delta_1, \Delta_2) \vdash t_1 \otimes t_2 : A \otimes B}
      \Gamma_1; \Psi_1; \Phi_1; \Delta_1 \vdash t_1 : A \otimes B \quad \Gamma_2; \Psi_2; \Phi_1; \Delta_2, x : A, y : B \vdash t_2 : B
                                                                                                                                                                   TENSORE
\overline{(\Gamma_1, \Gamma_2); (\Psi_1, \Psi_2); (\Phi_1, \Phi_2); (\Delta_1, \Delta_2) \vdash \mathsf{let}\, x \otimes y : A \otimes B \, \mathsf{be}\, t_1 \, \mathsf{in}\, t_2 : C}
                                                        \Gamma; \Psi; \Phi; x : A, \Delta \vdash t : B
                                                                                                                            LFUN
                                                \Gamma; \Psi; \Phi; \Delta \vdash \lambda_l x : A.t : A \rightarrow B
                                                        \Gamma; \Psi; \Phi; \Delta, x : A \vdash t : B
                                               \Gamma; \Psi; \Phi; \Delta \vdash \lambda_r x : A.t : B \leftarrow A
                       \Gamma_1; \Psi_1; \Phi_1; \Delta_1 \vdash t_1 : A \rightarrow B \quad \Gamma_2; \Psi_2; \Phi_1; \Delta_2 \vdash t_2 : A
                       (\Gamma_1, \Gamma_2); (\Psi_1, \Psi_2); (\Phi_1, \Phi_2); (\Delta_1, \Delta_2) \vdash \mathsf{app}_t t_1 t_2 : B
                      \Gamma_1; \Psi_1; \Phi_1; \Delta_1 \vdash t_1 : B \leftarrow A \quad \Gamma_2; \Psi_2; \Phi_1; \Delta_2 \vdash t_2 : A
                                                                                                                                                         RAPP
                       (\Gamma_1, \Gamma_2); (\Psi_1, \Psi_2); (\Phi_1, \Phi_2); (\Delta_1, \Delta_2) \vdash \mathsf{app}_r \, t_1 \, t_2 : B
                                                                    \cdot; \cdot; \Psi; \cdot \vdash t : A
                                                                                                                 wI
                                                               \overline{\cdot ; \cdot ; \Psi ; \cdot \vdash \mathsf{w} \, t : \mathsf{w} \, A}
                                                                    \cdot; \Phi; \cdot; \cdot \vdash t : A
                                                                 \overline{\cdot;\Phi;\cdot;\cdot\vdash \mathtt{C}\,t:\mathtt{C}\,A}
                                                                      \Gamma;\cdot;\cdot;\cdot \vdash t:A
                                                                 \overline{\Gamma;\cdot;\cdot;\cdot\vdash\mathsf{e}\,t:\mathsf{e}\,A}
                     \Gamma_1; \Psi_1; \Phi_1; \Delta_1 \vdash t_1 : \mathsf{w} A \quad \Gamma_2; \Psi_2; \Phi_1, x : A; \Delta_2 \vdash t_2 : B
                                                                                                                                                                     wE
           \overline{(\Gamma_1, \Gamma_2)}; (\Psi_1, \Psi_2); (\Phi_1, \Phi_2); (\Delta_1, \Delta_2) \vdash \text{let w } x : \text{w } A \text{ be } t_1 \text{ in } t_2 : B
                       \Gamma_1; \Psi_1; \Phi_1; \Delta_1 \vdash t_1 : cA \quad \Gamma_2; \Psi_2, x : A; \Phi_1; \Delta_2 \vdash t_2 : B
                                                                                                                                                                    cЕ
            \overline{(\Gamma_1,\Gamma_2)}; (\Psi_1,\Psi_2); (\Phi_1,\Phi_2); (\Delta_1,\Delta_2) \vdash \mathsf{let}\,\mathsf{c}\,x : \mathsf{c}\,A\,\mathsf{be}\,t_1\,\mathsf{in}\,t_2 : B
                      \Gamma_1; \Psi_1; \Phi_1; \Delta_1 \vdash t_1 : eA \quad \Gamma_2, x : A; \Psi_2; \Phi_1; \Delta_2 \vdash t_2 : B
                                                                                                                                                                     ьE
            \overline{(\Gamma_1,\Gamma_2)}; (\Psi_1,\Psi_2); (\Phi_1,\Phi_2); (\Delta_1,\Delta_2) \vdash \text{let e } x : e A \text{ be } t_1 \text{ in } t_2 : B
                                              \Gamma; \Psi; \Phi; \Delta \vdash t : B \quad x \notin \mathsf{FV}(t)
                                                                                                                              RWEAK
                                         \overline{\Gamma; \Psi; \Phi, x : A; \Delta \vdash \mathsf{weak}_r x \mathsf{in} t : B}
                                               \Gamma; \Psi; \Phi; \Delta \vdash t : B \quad x \notin FV(t)
                                         \Gamma; \Psi; x : A, \Phi; \Delta \vdash \mathsf{weak}_t x \mathsf{in} t : B
                                       \Gamma; \Psi_1, x : A, \Psi_2, y : A, \Psi_3; \Phi; \Delta \vdash t : B
                                                                                                                                               LCON
                             \overline{\Gamma; \Psi_1, z: A, \Psi_2, \Psi_3; \Phi; \Delta \vdash \operatorname{con}_l x, y \operatorname{to} z \operatorname{in} t: B}
                                       \Gamma; \Psi_1, x : A, \Psi_2, y : A, \Psi_3; \Phi; \Delta \vdash t : B
                                                                                                                                                RCON
                            \overline{\Gamma; \Psi_1, \Psi_2, z: A, \Psi_3; \Phi; \Delta \vdash \mathsf{con}_r x, y \mathsf{to} z \mathsf{in} t: B}
                                            \Gamma_1, x_1 : A, x_2 : B, \Gamma_2; \Psi; \Phi; \Delta \vdash t : C
                          \overline{\Gamma, z_1 : B, z_2 : A; \Psi; \Phi; \Delta} \vdash \operatorname{ex} x_1, x_2 \operatorname{with} z_1, z_2 \operatorname{in} t : C
```