```
vars, n, a, x, y, z, w, m, o
 ivar, i, k, j, l
 const, b
 A, B, C
                                              В
                                                                                                          Base type
                                              Unit
                                                                                                          Unit
                                             A\otimes B
                                                                                                          Non-commutative tensor
                                             A \rightharpoonup B
                                                                                                          Left implication
                                             A \leftarrow B
                                                                                                          Right implication
                                              \mathsf{w} A
                                              \mathsf{c} A
                                              eA
                                  ::=
                                             \boldsymbol{x}
                                              b
                                              unit
                                              let t_1: A be t_2 in t_3
                                                                                           S
                                              let t_1 be t_2 in t_3
                                             t_1 \otimes t_2
                                              \lambda_l x : A.t
                                              \lambda_r x : A.t
                                              app_l t_1 t_2
                                              app_r t_1 t_2
                                              \mathbf{W} t
                                              e t
                                              \mathbf{C}\,t
                                              \text{weak}_l t_1 \text{ in } t_2
                                              \operatorname{weak}_r t_1 \operatorname{in} t_2
                                              con_l x, y to t_1 in t_2
                                              con_r x, y to t_1 in t_2
                                              \operatorname{ex} x_1, x_2 \operatorname{with} t_1, t_2 \operatorname{in} t_3
                                              \operatorname{dist}_{\operatorname{ecw}} t
                                              \operatorname{dist}_{\operatorname{cw}} t
                                              \operatorname{dist}_{\operatorname{ew}} t
                                              dist_{ec} t
 Γ, Δ, Φ, Ψ
                                             \Gamma_1, \Gamma_2
                                             x:A
                                                                                           S
                                              (Γ)
\Gamma; \Psi; \Phi; \Delta \vdash t : A
                                                                                                       Lax
                                                                   \cdot;\cdot;\cdot;x:A\vdash x:A
                                                                                                       W_{\!AX}
                                                                   \overline{\cdot;\cdot;x:A;\cdot\vdash x:A}
```

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Cax
                                                             \overline{\cdot;x:A;\cdot;\cdot\vdash x:A}
                                                             \overline{x:A;\cdot;\cdot;\cdot\vdash x:A}
                                                                \overline{\cdot;\cdot;\cdot;\cdot\vdash b:B}
                                                                                                          UNITI
                                                          \cdot; \cdot; \cdot; \cdot \vdash unit : Unit
                       \Gamma_1; \Psi_1; \Phi_1; \Delta_1 \vdash t_1: Unit \Gamma_2; \Psi_2; \Phi_1; \Delta_2 \vdash t_2: C
                                                                                                                                                     UNITE
             \overline{(\Gamma_1,\Gamma_2);(\Psi_1,\Psi_2);(\Phi_1,\Phi_2);(\Delta_1,\Delta_2)} \vdash let unit be t_1 in t_2: C
                        \Gamma_1; \Psi_1; \Phi_1; \Delta_1 \vdash t_1 : A \quad \Gamma_2; \Psi_2; \Phi_1; \Delta_2 \vdash t_2 : B
                                                                                                                                             TENSORI
                  \overline{(\Gamma_1,\Gamma_2);(\Psi_1,\Psi_2);(\Phi_1,\Phi_2);(\Delta_1,\Delta_2)\vdash t_1\otimes t_2:A\otimes B}
     \Gamma_1; \Psi_1; \Phi_1; \Delta_1 \vdash t_1 : A \otimes B \quad \Gamma_2; \Psi_2; \Phi_1; \Delta_2, x : A, y : B \vdash t_2 : B
                                                                                                                                                             TENSORE
\overline{(\Gamma_1, \Gamma_2); (\Psi_1, \Psi_2); (\Phi_1, \Phi_2); (\Delta_1, \Delta_2)} \vdash \text{let } x \otimes y : A \otimes B \text{ be } t_1 \text{ in } t_2 : C
                                                      \Gamma; \Psi; \Phi; x : A, \Delta \vdash t : B
                                                                                                                       LFUN
                                              \overline{\Gamma; \Psi; \Phi; \Delta \vdash \lambda_l x : A.t : A \rightharpoonup B}
                                                      \Gamma; \Psi; \Phi; \Delta, x : A \vdash t : B
                                              \Gamma; \Psi; \Phi; \Delta \vdash \lambda_r x : A.t : B \leftarrow A
                      \Gamma_1; \Psi_1; \Phi_1; \Delta_1 \vdash t_1 : A \rightarrow B \quad \Gamma_2; \Psi_2; \Phi_1; \Delta_2 \vdash t_2 : A
                                                                                                                                                    LAPP
                       (\Gamma_1, \Gamma_2); (\Psi_1, \Psi_2); (\Phi_1, \Phi_2); (\Delta_1, \Delta_2) \vdash \mathsf{app}_l \, t_1 \, t_2 : B
                      \Gamma_1; \Psi_1; \Phi_1; \Delta_1 \vdash t_1 : B \leftharpoonup A \quad \Gamma_2; \Psi_2; \Phi_1; \Delta_2 \vdash t_2 : A
                                                                                                                                                   RAPP
                       (\Gamma_1, \Gamma_2); (\Psi_1, \Psi_2); (\Phi_1, \Phi_2); (\Delta_1, \Delta_2) \vdash \mathsf{app}_r \, t_1 \, t_2 : B
                                                                 \cdot; \cdot; \Psi; \cdot \vdash t : A
                                                                                                             wI
                                                             \overline{\cdot;\cdot;\Psi;\cdot\vdash\mathsf{w}\,t:\mathsf{w}\,A}
                                                                   \cdot; \Phi; \cdot; \cdot \vdash t : A
                                                               \overline{\cdot;\Phi;\cdot;\cdot\vdash\mathsf{C}\,t:\mathsf{C}\,A}
                                                                   \Gamma;\cdot;\cdot;\cdot \vdash t:A
                                                               \overline{\Gamma;\cdot;\cdot;\cdot\vdash\mathsf{e}\,t:\mathsf{e}\,A}
                    \Gamma_1; \Psi_1; \Phi_1; \Delta_1 \vdash t_1 : \mathsf{W}A \quad \Gamma_2; \Psi_2; \Phi_1, x : A; \Delta_2 \vdash t_2 : B
                                                                                                                                                               wE
          \overline{(\Gamma_1, \Gamma_2); (\Psi_1, \Psi_2); (\Phi_1, \Phi_2); (\Delta_1, \Delta_2)} \vdash \text{let } \mathbf{w} \, x : \mathbf{w} \, A \text{ be } t_1 \text{ in } t_2 : B
                      \Gamma_1; \Psi_1; \Phi_1; \Delta_1 \vdash t_1 : cA \quad \Gamma_2; \Psi_2, x : A; \Phi_1; \Delta_2 \vdash t_2 : B
                                                                                                                                                              cЕ
            \overline{(\Gamma_1, \Gamma_2); (\Psi_1, \Psi_2); (\Phi_1, \Phi_2); (\Delta_1, \Delta_2)} \vdash \text{let } cx : cA \text{ be } t_1 \text{ in } t_2 : B
                     \Gamma_1; \Psi_1; \Phi_1; \Delta_1 \vdash t_1 : eA \quad \Gamma_2, x : A; \Psi_2; \Phi_1; \Delta_2 \vdash t_2 : B
            \overline{(\Gamma_1,\Gamma_2)}; (\Psi_1,\Psi_2); (\Phi_1,\Phi_2); (\Delta_1,\Delta_2) \vdash \mathsf{let}\,\mathsf{e}\,x : \mathsf{e}\,A\,\mathsf{be}\,t_1\,\mathsf{in}\,t_2 : B
                                             \Gamma; \Psi; \Phi; \Delta \vdash t : B \quad x \notin FV(t)
                                                                                                                          RWEAK
                                        \overline{\Gamma; \Psi; \Phi, x : A; \Delta \vdash \mathsf{weak}_r x \mathsf{in} t : B}
                                             \Gamma; \Psi; \Phi; \Delta \vdash t : B \quad x \notin FV(t)
                                                                                                                         LWEAK
                                        \Gamma; \Psi; x : A, \Phi; \Delta \vdash \mathsf{weak}_{t} x \mathsf{in} t : B
                                      \Gamma; \Psi_1, x : A, \Psi_2, y : A, \Psi_3; \Phi; \Delta \vdash t : B
                                                                                                                                          LCON
                            \Gamma; \Psi_1, z : A, \Psi_2, \Psi_3; \Phi; \Delta \vdash con_l x, y to z in <math>t : B
                                     \Gamma; \Psi_1, x : A, \Psi_2, y : A, \Psi_3; \Phi; \Delta \vdash t : B
                                                                                                                                          RCON
                           \Gamma; \Psi_1, \Psi_2, z : A, \Psi_3; \Phi; \Delta \vdash \mathsf{con}_r x, y \mathsf{to} z \mathsf{in} t : B
```

$$\begin{split} & \Gamma_{1}, x_{1}: A, x_{2}: B, \Gamma_{2}; \Psi; \Phi; \Delta \vdash t: C \\ & \overline{\Gamma, z_{1}: B, z_{2}: A; \Psi; \Phi; \Delta \vdash ex x_{1}, x_{2} \text{ with } z_{1}, z_{2} \text{ in } t: C} \\ & \frac{\Gamma; \Psi; \Phi; \Delta \vdash t: \text{w.c.} A}{\Gamma; \Psi; \Phi; \Delta \vdash \text{dist}_{\text{cw}} t: \text{c.w.} A} \quad \text{DistCW} \\ & \frac{\Gamma; \Psi; \Phi; \Delta \vdash \text{dist}_{\text{cw}} t: \text{w.e.} A}{\Gamma; \Psi; \Phi; \Delta \vdash \text{dist}_{\text{ew}} t: \text{e.w.} A} \quad \text{DistEW} \\ & \frac{\Gamma; \Psi; \Phi; \Delta \vdash \text{dist}_{\text{ew}} t: \text{e.c.} A}{\Gamma; \Psi; \Phi; \Delta \vdash \text{dist}_{\text{ec}} t: \text{e.c.} A} \quad \text{DistEC} \\ & \frac{\Gamma; \Psi; \Phi; \Delta \vdash \text{dist}_{\text{ew}} t: \text{e.c.} A}{\Gamma; \Psi; \Phi; \Delta \vdash \text{dist}_{\text{ew}} t: \text{e.c.} wA} \quad \text{DistECW} \end{split}$$