

Navigation Controller API Interface Specification

Harman Connected Car

CoC_Nav_NavCtrl_Trunk_16103a

Navigation Controller API: Interface Specification

Harman Connected Car

Jacob Block < Jacob.Block@harman.com >

Person in charge: Jacob Block

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Revision History

Revision 2016-03-08 Jacob Block

CoC_Nav_NavCtrl_Trunk_16093a

Interface Changes:

- CCNAVCA-38 Settings attribute for map viewer instances
 - org_harman_nav_ctrl_mapv_MapViewControl.hbsi (1.1 to 1.2).
 - org_harman_nav_ctrl_mapv_MapViewControlTypes.hbtd (1.0 to 1.1).

Revision 2016-03-01 Jacob Block

CoC_Nav_NavCtrl_Trunk_16093a

Interface Changes:

- CCNAVCA-26 Guidance improvements with new waypoint attribute, broadcasts for maneuvers, and separation of static and dynamic data structures.
 - org_harman_nav_ctrl_Guidance.hbsi (0.3 to 0.4).
 - org harman nav ctrl GuidanceTypes.hbtd (1.1 to 1.2).
- CCNAVCA-34 TpegOverIP data download
 - org_harman_nav_ctrl_traffic_TrafficInformation.hbsi (2.0 to 2.1).
 - org_harman_nav_ctrl_traffic_TrafficInformationTypes.hbtd (2.0 to 2.1).
 - org_harman_nav_ctrl_highawymode_HighwayMode.hbsi (2.1to 2.2).
 - org_harman_nav_ctrl_highwaymode_HighwayModeTypes.hbtd (2.1 to 2.2).
- CCNAVCA-35 New HOV RoutePreferenceSource for avoidance
 - org_harman_nav_ctrl_Routing.hbsi (1.2 to 1.3).
 - org_harman_nav_ctrl_RoutingTypes.hbtd (1.1 to 1.2).
- Updated positioning descriptions for maps with variant types.
 - org_harman_nav_ctrl_PositioningTypes.hbsi (No Change).

Revision 2016-02-24 Jacob Block

CoC_Nav_NavCtrl_Trunk_16083a

Interface Changes:

- CCNAVCA-33 Adding date fields to DBUpdate
 - org harman nav ctrl dbupdate DBUpdate.hbsi (0.2 to 1.0).
 - org harman nav ctrl dbupdate DBUpdateTypes.hbtd (0.3 to 1.0).

Revision 2016-02-16 Jacob Block

CoC_Nav_NavCtrl_Trunk_16073a

Interface Changes:

- CCNAVCA-31 Change several requests to use item id in place of view id.
 - org_harman_nav_ctrl_memory_LocationMemory.hbsi (4.0 to 5.0).
- CCNAVCA-32 Retrieve details about specific item (e.g. click id)
 - org_harman_nav_ctrl_memory_LocationMemory.hbsi (4.0 to 5.0).
 - org_harman_nav_ctrl_memory_LocationMemoryTypes.hbtd (3.3 to 3.4).

Revision 2016-01-26 Jacob Block

CoC_Nav_NavCtrl_Trunk_16043a

Interface Changes:

- CCNAVCA-17 Semi Dynamic Routing
 - org_harman_nav_ctrl_Guidance.hsbi (0.2 to 0.3).
 - org_harman_nav_ctrl_GuidanceTypes.hbtd (1.0 to 1.1).
- CCNAVCA-23 LocationMemory new AddItem method
 - org_harman_nav_ctrl_di_OneBoxSearch.hsbi (2.2 to 2.3).
 - org_harman_nav_ctrl_memory_LocationMemory.hbsi (3.2 to 4.0).
 - org_harman_nav_ctrl_memory_LocationMemoryTypes.hbtd (3.2 to 3.3).
- CCNAVCA-25 New enum in LI for country abbreviation
 - org_harman_nav_ctrl_di_LocationInputTypes.hbtd (2.1 to 2.2).
 - org_harman_nav_ctrl_di_LocationInput.hbsi (2.1 to 2.2).
 - org_harman_nav_ctrl_di_OneBoxSearch.hsbi (2.2 to 2.3).
 - org_harman_nav_ctrl_di_SpeechLocationInput.hsbi (0.2 to 0.2).
 - org_harman_nav_ctrl_di_SpeechLocationInputTypes.hbtd (1.0 to 1.0).
 - org_harman_nav_ctrl_di_SpeechPoiSearch.hsbi (0.1 to 0.1).
 - org_harman_nav_ctrl_highwaymode_HighwayMode.hsbi (2.1 to 2.1).
 - org_harman_nav_ctrl_highwaymode_HighwayModeTypes.hbtd (2.1 to 2.1).
 - org_harman_nav_ctrl_memory_LocationMemory.hbsi (3.2 to 4.0).
 - org_harman_nav_ctrl_memory_LocationMemoryTypes.hbtd (3.2 to 3.3).
- CCNAVCA-29 SpeedCam increased functionality and refactoring
- org harman nav ctrl speedcam SpeedCamOnlineService.hsbi (0.2 to 1.0).
- org_harman_nav_ctrl_speedcam_SpeedCamOnlineServiceTypes.hbtd (1.0 to 1.0).
- org_harman_nav_ctrl_speedcam_SpeedCamService.hsbi (2.0 to 3.0).
- org_harman_nav_ctrl_speedcam_SpeedCamServiceTypes.hbtd (2.0 to 3.0).

Revision 2016-01-18 Jacob Block

CoC_Nav_NavCtrl_Trunk_16033a

Interface Changes:

- CCNAVCA-20 Enhanced traffic services (icon, message by id, tuner configuration)
 - org_harman_nav_ctrl_highwaymode_HighwayMode.hsbi (2.1 to 2.1). Upgraded hbtd dependency.
 - org_harman_nav_ctrl_highwaymode_HighwayModeTypes.hbtd (2.1 to 2.1). Upgraded hbtd dependency.
 - org_harman_nav_ctrl_traffic_TrafficInformation.hbsi (1.0 to 2.0)
 - org_harman_nav_ctrl_traffic_TrafficInformationTypes.hbtd (1.0 to 2.0)

Interfaces Removed:

Removed org_harman_nav_ctrl_PositioningInternal.hbsi from external delivery.

Revision	2016-01-07	Jacob Block
CoC_Nav_NavCtrl_Trunk_16014a		_
Interface Changes:		
 org_harman_nav_ctrl_speedc CCNAVCA-18 - New empty item org_harman_nav_ctrl_di_One org_harman_nav_ctrl_memory 	n.hsbi (1.1 to 1.2) Types.hbtd (1.0 to 1.1) dcam functionality. am_SpeedCamService.hbsi (1.0 to am_SpeedCamServiceTypes.hbtd type for lists.	(1.0 to 2.0)
Revision	2015-12-17	Oliver Kude
CoC_Nav_NavCtrl_Trunk_15413a Release NavCtrl Trunk CW 51		
Revision	2015-12-09	Jacob Block
CoC_Nav_NavCtrl_Trunk_15502a Release NavCtrl Trunk CW 50		_
CCNAVCA-16CCNAVCA-11CCNAVCA-9CCNAVCA-7		_
Revision CoC_Nav_NavCtrl_Trunk_15473a Release NavCtrl Trunk CW 47	2015-11-19	Oliver Kude
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Release NavCtrl Trunk CW 36		
Revision CoC_Nav_NavCtrl_Trunk_15273a Release NavCtrl Trunk CW 27	2015-07-02	Oliver Kude
Revision CoC_Nav_NavCtrl_Trunk_15243a Release NavCtrl Trunk CW 24	2015-06-11	Oliver Kude



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1 Introduction

1.1 Scope

Usually a navigation controller is tailored into a multi-layer architecture, at which each layer is encapsulating a certain set of functionality.

The human machine interface (HMI) represents textual and graphical information to the user and controls the interaction between the user and the system. It is also known as user interface. The HMI is a highly project-specific layer and is often developed by third parties or the customer itself. It is usually not a part of the navigation system itself.

The navigation application is the mediator between the user interface and the navigation controller components. It describes and coordinates the business and sequence logic and holds state information, that is relevant for the HMI but not for the navigation controller.

It is usually decomposed into several components with well-known interfaces, at which each component has a clear scope. Typical components are destination input, poi search, route calculation, guidance, positioning, map viewer, etc. The navigation controller API is designed to be generic as possible to guarantee a high re-use in multiple projects.

The described interfaces in this document are exclusively focused on the navigation controller, the so-called Navigation Controller API, for the purpose of developing the layers above (application and HMI).

The interfaces are grouped related to their functional domain, in particular:

- Application Service
 - DB Update
 - · LifeCycle Management
- Location Service
 - LocationInput
 - PoiSearch
 - OneBoxSearch
- Guidance Service
 - Routing
 - · Guidance Viewer
 - · Route Guidance
- MapControl Service
 - MapViewer



- · Positioning Service
 - Position
 - Simulation
 - Driver Assistance
- Traffic Service
 - Traffic

All interfaces are described in a programming-language neutral way by using a declarative XML language, called DSI (see next section). Internal interfaces and those, which are not compliant with DSI are out of scope and not part of this document.

1.2 **DSI**

All described interfaces in this document are specified using the DSI (Distributed Service Interface) modeling language. Basically DSI describes how two or more applications can exchange data through a standard protocol. This protocol has been designed to work well with MoCCAv2 service interfaces. The MoCCA Framework implements DSI in a transparent way, but it can be implemented in other environments which need to connect to a MoCCA application.

Interfaces are specified in HBSI (Service Interface) files and type definitions are usually described in HBTD (type definition) files. An interface can include one or more type definition files. Both HBSI and HBTD files support a versioning feature, by specifying a major and minor number. Minor version are increased after every change on the interface, major version only when incompatible changes occur. For DSI-capable service interfaces that might be used with DSI, the rule applies that nearly every interface change must be considered as major change. Only the addition of new methods or attributes can be considered as mino change.

DSI provides a set of primitive scalar types including **bool**, **Int8**, **Int16**, **Int32**, **Int64**, **float** and **double**. Unsigned versions of the integer data types will have a preceding **U** in the type name. These standard typedefs are to be preferred over the built-in C++ types, since they are guaranteed to have a well defined, processor independent data width. Furthermore there are some special utility types such as **Vector**, **Variant**, **String** and **ByteStream**.

1.3 Service Interface Elements

Attribute: An attribute is essentially a data object that is published via the service interface. A client can request that it be notified whenever an attribute is updated.

Request (Method): A request is a method that can be called by a client. This is the means by which a client can request that a service interface implementation do something.

Response (Method): A response is a method that can be called be the implementation. A client can be notified that a response method has been called and can then retrieve the values of the calling parameters for the response.



Information (Method): The server can notify clients even if they didn't send a request. A client can request that it be notified whenever this information is sent.

Register, **Unregister**(Method): The interface can provide a specific Register method that allows a client to get an information only if a user defined condition is fulfilled. Register and Unregister are always correlated to an information.

1.4 DataTypes

Type definition files (.hbtd) contain a formal description of enumerations, constants, structures and typedefs. Code generators are used to transform these formal descriptions into source code (C/C++, Java,...). The main purpose of .hbtd files is to define types centrally and use the same type definitions in multiple service interfaces (.hbsi) or other .hbtds without having to duplicate them.

1.5 Guidelines & Conventions

There some guidlines and conventions, that needs to be considered:

- Interfaces starts with the preifx **DNAVI**, whereby **D** means DSI, **NAV** means Navigation and **I** means Interface. Then follows the name of the functionality itself (e.g. LocationInput).
- The interface name is the same as the file name where the interface description is stored.
- TypeDefitions starts with the prefix T.
- Cross-cutting Type Definitions (means Type Definitions, which can not be dedicated to a certain subsystem) are located in the **common** area.



2 Application Service

2.1 org_harman_nav_ctrl_configuration_Configuration

Interface Version: 1.0

2.1.1 getCoordinatesFormat

requestGetCoordinatesFormat		
Methode for getting coordinates format.		
Parameter Type Description		Description

responseGetCoordinatesFormat		
Methode for getting coordinates format.		
Parameter	Туре	Description
getCoordinatesFormat_coordin	n ©tesiFcbriertet sFormat	

2.1.2 getLocale

requestGetLocale		
Methode for getting locale.		
Parameter	Туре	Description

responseGetLocale		
Methode for getting locale.		
Parameter	Туре	Description
getLocale_locale	Locale	

2.1.3 getNavigationVersion

requestGetNavigationVersion		
Methode for getting version of Navigation Controller.		
Parameter Type Description		



responseGetNavigationVers	ion		
Methode for getting version of	Navigation Controller.		
Parameter	Туре	Description	
getNavigationVersion_navigati	omakegsitoonVersion		

2.1.4 getSupportedCoordinatesFormats

requestGetSupportedCoordinatesFormats		
Methode for getting supported coordinates format.		
Parameter	Туре	Description

responseGetSupportedCoordinatesFormats				
Methode for getting supported	coordinates format.			
Parameter	Type Description			
getSupportedCoordinatesForm	altsocolinates faterats			

2.1.5 getSupportedLocales

requestGetSupportedLocales		
Methode for getting supported locales.		
Parameter Type Description		Description

responseGetSupportedLocales		
Methode for getting supported	locales.	
Parameter	Туре	Description
getSupportedLocales_locales	Locales	

2.1.6 getSupportedTimeFormats

requestGetSupportedTimeFormats		
Methode for getting supported time formats.		
Parameter Type Description		



responseGetSupportedTimeFormats			
Methode for getting supported	time formats.		
Parameter	Туре	Description	
getSupportedTimeFormats_tin	n eFroemats nats		

2.1.7 getSupportedUnitsOfMeasurement

requestGetSupportedUnitsOfMeasurement		
Methode for getting supported	units of measurements.	
Parameter Type Description		Description

responseGetSupportedUnitsOfMeasurement			
Methode for getting supported units of measurements.			
Parameter Type Description			
getSupportedUnitsOfMeasurer	ndenits@ilvleasuerement		

2.1.8 getTimeFormat

requestGetTimeFormat		
Methode for getting time format.		
Parameter Type Description		Description

responseGetTimeFormat			
Methode for getting time formation	at.		
Parameter	Туре	Description	
getTimeFormat_timeFormat	TimeFormat		

2.1.9 getUnitsOfMeasurement

requestGetUnitsOfMeasurement		
Methode for getting units of measurements.		
Parameter	Туре	Description



responseGetUnitsOfMeasur	ement		
Methode for getting units of m	easurements.		
Parameter	Туре	Description	
getUnitsOfMeasurement_units	OfMicastvicement		

2.1.10 setCoordinatesFormat

requestSetCoordinatesFormat			
Methode for setting coordinate	s format.		
Parameter Type		Description	
setCoordinatesFormat_R_coordinatesR_coordinatesFormat_R_coordinate	dinates Faters Ex ternat		

responseSetCoordinatesFormat		
Methode for setting coordinates format.		
Parameter	Туре	Description

2.1.11 setLocale

requestSetLocale			
Methode for setting locale.			
Parameter	Туре	Description	
setLocale_R_locale	Locale		

responseSetLocale		
Methode for setting locale.		
Parameter	Туре	Description

2.1.12 setStyleTheme

requestSetStyleTheme			
Methode for setting style for theme.			
Parameter Type Description			
setStyleTheme_R_style	StyleTheme		



responseSetStyleTheme		
Methode for setting style for theme.		
Parameter	Туре	Description

2.1.13 setTimeFormat

requestSetTimeFormat			
Methode for setting time forma	t.		
Parameter Type		Description	
setTimeFormat_R_timeFormat	TimeFormat		

responseSetTimeFormat		
Methode for setting time format.		
Parameter	Туре	Description

2.1.14 setUnitsOfMeasurement

requestSetUnitsOfMeasurement		
Methode for setting units of measurements.		
Parameter Type		Description
setUnitsOfMeasurement_R_units@fMeasurementent		

responseSetUnitsOfMeasurement		
Methode for setting units of measurements.		
Parameter	Туре	Description

2.1.15 configurationChanges

informationConfigurationChanges		
This signals there was a change is configuration.		
Parameter Type Description		



informationConfigurationChanges		
configurationChanges_change	Bétitings s	

2.1.16 Error

Error		
This is the type for error responses.		
Literal	Description	
ERROR_GetVersionError_INVALID		
ERROR_GetVersionError_GET_VERSION_FAILE	D	
ERROR_SetUnitsOfMeasurementError_INVALID		
ERROR_SetUnitsOfMeasurementError_SET_UNIT	S_OF_MEASUREMENTS_FAILED	
ERROR_SetTimeFormatError_INVALID		
ERROR_SetTimeFormatError_SET_TIME_FORM	AT_FAILED	
ERROR_GetSupportedTimeFormatsError_INVALII	D	
ERROR_GetSupportedTimeFormatsError_GET_S	UPPORTED_TIME_FORMAT_FAILED	
ERROR_SetCoordinatesFormatError_INVALID		
ERROR_SetCoordinatesFormatError_SET_COOR	DINATES_FORMAT_FAILED	
ERROR_SetLocaleError_INVALID		
ERROR_SetLocaleError_SET_LOCALE_FAILED		
ERROR_GetSupportedUnitsOfMeasurementError_	INVALID	
ERROR_GetSupportedUnitsOfMeasurementError_	GET_SUPPORTED_UNITS_OF_MEASUREMENT\$_F#	AILED
ERROR_GetUnitsOfMeasurementError_INVALID		
ERROR_GetUnitsOfMeasurementError_GET_UNI	TS_OF_MEASUREMENTS_FAILED	
ERROR_GetTimeFormatError_INVALID		
ERROR_GetTimeFormatError_GET_TIME_FORM	AT_FAILED	
ERROR_GetCoordinatesFormatError_INVALID		
ERROR_GetCoordinatesFormatError_GET_COOF	DINATES_FORMAT_FAILED	
ERROR_GetSupportedCoordinatesFormatsError_I	NVALID	
ERROR_GetSupportedCoordinatesFormatsError_0	GET_SUPPORTED_COORDINATES_FORMAT_FAILED	D
ERROR_GetLocaleError_INVALID		
ERROR_GetLocaleError_GET_LOCALE_FAILED		
ERROR_GetLocalesError_INVALID		
ERROR_GetLocalesError_GET_LOCALES_FAILE	D	
ERROR_SetStyleThemeError_INVALID		
ERROR_SetStyleThemeError_SET_STYLE_THEM	E_FAILED	



2.2 org_harman_nav_ctrl_configuration_Configuration

Interface Version: 1.0

2.2.1 getCoordinatesFormat

requestGetCoordinatesFormat		
Methode for getting coordinates format.		
Parameter Type Description		

responseGetCoordinatesFor			
Methode for getting coordinates format.			
Parameter Type		Description	
getCoordinatesFormat_coordin	n atesiFörnate tsFormat		

2.2.2 getLocale

requestGetLocale		
Methode for getting locale.		
Parameter	Туре	Description

responseGetLocale		
Methode for getting locale.		
Parameter	Туре	Description
getLocale_locale	Locale	

2.2.3 getNavigationVersion

requestGetNavigationVersion		
Methode for getting version.		
Parameter Type		Description



responseGetNavigationVersion			
Methode for getting version.			
Parameter Type Description		Description	
getNavigationVersion_navigat	omble gsition Version		

2.2.4 getStyleTheme

requestGetStyleTheme		
Methode for getting style theme.		
Parameter Type		Description

responseGetStyleTheme			
Methode for getting style t	heme.		
Parameter	Туре	Description	
getStyleTheme_style	StyleTheme		

2.2.5 getSupportedCoordinatesFormats

requestGetSupportedCoordinatesFormats		
Methode for getting supported coordinates format.		
Parameter Type Description		

responseGetSupportedCoordinatesFormats		
Methode for getting supported coordinates format.		
Parameter	Туре	Description
getSupportedCoordinatesForm	Otsocolorates Fat mats	

2.2.6 getSupportedLocales

requestGetSupportedLocales		
Methode for getting supported locales.		
Parameter	Туре	Description



responseGetSupportedLocales		
Methode for getting supported locales.		
Parameter	Туре	Description
getSupportedLocales_locales	Locales	

2.2.7 getSupportedUnitsOfMeasurement

requestGetSupportedUnitsOfMeasurement		
Methode for getting supported units of measurements.		
Parameter	Туре	Description

responseGetSupportedUnitsOfMeasurement		
Methode for getting supported units of measurements.		
Parameter	Туре	Description
getSupportedUnitsOfMeasurer	ndenits@ilvleasuerement	

2.2.8 getTimeFormat

requestGetTimeFormat		
Methode for getting time forma	t.	
Parameter	Туре	Description

responseGetTimeFormat			
Methode for getting time formation	at.		
Parameter	Туре	Description	
getTimeFormat_timeFormat	TimeFormat		

2.2.9 getUnitsOfMeasurement

requestGetUnitsOfMeasurement			
Methode for getting units of measurements.			
Parameter Type Description			



responseGetUnitsOfMeasurement			
Methode for getting units of me	easurements.		
Parameter	Туре	Description	
getUnitsOfMeasurement_units	OfMeastwement		

2.2.10 configurationChanges

informationConfigurationChanges			
This signals there was a chang	e is configuration.		
Parameter	Туре	Description	
configurationChanges_change	dissettings:		

2.2.11 Error

Error		
This is the type for error responses.		
Literal	Description	
ERROR_GetVersionError_INVALID		
ERROR_GetVersionError_GET_VERSION_FAILE	D	
ERROR_GetSupportedUnitsOfMeasurementError_	INVALID	
ERROR_GetSupportedUnitsOfMeasurementError_	GET_SUPPORTED_UNITS_OF_MEASUREMENT\$_FA	AILE
ERROR_GetUnitsOfMeasurementError_INVALID		
ERROR_GetUnitsOfMeasurementError_GET_UNI	TS_OF_MEASUREMENTS_FAILED	
ERROR_GetTimeFormatError_INVALID		
ERROR_GetTimeFormatError_GET_TIME_FORM	AT_FAILED	
ERROR_GetCoordinatesFormatError_INVALID		
ERROR_GetCoordinatesFormatError_GET_COOF	DINATES_FORMAT_FAILED	
ERROR_GetSupportedCoordinatesFormatsError_I	NVALID	
ERROR_GetSupportedCoordinatesFormatsError_0	SET_SUPPORTED_COORDINATES_FORMAT_FAILED	D
ERROR_GetLocaleError_INVALID		
ERROR_GetLocaleError_GET_LOCALE_FAILED		
ERROR_GetLocalesError_INVALID		
ERROR_GetLocalesError_GET_LOCALES_FAILE	D	
ERROR_GetStyleThemeError_INVALID		
ERROR_GetStyleThemeError_GET_STYLE_THEI	WE_FAILED	



2.3 org_harman_nav_ctrl_configuration_Configuration

Interface Version: 1.0

2.3.1 CoordinatesFormat

CoordinatesFormat		
Literal	Description	
CoordinatesFormat_INVALID		
CoordinatesFormat_DEGREES		
CoordinatesFormat_MINUTES		
CoordinatesFormat_SECONDS		

Referenced by: org_harman_nav_ctrl_configuration_Configuration::setCoordinatesFormat, org_harman_nav_ctrl_configuration_Configuration::getCoordinatesFormat, org_harman_nav_ctrl_configuration_ConfigurationBase::getCoordinatesFormat, org_harman_nav_ctrl_configuration_ConfigurationTypes::CoordinatesFormats

2.3.2 CoordinatesFormats

List for coordinates formats. Vector of element type CoordinatesFormat

Referenced by : org_harman_nav_ctrl_configuration_Configuration::getSupportedCoordinatesFormats, org_harman_nav_ctrl_configuration_ConfigurationBase::getSupportedCoordinatesFormats

2.3.3 GetCoordinatesFormatError

GetCoordinatesFormatError		
Literal	Description	
GetCoordinatesFormatError_BasicEnum_INVALID		
GetCoordinatesFormatError_GET_COORDINATES	_FORMAT_FAILED	

2.3.4 GetLocaleError

GetLocaleError	



GetLocaleError		
Literal	Description	
GetLocaleError_BasicEnum_INVALID		
GetLocaleError_GET_LOCALE_FAILED		

2.3.5 GetLocalesError

GetLocalesError		
Literal	Description	
GetLocalesError_BasicEnum_INVALID		
GetLocalesError_GET_LOCALES_FAILED		

2.3.6 GetStyleThemeError

GetStyleThemeError		
Literal	Description	
GetStyleThemeError_BasicEnum_INVALID		
GetStyleThemeError_GET_STYLE_THEME_FAILE	D	

2.3.7 GetSupportedCoordinatesFormatsError

GetSupportedCoordinatesFormatsError	
Literal	Description
GetSupportedCoordinatesFormatsError_BasicEnur	n_INVALID
GetSupportedCoordinatesFormatsError_GET_SUF	PORTED_COORDINATES_FORMAT_FAILED

2.3.8 GetSupportedTimeFormatsError

GetSupportedTimeFormatsError		
Literal	Description	
GetSupportedTimeFormatsError_BasicEnum_INVA	LID	
GetSupportedTimeFormatsError_GET_SUPPORTE	ED_TIME_FORMAT_FAILED	



2.3.9 GetSupportedUnitsOfMeasurementError

GetSupportedUnitsOfMeasurementError	
Literal	Description
GetSupportedUnitsOfMeasurementError_BasicEnu	m_INVALID
GetSupportedUnitsOfMeasurementError_GET_SU	PPORTED_UNITS_OF_MEASUREMENTS_FAILED

2.3.10 GetTimeFormatError

GetTimeFormatError	
Literal	Description
GetTimeFormatError_BasicEnum_INVALID	
GetTimeFormatError_GET_TIME_FORMAT_FAILE	D

2.3.11 GetUnitsOfMeasurementError

GetUnitsOfMeasurementError	
Literal	Description
GetUnitsOfMeasurementError_BasicEnum_INVALID	
GetUnitsOfMeasurementError_GET_UNITS_OF_M	EASUREMENTS_FAILED

2.3.12 GetVersionError

GetVersionError		
Literal	Description	
GetVersionError_BasicEnum_INVALID		
GetVersionError_GET_VERSION_FAILED		

2.3.13 Locale

Locale
Locale consists of language and country and script.



Locale		
Structure Element	Туре	Description
language	String	languageCode = ISO 639?3 language code (lower case)
country	String	countryCode = ISO 3166?1 alpha 3 country code (upper case)
scriptCode	String	scriptCode= ISO 15924 alpha 4 script code (upper case)

Referenced by: org_harman_nav_ctrl_configuration_Configuration::setLocale, org_harman_nav_ctrl_configuration_Configuration::getLocale, org_harman_nav_ctrl_configuration_ConfigurationBase::getLocale, org_harman_nav_ctrl_configuration_ConfigurationTypes::Locales

2.3.14 Locales

List for locales. Vector of element type Locale

Referenced by: org_harman_nav_ctrl_configuration_Configuration::getSupportedLocales, org_harman_nav_ctrl_configuration_ConfigurationBase::getSupportedLocales

2.3.15 NavigationVersion

NavigationVersion Version info. consists of major, minor, micro and release date.			
Structure Element	Туре	Description	
navigationMajor	UInt16		
navigationMinor	UInt16		
navigationMicro	UInt16		
navigationDate	String		

Referenced by: org_harman_nav_ctrl_configuration_Configuration::getNavigationVersion, org_harman_nav_ctrl_configuration_ConfigurationBase::getNavigationVersion

2.3.16 SetCoordinatesFormatError

SetCoordinatesFormatError	



SetCoordinatesFormatError	
Literal	Description
SetCoordinatesFormatError_BasicEnum_INVALID	
SetCoordinatesFormatError_SET_COORDINATES	_FORMAT_FAILED

2.3.17 SetLocaleError

SetLocaleError		
Literal	Description	
SetLocaleError_BasicEnum_INVALID		
SetLocaleError_SET_LOCALE_FAILED		

2.3.18 SetStyleThemeError

SetStyleThemeError	
Literal	Description
SetStyleThemeError_BasicEnum_INVALID	
SetStyleThemeError_SET_STYLE_THEME_FAILE	D

2.3.19 SetTimeFormatError

SetTimeFormatError	
Literal	Description
SetTimeFormatError_BasicEnum_INVALID	
SetTimeFormatError_SET_TIME_FORMAT_FAILE	D

2.3.20 SetUnitsOfMeasurementError

SetUnitsOfMeasurementError	
Literal	Description



SetUnitsOfMeasurementError
SetUnitsOfMeasurementError_BasicEnum_INVALID
SetUnitsOfMeasurementError_SET_UNITS_OF_MEASUREMENTS_FAILED

2.3.21 Setting

Setting		
Literal	Description	
Setting_INVALID		
Setting_UNITS_OF_MEASUREMENT		
Setting_LOCALE		
Setting_TIME_FORMAT		
Setting_COORDINATES_FORMAT		
Setting_STYLE_THEME		

Referenced by: org_harman_nav_ctrl_configuration_ConfigurationTypes::Settings

2.3.22 Settings

List for settings. Vector of element type Setting

Referenced by : org_harman_nav_ctrl_configuration_Configuration::configurationChanges, org_harman_nav_ctrl_configuration_ConfigurationBase::configurationChanges

2.3.23 StyleTheme

StyleTheme		
Literal	Description	
StyleTheme_INVALID		
StyleTheme_STYLE_DAY		
StyleTheme_STYLE_NIGHT		

 $\label{lem:configuration} Referenced \ by: org_harman_nav_ctrl_configuration_Configuration::setStyleTheme, org_harman_nav_ctrl_configuration_ConfigurationBase::getStyleTheme$



2.3.24 TimeFormat

TimeFormat		
Literal	Description	
TimeFormat_INVALID		
TimeFormat_TIME12H		
TimeFormat_TIME24H		

Referenced by: org_harman_nav_ctrl_configuration_Configuration::setTimeFormat, org_harman_nav_ctrl_configuration_Configuration::getTimeFormat, org_harman_nav_ctrl_configuration_ConfigurationBase::getTimeFormat, org_harman_nav_ctrl_configuration_ConfigurationTypes::TimeFormats

2.3.25 TimeFormats

List for time format. Vector of element type TimeFormat

Referenced by: org_harman_nav_ctrl_configuration_Configuration::getSupportedTimeFormats

2.3.26 UnitOfMeasurement

UnitOfMeasurement		
Structure for UnitsOfMeasurer	ment.	
Structure Element	Туре	Description
unitOfMeasurementKey	UnitOfMeasurementKey	
unitOfMeasurementValue	UnitOfMeasurementValue	

Referenced by : org_harman_nav_ctrl_configuration_ConfigurationTypes::UnitsOfMeasurement, org_harman_nav_ctrl_PositioningTypes::PositionItemValue

2.3.27 UnitOfMeasurementKey

UnitOfMeasurementKey	
Literal	Description
UnitOfMeasurementKey_INVALID	



UnitOfMeasurementKey	
UnitOfMeasurementKey_LENGTH	

Referenced by: org_harman_nav_ctrl_configuration_ConfigurationTypes::UnitOfMeasurement

2.3.28 UnitOfMeasurementValue

UnitOfMeasurementValue		
Literal	Description	
UnitOfMeasurementValue_INVALID		
UnitOfMeasurementValue_METER		
UnitOfMeasurementValue_MILE		
UnitOfMeasurementValue_KM		
UnitOfMeasurementValue_YARD		
UnitOfMeasurementValue_FOOT		

Referenced by: org_harman_nav_ctrl_configuration_ConfigurationTypes::UnitOfMeasurement

2.3.29 UnitsOfMeasurement

List for Units of measurement. Vector of element type UnitOfMeasurement

Referenced by: org_harman_nav_ctrl_configuration_Configuration::setUnitsOfMeasurement, org_harman_nav_ctrl_configuration_Configuration::getSupportedUnitsOfMeasurement, org_harman_nav_ctrl_configuration_Configuration::getUnitsOfMeasurement, org_harman_nav_ctrl_configuration_ConfigurationBase::getSupportedUnitsOfMeasurement, org_harman_nav_ctrl_configuration_ConfigurationBase::getUnitsOfMeasurement

2.4 org_harman_nav_ctrl_dbupdate_DBUpdate

Interface Version: 1.0

2.4.1 SetAutoModus

requestSetAutoModus	
enable/disable the automode for the iu	



requestSetAutoModus

The auto-mode is by default enabled. In auto mode the dbupdate happens in background and is more or less completely opaque for the customer/driver. In general, the dbupdate ctrl checks for updates in a cycle manner (every updateTime_sec seconds) or based on online notifications (which must supported by project). If an update is available, a download progress is initiated automatically. As soon as the update is applied, the client gets notified about the option to restart the system in order to work on the latest DB. This is done by attribute outstandingUpdates. Anyway the client can ignore this notification and with the next lifecycle the latest dbversion is used. If the automodus is disabled, the client must manually initiate any update process. For further details see requestUpdateList and requestApplyUpdate.

Parameter	Туре	Description
s_AutoModus	boolean	enable/disable the automode for the iu
		The auto-mode is by default enabled. In auto mode the dbupdate happens in background and is more or less completely opaque for the customer/driver. In general, the dbupdate ctrl checks for updates in a cycle manner (every updateTime_sec seconds) or based on online notifications (which must supported by project). If an update is available, a download progress is initiated automatically. As soon as the update is applied, the client gets notified about the option to restart the system in order to work on the latest DB. This is done by attribute outstandingUpdates. Anyway the client can ignore this notification and with the next lifecycle the latest dbversion is used. If the automodus is disabled, the client must manually initiate any update process. For further details see requestUpdateList and requestApplyUpdate.

responseSetAutoModus

enable/disable the automode for the iu

The auto-mode is by default enabled. In auto mode the dbupdate happens in background and is more or less completely opaque for the customer/driver. In general, the dbupdate ctrl checks for updates in a cycle manner (every updateTime_sec seconds) or based on online notifications (which must supported by project). If an update is available, a download progress is initiated automatically. As soon as the update is applied, the client gets notified about the option to restart the system in order to work on the latest DB. This is done by attribute outstandingUpdates. Anyway the client can ignore this notification and with the next lifecycle the latest dbversion is used. If the automodus is disabled, the client must manually initiate any update process. For further details see requestUpdateList and requestApplyUpdate.



responseSetAutoModus		
Parameter	Туре	Description
s_AutoModus	boolean	enable/disable the automode for the iu
		The auto-mode is by default enabled. In auto mode the dbupdate happens in background and is more or less completely opaque for the customer/ driver. In general, the dbupdate ctrl checks for updates in a cycle manner (every updateTime_sec seconds) or based on online notifications (which must supported by project). If an update is available, a download progress is initiated automatically. As soon as the update is applied, the client gets notified about the option to restart the system in order to work on the latest DB. This is done by attribute outstandingUpdates. Anyway the client can ignore this notification and with the next lifecycle the latest dbversion is used. If the automodus is disabled, the client must manually initiate any update process. For further details see requestUpdateList and requestApplyUpdate.

2.4.2 applyUpdate

requestApplyUpdate

manual request to download and apply an incremental update patch This method is used in case of auto-mode = off and the client is responsible to control the complete incremental update process himself. Preceding to this call, the client must have already called updateList to get a list of available updates. By passing the Tld of one of the patches in the list, the download and appliance of a patch is started. There are different error scenarios (see error codes)

Parameter	Туре	Description
applyUpdate_R_patchId	Tld	identifier of a certain patch

responseApplyUpdate

manual request to download and apply an incremental update patch This method is used in case of auto-mode = off and the client is responsible to control the complete incremental update process himself. Preceding to this call, the client must have already called updateList to get a list of available



responseApplyUpdate		
updates. By passing the Tld of one of the patches in the list, the download and appliance of a patch is started. There are different error scenarios (see error codes)		
Parameter Type Description		

2.4.3 cancelUpdate

requestCancelUpdate

Request to stop current applying process This method allows the client to stop an update progress. In essence this might lead to a stop-download or stop db-patch. A cancelled update will be cleaned up if the pausedProcess is set to false. Otherwise the client can resume the update later on. Please note: this call is only available in manual mode The controller stores the status of the current update and allows to resume the update process. The client can recall see requestApplyUpdate which internaly will resume the update (if Tld is the same). Multiple calls of requestCancelUpdate can be used to first pause an update and later on clean up. The controller will autocleanup update content automatically if the data is deprecated.

Parameter	Туре	Description
cancelUpdate_R_pauseProces	boolean	

responseCancelUpdate

Request to stop current applying process This method allows the client to stop an update progress. In essence this might lead to a stop-download or stop db-patch. A cancelled update will be cleaned up if the pausedProcess is set to false. Otherwise the client can resume the update later on. Please note: this call is only available in manual mode The controller stores the status of the current update and allows to resume the update process. The client can recall see requestApplyUpdate which internaly will resume the update (if Tld is the same). Multiple calls of requestCancelUpdate can be used to first pause an update and later on clean up. The controller will autocleanup update content automatically if the data is deprecated.

	_	
Parameter	Туре	Description

2.4.4 finalizeUpdate

requestFinalizeUpdate

initialize a HU restart which finalizes the DB-update process

This method allows the client to control the time in which the system gets restarted in order to finalize the DB-update process. Please note: for each updates (incremental/partial/full) a system restart is necessary to switch to the new DB-files. Intention of this method is to give the control about the restart-time to the client to avoid a restart during a critical guidance situation. Please note: in some cases a restart is not possible, in this case the E_INVALID_SYSTEM_STATE will be returned



requestFinalizeUpdate		
Parameter	Туре	Description

responseFinalizeUpdate

initialize a HU restart which finalizes the DB-update process

This method allows the client to control the time in which the system gets restarted in order to finalize the DB-update process. Please note: for each updates (incremental/partial/full) a system restart is necessary to switch to the new DB-files. Intention of this method is to give the control about the restart-time to the client to avoid a restart during a critical guidance situation. Please note: in some cases a restart is not possible, in this case the E_INVALID_SYSTEM_STATE will be returned

Parameter	Туре	Description
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2.4.5 updateList

requestUpdateList

manual request for search for available updates This method is used in case of auto-mode off. A client can use this method to a list of available updates for his HU. By specifying the E_RequestMode, the client can decide to fetch all interesting iu, the iu around current position or the iu at destionation. As a result, the user will get a list of available updates roughly ordered by distance to CCP/destination and depending on project settings. The list is valid for the current lifecycle and update-process only. That meas if an update was applied the client must request the list again.

In case that no online connection is available, the request returns with error code. Furthermore an error will responded in case that the auto mode is enabled. Please note: an empty list is not an error it simply tells the client that there are no updates available

Parameter	Туре	Description
updateList_R_mode	E_RequestMode	

responseUpdateList

manual request for search for available updates This method is used in case of auto-mode off. A client can use this method to a list of available updates for his HU. By specifying the E_RequestMode, the client can decide to fetch all interesting iu, the iu around current position or the iu at destionation. As a result, the user will get a list of available updates roughly ordered by distance to CCP/destination and depending on project settings. The list is valid for the current lifecycle and update-process only. That meas if an update was applied the client must request the list again.

In case that no online connection is available, the request returns with error code. Furthermore an error will responded in case that the auto mode is enabled. Please note: an empty list is not an error it simply tells the client that there are no updates available

Parameter Type Description



responseUpdateList		
updateList_list	TOTAUpdateList	

2.4.6 dealerUpdateAvailable

informationDealerUpdateAvailable

notify the client about a dealer update media than can be applied This broadcast is emitted by IUcontroller if an update media is connected to the HU which contains a valid update for the system. The client then can decide to apply the update by see applyUpdate. Please note: in contrast to incremental updates, this requestApplyUpdate will then switch the system to Full-Update-Mode in which no iu request is possible.

Parameter	Туре	Description
dealerUpdateAvailable_dealer	டிறித் B ealer Update	

2.4.7 aautoModus

Attribute aautoModus

enable/disable the automode for the iu

The auto-mode is by default enabled. In auto mode the dbupdate happens in background and is more or less completely opaque for the customer/driver. In general, the dbupdate ctrl checks for updates in a cycle manner (every updateTime_sec seconds) or based on online notifications (which must supported by project). If an update is available, a download progress is initiated automatically. As soon as the update is applied, the client gets notified about the option to restart the system in order to work on the latest DB. This is done by attribute outstandingUpdates. Anyway the client can ignore this notification and with the next lifecycle the latest dbversion is used. If the automodus is disabled, the client must manually initiate any update process. For further details see requestUpdateList and requestApplyUpdate.

Туре	Notification Type
boolean	ON_CHANGE

2.4.8 adealerUpdateProgress

Attribute adealerUpdateProgress

progress indication for dealer-update process This indication allows to give feedback about the progress when running a dealer update (don't mix up with incremental update). The valid range is between 0 and 100. As soon as the complete update is applied, the outstandingUpdates attribute will be increased to 1 and the fullUpdateProgress will indicate 100 (percent). In normal mode (meaning no



Attribute adealerUpdateProgress		
update device is plugged to HU) the fullUpdateProgress will always be equal to 0 which indicates no full update progress in process.		
Туре	Notification Type	
UInt8	ON_CHANGE	

2.4.9 aoutstandingUpdates

Attribute aoutstandingUpdates

an indication on how many updates are ready to be applied This attribute allow the client to get feedback about the current update status. All updates that were downloaded and applied will increase this counter. Due to the fact that the DB itself must be switch after the update was applied successfully, the client can decide to trigger an system restart to get the latest update available for his current navigation. The interpretation of this attribute is very simple: outstandingUpdates!=0 - restart in order to switch to new database outstandingUpdates==0 - nothing to do The client can use see requestFinalizeUpdate to initialize a HU restart. With the next lifecylce of the system, the updates will be finalized automatically. In this case the outstandingUpdates will be reset to zero.

Туре	Notification Type
Int8	ON_CHANGE

2.4.10 aversionId

Attribute aversionId		
human readable version information of the database conglomerate This attribute is used to give the customer/driver information about the database that is currently available on his system.		
Type Notification Type		
SVersion	ON_CHANGE	

2.4.11 Error

Error	
This is the type for error responses.	
Literal	Description
ERROR_updateList_E_AUTOMODE_ACTIVE	
ERROR_updateList_E_NO_ONLINE_SERVICE	
ERROR_applyUpdate_E_AUTOMODE_ACTIVE	



Error	
ERROR_applyUpdate_E_NO_ONLINE_SERVICE	
ERROR_applyUpdate_E_PATCH_NOT_AVAILABLE	E
ERROR_applyUpdate_E_PATCH_NOT_APPLICAB	LE
ERROR_applyUpdate_E_VERIFICATION_FAILURE	
ERROR_applyUpdate_E_RESSOURCE_BUSY	
ERROR_cancelUpdate_E_AUTOMODE_ACTIVE	
ERROR_cancelUpdate_E_UPDATE_NOT_ACTIVE	
ERROR_finalizeUpdate_E_UPDATE_NOT_ACTIVE	
ERROR_finalizeUpdate_E_INVALID_SYSTEM_STA	ATE .

2.5 org_harman_nav_ctrl_dbupdate_DBUpdateTypes

Interface Version: 1.0

2.5.1 E_RequestMode

E_RequestMode	
Literal	Description
E_RequestMode_E_REQUEST_DEFAULT_IU	request all iu according to project/default behaviour
E_RequestMode_E_REQUEST_ALL_IU	request all iu which are available for current system
E_RequestMode_E_REQUEST_CPP_IU	request all iu around the current car position
E_RequestMode_E_REQUEST_DEST_IU	request all iu around the desctination

Referenced by : org_harman_nav_ctrl_dbupdate_DBUpdate::updateList

2.5.2 E_UpdateType

E_UpdateType	
Literal	Description
E_UpdateType_E_UNKNOWN_DEFAULT	update type unknown/default: should be used if there is only one update type supported



E_UpdateType	
E_UpdateType_E_INCREMENTAL_UPDATE	incremental update (OTA-update)
E_UpdateType_E_PARTIAL_UPDATE	partial update (several update regions only)
E_UpdateType_E_FULL_UPDATE	full update (all regions and libs)
E_UpdateType_E_NO_UPDATE	none update (media has no update or primary check failed)

Referenced by: org_harman_nav_ctrl_dbupdate_DBUpdateTypes::SDBDealerUpdate

2.5.3 SDBDealerUpdate

SDBDealerUpdate

struct describing a full/partial update this structure combines the different dealer update types in a single container: partial and full update. For the customer a mandatory title describes in short the content of the update. An optional description field allows to provide more detailed information. The type identifier is more or less for information only - it points out if this is a full update (all UR getting updated) or a partial one (e.g. only germany is getting updated).

Structure Element	Туре	Description
id	Tld	id for this update
type	E_UpdateType	information about update type
_version	SVersion	version of update which is used by version check functionality
title	String	mandatory short description of the update, e.g. "Central-Europe Q15.1"
description	String	optional detailed description of the update, e.g. list of URs, date, version
path	String	full path to root folder of DB, does not contain ROOT.NDS because there can be another entry point

Referenced by : org_harman_nav_ctrl_dbupdate_DBUpdate::dealerUpdateAvailable

2.5.4 SDBOTAUpdate

SDBOTAUpdate

description of an OTA incremental update This struct is used to describe a certain patch. It contains a short title (e.g. Germany Q1.15) and an optional more detailed description. The id is used to reference



SDBOTAUpdate		
a certain patch from the I size and estimated time t	•	struct furthermore contains optional fields for patch
Structure Element Type Description		
id	Tld	id to identify a patch (mandatory)
title	String	information about the patch, e.g. Germany Q1.15 (mandatory)
description	String	additional optional information about the patch content (optional)
size_byte	UInt32	size of the patch in bytes (optional)
estimatedTime_sec	UInt32	expected time to download and to apply the patch (optional)

Referenced by: org_harman_nav_ctrl_dbupdate_DBUpdateTypes::TOTAUpdateList

2.5.5 SVersion

SVersion		
DB version information This struct is used to give information about the database that is currently used in HU. The details about representation of version are project specific.		
Structure Element Type Description		
db_version	String	textual description of DB version, e.g. "ECE-101151"
title	String	optional textual description
lib_version	String	textual description of ndsupdate lib version
fud_db	UInt32	UTC of when the current database was first used.

Referenced by : org_harman_nav_ctrl_dbupdate_DBUpdate::aversionId, org_harman_nav_ctrl_dbupdate_DBUpdateTypes::SDBDealerUpdate

2.5.6 Tld

id of a patch Alias of actual type: UInt32

Referenced by: org_harman_nav_ctrl_dbupdate_DBUpdate::applyUpdate, org_harman_nav_ctrl_dbupdate_DBUpdateTypes::SDBDealerUpdate, org_harman_nav_ctrl_dbupdate_DBUpdateTypes::SDBOTAUpdate



2.5.7 TOTAUpdateList

a list of available patches Vector of element type SDBOTAUpdate

Referenced by : org_harman_nav_ctrl_dbupdate_DBUpdate::updateList

2.6 org_harman_nav_ctrl_Simulation

Interface Version: 0.1

2.6.1 getSimulationSpeed

requestGetSimulationSpeed		
Returns the speed factor for the simulation mode		
Parameter	Туре	Description

responseGetSimulationSpeed		
Returns the speed factor for the simulation mode		
Parameter	Туре	Description
getSimulationSpeed_speedFaction8		speedFactor = speed factor

2.6.2 getSimulationStatus

requestGetSimulationStatus		
Retrieves the simulation status	3	
Parameter	Туре	Description

responseGetSimulationS	tatus	
Retrieves the simulation st	atus	
Parameter	Туре	Description
getSimulationStatus_simul	ationStatustionStatus	simulationStatus = enum(SIMULATION_STATUS_NO_SIMULATION, SIMULATION_STATUS_RUNNING, SIMULATION_STATUS_PAUSED, SIMULATION_STATUS_FIXED_POSITION)



2.6.3 pauseSimulation

requestPauseSimulation		
Freezes the current location		
Parameter	Туре	Description

responsePauseSimulation		
Freezes the current location		
Parameter	Туре	Description

2.6.4 resumeSimulation

requestResumeSimulation		
Resumes a follow active route simulation		
Parameter Type Description		Description

responseResumeSimulation		
Resumes a follow active route simulation		
Parameter Type Description		

2.6.5 setPosition

requestSetPosition			
Sets the position to a spec	fic location		
Parameter	Туре	Description	
setPosition_R_position	PositionItemDict		

responseSetPosition		
Sets the position to a specific location		
Parameter Type Description		



2.6.6 setSimulationMode

requestSetSimulationMode		
Activates or deactivates simulation mode		
Parameter	Туре	Description
setSimulationMode_R_activate	boolean	activate = flag. TRUE means that the simulation mode is activated.

responseSetSimulationMode	
Activates or deactivates simulation mode	
Parameter Type Description	

2.6.7 setSimulationSpeed

requestSetSimulationSpeed		
Sets the speed factor for the simulation mode		
Parameter	Туре	Description
setSimulationSpeed_R_speed	Fiat∨	speedFactor = speed factor

responseSetSimulationSpeed		
Sets the speed factor for the simulation mode		
Parameter Type Description		

2.6.8 simulationSpeedChanged

informationSimulationSpeedChanged		
Notification when the simulation speed factor has changed		
Parameter	Туре	Description
simulationSpeedChanged_spe	entB actor	speedFactor = speed factor

2.6.9 simulationStatusChanged

informationSimulationStatusChanged
Notification when the Simulation Status has changed



informationSimulationStatusChanged		
Parameter	Туре	Description
simulationStatusChange	d_sim ušatiohstatus tatus	simulationStatus = enum(SIMULATION_STATUS_NO_SIMULATION_STATUS_RUNNING, SIMULATION_STATUS_PAUSED, SIMULATION_STATUS_FIXED_POSITION)

2.7 org_harman_nav_ctrl_SimulationTypes

Interface Version: 1.0

2.7.1 SimulationStatus

SimulationStatus		
Literal	Description	
SimulationStatus_BasicEnum_INVALID		
SimulationStatus_SIMULATION_STATUS_NO_SIM	MULATION	
SimulationStatus_SIMULATION_STATUS_RUNNII	NG	
SimulationStatus_SIMULATION_STATUS_PAUSE	D	
SimulationStatus_SIMULATION_STATUS_FIXED_	POSITION	

Referenced by : org_harman_nav_ctrl_Simulation::getSimulationStatus, org_harman_nav_ctrl_Simulation::simulationStatusChanged



3 Location Service

3.1 org_harman_nav_ctrl_di_LocationInput

Interface Version: 2.2

3.1.1 createLocationInput

requestCreateLocationInput		
createLocationInput = This method creates a new location input and retrieves a handle		
Parameter Type Description		

responseCreateLocationInput		
createLocationInput = This method creates a new location input and retrieves a handle		
Parameter	Type Description	
createLocationInput_locationIr	blatha iodle	Location input handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value

3.1.2 deleteLocationInput

requestDeleteLocationInput			
deleteLocationInput = This method deletes a location input and its associated resources			
Parameter	Parameter Type Description		
deleteLocationInput_R_locatio	r lliaputilel andle	locationInputHandle = Location input handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value	

responseDeleteLocationInput		
deleteLocationInput = This method deletes a location input and its associated resources		
Parameter Type Description		



3.1.3 getEntry

requestGetEntry		
getEntry = This method synchronously gets the address for the given result list entry		
Parameter Type Description		
getEntry_R_locationInputHand	le andle	locationInputHandle = Location input handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
getEntry_R_index	UInt16	index = list index of the entry to be returned

responseGetEntry		
getEntry = This method synchronously gets the address for the given result list entry		
Parameter Type Description		Description
getEntry_address	Address	

3.1.4 getSupportedAddressAttributes

requestGetSupportedAddressAttributes		
getSupportedAddressAttributes = This method retrieves the supported address attributes		
Parameter Type Description		

responseGetSupportedAddressAttributes		
getSupportedAddressAttributes = This method retrieves the supported address attributes		
Parameter Type Description		
getSupportedAddressAttributes <u>A</u> dddressAttbibutestList		

3.1.5 getVersion

requestGetVersion		
getVersion = This method returns the API version implemented by the server application		
Parameter Type Description		

responseGetVersion
getVersion = This method returns the API version implemented by the server application



responseGetVersion		
Parameter Type Description		Description
getVersion_version	Version	

3.1.6 requestListUpdate

requestRequestListUpdate		
requestListUpdate = This method sends a request for more list elements for the current session If a session changes, e.g. new character is entered, a new list is generated. Offset is starting at 0 again.		
Parameter Type Description		
requestListUpdate_R_location	inputelandle	locationInputHandle = Location input handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
requestListUpdate_R_offset	UInt16	offset = starting offset of the newly requested list elements
requestListUpdate_R_maxWir	ddwSize	maxWindowSize = maximum number of elements that should be returned as result

responseRequestListUpdate		
requestListUpdate = This method sends a request for more list elements for the current session If a session changes, e.g. new character is entered, a new list is generated. Offset is starting at 0 again.		
Parameter	Туре	Description

3.1.7 reverseGeocode

requestReverseGeocode			
reverseGeocode = This method transforms a geocoordinate into an address			
Parameter	rameter Type Description		
reverseGeocode_R_locationIn	phallaledie	locationInputHandle = Location input handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value	
reverseGeocode_R_coordinateCoordinate2D			

responseReverseGeocode		
reverseGeocode = This method transforms a geocoordinate into an address		
Parameter Type Description		



3.1.8 search

requestSearch				
search = This method sets the inputString for the current selection criterion TBD: expected broadcasts				
Parameter	Туре	Type Description		
search_R_locationInputHan	dleHandle	locationInputHandle = Location input handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value		
search_R_inputString	String	inputString = contains the String, that is searched		

responseSearch		
search = This method sets the inputString for the current selection criterion TBD: expected broadcasts		
Parameter Type Description		

3.1.9 selectEntry

requestSelectEntry			
selectEntry = This method trigg	selectEntry = This method triggers selection of a result list entry by index		
Parameter	ameter Type Description		
selectEntry_R_locationInputHa	a htale dle	locationInputHandle = Location input handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value	
selectEntry_R_index	UInt16	index = absolute list index of the entry to be selected	

responseSelectEntry		
selectEntry = This method triggers selection of a result list entry by index		
Parameter Type Description		

3.1.10 setAddress

requestSetAddress		
setAddress = This method sets the address to start with for the LocationInput identified by the given handle		
Parameter Type Description		



requestSetAddress		
setAddress_R_locationInputHa	a hldlie dle	locationInputHandle = Location input handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
setAddress_R_address	Address	

responseSetAddress		
setAddress = This method sets the address to start with for the LocationInput identified by the given handle		
Parameter Type Description		Description

3.1.11 setSelectionCriterion

requestSetSelectionCriterion	n		
setSelectionCriterion = This m and the corresponding result-li		on for the current speller, search input	
Parameter Type Description			
setSelectionCriterion_R_locati	d ritmplitH andle	locationInputHandle = Location input handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value	
setSelectionCriterion_R_selection	ti odOnites/om ribute	selectionCriterion = enum(INVALID,LATITUDE,LONGITUDE)	,ALTITUDE,FL

responseSetSelectionCriterion		
setSelectionCriterion = This method sets the selection criterion for the current speller, search input and the corresponding result-lists for the current session		
Parameter	Type Description	

3.1.12 spell

requestSpell		
spell = This method sends the next spell input for the current session TBD: expected broadcasts		
Parameter	Туре	Description
spell_R_locationInputHandle	Handle	locationInputHandle = Location input handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value



requestSpell		
spell_R_inputCharacter	String	inputCharacter = last input character (UTF-8) (0x08(Backspace) for delete last character, 0x0D(Carriage Return) for delete entire input)

responseSpell		
spell = This method sends the next spell input for the current session TBD: expected broadcasts		
Parameter Type Description		

3.1.13 validateAddress

requestValidateAddress		
validateAddress = This method validates an address from different sources than Navigation TBD: functionality to be clarified		
Parameter	Туре	Description
validateAddress_R_loc	cationInp ultahahe lle	locationInputHandle = Location input handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
validateAddress_R_inputAddress		

responseValidateAddress		
validateAddress = This method validates an address from different sources than Navigation TBD: functionality to be clarified		
Parameter Type Description		

3.1.14 addressValidationResult

informationAddressValidationResult		
addressValidationResult = This signal notifies the validation result of a former ValidateAddress call TBD: functionality to be clarified		
Parameter	Туре	Description
addressValidationResult_locat	i blalnølæ Handle	locationInputHandle = Location input handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
addressValidationResult_valid	aTedBAdetress_LAstdress_	
addressValidationResult_valid	a TidBS/tatusL_is/t alidationStatus_	



3.1.15 contentUpdated

informationContentUpdated contentUpdated = This signal updates the input content data for the specified session		
contentUpdated_locationInput	Hakarokti le	locationInputHandle = Location input handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
contentUpdated_guidable	boolean	guidable = flag indicating whether the current address is guidable
contentUpdated_availableSele	atlobCeteaa_AddressAttribute_	-
contentUpdated_address	Address	

3.1.16 currentSelectionCriterion

informationCurrentSelectionCriterion currentSelectionCriterion = This signal notifies the SelectionCriterion for the current speller input or search.			
Parameter	Туре	Description	1
currentSelectionCriterion_loca	t idahrji atHandle	locationInputHandle = Location input handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value	
currentSelectionCriterion_sele	ofidd Gritefilori bute	selectionCriterion = enum(INVALID,LATITUDE,LONGITUDE)	ALTITUD

DE,FL

3.1.17 searchResultList

informationSearchResultList		
searchResultList = This signal updates the address result list (e.g. after a Search/Spell/Scroll call)		
Parameter	Туре	Description
searchResultList_locationInpu	Handle	locationInputHandle = Location input handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
searchResultList_totalSize	UInt16	totalSize = total size of the result list
searchResultList_windowOffse	UInt16	windowOffset = window offset within the complete list
searchResultList_windowSize	UInt16	windowSize = size of the provided window



informationSearchResultList	
searchResultList_resultListWindtwBVector_Address_	

3.1.18 searchResultListSizeChanged

informationSearchResultListSizeChanged		
searchResultListSizeChanged = This signal updates the size of the address result list		
Parameter	Туре	Description
searchResultListSizeChanged	HooadienInputHandle	locationInputHandle = Location input handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
searchResultListSizeChanged	<u>LtbinaliSsi</u> ze	totalSize = total size of the result list

3.1.19 spellResult

informationSpellResult		
spellResult = This signal notifies the result of the previous Spell method		
Parameter	Туре	Description
spellResult_locationInputHandlelandle		locationInputHandle = Location input handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
spellResult_uniqueString	String	uniqueString = unique string derived from spell input (i.e. including autocompletion if applicable)
spellResult_validCharacters	String	validCharacters = set of (UTF-8 encoded) characters valid for next input (unified in a single string). A Backspace(0x08) is returned if the input character passed to the Spell method was invalid
spellResult_fullMatch	boolean	fullMatch = flag indicating whether the value in UniqueCharacters is already a full match for an existing list entry

3.1.20 Error

Error	
This is the type for error responses.	



Error		
Literal	Description	
ERROR_createLocationInput_NoMorelocationInput	Handles	
ERROR_setAddress_InvalidAddressError		
ERROR_setSelectionCriterion_InvalidSelectionCriterion	erion	
ERROR_spell_InvalidCharacterError		
ERROR_search_InvalidStringError		
ERROR_requestListUpdate_OffsetBeyondListSize	Error	
ERROR_requestListUpdate_WindowSizeTooLarge	Error	
ERROR_selectEntry_InvalidIndex		
ERROR_selectEntry_InvalidHandle		

3.1.21 THBVector_AddressAttribute_

Vector of element type AddressAttribute

Referenced by: org_harman_nav_ctrl_di_LocationInput::contentUpdated

3.1.22 THBVector_Address_

Vector of element type Address

Referenced by : org_harman_nav_ctrl_di_LocationInput::searchResultList, org_harman_nav_ctrl_di_LocationInput::addressValidationResult

3.1.23 THBVector_ValidationStatus_

Vector of element type ValidationStatus

 $Referenced\ by: org_harman_nav_ctrl_di_LocationInput:: address ValidationResult$

3.2 org_harman_nav_ctrl_di_LocationInputTypes

Interface Version: 2.2

3.2.1 Address

Address		
Map Element	Туре	Description



Address		
keyType	AddressAttribute	
valueType	AddressValue	

Referenced by: org_harman_nav_ctrl_di_LocationInput::setAddress, org_harman_nav_ctrl_di_LocationInput::getEntry, org_harman_nav_ctrl_di_LocationInput::validateAddress, org_harman_nav_ctrl_di_LocationInput::contentUpdated, org_harman_nav_ctrl_di_LocationInput::THBVector_Address_, org_harman_nav_ctrl_highwaymode_HighwayModeTypes::Addresses, org_harman_nav_ctrl_memory_LocationMemoryTypes::Location

3.2.2 AddressAttribute

AddressAttribute		
Literal	Description	
AddressAttribute_BasicEnum_INVALID		
AddressAttribute_LATITUDE		
AddressAttribute_LONGITUDE		
AddressAttribute_ALTITUDE		
AddressAttribute_COUNTRY		
AddressAttribute_STATE		
AddressAttribute_CITY		
AddressAttribute_ZIPCODE		
AddressAttribute_STREET		
AddressAttribute_HOUSENUMBER		
AddressAttribute_CROSSING		
AddressAttribute_DISTRICT		
AddressAttribute_TOWNCENTER		
AddressAttribute_REFINEMENT		
AddressAttribute_FULL_ADDRESS		
AddressAttribute_COUNTRYFLAG		
AddressAttribute_COUNTRYSET		
AddressAttribute_COUNTRYABBR		
AddressAttribute_INTERNAL_DATA		

Referenced by : org_harman_nav_ctrl_di_LocationInput::setSelectionCriterion, org_harman_nav_ctrl_di_LocationInput::currentSelectionCriterion,



org_harman_nav_ctrl_di_LocationInput::THBVector_AddressAttribute_, org_harman_nav_ctrl_di_LocationInputTypes::AddressAttributeList

3.2.3 AddressAttributeList

Vector of element type AddressAttribute

Referenced by : org_harman_nav_ctrl_di_LocationInput::getSupportedAddressAttributes, org_harman_nav_ctrl_di_SpeechLocationInputTypes::SpeechMode

3.2.4 AddressValue

AddressValue			
Variant Element	Туре	Description	
intValue	Int32		
doubleValue	double		
stringValue	String		
coordinateValue	Coordinate3D		
internalData	Buffer		

3.2.5 SearchStatus

SearchStatus		
Literal	Description	
SearchStatus_BasicEnum_INVALID		
SearchStatus_SEARCHING		
SearchStatus_FINISHED		

Referenced by : org_harman_nav_ctrl_di_OneBoxSearch::searchStatus

3.2.6 ValidationStatus

ValidationStatus	



ValidationStatus			
Map Element	Туре	Description	
keyType	AddressAttribute		
valueType	ValidationType		

Referenced by: org_harman_nav_ctrl_di_LocationInput::THBVector_ValidationStatus_

3.2.7 ValidationType

ValidationType		
Literal	Description	
ValidationType_BasicEnum_INVALID		
ValidationType_OK		
ValidationType_UNKNOWN		
ValidationType_AMBIGUOUS		
ValidationType_INCONSISTENT		

3.3 org_harman_nav_ctrl_di_OneBoxSearch

Interface Version: 2.3

3.3.1 cancelOneBoxSearch

requestCancelOneBoxSearch		
cancelFtsSearch = This method cancels the search for the current session		
Parameter Type Description		
cancelOneBoxSearch_R_oneB	BidxxSelarchHandle	oneBoxSearchHandle = one box search unique handle

responseCancelOneBoxSearch		
cancelFtsSearch = This method cancels the search for the current session		
Parameter Type Description		



3.3.2 createOneBoxSearch

requestCreateOneBoxSearch		
createOneBoxSearch = This method creates a new OneBoxSearch and retrieves a handle		
Parameter Type Description		

responseCreateOneBoxSearch		
createOneBoxSearch = This method creates a new OneBoxSearch and retrieves a handle		
Parameter	Type Description	
createOneBoxSearch_oneBox	Steardht-Handle	Location input handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value

3.3.3 deleteOneBoxSearch

requestDeleteOneBoxSearch		
deleteLocationInput = This method deletes a location input and its associated resources		
Parameter	Type Description	
deleteOneBoxSearch_R_oneE	ok&ete chHandle	oneBoxSearchHandle = Search handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value

responseDeleteOneBoxSearch		
deleteLocationInput = This method deletes a location input and its associated resources		
Parameter Type Description		

3.3.4 getEntry

requestGetEntry			
getEntry = This method synchronously gets the address for the given result list entry			
Parameter	Type Description		
getEntry_R_oneBoxSearchHa	n dæ ndle	oneBoxSearchHandle = One Box input handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value	



requestGetEntry		
getEntry_R_index	UInt16	index = list index of the entry to be returned

responseGetEntry			
getEntry = This method synchronously gets the address for the given result list entry			
Parameter	neter Type Description		
getEntry_locItem	Location	location = Location selected for the result list. For a phonebook contact with two addresses, two separate entries will be returned.	

3.3.5 getVersion

requestGetVersion		
getVersion = This method returns the API version implemented by the server application		
Parameter Type Description		

responseGetVersion		
getVersion = This method returns the API version implemented by the server application		
Parameter Type Description		
getVersion_version	Version	

3.3.6 requestResultList

requestRequestResultList		
requestListUpdate = This method sends a request for more list elements for the current session		
Parameter Type Description		Description
requestResultList_R_oneBox	S etarobldandle	oneBoxSearchHandle = One box handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
requestResultList_R_offset	UInt16	offset = starting offset of the newly requested list elements
requestResultList_R_maxWin	dblw&iz&	maxWindowSize = maximum number of elements that should be returned as result



responseRequestResultList			
requestListUpdate = This method sends a request for more list elements for the current session			
Parameter	Туре		
requestResultList_statusValue	UInt16	enum(INVALID,NOT_STARTED,SEARC	HING,FINISHE
).	
requestResultList_resultListSiz	e lInt16	Number of items of the results list.	
requestResultList_locations	LocationList	array[locations].	

3.3.7 selectEntry

requestSelectEntry			
selectEntry = This method triggers selection of a result list entry by index			
Parameter	er Type Description		
selectEntry_R_oneBoxSearch	Tandibe	oneBoxSearchHandle = One Box handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value	
selectEntry_R_index	UInt16	index = absolute list index of the entry to be selected	

responseSelectEntry			
selectEntry = This method triggers selection of a result list entry by index			
Parameter	Туре	Description	

3.3.8 setSearchCountry

requestSetSearchCountry			
setSearchCountry = This method sets the target country for the current search, If no country is set the current center position is used to determine the country			
Parameter	Туре	Description	
setSearchCountry_R_oneBox	S d ar dh landle	oneBoxSearchHandle = one box search unique handle	
setSearchCountry_R_country	String	country = Deutschland, Frankreich, Utah, New Jersey, no country set allowed zB USA, European Union, Canada	



responseSetSearchCountry		
setSearchCountry = This method sets the target country for the current search, If no country is set the current center position is used to determine the country		
Parameter	Туре	Description

3.3.9 setSearchLanguage

requestSetSearchLanguage			
setSearchLanguage = for the phonetic search algorithms the language and script are important			
Parameter	Туре	Description	
setSearchLanguage_R_ftsSea	i dahlale dle	oneBoxSearchHandle = one box search unique handle	
setSearchLanguage_R_langua	a §tr ing	language = ISO language used for the search eng deu fra ita	
setSearchLanguage_R_script	String	script = ISO script Latn1, Latn2, Cyrillic, etc	

responseSetSearchLanguage			
setSearchLanguage = for the phonetic search algorithms the language and script are important			
Parameter Type Description			

3.3.10 setSearchParameters

requestSetSearchParameter	S	
setSearchParameters = SetSearchParameters = configure if we want to search for addresses and/ or pois. configure if we want to search in the vicinity of the specified center. configure if we want to search using fuzziness. Default behaviour if no option is set we search everywhere		
Parameter	Туре	Description
setSearchParameters_R_onel	BdxSdxrchHandle	oneBoxSearchHandle = one box search unique handle
setSearchParameters_R_sear	d រល្ ក់ស្វែក	searchOptions = bitmask, default value is 0xFFFF FTS_SEARCH_BITMASK_ADDRESSES = 0x1, enable search for addresses FTS_SEARCH_BITMASK_POIS = 0x2, enable search for pois FTS_SEARCH_BITMASK_VICINITY = 0x4 enable search arround position



requestSetSearchParameters		
	FTS_SEARCH_BITMASK_FUZZINESS = 0x8 enable fuzziness	

responseSetSearchParameters

setSearchParameters = SetSearchParameters = configure if we want to search for addresses and/ or pois. configure if we want to search in the vicinity of the specified center. configure if we want to search using fuzziness. Default behaviour if no option is set we search everywhere

Parameter	Туре	Description
Parameter	Type	Description

3.3.11 startOneBoxSearch

requestStartOneBoxSearch		
startOneBoxSearch = This method sends the search input for the search handle. The search will start with the location.		
Parameter	Туре	Description
startOneBoxSearch_R_oneBo	XS@addn Handle	oneBoxSearchHandle = one box search unique handle
startOneBoxSearch_R_inputS	t Sahirij ng	inputString = contains the name of the poi, address, contact that is searched. It cannot be an empty string.

responseStartOneBoxSearch		
startOneBoxSearch = This method sends the search input for the search handle. The search will start with the location.		
Parameter	Туре	Description

3.3.12 searchResultList

informationSearchResultList			
searchResultList = This signal updates the address result list (e.g. after a Search/Spell/Scroll call)			
Parameter	Туре	Description	
searchResultList_oneBoxSear	d hla radidle	oneBoxSearchHandle = Location input handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value	
searchResultList_totalSize	UInt16	totalSize = total size of the result list	
searchResultList_windowOffse	UInt16	windowOffset = window offset within the complete list	



informationSearchResultList		
searchResultList_windowSize	UInt16	windowSize = size of the provided window

3.3.13 searchResultListSizeChanged

informationSearchResultListSizeChanged		
searchResultListSizeChanged = This signal updates the size of the address result list		
Parameter Type Description		
searchResultListSizeChanged	lltxxxtienInpuHandle	oneBoxSearchHandle = Location input handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
searchResultListSizeChanged	LttbitainStize	totalSize = total size of the result list

3.3.14 searchStatus

informationSearchStatus			
searchStatus = This signal upo	dates the search status	of the specified session	
Parameter	Туре	Description	
searchStatus_oneBoxSearchH	lahadiele	oneBoxSearchHandle = Location input handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value	
searchStatus_statusValue	SearchStatus	statusValue = enum(INVALID,NOT_STARTED,SEARC)	HING,FINISHE

3.3.15 Error

Error		
This is the type for error responses.		
Literal	Description	
ERROR_createOneBoxSearch_NoMoreOneBoxHa	ndles	
ERROR_setSearchCountry_HandleNotAvailable		
ERROR_setSearchLanguage_HandleNotAvailable		
ERROR_setSearchParameters_HandleNotAvailabl	e	
ERROR_startOneBoxSearch_HandleNotAvailable		
ERROR_cancelOneBoxSearch_HandleNotAvailabl	е	



3.4 org_harman_nav_ctrl_di_OneBoxSearchTypes

Interface Version: 1.0

3.4.1 FtsOptions

FtsOptions	
Literal	Description
FtsOptions_BasicEnum_INVALID	
FtsOptions_ONEBOX_SEARCH_BITMASK_ADDR	ESSES
FtsOptions_x0001	
FtsOptions_ONEBOX_SEARCH_BITMASK_POIS	
FtsOptions_x0002	
FtsOptions_ONEBOX_SEARCH_BITMASK_VICIN	TY
FtsOptions_x0003	
FtsOptions_ONEBOX_SEARCH_BITMASK_FUZZI	NESS
FtsOptions_x0004	
FtsOptions_ONEBOX_SEARCH_BITMASK_RECE	NT
FtsOptions_x0008	
FtsOptions_ONEBOX_SEARCH_BITMASK_FAVO	RITES
FtsOptions_x0010	
FtsOptions_ONEBOX_SEARCH_BITMASK_CONT	ACTS
FtsOptions_x0020	

3.5 org_harman_nav_ctrl_di_POIContentAccess

Interface Version: 1.0

3.5.1 addCategories

requestAddCategories		
Add new categories to the POI service component. The CAM provides for each categories the name, the parent categories, the top level attribute, the list of attributes, the icons,		
Parameter Type Description		
addCategories_R_camId	UInt8	Content access module unique id as known by the POI service component.



requestAddCategories	
addCategories_R_poiCategoriesHBVector_CAMCategory_	List of details for all the POI categories.

responseAddCategories			
Add new categories to the POI service component. The CAM provides for each categories the name, the parent categories, the top level attribute, the list of attributes, the icons,			
Parameter	Type Description		
addCategories_poiCategoriesI	Categories_poiCategoriesIdTHBVector_CategoryID_ array of unique POI categories as registered by the POI service component. Note: A POI category is unique ID		

3.5.2 registerContentAccessModule

requestRegisterContentAccessModule

Register to the POI provider module When the CAM registers, it provides a name and then get a unique id. This id must be used everytime the CAM communicates with the POI service component. After the registration is done, the CAM can start to update POI categories and POI attributes as well as registers POI categories to search for.

Parameter	Туре	Description
registerContentAccessModule	S tri n goduleName	The name of the CAM.

responseRegisterContentAccessModule

Register to the POI provider module When the CAM registers, it provides a name and then get a unique id. This id must be used everytime the CAM communicates with the POI service component. After the registration is done, the CAM can start to update POI categories and POI attributes as well as registers POI categories to search for.

Parameter	Туре	Description
registerContentAccessModule		Content access module unique id as known by the POI service component.

3.5.3 registerPoiCategories

requestRegisterPoiCategories

Register to the POI provider module the categories you can search for POI. The categories could be predifined one or customized ones. In order to register a customized category, you might need to create it before and add it to the POI service component.



requestRegisterPoiCategories		
Parameter	Туре	Description
registerPoiCategories_R_cam	யInt8	Content access module unique id as known by the POI service component.
registerPoiCategories_R_poiC	a ītelfjò/ies tor_CategoryID_	array[unique_id]. List of POI categories to register. unique_id = Unique category id.

responseRegisterPoiCategories

Register to the POI provider module the categories you can search for POI. The categories could be predifined one or customized ones. In order to register a customized category, you might need to create it before and add it to the POI service component.

Parameter Type	Description
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3.5.4 removeCategories

requestRemoveCategories

Remove categories from the POI service component. It could be a predifined or a customed one. Depending on the local database write policy, the CAM might only not be able to remove some categories.

Parameter	Туре	Description
removeCategories_R_camId		Content access module unique id as known by the POI service component.
removeCategories_R_poiCate	gd riB\$ /ector_CategoryID_	array[unique_id]. List of POI categories to remove.

responseRemoveCategories

Remove categories from the POI service component. It could be a predifined or a customed one. Depending on the local database write policy, the CAM might only not be able to remove some categories.

Parameter	Туре	Description
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3.5.5 unRegisterContentAccessModule

requestUnRegisterContentAccessModule		
Remove CAM from POI provider module.		
Parameter Type Description		



requestUnRegisterContentAccessModule	
unRegisterContentAccessMod	Content access module unique id as
	known by the POI service component.

responseUnRegisterContentAccessModule		
Remove CAM from POI provider module.		
Parameter Type Description		

3.5.6 updateCategories

requestUpdateCategories

Update categories in the POI service component. It could be a predifined or a customed one. The CAM provides for each categories the list of attributes (mandatories like name or optional) it wants to update. Depending on the local database write policy, the CAM might only be able to update customized attributes for a category and not the predefined ones so some update could be rejected.

Parameter	Туре	Description
updateCategories_R_camId		Content access module unique id as known by the POI service component.
updateCategories_R_poiCateg	orites Vector_CAMCategoryUpd	அ ச <u>a</u> y[unique_id, attributes, sortOptions].

responseUpdateCategories

Update categories in the POI service component. It could be a predifined or a customed one. The CAM provides for each categories the list of attributes (mandatories like name or optional) it wants to update. Depending on the local database write policy, the CAM might only be able to update customized attributes for a category and not the predefined ones so some update could be rejected.

Parameter	Туре	Description

3.5.7 THBVector_CAMCategoryUpdate_

array[unique_id, attributes, sortOptions]. Vector of element type CAMCategoryUpdate

Referenced by : org_harman_nav_ctrl_di_POIContentAccess::updateCategories

3.5.8 THBVector_CAMCategory_

List of details for all the POI categories. Vector of element type CAMCategory

Referenced by: org_harman_nav_ctrl_di_POIContentAccess::addCategories



3.5.9 THBVector_CategoryID_

array[unique_id]. List of POI categories to register. unique_id = Unique category id. Vector of element type **CategoryID**

Referenced by: org_harman_nav_ctrl_di_POIContentAccess::registerPoiCategories, org_harman_nav_ctrl_di_POIContentAccess::addCategories, org_harman_nav_ctrl_di_POIContentAccess::removeCategories

3.6 org_harman_nav_ctrl_di_POIContentAccessMod

Interface Version: 2.0

3.6.1 getVersion

requestGetVersion		
This method returns the API version implemented by the content access module.		
Parameter Type Description		

responseGetVersion		
This method returns the API version implemented by the content access module.		
Parameter Type Description		
getVersion_version	Version	

3.6.2 poiDetailsRequested

requestPoiDetailsRequested		
This method retrieves the details associated to one or more POI. It contains the name, the parent categories, the list of attributes, the icons,		
Parameter Type Description		
poiDetailsRequested_R_source	eTittBVector_POI_ID_	array[unique_poi_id].

responsePoiDetailsRequested

This method retrieves the details associated to one or more POI. It contains the name, the parent categories, the list of attributes, the icons,



responsePoiDetailsRequested		
Parameter	Туре	Description
poiDetailsRequested_results	THBVector_SearchResultDeta	iærray[(details, categories, attributes)].

3.6.3 poiSearchCanceled

requestPoiSearchCanceled		
This method cancels the search for the current id.		
Parameter Type I		Description
poiSearchCanceled_R_poiSeardahtandle		poi search unique handle.

responsePoiSearchCanceled		
This method cancels the search for the current id.		
Parameter Type Description		Description

3.6.4 poiSearchStarted

requestPoiSearchStarted

This method is sent by the POI service component to inform all the CAM that a new POI search was started. It provides all the relevant search parameters. Of course the CAM will only be aware of the search if it registers one of the search categories.

search in it registers one or the	search categories.	l	
Parameter	Туре	Description	
poiSearchStarted_R_poiSearc	h ll te mdite	poi search unique handle. It must be used by the CAM to send the list of results to the component.	
poiSearchStarted_R_maxSize	UInt16	max size of the results list.	
poiSearchStarted_R_locations	THBVector_Coordinate3D_	array[struct(lat,lon,alt)].	
poiSearchStarted_R_poiCateg	dīries Vector_CategoryAndRadi	array[struct(id,radius)].	
poiSearchStarted_R_poiAttribu	ıīds BVector_AttributeDetails_	array[struct(name, poiCategory, type, value, operator, mandatory)].	
poiSearchStarted_R_inputStrin	n § tring	contains the name of the poi that is searched. It could be a partial name or an empty string.	
poiSearchStarted_R_sortOption	ฟInt16	enum(SORT_DEFAULT,SORT_BY_DIS) If more than one category was defined for this search, the sort criteria should be compliant with all categories.	FANCE,SORT



responsePoiSearchStarted

This method is sent by the POI service component to inform all the CAM that a new POI search was started. It provides all the relevant search parameters. Of course the CAM will only be aware of the search if it registers one of the search categories.

Parameter	Туре	Description
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3.6.5 resultListRequested

requestResultListRequested

This method provides the poi results list found by the CAM. As the POI unique id is managed by the POI component, the CAM only provides the POI name, the category and coordinates as well as all the relevant detailed information.

Parameter	Туре	Description
resultListRequested_R_camId		Content access module unique id as known by the POI service component.
resultListRequested_R_poiSea	a rchn-the dle	poi search unique handle.
resultListRequested_R_attribu	t ē slBVector_AttributeID_	List of attributes id to retrieve. This is optional and the list could be empty.

responseResultListRequested

This method provides the poi results list found by the CAM. As the POI unique id is managed by the POI component, the CAM only provides the POI name, the category and coordinates as well as all the relevant detailed information.

Parameter	Туре	Description	
resultListRequested_statusVal	ևelnt16	enum(INVALID,NOT_STARTED,SEARC).	HING,FINISHE
resultListRequested_resultList	Subtret16	Number of items of the results list.	
resultListRequested_resultList	THBVector_PoiCAMDetails_	array[struct(source_id, name, category, location, distance, attributes)].	

3.6.6 setLanguage

requestSetLanguage

Set the current language set for the search by poi provider module. The language defines the poi and categories name and details language. If the language is not supported, the default details will be returned in the native language.

Parameter	Туре	Description
setLanguage_R_languageCod	€ tring	the language to be used.



requestSetLanguage		
setLanguage_R_countryCode String the country specific variant for the		
		language to be used.

responseSetLanguage		
Set the current language set for the search by poi provider module. The language defines the poi and categories name and details language. If the language is not supported, the default details will be returned in the native language.		
Parameter	Туре	Description

3.6.7 searchStatus

informationSearchStatus			
This signal updates the search	h or proximity alert status	of the specified handle.	
Parameter Type Description			
searchStatus_poiSearchHand	dleHandle	poi search unique handle.	
searchStatus_statusValue	SearchStatusState	enum(INVALID,NOT_STARTED,SEARC).	HING,FINISH
searchStatus_resultListSize	UInt16	Number of items of the results list.	

3.6.8 THBVector_AttributeDetails_

array[struct(name, poiCategory, type, value, operator, mandatory)]. Vector of element type AttributeDetails

Referenced by: org_harman_nav_ctrl_di_POIContentAccessModule::poiSearchStarted

3.6.9 THBVector_AttributeID_

List of attributes id to retrieve. This is optional and the list could be empty. Vector of element type **AttributeID**

 $Referenced\ by: org_harman_nav_ctrl_di_POIContentAccessModule::resultListRequested$

3.6.10 THBVector_CategoryAndRadius_

array[struct(id,radius)]. Vector of element type CategoryAndRadius

Referenced by: org_harman_nav_ctrl_di_POIContentAccessModule::poiSearchStarted



3.6.11 THBVector_Coordinate3D_

array[struct(lat,lon,alt)]. Vector of element type Coordinate3D

Referenced by: org_harman_nav_ctrl_di_POIContentAccessModule::poiSearchStarted

3.6.12 THBVector_POI_ID_

array[unique_poi_id]. Vector of element type POI_ID

Referenced by: org_harman_nav_ctrl_di_POIContentAccessModule::poiDetailsRequested

3.6.13 THBVector_PoiCAMDetails_

array[struct(source_id, name, category, location, distance, attributes)]. Vector of element type **PoiCAMDetails**

Referenced by: org_harman_nav_ctrl_di_POIContentAccessModule::resultListRequested

3.6.14 THBVector_SearchResultDetails_

array[(details, categories, attributes)] . Vector of element type SearchResultDetails

Referenced by: org_harman_nav_ctrl_di_POIContentAccessModule::poiDetailsRequested

3.7 org_harman_nav_ctrl_di_POISearch

Interface Version: 1.1

3.7.1 cancelPoiSearch

requestCancelPoiSearch		
This method cancels the search for the current session.		
Parameter Type Description		
cancelPoiSearch_R_poiSearch	nHandle	poi search unique handle.

responseCancelPoiSearch	
This method cancels the search for the current session.	



responseCancelPoiSearch		
Parameter	Туре	Description

3.7.2 createPoiSearchHandle

requestCreatePoiSearchHandle		
This method creates a new search input and retrieves a handle .		
Parameter Type Description		

responseCreatePoiSearchHandle		
This method creates a new search input and retrieves a handle .		
Parameter Type Description		Description
createPoiSearchHandle_poiSe	archtlendle	poi search unique handle.

3.7.3 deletePoiSearchHandle

requestDeletePoiSearchHandle		
This method deletes a search input and its associated resources.		
Parameter Type Description		
deletePoiSearchHandle_R_po	Searde Handle	poi search unique handle.

responseDeletePoiSearchHandle		
This method deletes a search input and its associated resources.		
Parameter Type Description		

3.7.4 getAvailableCategories

requestGetAvailableCategories		
This method retrieves the list of POI categories available (predefined and custom).		
Parameter Type Description		Description



responseGetAvailableCategories		
This method retrieves the list of POI categories available (predefined and custom).		
Parameter	Туре	Description
getAvailableCategories_categories		<u>d_ist</u> of categories (id, name and top_level).

3.7.5 getCategoriesDetails

requestGetCategoriesDetails	S .		
		ssociated to one or more POI categories. It ibute, the list of attributes, the icons,	
Parameter	Type Description		
getCategoriesDetails_R_categ	j dīriedS Vector_CategoryID_	list of categories enum(INVALID,ALL_CATEGORIES,AIRI) Note: A POI category is a unique ID. It could be a predefined category or a custom one defined by a POI plug-in.	PORT,RESTA

responseGetCategoriesDetails			
GetCategoriesDetails = This method retrieves the details associated to one or more POI categories. It contains the name, the parent categories, the top level attribute, the list of attributes, the icons,			
Parameter	Type Description		
getCategoriesDetails_results	THBVector_Category_	List of details for all the POI categories.	

3.7.6 getChildrenCategories

requestGetChildrenCategories		
Get the children categories id and type (top level) from the a parent unique id.		
Parameter Type Descrip		Description
getChildrenCategories_R_cate@artyegoryID		unique category id.

responseGetChildrenCategories		
Get the children categories id and type (top level) from the a parent unique id.		
Parameter Type Description		



responseGetChildrenCategories

getChildrenCategories_categories_categories_list of categories (id and top_level).

3.7.7 getParentCategories

requestGetParentCategories			
Get the parent categories id and type (top level) from the a unique id.			
Parameter	Type Description		
getParentCategories_R_categoryID		unique catego	ory id.

responseGetParentCategories			
Get the parent categories id and type (top level) from the a unique id.			
Parameter	Type Description		
getParentCategories_categories_HBVector_CategoryAndLevelList of categories (id and top_level).			

3.7.8 getPoiData

requestGetPoiData		
This method returns the POI data for a preview map. The same data as for the last requestResultList is returned.		
Parameter Type Description		
poiSearchHandle	Handle	poi search unique handle.

responseGetPoiData			
This method returns the POI data for a preview map. The same data as for the last requestResultList is returned.			
Parameter	Type Description		
poiList	THBVector_PreviewDetails_	id, icon, latitude, longitude.	

3.7.9 getPoiDetails

requestGetPoiDetails

This method retrieves the details associated to one or more POI. It contains the name, the parent categories, the list of attributes, the icons,



requestGetPoiDetails		
Parameter	Туре	Description
getPoiDetails_R_id	THBVector_POI_ID_	list of poi.

responseGetPoiDetails		
This method retrieves the details associated to one or more POI. It contains the name, the parent categories, the list of attributes, the icons,		
Parameter Type Description		
getPoiDetails_results	THBVector_SearchResultDeta	iærray[details, categories, attributes].

3.7.10 getRootCategory

requestGetRootCategory		
Get the root category id. That would be ALL_CATEGORIES.		
Parameter Type Description		

responseGetRootCategory		
Get the root category id. That would be ALL_CATEGORIES.		
Parameter	Туре	Description
getRootCategory_category	CategoryID	The root category is a top level one by design.

3.7.11 getVersion

requestGetVersion		
This method returns the API version implemented by the content access module.		
Parameter Type Description		

responseGetVersion			
This method returns the API version implemented by the content access module.			
Parameter Type Description			
getVersion_version	Version		



3.7.12 requestResultList

requestRequestResultList		
This method gets the poi result list (e.g. after a Search/Scroll call) .		
Parameter	Туре	Description
requestResultList_R_poiSearchilltandite		poi search unique handle.
requestResultList_R_offset	UInt16	starting offset of the newly requested list elements. If invalid (more that total list for instance) it starts from the begining.
requestResultList_R_maxWin	dbW8it&e	maximum number of elements that should be returned as result.
requestResultList_R_attribute	sTHBVector_AttributeID_	List of attributes id to retrieve. This is optional and the list could be empty.

responseRequestResultList			
This method gets the poi result list (e.g. after a Search/Scroll call) .			
Parameter	Туре	Description	1
requestResultList_statusValue	SearchStatusState	enum(INVALID,NOT_STARTED,SEARC).	HING,FINISHE
requestResultList_resultListSiz	≱ e ∕Int16	Number of items of the results list.]
requestResultList_resultListWi	ก ัต่งผ ัVector_SearchResult_	array[unique_id, distance, route_status, attributes].	

3.7.13 setAttributes

requestSetAttributes			
This method filters for POI attributes (optional) for the current search input and the corresponding result-lists for the current session An attribute is attached to a category.			
Parameter	Туре	Description	
setAttributes_R_poiSearchHar	diendle	poi search unique handle.	
setAttributes_R_poiAttributes	THBVector_AttributeDetails_	array[struct(name, poiCategory, type, value, operator, mandatory)].	

responseSetAttributes		
This method filters for POI attributes (optional) for the current search input and the corresponding result-lists for the current session An attribute is attached to a category.		
Parameter Type Description		



3.7.14 setCategories

requestSetCategories		
This method sets the POI categories for the current search input and the corresponding result-lists for the current session .		
Parameter	Туре	Description
setCategories_R_poiSearchHa	a hdle dle	poi search unique handle.
setCategories_R_poiCategorie	SHBVector_CategoryID_	List of categories to search.

responseSetCategories		
This method sets the POI categories for the current search input and the corresponding result-lists for the current session .		
Parameter Type Description		

3.7.15 setCenter

requestSetCenter		
This method sets the location to start the search around. If a route handle was defined before, it will be replaced by this location.		
Parameter Type Description		
setCenter_R_poiSearchHandleHandle poi search unique handle.		poi search unique handle.
setCenter_R_location	Coordinate3D	location of the center.

responseSetCenter		
This method sets the location to start the search around. If a route handle was defined before, it will be replaced by this location.		
Parameter Type Description		

3.7.16 setMaximumResults

requestSetMaximumResults		
This method sets the maximum number of results to retrieve.		
Parameter Type		Description
setMaximumResults_R_poiSe	a rktnidte ndle	poi search unique handle.



requestSetMaximumResults		
setMaximumResults_R_maxRedsluft§2	maximum number of results to search.	
setMaximumResults_R_findAt	search until at least one POI is found, even if radius is larger than the set maximum.	

responseSetMaximumResults		
This method sets the maximum number of results to retrieve.		
Parameter Type Description		

3.7.17 setRouteHandle

requestSetRouteHandle This method allows to start a POI search along a route. The route handle must be valid or the POI search will fail. If a search location was defined before, it will be replaced by the route.		
setRouteHandle_R_poiSearch	HHaamodlee	poi search unique handle.
setRouteHandle_R_routeHand	le andle	route handle.
setRouteHandle_R_startSearc	h.Ontiset	(optional) Distance from destination (in meters) from where to start the search along. Invalid (>route length) distance means start from start of route.
setRouteHandle_R_endSearch	hOffisa2	(optional) Distance from destination (in meters) where to end the search. Invalid (>route length) means end is the start of route.

responseSetRouteHandle		
This method allows to start a POI search along a route. The route handle must be valid or the POI search will fail. If a search location was defined before, it will be replaced by the route.		
Parameter Type Description		

3.7.18 setSearchRadius

requestSetSearchRadius
This method sets the search radius.



requestSetSearchRadius		
Parameter Type Description		Description
setSearchRadius_R_poiSearc	httandle	poi search unique handle.
setSearchRadius_R_radius	UInt32	Radius to search (in meters).

responseSetSearchRadius	
This method sets the search radius.	
Parameter Type Description	

3.7.19 startPoiSearch

requestStartPoiSearch

This method sends the search input for the search handle. The search will start with the either the location or the route handle. If no position or route handle were configured, the search will use the vehicle position are center location.

Parameter	Туре	Description	
startPoiSearch_R_poiSearch	ahadie lle	poi search unique handle.	
startPoiSearch_R_inputString	String	contains the name of the poi that is searched. It could be a partial name or an empty string.	
startPoiSearch_R_sortOption		enum(SORT_DEFAULT,SORT_BY_DIS) If more than one category was defined for this search, the sort criteria should be compliant with all categories.	TANCE,SORT

responseStartPoiSearch

This method sends the search input for the search handle. The search will start with the either the location or the route handle. If no position or route handle were configured, the search will use the vehicle position are center location.

Parameter	Туре	Description
		•

3.7.20 categoriesUpdated

informationCategoriesUpdated		
This signal indicates that one or more POI categories were added, updated or removed.		
Parameter Type Description		



informationCategoriesUpdated		
categoriesUpdated_poiCategoriesBVector_CategoryAndReas thist of POI categories modified or		
		added.

3.7.21 poiStatus

informationPoiStatus			
This signal updates the search	h status of the specified ha	andle.	
Parameter	Туре	Description	-
poiStatus_poiSearchHandle	Handle	poi search unique handle.	
poiStatus_statusValue	SearchStatusState	SearchStatusState enum(INVALID,NOT_STARTED,SEARC).	HING,FINISHI
poiStatus_coveredSearchRad	diudsInt32	covered radius of the search, respectively distance along the route (in meters).	

3.7.22 resultListChanged

informationResultListChanged		
This signal updates in the poi results list.		
Parameter	Туре	Description
resultListChanged_poiSearchl	Haladle e	poi search unique handle.
resultListChanged_resultListSi	zlelnt16	Number of items of the results list.

3.7.23 Error

Error		
This is the type for error responses.		
Literal	Description	
ERROR_createPoiSearchHandle_NoHandleAvailate	ole	
ERROR_setCenter_ImpossibleToSetWhenSearchI	sStarted	
ERROR_setRouteHandle_StartEqualsEndError		
ERROR_setCategories_UnmatchedCategoryError		
ERROR_setSearchRadius_NotPossibleForSearchA	AlongRouteError	
ERROR_setSearchRadius_RadiusTooSmallError		



Error	
ERROR_setMaximumResults_RadiusTooSmallErro	Dr.
ERROR_setAttributes_UnsupportedFilterError	
ERROR_cancelPoiSearch_InvalidHandleError	

3.7.24 THBVector_AttributeDetails_

array[struct(name, poiCategory, type, value, operator, mandatory)]. Vector of element type AttributeDetails

Referenced by: org_harman_nav_ctrl_di_POISearch::setAttributes

3.7.25 THBVector_AttributeID_

List of attributes id to retrieve. This is optional and the list could be empty. Vector of element type **AttributeID**

Referenced by: org_harman_nav_ctrl_di_POISearch::requestResultList

3.7.26 THBVector_CategoryAndLevel_

List of categories (id and top_level). Vector of element type CategoryAndLevel

Referenced by : org_harman_nav_ctrl_di_POISearch::getChildrenCategories, org_harman_nav_ctrl_di_POISearch::getParentCategories

3.7.27 THBVector_CategoryAndName_

List of categories (id, name and top_level). Vector of element type CategoryAndName

Referenced by : org_harman_nav_ctrl_di_POISearch::getAvailableCategories

3.7.28 THBVector_CategoryAndReason_

List of POI categories modified or added. Vector of element type CategoryAndReason

Referenced by: org_harman_nav_ctrl_di_POISearch::categoriesUpdated

3.7.29 THBVector_CategoryID_

list of categories

enum(INVALID,ALL_CATEGORIES,AIRPORT,RESTAURANT,HOTEL,GAZ_STATION,CAR_PARK,



...) Note: A POI category is a unique ID. It could be a predefined category or a custom one defined by a POI plug-in. Vector of element type **CategoryID**

Referenced by : org_harman_nav_ctrl_di_POISearch::getCategoriesDetails, org_harman_nav_ctrl_di_POISearch::setCategories

3.7.30 THBVector_Category_

List of details for all the POI categories. Vector of element type Category

Referenced by : org_harman_nav_ctrl_di_POISearch::getCategoriesDetails

3.7.31 THBVector_POI_ID_

list of poi. Vector of element type POI_ID

Referenced by : org_harman_nav_ctrl_di_POISearch::getPoiDetails

3.7.32 THBVector_SearchResultDetails_

array[details, categories, attributes]. Vector of element type SearchResultDetails

Referenced by : org_harman_nav_ctrl_di_POISearch::getPoiDetails

3.7.33 THBVector_SearchResult_

array[unique id, distance, route status, attributes]. Vector of element type SearchResult

Referenced by: org_harman_nav_ctrl_di_POISearch::requestResultList

3.8 org_harman_nav_ctrl_di_POIServiceTypes

Interface Version: 1.1

3.8.1 AttributeDetails

AttributeDetails		
used in setAttrbutes and CAM startPOISearch		
Structure Element	Туре	Description
id	AttributeID	id of attribute .



AttributeDetails		
categoryld	CategoryID	enum(INVALID,ALL_CATEGORIES,AIRPORT,RESTA). Note: A POI category is a unique ID. It could be a predefined category or a custom one defined by a POI plug-in
type	AttributeType	enum(INVALID,STRING,INTEGER,COORDINATES).
value	AttributeValue	value or partial value. The value depends on the attribute specifications and type.
oper	OperatorType	enum(INVALID,MORE_THAN,LESS_THAN,EQUAL,).
mandatory	boolean	true if the attribute is mandatory for the search and false for optional.

Referenced by: org_harman_nav_ctrl_di_POIContentAccessModule::THBVector_AttributeDetails_, org_harman_nav_ctrl_di_POISearch::THBVector_AttributeDetails_

3.8.2 AttributeID

Alias of actual type: UInt32

 $Referenced\ by: org_harman_nav_ctrl_di_POIContentAccessModule::THBVector_AttributeID_,$

org_harman_nav_ctrl_di_POISearch::THBVector_AttributeID_,

org_harman_nav_ctrl_di_POIServiceTypes::PoiAttribute,

 $org_harman_nav_ctrl_di_POIServiceTypes:: Category Attribute,$

org_harman_nav_ctrl_di_POIServiceTypes::AttributeDetails

3.8.3 AttributeType

AttributeType		
Type of Attribute		
Literal	Description	
AttributeType_INTEGER		
AttributeType_BOOLEAN		
AttributeType_COORDINATE		
AttributeType_STRING		

Referenced by: org_harman_nav_ctrl_di_POIServiceTypes::PoiAttribute, org_harman_nav_ctrl_di_POIServiceTypes::CategoryAttribute, org_harman_nav_ctrl_di_POIServiceTypes::AttributeDetails



3.8.4 AttributeValue

AttributeValue			
values for attributes.			
Variant Element	Туре	Description	
intListValue	THBVector_Int32_		
stringListValue	THBVector_CHBString_		
boolListValue	THBVector_bool_		
coordinateListValue	THBVector_Coordinate2D_		

Referenced by : org_harman_nav_ctrl_di_POIServiceTypes::PoiAttribute, org_harman_nav_ctrl_di_POIServiceTypes::Operator, org_harman_nav_ctrl_di_POIServiceTypes::AttributeDetails

3.8.5 CAMCategory

CAMCategory		
Structure Element	Туре	Description
details	Details	struct(list of parents_id, icons, name, short_desc, media).
attributes	THBVector_CategoryAttribute	array[struct(name, type, array[struct(operator_id, operator_name)])].
sortOptions	THBVector_CategorySortOption	array[struct(id, name)].

Referenced by: org_harman_nav_ctrl_di_POIContentAccess::THBVector_CAMCategory_

3.8.6 CAMCategoryUpdate

CAMCategoryUpdate			
Structure Element	Туре	Description	
id	CategoryID	enum(INVALID,ALL_CATEGORIES,AIRI). Note: A POI category is a unique ID. It could be a predefined category or a custom one defined by a POI plug-in	PORT,RESTAL



CAMCategoryUpdate		
attributes	THBVector_CategoryAttribute	_array[struct(name, type, array[struct(operator_id, operator_name)])].
sortOptions	THBVector_CategorySortOption	array[struct(id, name)].

Referenced by: org_harman_nav_ctrl_di_POIContentAccess::THBVector_CAMCategoryUpdate_

3.8.7 Category

Category			
Detailed description of a category including attributes and sort options			
Structure Element Type Description			
details	CategoryDetails	struct(unique_id, list of parents_id, icons, name, top_level, short_desc, media).	
attributes	THBVector_CategoryAttribute	_array[struct(name, type, array[struct(operator_id, operator_name)].	
sortOptions	THBVector_CategorySortOption	array[struct(id, name)].	

Referenced by: org_harman_nav_ctrl_di_POISearch::THBVector_Category_

3.8.8 CategoryAndLevel

CategoryAndLevel Pair of catgory and description of level		
uniqueld	CategoryID	Category unique id.
topLevel	boolean	true if the category is a pre-defined one (top level), false for customized categories created by plug-in.
hasChildCategories	boolean	

Referenced by: org_harman_nav_ctrl_di_POISearch::THBVector_CategoryAndLevel_



3.8.9 CategoryAndName

CategoryAndName		
pair of category and name		
Structure Element	Туре	Description
uniqueld	CategoryID	Category unique id.
name	String	name.
topLevel	boolean	true if the category is a pre-defined one (top level), false for customized categories created by plug-in.

Referenced by: org_harman_nav_ctrl_di_POISearch::THBVector_CategoryAndName_

3.8.10 CategoryAndRadius

CategoryAndRadius		
Structure Element	Туре	Description
id	CategoryID	enum(INVALID,ALL_CATEGORIES,AIRPORT,REST). Note: A POI category is a unique ID. It could be a predefined category or a custom one defined by a POI plug-in
radius	UInt32	activation or search radius around the position (in 10 meters) for the category. If value is 0 (zero), the default radius (defined for a category) is applied.

Referenced by:

org_harman_nav_ctrl_di_POIContentAccessModule::THBVector_CategoryAndRadius_

3.8.11 CategoryAndReason

CategoryAndReason			
pair of category and reson for update			
Structure Element	Туре	Description	
unique_id	CategoryID	Category unique id.	



CategoryAndReason			
reason	UInt16	enum(ADDED,REMOVED,ATTR_ADDEI	D,ATTR_MOD
).	

Referenced by: org_harman_nav_ctrl_di_POISearch::THBVector_CategoryAndReason_

3.8.12 CategoryAndStatus

CategoryAndStatus		
pair of category and the this category is available		
Structure Element	Туре	Description
uniqueld	CategoryID	Category unique id.
status	boolean	true if the category is available.

3.8.13 CategoryAttribute

CategoryAttribute		
		. Use more than one operator to specify n categor details and update category
Structure Element	Туре	Description
id	AttributeID	id of attribute .
name	String	localized display name.
type	AttributeType	enum(INVALID,STRING,INTEGER,COORDINATES).
operators	THBVector_Operator_	

 $Referenced\ by: org_harman_nav_ctrl_di_POIServiceTypes::THBVector_CategoryAttribute_$

3.8.14 CategoryDetails

CategoryDetails			
Detailed descripton of a category			
Structure Element	Туре	Description	
uniqueld	CategoryID	Category unique id.	



CategoryDetails		
parentsId	THBVector_CategoryID_	list of parent categories unique id.
icons	Icon	visual icons set.
name	String	name.
topLevel	boolean	true if the category is a pre-defined one (top level), false for customized categories created by plug-in.
description	String	short category description (optional).
media	Media	media associated (html web site, audio, video,) (optional).

Referenced by: org_harman_nav_ctrl_di_POIServiceTypes::Category

3.8.15 CategoryID

Unique ID for a POI Categories Alias of actual type: UInt32

```
Referenced by: org harman nav ctrl di POIContentAccess::THBVector CategoryID,
org harman nav ctrl di POISearch::getRootCategory,
org_harman_nav_ctrl_di_POISearch::getChildrenCategories,
org_harman_nav_ctrl_di_POISearch::getParentCategories,
org harman nav ctrl di POISearch::THBVector CategoryID,
org_harman_nav_ctrl_di_POIServiceTypes::CategoryAndStatus,
org_harman_nav_ctrl_di_POIServiceTypes::CategoryAndReason,
org_harman_nav_ctrl_di_POIServiceTypes::CategoryAndName,
org_harman_nav_ctrl_di_POIServiceTypes::CategoryAndLevel,
org_harman_nav_ctrl_di_POIServiceTypes::AttributeDetails,
org harman nav ctrl di POIServiceTypes::PoiCAMDetails,
org harman nav ctrl di POIServiceTypes::THBVector CategoryID,
org harman nav ctrl di POIServiceTypes::CategoryAndRadius,
org_harman_nav_ctrl_di_POIServiceTypes::CategorySortOption,
org_harman_nav_ctrl_di_POIServiceTypes::CAMCategoryUpdate,
org harman nav ctrl di POIServiceTypes::CategoryDetails,
org_harman_nav_ctrl_di_SpeechPoiSearch::getSpeechInputModes,
org_harman_nav_ctrl_di_SpeechPoiSearch::getCategoriesSpeechInfoList
```

3.8.16 CategorySortOption

CategorySortOption			
Structure Element	Туре	Description	
id	CategoryID	enum(SORT_DEFAULT,SORT_BY_DIS	TANCE,SORT
).	



CategorySortOption		
name	String	localized name to be displayed by application.

Referenced by: org_harman_nav_ctrl_di_POIServiceTypes::THBVector_CategorySortOption_

3.8.17 Category_t

TODO: This is a placeholder for a Category which used into the POISearch.fidl. Alias of actual type: **UInt16**

3.8.18 **Details**

Details			
Structure Element	Туре	Description	
parentsId	THBVector_CategoryID_	list of parent categories unique id.	
icons	Icon	visual icons set.	
name	String	name.	
shortDesc	String	short category description (optional).	
media	Media	media associated (html web site, audio, video,) (optional).	

Referenced by: org_harman_nav_ctrl_di_POIServiceTypes::CAMCategory

3.8.19 Icon

Icon			
Different types of resour	ces for icons		
Variant Element	Туре	Description	
id	THBVector_ResourceID_		
url	String		

Referenced by : org_harman_nav_ctrl_di_POIServiceTypes::CategoryDetails, org_harman_nav_ctrl_di_POIServiceTypes::Details, org_harman_nav_ctrl_di_POIServiceTypes::PreviewDetails



3.8.20 Media

Media			
Differtent type of media			
Variant Element	Туре	Description	
id	THBVector_ResourceID_		
url	String		

Referenced by : org_harman_nav_ctrl_di_POIServiceTypes::CategoryDetails, org_harman_nav_ctrl_di_POIServiceTypes::Details

3.8.21 Operator

Operator		
Structure Element	Туре	Description
type	OperatorType	enum(INVALID,MORE_THAN,LESS_THAN,EQUAL,).
name	String	localized display name.
value	AttributeValue	value to use if this comparator is selected.

Referenced by : org_harman_nav_ctrl_di_POIServiceTypes::THBVector_Operator_

3.8.22 OperatorType

OperatorType		
Type of Operator		
Literal	Description	
OperatorType_INVALID		
OperatorType_MORE_THAN		
OperatorType_LESS_THAN		
OperatorType_EQUAL		

Referenced by : org_harman_nav_ctrl_di_POIServiceTypes::Operator, org_harman_nav_ctrl_di_POIServiceTypes::AttributeDetails



3.8.23 POI_ID

Unique ID for a POI results Alias of actual type: UInt32

Referenced by: org_harman_nav_ctrl_di_POIContentAccessModule::THBVector_POI_ID_,

org_harman_nav_ctrl_di_POISearch::THBVector_POI_ID_,

org_harman_nav_ctrl_di_POIServiceTypes::PoiDetails,

org_harman_nav_ctrl_di_POIServiceTypes::SearchResult,

org_harman_nav_ctrl_di_POIServiceTypes::PoiCAMDetails,

org_harman_nav_ctrl_di_POIServiceTypes::PreviewDetails,

org_harman_nav_ctrl_highwaymode_HighwayModeTypes::POIInformation

3.8.24 PoiAddedDetails

PoiAddedDetails			
Structure Element	Туре	Description	
name	String	POI name	
location	Coordinate3D	POI location.	
attributes	THBVector_PoiAttribute_	array[struct(name,type,value)].	

3.8.25 PoiAttribute

PoiAttribute		
Attribute associcated to a	an POI used in addPOI and F	POI Search Result(both CAM and Service)
Structure Element	Туре	Description
id	AttributeID	attribute unique id (see data model)
type	AttributeType	enum(INVALID,STRING,INTEGER,COORDINATE)
value	AttributeValue	The value depends on the attribute specifications and type

Referenced by: org_harman_nav_ctrl_di_POIServiceTypes::THBVector_PoiAttribute_

3.8.26 PoiCAMDetails

PoiCAMDetails		
Structure Element	Туре	Description



PoiCAMDetails			
sourceld	POI_ID	POI unique id as known by the content access module. This id will be used by POI service to request POI details.	
name	String	POI name.	
category	CategoryID	POI category unique id.	
location	Coordinate3D	POI location.	
distance	UInt16	distance in meters to poi from center of the search.	
attributes	THBVector_PoiAttribute_	List of attributes requested. It could be empty.	

Referenced by: org_harman_nav_ctrl_di_POIContentAccessModule::THBVector_PoiCAMDetails_

3.8.27 PoiDetails

PoiDetails			
Structure Element	Туре	Description	
id	POI_ID	POI id	
name	String	POI name	
location	Coordinate3D	POI location.	

 $Referenced\ by: org_harman_nav_ctrl_di_POIServiceTypes::SearchResultDetails$

3.8.28 PreviewDetails

PreviewDetails				
Details for a POI preview on map				
Structure Element Type Description				
index	UInt32	Index in list.		
displayedIndex	String	Displayed index (can differ, e.g. advertisemenet).		
Id	POI_ID	POI ld.		
category	THBVector_CategoryID_	list of parent categories unique id.		
icon	Icon	visual icon.		
geopos	Coordinate3D	position.		
name	String	name, optional.		



Referenced by: org_harman_nav_ctrl_di_POIServiceTypes::THBVector_PreviewDetails_

3.8.29 ResourceID

Unique ID for a POI Icon Resource Alias of actual type: UInt32

Referenced by : org_harman_nav_ctrl_di_POIServiceTypes::THBVector_ResourceID_, org_harman_nav_ctrl_highwaymode_HighwayModeTypes::POIInformation

3.8.30 SearchResult

SearchResult			
Structure Element	Structure Element Type Description		
id	POI_ID	POI id	
distance	UInt32	distance in meters to poi from center of the search or from vehicle if search along	
routeStatus	UInt16	enum(OFF_ROUTE,ON_ROUTE,INSIDE)	_CORRIDOR
attributes	THBVector_PoiAttribute_	List of attributes requested. It could be empty	

 $Referenced\ by: org_harman_nav_ctrl_di_POISearch:: THBVector_SearchResult_instance and the property of the p$

3.8.31 SearchResultDetails

SearchResultDetails				
Structure Element	Туре	Description		
details	PoiDetails	struct(id,name,latitude,longitude,altitude)		
categories	THBVector_CategoryID_	array[unique_id].		
attributes	THBVector_PoiAttribute_	array[struct(name,type,value)].		

Referenced by:

org_harman_nav_ctrl_di_POIContentAccessModule::THBVector_SearchResultDetails_,

 $org_harman_nav_ctrl_di_POISearch:: THBVector_SearchResultDetails_,$

org_harman_nav_ctrl_highwaymode_HighwayModeTypes::POIDetailsArray,

org_harman_nav_ctrl_highwaymode_HighwayModeTypes::HighwayItemDetails,

org_harman_nav_ctrl_memory_LocationMemoryTypes::Location



3.8.32 SearchStatusState

SearchStatusState		
Current state of the search		
Literal	Description	
SearchStatusState_INVALID		
SearchStatusState_NOT_STARTED		
SearchStatusState_SEARCHING		
SearchStatusState_FINISHED		

Referenced by : org_harman_nav_ctrl_di_POIContentAccessModule::searchStatus, org_harman_nav_ctrl_di_POISearch::requestResultList, org_harman_nav_ctrl_di_POISearch::poiStatus

3.8.33 SortOptions

SortOptions		
sort option of result list		
Literal	Description	
SortOptions_SORT_BY_DISTANCE		
SortOptions_SORT_BY_NAME		
SortOptions_SORT_BY_TIME		
SortOptions_SORT_BY_PRICE		

Referenced by: org_harman_nav_ctrl_di_POISearch::startPoiSearch

3.8.34 THBVector_CHBString_

Vector of element type String

 $Referenced\ by: org_harman_nav_ctrl_di_POIServiceTypes::AttributeValue$

3.8.35 THBVector_CategoryAttribute_

array[struct(name, type, array[struct(operator_id, operator_name)])]. Vector of element type CategoryAttribute



Referenced by: org_harman_nav_ctrl_di_POIServiceTypes::CAMCategoryUpdate, org_harman_nav_ctrl_di_POIServiceTypes::Category, org_harman_nav_ctrl_di_POIServiceTypes::CAMCategory

3.8.36 THBVector_CategoryID_

array[unique_id]. Vector of element type CategoryID

Referenced by: org_harman_nav_ctrl_di_POIServiceTypes::SearchResultDetails, org_harman_nav_ctrl_di_POIServiceTypes::CategoryDetails, org_harman_nav_ctrl_di_POIServiceTypes::Details, org_harman_nav_ctrl_di_POIServiceTypes::PreviewDetails

3.8.37 THBVector_CategorySortOption_

array[struct(id, name)]. Vector of element type CategorySortOption

Referenced by: org_harman_nav_ctrl_di_POIServiceTypes::CAMCategoryUpdate, org_harman_nav_ctrl_di_POIServiceTypes::Category, org_harman_nav_ctrl_di_POIServiceTypes::CAMCategory

3.8.38 THBVector_Coordinate2D_

Vector of element type Coordinate2D

Referenced by : org_harman_nav_ctrl_di_POIServiceTypes::AttributeValue

3.8.39 THBVector_Int32_

Vector of element type Int32

Referenced by : org_harman_nav_ctrl_di_POIServiceTypes::AttributeValue

3.8.40 THBVector_Operator_

Vector of element type Operator

Referenced by : org_harman_nav_ctrl_di_POIServiceTypes::CategoryAttribute

3.8.41 THBVector_PoiAttribute_

array[struct(name,type,value)]. Vector of element type PoiAttribute



Referenced by: org_harman_nav_ctrl_di_POIServiceTypes::PoiAddedDetails, org_harman_nav_ctrl_di_POIServiceTypes::SearchResult, org_harman_nav_ctrl_di_POIServiceTypes::PoiCAMDetails, org_harman_nav_ctrl_di_POIServiceTypes::SearchResultDetails

3.8.42 THBVector_PreviewDetails_

Vector of element type PreviewDetails

Referenced by : org_harman_nav_ctrl_di_POISearch::getPoiData

3.8.43 THBVector_ResourceID_

Vector of element type ResourceID

Referenced by : org_harman_nav_ctrl_di_POIServiceTypes::Media, org_harman_nav_ctrl_di_POIServiceTypes::Icon

3.8.44 THBVector_bool_

Vector of element type boolean

Referenced by : org_harman_nav_ctrl_di_POIServiceTypes::AttributeValue

3.8.45 UpdateReason

UpdateReason		
Reason of update		
Literal	Description	
UpdateReason_ADDED		
UpdateReason_REMOVED		
UpdateReason_ATTR_ADDED		
UpdateReason_ATTR_MODIFIED		
UpdateReason_ATTR_REMOVED		

3.9 org_harman_nav_ctrl_di_POIServiceTypesExt

Interface Version: 1.0



3.9.1 POIStandardCat

POIStandardCat		
NDS predefined standard categories		
Literal	Description	
POICAT_ACCESS_POINT		
POICAT_ACTIVATION_POINT		
POICAT_LOGICAL_ACCESS_POINT		
POICAT_GUIDANCE_POINT		
POICAT_NDSGENERAL		
POICAT_VEHICLE_REPAIR		
POICAT_PETROL_STATION		
POICAT_RENT_A_CAR		
POICAT_CAR_WASH		
POICAT_CAR_DEALERSHIP		
POICAT_MOTORCYCLE_DEALERSHIP		
POICAT_TRUCK_DEALERSHIP		
POICAT_PARKING_GARAGE		
POICAT_OPEN_PARKING		
POICAT_REST_AREA		
POICAT_ROAD_ASSISTANCE		
POICAT_CAMPING		
POICAT_CARAVAN_SITE		
POICAT_COACH_AND_LORRY_PARKING		
POICAT_MOTORING_ORG_OFFICE		
POICAT_CAR_SHIPPING_TERMINAL		
POICAT_HOTEL_MOTEL		
POICAT_RESTAURANT		
POICAT_FAST_FOOD		
POICAT_COFFEE_SHOP		
POICAT_BAR_OR_PUB		
POICAT_CINEMA		
POICAT_MUSEUM		
POICAT_THEATRE		
POICAT_LIBRARY		
POICAT_HOSPITAL		
POICAT_PHYSICIAN		



POIStandardCat	
POICAT_DENTIST	
POICAT_PHARMACY	
POICAT_VETERINARIAN_SERVICE	
POICAT_POLICE_STATION	
POICAT_POST_OFFICE	
POICAT_CITY_HALL	
POICAT_EMBASSY	
POICAT_COURT_HOUSE	
POICAT_GOVERNMENT_OFFICE	
POICAT_COMMUNITY_CENTRE	
POICAT_SHOPPING_CENTRE	
POICAT_STORE	
POICAT_BANK	
POICAT_ATM	
POICAT_CURRENCY_EXCHANGE	
POICAT_TOURIST_OFFICE	
POICAT_TRAVEL_AGENCY	
POICAT_TOURIST_ATTRACTION	
POICAT_HISTORICAL_MONUMENT	
POICAT_NATIONAL_PARK	
POICAT_CITY_CENTRE	
POICAT_HAMLET	
POICAT_ZOO	
POICAT_AMUSEMENT_PARK	
POICAT_GOINGOUT	
POICAT_STADIUM	
POICAT_SPORTS_CENTRE	
POICAT_RECREATION	
POICAT_SKI_RESORT	
POICAT_SWIMMING_POOL	
POICAT_GOLF_COURSE	
POICAT_FERRY_TERMINAL	
POICAT_MARINA	
POICAT_HARBOUR	
POICAT_BUSINESS_FACILITY	
POICAT_EXIBITION_CONFERENCE_CENTRE	



POIStandardCat	
POICAT_RAILWAY_STATION	
POICAT_PUBLIC_TRANSIT_STOP	
POICAT_PARK_AND_RIDE	
POICAT_AIRPORT	
POICAT_AIRLINE_ACCESS	
POICAT_TAXI_STAND	
POICAT_EMERGENCY_CALL_STATION	
POICAT_EMERGENCY_MEDICAL_SERVICE	
POICAT_FIRST_AID_POST	
POICAT_FIREBRIGADE	
POICAT_PLACE_OF_WORSHIP	
POICAT_EDUCATION	
POICAT_CUSTOMS	
POICAT_FRONTIER_CROSSING	
POICAT_TOLL_LOCATION	
POICAT_PUBLIC_RESTROOM	
POICAT_PUBLIC_PHONE	
POICAT_KINDERGARTEN	
POICAT_MOUNTAIN_PASS_SUMMIT	
POICAT_SPEED_CAMERA	
POICAT_EVS_CHARGING_STATION	
POICAT_CONTROLLED_ACCESS_INTERSECTION	DN
POICAT_CONTROLLED_ACCESS_ENTRY_EXIT	
POICAT_CONTROLLED_ACCESS_SMART_IC	

3.9.2 PredefinedPoiAttributeIDs

PredefinedPoiAttributeIDs		
Predefined IDs for common POI or category attributes.		
Literal	Description	
POIATTR_INVALID		
POIATTR_DISTANCE_2_DESTINATION		
POIATTR_DISTANCE_2_POI		
POIATTR_OFF_ROUTE_DISTANCE		
POIATTR_TRAVEL_TIME		
POIATTR_ROUTE_STATUS		
POIATTR_NAME		



PredefinedPoiAttributeIDs	
POIATTR_DESCRIPTION	
POIATTR_ADDRESS	
POIATTR_PHONE_NUMBER	
POIATTR_URL	
POIATTR_OPEN247	
POIATTR_ICON	
POIATTR_POI_ID	
POIATTR_CLICK_ID	
POIATTR_CATEGORY	
POIATTR_STD_CATID	
POIATTR_GEOPOSITION	
POIATTR_COUNTRY	
POIATTR_STATE	
POIATTR_CITY	
POIATTR_POSTALCODE	
POIATTR_STREET	
POIATTR_HOUSE_NUMBER	
POIATTR_JUNCTION	
POIATTR_INTERNAL_ID	
POIATTR_BRAND	
POIATTR_AVAILABILITY	
POIATTR_PLUGTYPE	
POIATTR_FUELTYPE	
POIATTR_FUELPRICE	
POIATTR_CURRENCY	
POIATTR_STARRANKING	
POIATTR_PRICERANGE	
POIATTR_PREFERRED_PARTNER	
POIATTR_SPONSORED_LINK	
POIATTR_PARKING_TYPE	
POIATTR_PARKING_COST_DAY	
POIATTR_PARKING_COST_HOUR	
POIATTR_PARKING_COST_HOUR2	
POIATTR_PARKING_SLOTS	
POIATTR_PARKING_SLOTS_FREE	
POIATTR_PROVIDER_ID	



PredefinedPoiAttributeIDs	
POIATTR_PROVIDER_NAME	
POIATTR_SEARCH_MAX_RESULTS	
POIATTR_SEARCH_MAX_CORRIDOR	
POIATTR_SEARCH_MAX_REALROAD	
POIATTR_SEARCH_AT_LEAST_ONE	

3.10 org_harman_nav_ctrl_di_SpeechLocationInput

Interface Version: 0.2

3.10.1 getSpeechList

requestGetSpeechList		
Retrieves a file containing all data for speech input. The user has to take care of the file housekeeping		
Parameter Type Description		
getSpeechList_R_locationInpu		locationInpuHandle = Location input handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
getSpeechList_R_inputMode	SpeechMode	Mode for speech input.

responseGetSpeechList		
Retrieves a file containing all data for speech input. The user has to take care of the file housekeeping		
Parameter Type Description		
getSpeechList_pathToListFile	String	Path to the file containing the list of entries.

3.10.2 getSpeechModesList

requestGetSpeechModesList		
Get the available modes for speech input, i.e. language and mode (oneshot,fullword,spelling).		
Parameter Type Description		
getSpeechModesList_R_locati	omanpileHandle	locationInpuHandle = Location input handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value



requestGetSpeechModesList		
getSpeechModesList_R_langu	age6led e	Language for which the speech input should be performed.

responseGetSpeechModesList		
Get the available modes for speech input, i.e. language and mode (oneshot,fullword,spelling).		
Parameter Type Description		
getSpeechModesList_availableTriptitMottes_SpeechMode_ List of available modes for speech input.		

3.10.3 getSpeechOrtographies

requestGetSpeechOrtographies

Retrieves the orthographies and phonemes to the index entries. The result is returned as an SDS file to give the system the possibility to display the name and prompt the phonemes. To safe space compressed SDS files do not include the orthographical name of an entry.

Note that phonemes are only available for unrotated names. If the ID of a rotated name is given, the phoneme of the unrotated name is returned!

Parameter	Туре	Description
getSpeechOrtographies_R_en	tīviltās et ctor_Entryld_	Every entry in the compressed SDS file has a unique id (entryld). With this entryld the engine can find the orthographical name and phoneme for an entry.
getSpeechOrtographies_R_loc	ationInpuHandle	locationInpuHandle = Location input handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
getSpeechOrtographies_R_vo	icebatæle	SDS language code.

responseGetSpeechOrtographies

Retrieves the orthographies and phonemes to the index entries. The result is returned as an SDS file to give the system the possibility to display the name and prompt the phonemes. To safe space compressed SDS files do not include the orthographical name of an entry.

Note that phonemes are only available for unrotated names. If the ID of a rotated name is given, the phoneme of the unrotated name is returned!

Parameter	Туре	Description
getSpeechOrtographies_pathT	S ituist g ile	Path to the file containing the list of
		entries.



3.10.4 Error

Error	
This is the type for error responses.	
Literal	Description
ERROR_getSpeechModesList_SpeechInputError	
ERROR_getSpeechList_SpeechInputError	
ERROR_getSpeechOrtographies_SpeechInputErro	r

3.10.5 THBVector_EntryId_

Every entry in the compressed SDS file has a unique id (entryld). With this entryld the engine can find the orthographical name and phoneme for an entry. Vector of element type **Entryld**

Referenced by: org_harman_nav_ctrl_di_SpeechLocationInput::getSpeechOrtographies

3.10.6 THBVector_SpeechMode_

List of available modes for speech input. Vector of element type SpeechMode

Referenced by: org_harman_nav_ctrl_di_SpeechLocationInput::getSpeechModesList

3.11 org_harman_nav_ctrl_di_SpeechLocationInput

Interface Version: 1.0

3.11.1 **Entryld**

Alias of actual type: Buffer

Referenced by: org_harman_nav_ctrl_di_SpeechLocationInput::THBVector_Entryld_, org_harman_nav_ctrl_di_SpeechPoiSearch::THBVector_Entryld_

3.11.2 Locales

Locales		
Locale data structure - maybe it should be moved in Common Types.		
Structure Element Type Description		



Locales		
languageCode	String	the language used. ISO 639_3 language code (lower case)
countryCode	String	the country specific variant for the language used. ISO 3166_1 alpha 3 country code (upper case)
scriptCode	String	the script specific variant for the language used. ISO 15924 alpha 4 script code (upper case)

Referenced by: org_harman_nav_ctrl_di_SpeechLocationInput::getSpeechModesList, org_harman_nav_ctrl_di_SpeechLocationInput::getSpeechOrtographies, org_harman_nav_ctrl_di_SpeechLocationInputTypes::SpeechMode, org_harman_nav_ctrl_di_SpeechPoiSearch::getSpeechInputModes, org_harman_nav_ctrl_di_SpeechPoiSearch::getCategoriesSpeechOrthographies

3.11.3 SpeechInputMode

SpeechInputMode		
Literal	Description	
SpeechInputMode_BasicEnum_INVALID		
SpeechInputMode_SPEECHINPUT_MODE_SPELI	LING	
SpeechInputMode_SPEECHINPUT_MODE_FULL\	VORD	
SpeechInputMode_SPEECHINPUT_MODE_ONES	НОТ	
SpeechInputMode_SPEECHINPUT_MODE_POI_N	IAME	
SpeechInputMode_SPEECHINPUT_MODE_POI_0	ATEGORY	

 $Referenced\ by: org_harman_nav_ctrl_di_SpeechLocationInputTypes::SpeechMode$

3.11.4 SpeechMode

SpeechMode			
Available modes and parameters for speech input.			
Structure Element Type Description			
inputeMode	SpeechInputMode		
language	Locales		
fileFormat	String		



SpeechMode		
fieldTypes	AddressAttributeList	

Referenced by: org_harman_nav_ctrl_di_SpeechLocationInput::getSpeechList, org_harman_nav_ctrl_di_SpeechLocationInput::THBVector_SpeechMode_, org_harman_nav_ctrl_di_SpeechPoiSearch::getCategoriesSpeechInfoList, org_harman_nav_ctrl_di_SpeechPoiSearch::THBVector_SpeechMode_

3.12 org_harman_nav_ctrl_di_SpeechPoiSearch

Interface Version: 0.1

3.12.1 getCategoriesSpeechInfoList

requestGetCategoriesSpeechInfoList		
Returns the associated speech information file according to the selected search result identifier. The provided file needs to be removed by the user (if generated on-the-fly).		
Parameter Type Description		
getCategoriesSpeechInfoList_	R_adategronVId	ALL_CATEGORIES is the root categoryld.
getCategoriesSpeechInfoList_	RS_pie:patWlade	Mode for speech input.

responseGetCategoriesSpeechInfoList		
Returns the associated speech information file according to the selected search result identifier. The provided file needs to be removed by the user (if generated on-the-fly).		
Parameter	rameter Type Description	
getCategoriesSpeechInfoList_	கூ ய் ள் அListFile	Path to the file containing the list of entries.

3.12.2 getCategoriesSpeechOrthographies

requestGetCategoriesSpeechOrthographies		
Retrieves the orthographies and phonemes to the index entries. The result is returned as an SDS file to give the system the possibility to display the name and prompt the phonemes. To safe space compressed SDS files do not include the orthographical name of an entry.		
Parameter	Туре	Description



requestGetCategoriesSpeechOrthographies		
getCategoriesSpeechOrthographiles/ectentEylldset	Every entry in the compressed SDS file has a unique id (entryld). With this entryld the engine can find the orthographical name and phoneme for an entry.	
getCategoriesSpeechOrthographriesleR_voiceLocale	SDS language code.	

responseGetCategoriesSpeechOrthographies			
Retrieves the orthographies and phonemes to the index entries. The result is returned as an SDS file to give the system the possibility to display the name and prompt the phonemes. To safe space compressed SDS files do not include the orthographical name of an entry.			
Parameter	Parameter Type Description		
getCategoriesSpeechOrthogra	திtie் ஆpathToListFile	Path to the file containing the list of entries.	

3.12.3 getSpeechInputModes

requestGetSpeechInputModes		
Get the available modes for speech input, i.e. language and mode (oneshot,fullword,spelling).		
Parameter Type Description		
getSpeechInputModes_R_cate	• Grantyelglory ID	ALL_CATEGORIES is the root categoryld.
getSpeechInputModes_R_lane	juag a 6ede	Language for which the speech input should be performed.

responseGetSpeechInputModes		
Get the available modes for speech input, i.e. language and mode (oneshot,fullword,spelling).		
Parameter Type Description		
getSpeechInputModes_availab	Tell/14p/viet/vltood_speechMode_	List of available modes for speech input.

3.12.4 Error

Error	
This is the type for error responses.	
Literal	Description



Error	
ERROR_getSpeechInputModes_SpeechInputError	
ERROR_getCategoriesSpeechInfoList_SpeechInpu	ıtError
ERROR_getCategoriesSpeechOrthographies_Spee	echInputError

3.12.5 THBVector_EntryId_

Every entry in the compressed SDS file has a unique id (entryld). With this entryld the engine can find the orthographical name and phoneme for an entry. Vector of element type **Entryld**

Referenced by: org_harman_nav_ctrl_di_SpeechPoiSearch::getCategoriesSpeechOrthographies

3.12.6 THBVector_SpeechMode_

List of available modes for speech input. Vector of element type SpeechMode

Referenced by: org_harman_nav_ctrl_di_SpeechPoiSearch::getSpeechInputModes



4 DriverAssist Service

4.1 org_harman_nav_ctrl_DriverAssist

Interface Version: 0.1

4.1.1 getAllCountryInfo

requestGetAllCountryInfo		
getAllCountryInfo = This method returns all country information available.		
Parameter Type Description		

responseGetAllCountryInfo		
getAllCountryInfo = This method returns all country information available.		
Parameter Type Description		
getAllCountryInfo_countryInfoDccbuntryInfoDict		Dictionary of available country codes and their associated information.

4.1.2 getAvailableCountries

requestGetAvailableCountries		
getCountryInfo = This method returns an array of countries with information available.		
Parameter Type Description		

responseGetAvailableCountries		
getCountryInfo = This method returns an array of countries with information available.		
Parameter Type Description		
getAvailableCountries_country Codes Array of countries info is available for		

4.1.3 getCountryInfo

requestGetCountryInfo
getCountryInfo = This method returns country-wide information for the given country.



requestGetCountryInfo		
Parameter Type Description		
getCountryInfo_R_countryCod	€ountryCode	Country to get country info for.

responseGetCountryInfo		
getCountryInfo = This method returns country-wide information for the given country.		
Parameter Type Description		
getCountryInfo_countryInfo	CountryInfo	Returns the country's information.

4.1.4 getSettings

requestGetSettings		
Parameter	Туре	Description
getSettings_R_types	SettingTypes	

responseGetSettings		
Parameter	Туре	Description
getSettings_settings	Settings	

4.1.5 setSettings

requestSetSettings		
Parameter	Туре	Description
setSettings_R_settings	Settings	

responseSetSettings		
Parameter	Туре	Description

4.1.6 countryInfoUpdate

informationCountryInfoUpdate
Broadcasts the current location's country info.



informationCountryInfoUpdate		
Parameter Type Description		
countryInfoUpdate_countryCo	© ountryCode	Country code of current country.
countryInfoUpdate_countryInfo	CountryInfo	Country info of current country.

4.1.7 settingsChanged

informationSettingsChanged		
Notifies if settings have changed		
Parameter	Туре	Description
settingsChanged_settings	SettingTypes	

4.1.8 speedLimitExceeded

informationSpeedLimitExceeded		
Broadcasts the current location's country info.		
Parameter	Туре	Description
speedLimitExceeded_currentS	Speed ed	
speedLimitExceeded_currentS	Specifici mit	

4.2 org_harman_nav_ctrl_DriverAssistTypes

Interface Version: 1.1

4.2.1 CountryCode

ISO 3166-1 alpha 3 country code (upper case). Alias of actual type: String

Referenced by : org_harman_nav_ctrl_DriverAssist::getCountryInfo, org_harman_nav_ctrl_DriverAssist::countryInfoUpdate, org_harman_nav_ctrl_DriverAssistTypes::CountryCodes

4.2.2 CountryCodes

Vector of element type CountryCode



Referenced by : org_harman_nav_ctrl_DriverAssist::getAvailableCountries

4.2.3 CountryInfo

CountryInfo		
Structure Element	Туре	Description
alcoholLimit	double	Maximum alcohol limit in units of "undecided".
requiresSpareBulbs	CountryRequirement	
requiresTowRope	CountryRequirement	
requiresWarningVest	CountryRequirement	
requiresLightsOnDuringDay	CountryRequirement	
maxSpeedLimitInCity	Speed	
maxSpeedLimitOutsideCity	Speed	
maxSpeedLimitOnHighway	Speed	

Referenced by : org_harman_nav_ctrl_DriverAssist::getCountryInfo, org_harman_nav_ctrl_DriverAssist::countryInfoUpdate

4.2.4 CountryInfoDict

CountryInfoDict		
Map Element Type Description		
keyType	CountryCode	ISO 3166-1 alpha 3 country code (upper case).
valueType	CountryInfo	

Referenced by: org_harman_nav_ctrl_DriverAssist::getAllCountryInfo

4.2.5 CountryRequirement

CountryRequirement	
Literal	Description
CountryRequirement_NOT_REQUIRED	



CountryRequirement	
CountryRequirement_REQUIRED	
CountryRequirement_PREFERRED	

Referenced by: org_harman_nav_ctrl_DriverAssistTypes::CountryInfo, org_harman_nav_ctrl_DriverAssistTypes::CountryInfo, org_harman_nav_ctrl_DriverAssistTypes::CountryInfo, org_harman_nav_ctrl_DriverAssistTypes::CountryInfo

4.2.6 GetSettingsError

GetSettingsError	
Literal	Description
GetSettingsError_GET_SETTINGS_FAILED	

4.2.7 SetSettingsError

SetSettingsError	
Literal	Description
SetSettingsError_GET_VERSION_FAILED	

4.2.8 SettingType

SettingType	
Literal Description	
SettingType_SPEED_WARNING	

Referenced by : org_harman_nav_ctrl_DriverAssistTypes::SettingTypes

4.2.9 SettingTypes

Vector of element type **SettingType**

Referenced by : org_harman_nav_ctrl_DriverAssist::getSettings, org_harman_nav_ctrl_DriverAssist::settingsChanged



4.2.10 SettingValue

SettingValue		
Variant Element	Туре	Description
speedWarningValue	SpeedWarning	

4.2.11 Settings

Settings			
Map Element	Туре	Description	
keyType	SettingType		
valueType	SettingValue		

Referenced by : org_harman_nav_ctrl_DriverAssist::getSettings, org_harman_nav_ctrl_DriverAssist::setSettings

4.2.12 Speed

Speed			
Structure Element	Туре	Description	
units	SpeedUnit		
value	UInt32		

Referenced by: org_harman_nav_ctrl_DriverAssist::speedLimitExceeded, org_harman_nav_ctrl_DriverAssist::speedLimitExceeded, org_harman_nav_ctrl_DriverAssistTypes::SpeedWarning, org_harman_nav_ctrl_DriverAssistTypes::CountryInfo, org_harman_nav_ctrl_DriverAssistTypes::CountryInfo, org_harman_nav_ctrl_DriverAssistTypes::CountryInfo

4.2.13 SpeedUnit

SpeedUnit	
Literal	Description



SpeedUnit	
SpeedUnit_KM_P_H	
SpeedUnit_MPH_UK	
SpeedUnit_MPH_US	

Referenced by : org_harman_nav_ctrl_DriverAssistTypes::Speed

4.2.14 SpeedWarning

SpeedWarning		
Cotains speed warning settings. @param notification is the type of warning (or off). @param speedExcess is the overage that triggers the warning.		
Structure Element	Туре	Description
notification	SpeedWarningNotification	
speedExcess	Speed	

Referenced by: org_harman_nav_ctrl_DriverAssistTypes::SettingValue

4.2.15 SpeedWarningNotification

SpeedWarningNotification		
Literal	Description	
SpeedWarningNotification_SPEEDLIMIT_NOTIFIC	ATION_OFF	
SpeedWarningNotification_SPEEDLIMIT_NOTIFIC	ATION_MAP	
SpeedWarningNotification_SPEEDLIMIT_NOTIFIC	ATION_AUDIBLE	
SpeedWarningNotification_SPEEDLIMIT_NOTIFIC	ATION_MAP_AND_AUDIBLE	

Referenced by: org_harman_nav_ctrl_DriverAssistTypes::SpeedWarning



5 Guidance Service

5.1 org_harman_nav_ctrl_GuidanceViewer

Interface Version: 1.0

5.1.1 displayable Valid

informationDisplayableValid		
Updates info about validity of displayable		
Parameter Type Description		Description
displayableValid_displayableLalyne3021anagerID		
displayableValid_valid	boolean	

5.1.2 maneuverStatusChanged

informationManeuverStatusChanged		
Updates info about maneuver status		
Parameter Type Description		Description
maneuverStatusChanged_mar	n ēMærStatus Status	

5.2 org_harman_nav_ctrl_GuidanceViewerTypes

Interface Version: 1.0

5.2.1 ECharacterCodeOfStreetName

ECharacterCodeOfStreetName		
Literal	Description	
ECharacterCodeOfStreetName_UTF8		
ECharacterCodeOfStreetName_UCS2		
ECharacterCodeOfStreetName_ASCII		



ECharacterCodeOfStreetName	
ECharacterCodeOfStreetName_SJIS	

Referenced by : org_harman_nav_ctrl_GuidanceViewerTypes::TManeuverStatus, org_harman_nav_ctrl_GuidanceViewerTypes::TManeuverStatus

5.2.2 EDistanceUnit

EDistanceUnit		
Literal	Description	
EDistanceUnit_METER		
EDistanceUnit_KM		
EDistanceUnit_FEET		
EDistanceUnit_YARD		
EDistanceUnit_MILE		

Referenced by : org_harman_nav_ctrl_GuidanceViewerTypes::TManeuverStatus, org_harman_nav_ctrl_GuidanceViewerTypes::TManeuverStatus, org_harman_nav_ctrl_GuidanceViewerTypes::TManeuverStatus

5.2.3 EIncreasedLane

ElncreasedLane		
Literal	Description	
EIncreasedLane_NOT_INCREASED		
EIncreasedLane_INCREASED		

 $Referenced\ by: org_harman_nav_ctrl_GuidanceViewerTypes::TLaneFlags$

5.2.4 ElncreasedLaneOption

ElncreasedLaneOption	



ElncreasedLaneOption	
Literal	Description
EIncreasedLaneOption_INCREASED_LANE_OPTI	ON
EIncreasedLaneOption_DECREASED_LANE_OPT	ION

Referenced by: org_harman_nav_ctrl_GuidanceViewerTypes::TLaneFlags

5.2.5 ElncreasedLaneSide

ElncreasedLaneSide	
Literal	Description
EIncreasedLaneSide_INCREASED_LANE_LEFT	
EIncreasedLaneSide_INCREASED_LANE_RIGHT	

 $Referenced\ by: org_harman_nav_ctrl_GuidanceViewerTypes::TLaneFlags$

5.2.6 EManeuverOrientation

EManeuverOrientation		
Literal	Description	
EManeuverOrientation_OUTWARD		
EManeuverOrientation_INWARD		

Referenced by: org_harman_nav_ctrl_GuidanceViewerTypes::TManeuverStatus, org_harman_nav_ctrl_GuidanceViewerTypes::TManeuverStatus, org_harman_nav_ctrl_GuidanceViewerTypes::TManeuverStatus

5.2.7 EPresenceOfRotary

EPresenceOfRotary	
Literal	Description
EPresenceOfRotary_ABSENCE	



EPresenceOfRotary	
EPresenceOfRotary_PRESENCE	

Referenced by : org_harman_nav_ctrl_GuidanceViewerTypes::TManeuverStatus, org_harman_nav_ctrl_GuidanceViewerTypes::TManeuverStatus, org_harman_nav_ctrl_GuidanceViewerTypes::TManeuverStatus

5.2.8 ERecomendLane

ERecomendLane		
Literal	Description	
ERecomendLane_NOT_RECOMMENDED		
ERecomendLane_RECOMMENDED		

Referenced by: org_harman_nav_ctrl_GuidanceViewerTypes::TLaneFlags

5.2.9 ESpecialRoadShapeForTbT

ESpecialRoadShapeForTbT	
Literal	Description
ESpecialRoadShapeForTbT_NONDISPLAY	
ESpecialRoadShapeForTbT_GOALONGTHEROAL	RIGHT
ESpecialRoadShapeForTbT_GOALONGTHEROAL	DLEFT
ESpecialRoadShapeForTbT_UTURNRIGHT	
ESpecialRoadShapeForTbT_UTURNLEFT	
ESpecialRoadShapeForTbT_UTURNLEFTROTAR	YTRAFFICCIRCLEUTURNRIGHT
ESpecialRoadShapeForTbT_ROTARYTRAFFICCI	RCLEUTURNLEFT
ESpecialRoadShapeForTbT_MICHIGANTURNRIG	НТ
ESpecialRoadShapeForTbT_MICHIGANTURNLEF	Т
ESpecialRoadShapeForTbT_DESTINATIONROUN	D
ESpecialRoadShapeForTbT_TRANSITPOINTROU	ND
ESpecialRoadShapeForTbT_DESTINATIONFLAG	
ESpecialRoadShapeForTbT_TRANSITPOINTFLAC	
ESpecialRoadShapeForTbT_ROTARYTRAFFICCI	RCLEHEADINGFORINWARDRIGHT



ESpecialRoadShapeForTbT	
ESpecialRoadShapeForTbT_ROTARYTRAFFICCII	RCLEHEADINGFORINWARDLEFT
ESpecialRoadShapeForTbT_HOOKTURN	

Referenced by: org_harman_nav_ctrl_GuidanceViewerTypes::TManeuverStatus, org_harman_nav_ctrl_GuidanceViewerTypes::TManeuverStatus, org_harman_nav_ctrl_GuidanceViewerTypes::TManeuverStatus

5.2.10 TLaneFlags

TLaneFlags		
Descripts lane flags		
Structure Element	Туре	Description
recomended	ERecomendLane	Recomend Lane
increasedLane	ElncreasedLane	Increased lane.
increasedLaneSide	EIncreasedLaneSide	Increased lane side
increasedLaneOption	EIncreasedLaneOption	Increased lane option

Referenced by: org_harman_nav_ctrl_GuidanceViewerTypes::TLanesFlagList

5.2.11 TLanesDirectionList

Vector of element type UInt16

Referenced by : org_harman_nav_ctrl_GuidanceViewerTypes::TManeuverStatus

5.2.12 TLanesFlagList

Vector of element type TLaneFlags

 $Referenced\ by: org_harman_nav_ctrl_GuidanceViewerTypes::TManeuverStatus$

5.2.13 TManeuverStatus

TManeuverStatus	
Descripts maneuver status	



TManeuverStatus		
Structure Element	Туре	Description
uiVehicleDirection	UInt8	
eSpecialRoadShapeForTbT	ESpecialRoadShapeForTbT	
ePresenceOfRotary	EPresenceOfRotary	
eOutward	EManeuverOrientation	
uiDistanceToIntersection	UInt8	
eDistanceUnit	EDistanceUnit	
uiDirectionOfMovement	UInt8	
uiRoadShapeInformation	UInt32	
eSpecialRoadShapeForArrow	CELECTE CIAIROAD SHAPE FOR TOTAL	
ePresenceOfRotaryArrow	EPresenceOfRotary	
eOutwardArrow	EManeuverOrientation	
uiDistanceToIntersectionArro	wUInt16	
eDistanceUnitToIntersectionA	r rō№ istanceUnit	
uiDirectionOfMovementArrow	UInt8	
uiTotalLaneNumber	UInt8	
vLanesFlags	TLanesFlagList	
vLanesDirection	TLanesDirectionList	
eSpecialRoadShapeOfNextIn	ters@poionialRoadShapeForTbT	
ePresenceOfRotaryNextInters	ections before a tion tary	
eOutwardNextIntersectionInfo	rinationeuverOrientation	
uiDistanceToIntersectionNext	IntersectionInformation	
eDistanceUnitNextIntersection	n Efloirstratice Unit	
eDirectionOfNextMovementN	extilinitersectionInformation	
uiRoadShapeInformationNext	InttenseztionInformation	
uiAzimuthInfromationToDestir	attibut8	
eCharacterCodeOfCurrentStr	etNamecterCodeOfStreetNam	ne
chbCurrentStreetName	Buffer	
eCharacterCodeofNextStreet	√arûe aracterCodeOfStreetNam	ne
chbNextStreetName	Buffer	

Referenced by: org_harman_nav_ctrl_GuidanceViewer::maneuverStatusChanged

5.3 org_harman_nav_ctrl_Guidance

Interface Version: 0.4



5.3.1 getDestinationInformation

requestGetDestinationInformation		
getDestinationInformation = This method retrieves the information on the final destination @deprecated Please use waypoints attribute and waypointTravelCostsChanged broadcast		
Parameter Type Description		

responseGetDestinationInformation		
getDestinationInformation = This method retrieves the information on the final destination @deprecated Please use waypoints attribute and waypointTravelCostsChanged broadcast		
Parameter Type		Description
getDestinationInformation_offsetInt32	2	offset = offset of the destination in meter from the beginning of the route
getDestinationInformation_trave/Int84	2	travelTime = time to reach the destination in second
getDestinationInformation_dire thit392		direction = direction of the destination in degree relatively to the North. Range [0:360]
getDestinationInformation_sideUInt10	6	side = enum(LEFT,RIGHT,NOT_AVAILABLE)
getDestinationInformation_time ம்மா		timeZone = time zone of the destination. It is expressed as the time difference from the UTC in minutes
getDestinationInformation_day	avingTime	daylightSavingTime = daylight saving time of the destination. It is expressed as the time difference from the UTC in minutes

5.3.2 getGuidanceDetails

requestGetGuidanceDetails		
getGuidanceDetails = This method retrieves guidance information		
Parameter Type Description		

responseGetGuidanceDetails		
getGuidanceDetails = This method retrieves guidance information		
Parameter Type Description		



responseGetGuidanceDetails		
getGuidanceDetails_voiceGuidbnotean	voiceGuidance = if TRUE voice guidance is active	
getGuidanceDetails_vehicleOntheleaad	vehicleOnTheRoad = if TRUE the vehicle is located on the road network	
getGuidanceDetails_isDestinationoRearched	isDestinationReached = if TRUE the destination has been reached	
getGuidanceDetails_maneuverManueverPhase	maneuver = enum(INVALID,CRUISE,MANEUVER_AF)	PPEARED,PR

5.3.3 getGuidanceStatus

requestGetGuidanceStatus		
getGuidanceStatus = This method retrieves the guidance status		
Parameter Type Description		

responseGetGuidanceStatus		
getGuidanceStatus = This method retrieves the guidance status		
Parameter Type Description		
getGuidanceStatus_guidance	Satuis ance Status	guidanceStatus = enum(INVALID,ACTIVE,INACTIVE)
getGuidanceStatus_routeHan	d lé andle	routeHandle = Active route handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value. Should be ignored when guidanceStatus=INACTIVE

5.3.4 getManeuversList

requestGetManeuversList		
getManeuversList = This method retrieves the list of next maneuvers @deprecated Please maneuverAvailable broadcast and		
Parameter Type Description		
getManeuversList_R_requeste	d/MountaberOfManeuvers	requestedNumberOfManeuvers = the number of requested maneuvers
getManeuversList_R_maneuve	ekDifts e t	maneuverOffset = the offset of the first maneuver to retrieve



responseGetManeuversList		
getManeuversList = This method retrieves the list of next maneuvers @deprecated Please maneuverAvailable broadcast and		
Parameter	Туре	Description
getManeuversList_numberOfN	lahmet/1v6ers	numberOfManeuvers = the number of retrieved maneuvers
getManeuversList_maneuvers	LTstBVector_Maneuver_	

5.3.5 getVoiceGuidanceSettings

requestGetVoiceGuidanceSettings		
getVoiceGuidanceSettings = This method returns the used voice guidance settings		
Parameter Type Description		

responseGetVoiceGuidance	Settings		
getVoiceGuidanceSettings = This method returns the used voice guidance settings			
Parameter Type Description			
getVoiceGuidanceSettings_pr	o Proprincial de la companya de la c	mode = enum(INVALID,DISABLED_PROMPT,AU)	JTOMATIC_P!

5.3.6 getWaypointInformation

requestGetWaypointInformation		
getWaypointInformation = This method retrieves the information on the remaining way points of the route. A point can be the final destination as well as a stage defined by the user. The returned waypoints are ordered by their 'number'. @deprecated Please use waypoints attribute		
Parameter	Туре	Description
getWaypointInformation_R_red	ุปโรมีโดี NumberOfWaypoints	requestedNumberOfWaypoints = the number of requested waypoints. If 0, all waypoints will be returned.

response Get Way point Information

getWaypointInformation = This method retrieves the information on the remaining way points of the route. A point can be the final destination as well as a stage defined by the user. The returned waypoints are ordered by their 'number'. @deprecated Please use waypoints attribute



responseGetWaypointInformation		
Parameter	Туре	Description
getWaypointInformation_numb	e.HΩfW6 aypoints	numberOfWaypoints = the number of retrieved waypoints(NOTE: the number corresponds to the number of elements in the array)
getWaypointInformation_wayp	oTiht&Listctor_tWaypointStruct_	

5.3.7 pauseGuidance

requestPauseGuidance

pauseGuidance = This method diables display guidance on the map, voice guidance prompts and boradcast events of an active guidance. While paused, the guidance remains active in the background, and will recalculate the route if the user diverts from the initial route.

This method should be called when guidance is in active status.

responsePauseGuidance

pauseGuidance = This method diables display guidance on the map, voice guidance prompts and boradcast events of an active guidance. While paused, the guidance remains active in the background, and will recalculate the route if the user diverts from the initial route.

This method should be called when guidance is in active status.

- 1			
	Parameter	Туре	Description

5.3.8 playVoiceManeuver

requestPlayVoiceManeuver		
playVoiceManeuver = This method plays or repeats the last voice guidance		
Parameter Type Description		

responsePlayVoiceManeuver		
playVoiceManeuver = This method plays or repeats the last voice guidance		
Parameter Type Description		



5.3.9 resumeGuidance

requestResumeGuidance

pauseGuidance = This method resumes guidance from pasued state to normal state. When resumed, display guidance on the map and broadcasts events are enabled, and voice guidance prompts are resumed to the original state.

This method should be called when guidance is in active status.

F	Parameter	Type	Description
1 -		- 7	

responseResumeGuidance

pauseGuidance = This method resumes guidance from pasued state to normal state. When resumed, display guidance on the map and broadcasts events are enabled, and voice guidance prompts are resumed to the original state.

This method should be called when guidance is in active status.

Parameter	Туре	Description
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5.3.10 selectAlternativeTIRoute

requestSelectAlternativeTIRoute

selectAlternativeTIRoute = This method selects the given route for semi dynamic rerouting. The routeHandle can be the original guided route or the alternative route.

If the user selects the alternative route successfully, Guidance will broadcast the route handle via guidanceStatusChanged.

Parameter	Туре	Description
selectAlternativeTIRoute_R_rd		routeHandle = Route handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value

responseSelectAlternativeTIRoute

selectAlternativeTIRoute = This method selects the given route for semi dynamic rerouting. The routeHandle can be the original guided route or the alternative route.

If the user selects the alternative route successfully, Guidance will broadcast the route handle via guidanceStatusChanged.

9	0		
Parameter		Туре	Description



5.3.11 setRouteCalculationMode

requestSetRouteCalculation	Mode	
setRouteCalculationMode = T navigation core to behave of re	•	way the navigation application wants the
Parameter	Туре	Description
setRouteCalculationMode_R_	OuteOutolationNode	routeCalculationMode = enum(INVALID,ALL_MANUAL,ALL_AUT

responseSetRouteCalculationMode		
setRouteCalculationMode = This method configures the way the navigation application wants the navigation core to behave of reroute trigger		
Parameter Type Description		

5.3.12 setVoiceGuidance

requestSetVoiceGuidance			
setVoiceGuidance = This method switch on/off the voice guidance			
Parameter	Туре	Description	
setVoiceGuidance_R_activate	boolean	activation of the voice guidance	
setVoiceGuidance_R_voice	String	kind of voice (to be defined)	

responseSetVoiceGuidance		
setVoiceGuidance = This method switch on/off the voice guidance		
Parameter Type Description		

5.3.13 setVoiceGuidanceSettings

requestSetVoiceGuidanceSe	ettings		
setVoiceGuidanceSettings = T	his method sets the voice	e guidance settings	
Parameter	Туре	Description	
setVoiceGuidanceSettings_R_	promptWoole	mode = enum(INVALID,DISABLED_PROMPT,AL)	JTOMATIC_



responseSetVoiceGuidanceSettings		
setVoiceGuidanceSettings = This method sets the voice guidance settings		
Parameter Type Description		

5.3.14 skipNextManeuver

requestSkipNextManeuver			
skipNextManeuver = This method allows to jump behind the current maneuver			
Parameter Type Description			

responseSkipNextManeuver		
skipNextManeuver = This method allows to jump behind the current maneuver		
Parameter Type Description		

5.3.15 startGuidance

requestStartGuidance			
startGuidance = This method starts the guidance for a given route			
Parameter	Туре	Description	
startGuidance_R_routeHandle	Handle	routeHandle = Route handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value	

responseStartGuidance		
startGuidance = This method starts the guidance for a given route		
Parameter Type Description		

5.3.16 stopGuidance

requestStopGuidance	
stopGuidance = This method stops the guidance	



requestStopGuidance		
Parameter	Туре	Description

responseStopGuidance			
stopGuidance = This method s	stops the guidance		
Parameter	Туре	Description	

5.3.17 activeRouteChanged

informationActiveRouteChang	ged		
activeRouteChanged = This sign	nal is emitted when the ac	tive route changes	
Parameter 1	Гуре	Description	
activeRouteChanged_changeO	auste Changed Cause	changeCause = enum(INVALID,TRAFFIC,OFF_ROUTE,M)	ΛΑN

5.3.18 alternativeTIRouteAvailable

informationAlternativeTIRou	teAvailable		
alternativeTIRouteAvailable = This signal is emitted when a better TI route is available			
Parameter Type Description			
alternativeTIRouteAvailable_co	ostobiffeiferrence	costDifference = time and distance differences	
alternativeTIRouteAvailable_idsTMessageIds ids = ids of traffic messages causing delay			

5.3.19 alternativeTIRouteInvalidated

informationAlternativeTIRou	telnvalidated			
alternativeTIRouteInvalidated = this signal is emitted when the alternative route is invalidated, ex. when the car passes the exit to the alternative route or a new alternative route is calculated.				
Parameter Type Description				
alternativeTIRouteInvalidated_rdateHandle		routeHandle = invalidated alternative route handle. Range(0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value.		



5.3.20 guidancePaused

informationGuidancePaused		
guidancePaused = This signal is emitted when guidance is paused		
Parameter	Туре	Description

5.3.21 guidanceResumed

informationGuidanceResumed		
guidancePaused = This signal is emitted when guidance is resumed		
Parameter	Туре	Description

5.3.22 guidanceStatusChanged

informationGuidanceStatusChanged			
guidanceStatusChanged = This signal is emitted when the guidance status changes			
Parameter Type Description			
guidanceStatusChanged_guid	a GoeStabeS tatus	guidanceStatus = enum(INVALID,ACTIVE,INACTIVE)	
guidanceStatusChanged_route	Handle	routeHandle = Active route handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value. Should be ignored when guidanceStatus=INACTIVE.	

5.3.23 laneGuidanceChanged

informationLaneGuidanceChanged			
The lane guiding of the maneuver has changed			
Parameter Type Description			
laneGuidanceChanged_mane	euWent64	The unique id of the maneuver that has been passed	
laneGuidanceChanged_lane0	Guitta@ceIndex	The index of the laneGuidingInfo in ManeuverInfo.laneGuidings	



5.3.24 maneuverAvailable

informationManeuverAvaila	able			
This broadcast is fired whenever a new maneuver group is a available				
Parameter	Parameter Type Description			
maneuverAvailable_group	ManeuverGroup	A maneuver group usually consists of one maneuver. It conatins more than one maneuver just in case of combined/joined maneuvers.		

5.3.25 maneuverChanged

informationManeuverChang	ed		
maneuverChanged = This sign	nal is emitted each time a mane	euver event is going	
Parameter	Туре	Description	
maneuverChanged_maneuver		maneuver = enum(INVALID,CRUISE,MANEUVER_A)	PPEARED,PR

5.3.26 maneuverPhaseChanged

informationManeuverPhase0	Changed		
The maneuver phase has char	nged		
Parameter	Туре	Description	
maneuverPhaseChanged_man	nelmead	The unique id of the maneuver that has changed	
maneuverPhaseChanged_pha	sé anueverPhase	phase = enum(INVALID,CRUISE,MANEUVER_A)	PPEARED,PR

5.3.27 maneuverTravelCostsChanged

informationManeuverTravelCostsChanged		
The travel costs to the maneuver have changed		
Parameter	Туре	Description
maneuverTravelCostsChange	d ∐int 6AeuverID	The unique id of the maneuver that has changed



informationManeuverTravelCostsChanged	
maneuverTravelCostsChanged <u>T</u> travedCosts	travel costs to the maneuver

5.3.28 positionOnRouteChanged

informationPositionOnRouteChanged		
positionOnRouteChanged = This signal is emitted when the position on the route changes		
Parameter	Туре	Description
positionOnRouteChanged_offs	etlOt32 oute	offsetOnRoute = the current offset on the route in meters from the beginning of the route

5.3.29 positionToRouteChanged

informationPositionToRouteChanged		
positionToRouteChanged = This signal is emitted when the vehicle is off-the-road network and either the heading or the distance (or both) to the closest point on the active route changes		
Parameter	Туре	Description
positionToRouteChanged_dist	auhtrei32	distance = distance in meters to the closest point on the active route
positionToRouteChanged_dire	drit32	direction = direction in degrees relatively to the closest point on the active route. Range [0:360]

5.3.30 vehicleLeftTheRoadNetwork

informationVehicleLeftTheRoadNetwork		
vehicleLeftTheRoadNetwork = This signal is emitted when the vehicle exits from the road network		
Parameter	Туре	Description

5.3.31 vehicleLeftTheRoute

informationVehicleLeftTheRoute		
vehicleLeftTheRoute = This signal is emitted when the vehicle has left the route		
Parameter	Туре	Description



5.3.32 waypointReached

informationWaypointReached			
waypointReached = This signal is emitted when the destination is reached			
Parameter Type Description			
waypointReached_isDestination		isDestination = flag. TRUE means that the way point is the destination	

5.3.33 waypointTravelCostsChanged

informationWaypointTravelCostsChanged		
The travel costs to the waypoints have changed		
Parameter Type Description		Description
waypointTravelCostsChanged	WaypointCostsList	travel costs to the waypoints

5.3.34 awaypoints

Attribute awaypoints		
Information about the waypoints (destinations) along the route.		
Type Notification Type		
WaypointInfoList	ON_CHANGE	

5.3.35 THBVector_Maneuver_

Vector of element type Maneuver

Referenced by : org_harman_nav_ctrl_Guidance::getManeuversList

5.3.36 THBVector_tWaypointStruct_

Vector of element type tWaypointStruct

 $Referenced\ by: org_harman_nav_ctrl_Guidance::getWaypointInformation$

5.4 org_harman_nav_ctrl_GuidanceTypes

Interface Version: 1.2



5.4.1 CalculationMode

CalculationMode		
Literal	Description	
CalculationMode_BasicEnum_INVALID		
CalculationMode_ALL_MANUAL		
CalculationMode_ALL_AUTOMATIC		
CalculationMode_TRAFFIC_MANUAL		
CalculationMode_OFF_ROUTE_MANUAL		

 $Referenced\ by: org_harman_nav_ctrl_Guidance::setRouteCalculationMode$

5.4.2 CompassDirection

CompassDirection		
Literal	Description	
CompassDirection_UNDEFINED	Undefined.	
CompassDirection_NORTH	North.	
CompassDirection_EAST	East.	
CompassDirection_WEST	West.	
CompassDirection_SOUTH	South.	

Referenced by: org_harman_nav_ctrl_GuidanceTypes::RoadNumber

5.4.3 CostDifference

CostDifference			
struct for CostDifference Costs of the original route and the alternative route			
Structure Element Type Description			
originalRoute	RouteCostData		
alternativeRoute	RouteCostData		

 $Referenced\ by: org_harman_nav_ctrl_Guidance:: alternative TIR oute Available$



5.4.4 GuidanceStatus

GuidanceStatus		
Literal	Description	
GuidanceStatus_BasicEnum_INVALID		
GuidanceStatus_ACTIVE		
GuidanceStatus_INACTIVE		

Referenced by : org_harman_nav_ctrl_Guidance::getGuidanceStatus, org_harman_nav_ctrl_Guidance::guidanceStatusChanged

5.4.5 LaneDirection

LaneDirection	
Literal	Description
LaneDirection_LANE_INFO_BITMASK_NONE	
LaneDirection_LANE_INFO_BITMASK_STRAIGHT	
LaneDirection_LANE_INFO_BITMASK_SLIGHTRIGHTRIGHTRIGHTRIGHTRIGHTRIGHTRIGHTR	ЭНТ
LaneDirection_LANE_INFO_BITMASK_RIGHT	
LaneDirection_LANE_INFO_BITMASK_SHARPRIC	НТ
LaneDirection_LANE_INFO_BITMASK_RIGHTUTU	JRN
LaneDirection_LANE_INFO_BITMASK_SLIGHTLE	FT
LaneDirection_LANE_INFO_BITMASK_LEFT	
LaneDirection_LANE_INFO_BITMASK_SHARPLEI	Т
LaneDirection_LANE_INFO_BITMASK_LEFTUTUF	RN

Referenced by : org_harman_nav_ctrl_GuidanceTypes::LaneInfo, org_harman_nav_ctrl_GuidanceTypes::LaneInfo

5.4.6 LaneDivider

LaneDivider	
Literal	Description
LaneDivider_BasicEnum_INVALID	
LaneDivider_DIVIDER_UNDEFINED	



LaneDivider	
LaneDivider_DIVIDER_INTERRUPTEDLONG	
LaneDivider_DIVIDER_INTERRUPTEDSHORT	
LaneDivider_DIVIDER_SOLIDSINGLE	
LaneDivider_DIVIDER_SOLIDDOUBLE	
LaneDivider_DIVIDER_SOLIDINTERRUPTED	
LaneDivider_DIVIDER_INTERRUPTEDSOLID	

Referenced by : org_harman_nav_ctrl_GuidanceTypes::LaneInfo

5.4.7 LaneGuidanceInfo

LaneGuidanceInfo Information related to lane guidance		
lanes	LaneInfoList	A list of LaneInfo-structs. The first entry is only used to store the lane-divider left of the first lane (i.e. the first actual lane is at index 1). The order of the lanes should be left-to-right (as shown to the driver).
distance	Distance	The distance (to destination) at which the lane-change should be completed.
geoCoordinate	Coordinate2D	

 $Referenced\ by: org_harman_nav_ctrl_GuidanceTypes::LaneGuidanceInfoList$

5.4.8 LaneGuidanceInfoList

Vector of element type LaneGuidanceInfo

Referenced by : org_harman_nav_ctrl_GuidanceTypes::ManeuverInfo

5.4.9 LaneInfo

LaneInfo		
Information describing a single lane-guiding lane		
Structure Element Type Description		



LaneInfo		
laneDirections	LaneDirection	A bitmask of LaneDirection values, that specifies which directions can be taken from this lane in the upcoming intersection.
directionToFollow	LaneDirection	A single LaneDirection value that specifies which of the possible directions the driver should follow. Should be LANE_INFO_BITMASK_NONE, in case this is not a possible or recommended lane.
divider	LaneDivider	Specifies the lane divider type to the right of this lane.
type	LaneTypeCategory	Specifies the lane type (RECOMMENDED, POSSIBLE, OTHER,).

Referenced by : org_harman_nav_ctrl_GuidanceTypes::LaneInfoList

5.4.10 LaneInfoList

Vector of element type LaneInfo

Referenced by : org_harman_nav_ctrl_GuidanceTypes::LaneGuidanceInfo

5.4.11 LaneType

LaneType	
Literal	Description
LaneType_BasicEnum_INVALID	
LaneType_LANE_INFO_BITMASK_STRAIGHT	
LaneType_LANE_INFO_BITMASK_SLIGHTRIGHT	
LaneType_LANE_INFO_BITMASK_RIGHT	
LaneType_LANE_INFO_BITMASK_SHARPRIGHT	
LaneType_LANE_INFO_BITMASK_RIGHTUTURN	
LaneType_LANE_INFO_BITMASK_SLIGHTLEFT	
LaneType_LANE_INFO_BITMASK_LEFT	
LaneType_LANE_INFO_BITMASK_SHARPLEFT	
LaneType_LANE_INFO_BITMASK_LEFTUTURN	



5.4.12 LaneTypeCategory

LaneTypeCategory		
Literal	Description	
LaneTypeCategory_POSSIBLE_LANE	It is possible to reach the maneuver using this lane.	
LaneTypeCategory_RECOMMENDED_LANE	Using this lane is recommended.	
LaneTypeCategory_BUS_LANE	This lane is reserved for busses.	
LaneTypeCategory_HOV_LANE	This lane is reserved for high occupancy vehicles (relevant e.g. in the US).	
LaneTypeCategory_OTHER_LANE	Some other lane, which will not lead to the maneuver.	

Referenced by: org_harman_nav_ctrl_GuidanceTypes::LaneInfo

5.4.13 Maneuver

Maneuver Maneuver		
roadNumberAfterManeuver	String	
roadNameAfterManeuver	String	
roadPropertyAfterManeuver	UInt16	
drivingSide	Side	
offsetOfNextManeuver	UInt32	
items	THBVector_tManeuverItem_	

Referenced by: org_harman_nav_ctrl_Guidance::THBVector_Maneuver_

5.4.14 ManeuverDetails

ManeuverDetails		
Extended maneuver information		
Structure Element Type		Description



ManeuverDetails		
entryRoadClass	ERoadClass	Road class of the road that leads to the maneuver point.
wayPointStopoverNumber	UInt16	The stopover-number (starting from 0), if this maneuver represents reaching a waypoint/destination.

 $Referenced\ by: org_harman_nav_ctrl_GuidanceTypes::ManeuverInfo$

5.4.15 ManeuverDirection

ManeuverDirection		
Literal	Description	
ManeuverDirection_BasicEnum_INVALID		
ManeuverDirection_STRAIGHT_ON		
ManeuverDirection_LEFT		
ManeuverDirection_SLIGHT_LEFT		
ManeuverDirection_HARD_LEFT		
ManeuverDirection_RIGHT		
ManeuverDirection_SLIGHT_RIGHT		
ManeuverDirection_HARD_RIGHT		
ManeuverDirection_UTURN_RIGHT		
ManeuverDirection_UTURN_LEFT		

Referenced by : org_harman_nav_ctrl_GuidanceTypes::ManeuverTurn, org_harman_nav_ctrl_GuidanceTypes::ManeuverInfo

5.4.16 ManeuverDirectionType

ManeuverDirectionType	
Literal	Description
ManeuverDirectionType_BasicEnum_INVALID	
ManeuverDirectionType_LENGTH	
ManeuverDirectionType_DIRECTION	
ManeuverDirectionType_EXIT_NUMBER	



ManeuverDirectionType	
ManeuverDirectionType_ROAD_FORM	
ManeuverDirectionType_LANE_INFO	

5.4.17 ManeuverGroup

ManeuverGroup		
A set of maneuvers that a	are close to each other	
Structure Element	Туре	Description
maneuvers	ManeuverInfoList	The list of maneuvers that are part of the group (sorted by their distance to destination).

 $Referenced\ by: org_harman_nav_ctrl_Guidance::maneuver Available$

5.4.18 ManeuverInfo

ManeuverInfo		
Information that describes a maneuver		
Structure Element	Туре	Description
uniqueID	UInt64	An Id that can be used to uniquely identify this maneuver.
distance	Distance	The distance from the start of the maneuver to the destination.
geoCoordinate	Coordinate2D	
maneuverLength	Distance	The length of the maneuver in meters.
comingRoadInfo	RoadInfo	Information about the road coming after the maneuver.
signPostInfo	SignPostInfo	Signpost related information.
turnDirection	ManeuverDirection	The direction that the driver should turn to during the maneuver (STRAIGHT_ON, LEFT, SLIGHT_LEFT,).
maneuverType	ManeuverType	The type of maneuver (STRAIGHT_ON, TURN, CROSSROAD, ROUNDABOUT,).
maneuverDetails	ManeuverDetails	More detailed maneuver information.



ManeuverInfo		
laneGuidanceList	LaneGuidanceInfoList	Lane guiding information associated with the maneuver.

 $Referenced\ by: org_harman_nav_ctrl_GuidanceTypes::ManeuverInfoList$

5.4.19 ManeuverInfoList

Vector of element type ManeuverInfo

Referenced by: org_harman_nav_ctrl_GuidanceTypes::ManeuverGroup

5.4.20 ManeuverSegment

ManeuverSegment			
Maneuver segment			
Structure Element	Туре	Description	
maneuver	ManeuverType		
maneuverLength	UInt16		

Referenced by : org_harman_nav_ctrl_GuidanceTypes::tManeuverItem

5.4.21 ManeuverTurn

ManeuverTurn			
Maneuver turn			
Structure Element	Туре	Description	
maneuverDirection	ManeuverDirection		
exitNumber	String		

Referenced by : org_harman_nav_ctrl_GuidanceTypes::tManeuverItem

5.4.22 ManeuverType

ManeuverType	



ManeuverType	
Literal	Description
ManeuverType_BasicEnum_INVALID	
ManeuverType_STRAIGHT_ON	
ManeuverType_TURN	
ManeuverType_CROSSROAD	
ManeuverType_ROUNDABOUT	
ManeuverType_HIGHWAY_ENTER	
ManeuverType_HIGHWAY_EXIT	
ManeuverType_BIFURCATION	
ManeuverType_HIGHWAY_CHANGE_LANE	
ManeuverType_DESTINATION	
ManeuverType_WAYPOINT	

Referenced by : org_harman_nav_ctrl_GuidanceTypes::ManeuverInfo, org_harman_nav_ctrl_GuidanceTypes::ManeuverSegment

5.4.23 ManueverPhase

ManueverPhase	
Literal	Description
ManueverPhase_BasicEnum_INVALID	
ManueverPhase_CRUISE	
ManueverPhase_MANEUVER_APPEARED	
ManueverPhase_PRE_ADVICE	
ManueverPhase_ADVICE	
ManueverPhase_PASSED	

Referenced by : org_harman_nav_ctrl_Guidance::getGuidanceDetails, org_harman_nav_ctrl_Guidance::maneuverChanged, org_harman_nav_ctrl_Guidance::maneuverPhaseChanged

5.4.24 PromptMode

PromptMode	



PromptMode		
Literal	Description	
PromptMode_BasicEnum_INVALID		
PromptMode_DISABLED_PROMPT		
PromptMode_AUTOMATIC_PROMPT		
PromptMode_MANUAL_PROMPT		

Referenced by : org_harman_nav_ctrl_Guidance::setVoiceGuidanceSettings, org_harman_nav_ctrl_Guidance::getVoiceGuidanceSettings

5.4.25 RoadInfo

RoadInfo Information about a Road		
roadNumbers	RoadNumberList	A list of RoadNumber structs. The list should be ordered by relevance, so that in case not all items fit in the HMI, the most relevant are shown. E.g. in Germany A9 should be placed before E45.
roadNames	RoadNameList	A list of road names. The list should be ordered by relevance, so that at least the most relevant ones are shown, if not all names fit in the HMI.
roadClass	ERoadClass	The road class.

Referenced by : org_harman_nav_ctrl_GuidanceTypes::ManeuverInfo

5.4.26 RoadName

Alias of actual type: String

 $Referenced\ by: org_harman_nav_ctrl_GuidanceTypes::RoadNameList$

5.4.27 RoadNameList

Vector of element type RoadName

Referenced by : org_harman_nav_ctrl_GuidanceTypes::RoadInfo



5.4.28 RoadNumber

RoadNumber Information about a Road Number		
text	String	A string representation of the road- number (e.g. "A8" for German Autobahn 8.)
compassDirection	CompassDirection	The compass direction of a road- number (mostly relevent for US).

Referenced by : org_harman_nav_ctrl_GuidanceTypes::RoadNumberList

5.4.29 RoadNumberList

Vector of element type RoadNumber

Referenced by : org_harman_nav_ctrl_GuidanceTypes::RoadInfo, org_harman_nav_ctrl_GuidanceTypes::Towards

5.4.30 RoadProperty

RoadProperty	
Literal	Description
RoadProperty_BasicEnum_INVALID	

5.4.31 RouteChangedCause

RouteChangedCause		
Literal	Description	
RouteChangedCause_BasicEnum_INVALID		
RouteChangedCause_TRAFFIC		
RouteChangedCause_OFF_ROUTE		
RouteChangedCause_MANUAL		

Referenced by: org_harman_nav_ctrl_Guidance::activeRouteChanged



5.4.32 RouteCostData

RouteCostData		
Structure Element	Туре	Description
routeHandle	Handle	routeHandle = Route handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
freeFlowTravelTime	UInt32	remaining travel time in seconds. This is the travel time from the decision point to the end of the route. This duration does not include the extra time caused by traffic information. If no decision point exists, then the value is 0.
additionalTravelTime	UInt32	additional travel time in seconds. This is the travel time from the decision point to the end of the route. This duration only contains the extra time caused by traffic information. If no decision point exists, then the value is 0.
distance	UInt32	remaining distance in meters. This is the distance from the decision point to the end of the route. If no decision point exists, then the value is 0.

 $\label{lem:costDifference} Referenced \ by: org_harman_nav_ctrl_GuidanceTypes::CostDifference, org_harman_nav_ctrl_GuidanceTypes::CostDifference$

5.4.33 Side

Side		
Literal	Description	
Side_BasicEnum_INVALID		
Side_LEFT		
Side_RIGHT		
Side_NOT_AVAILABLE		

Referenced by : org_harman_nav_ctrl_GuidanceTypes::WaypointInfo, org_harman_nav_ctrl_GuidanceTypes::Maneuver, org_harman_nav_ctrl_GuidanceTypes::tWaypointStruct



5.4.34 SignPostInfo

SignPostInfo		
Defines sign-post information.		
Structure Element	Туре	Description
exitNumber	String	Exit number of a road-exit.
towardsList	TowardsList	Contains the towards-entries of a sign- post at the maneuver

Referenced by : org_harman_nav_ctrl_GuidanceTypes::ManeuverInfo

5.4.35 THBVector_tManeuverItem_

Vector of element type tManeuverItem

Referenced by : org_harman_nav_ctrl_GuidanceTypes::Maneuver

5.4.36 Towards

Towards		
Defines on "towards"-entry on the sign-post; e.g. "[A9] Nrnberg/Berlin/Leipzig" or "[490] [East] Rochester		
Structure Element	Туре	Description
viaRoad	RoadNumberList	The road(s) which leads up to the city/poi/etc. mentioned on the sign-post

Referenced by : org_harman_nav_ctrl_GuidanceTypes::TowardsList

5.4.37 TowardsList

Vector of element type Towards

Referenced by : org_harman_nav_ctrl_GuidanceTypes::SignPostInfo

5.4.38 TravelCosts

TravelCosts	



TravelCosts		
Structure Element	Туре	Description
distance	Distance	Remaining distance to the waypoint.
travelTime	UInt32	Remaining time to the waypoint in seconds.
direction	Int32	Direction to the waypoint in degrees relative to North.

Referenced by : org_harman_nav_ctrl_Guidance::maneuverTravelCostsChanged, org_harman_nav_ctrl_GuidanceTypes::WaypointCosts

5.4.39 WaypointCosts

WaypointCosts		
Structure Element	Туре	Description
number	UInt16	Waypoint number
travelCosts	TravelCosts	Remaining distance to the waypoint.

 $Referenced\ by: org_harman_nav_ctrl_GuidanceTypes::WaypointCostsList$

5.4.40 WaypointCostsList

Vector of element type WaypointCosts

 $Referenced\ by: org_harman_nav_ctrl_Guidance::waypointTravelCostsChanged$

5.4.41 WaypointInfo

WaypointInfo WaypointInfo = Information about a Waypoint		
waypointld	UniqueItemId	Unique location id for the waypoint. To be used with LocationMemory to retrieve details about the destination.
side	Side	Roadside (left, right) of the waypoint.
hasBeenReached	boolean	True, if this destination has already been reached in the current guidance session.



WaypointInfo		
number	UInt16	The stop-over number of this waypoint (starting at 0).
position	Coordinate3D	The position of this waypoint in GPS coordinates.
timeZone	Int16	timeZone = time zone of the destination. It is expressed as the time difference from the UTC in minutes
daylightSavingTime	Int16	daylightSavingTime = daylight saving time of the destination. It is expressed as the time difference from the UTC in minutes

 $Referenced\ by: org_harman_nav_ctrl_GuidanceTypes::WaypointInfoList$

5.4.42 WaypointInfoList

Vector of element type WaypointInfo

Referenced by : org_harman_nav_ctrl_Guidance::awaypoints

5.4.43 tManeuverItem

tManeuverItem			
Maneuver Item			
Structure Element	Туре	Description	
offsetOfManeuver	UInt32		
travelTime	UInt32		
direction	Int32		
segment	ManeuverSegment		
turnTo	ManeuverTurn		

Referenced by: org_harman_nav_ctrl_GuidanceTypes::THBVector_tManeuverItem_

5.4.44 tWaypointStruct

tWaypointStruct	



tWaypointStruct			
Structure Element	Туре	Description	
waypointOffset	UInt32		
travelTime	UInt32		
direction	Int32		
side	Side		
timeZone	Int16		
daylightSavingTime	Int16		
isDestination	boolean		
number	UInt16		

Referenced by : org_harman_nav_ctrl_Guidance::THBVector_tWaypointStruct_

5.5 org_harman_nav_ctrl_Routing

Interface Version: 1.3

5.5.1 calculateAlternateRoute

requestCalculateAlternateRoute		
calculateAlternateRoute = This method calculates an alternate route based on an existing handle. Optionally a different CostModel and RoutePreferences can be used.		
Parameter Type Description		
calculateAlternateRoute_R_calculatedRoute		

responseCalculateAlternateRoute		
calculateAlternateRoute = This method calculates an alternate route based on an existing handle. Optionally a different CostModel and RoutePreferences can be used.		
Parameter Type Description		
calculateAlternateRoute_alternatelenaterdativeRectteListandle_		

5.5.2 calculateRoute

requestCalculateRoute
calculateRoute = This method starts a route calculation



requestCalculateRoute		
Parameter Type Description		
calculateRoute_R_routeHandle	Handle	routeHandle = Route handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value

responseCalculateRoute		
calculateRoute = This method starts a route calculation		
Parameter Type Description		Description

5.5.3 cancelRouteCalculation

requestCancelRouteCalculation		
cancelRouteCalculation = This method cancels a route calculation		
Parameter	Type Description	
cancelRouteCalculation_R_rou	utétratide	routeHandle = Route handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value

responseCancelRouteCalculation		
cancelRouteCalculation = This method cancels a route calculation		
Parameter Type Description		

5.5.4 createRoute

requestCreateRoute		
This method creates a route		
Parameter	Туре	Description

responseCreateRoute		
This method creates a route		
Parameter	Туре	Description



responseCreateRoute		
createRoute_routeHandle	Handle	Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value

5.5.5 deleteRoute

requestDeleteRoute		
This method deletes a route and its associated resources		
Parameter	Туре	Description
deleteRoute_R_routeHandle		Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value

responseDeleteRoute		
This method deletes a route and its associated resources		
Parameter Type Description		

5.5.6 getAllRoutes

requestGetAllRoutes		
getAllRoutes = This method retrieves the handles of all created routes		
Parameter Type Description		

responseGetAllRoutes		
getAllRoutes = This method retrieves the handles of all created routes		
Parameter Type Description		Description
getAllRoutes_routesList	THBVector_Handle_	

5.5.7 getCostModel

requestGetCostModel		
This method retrieves the selected cost model		
Parameter	Туре	Description
getCostModel_R_routeHandle	Handle	Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value



responseGetCostModel			
This method retrieves the se	lected cost model		
Parameter	Туре	Description	
getCostModel_costModel	CostModel	enum(INVALID,FASTEST,SHORTEST,EC	COLOGICAL

5.5.8 getRouteOverview

requestGetRouteOverview		
getRouteOverview = This method retrieves general information about a given route		
Parameter Type Description		
getRouteOverview_R_routeHandle routeHandle = Route handle. Range[0x0:0x7fffffff]. 0x0 is reserved an invalid handle value		Range[0x0:0x7fffffff]. 0x0 is reserved as
getRouteOverview_R_valuesT	₫₨₨₥ ector_RouteOverviewTy	pe_

responseGetRouteOverview		
getRouteOverview = This method retrieves general information about a given route		
Parameter Type Description		Description
getRouteOverview_routeOverv	Rew uteOverview	

5.5.9 getRoutePreferences

requestGetRoutePreferences		
This method retrieves a list of selected route preferences		
Parameter	Туре	Description
getRoutePreferences_R_route	Hlamdle	Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value

responseGetRoutePreferences		
This method retrieves a list of selected route preferences		
Parameter Type		Description
getRoutePreferences_roadPre	f ēren∕ecis tr_RoutePreference_	



response Get Route Preferences

getRoutePreferences_conditionPreference_L0stniditionPreference_

5.5.10 getRouteSchedule

requestGetRouteSchedule			
This method gets the time schedule for the route to be calculated			
Parameter	Type Description		
getRouteSchedule_R_routeHa	htile dle	Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value	
getRouteSchedule_R_valuesT	dRt⊞v/mector_Schedule_		

responseGetRouteSchedule			
This method gets the time schedule for the route to be calculated			
Parameter Type Description			
getRouteSchedule_routeSchedule	Me uteSchedule		

5.5.11 getRouteSettings

requestGetRouteSettings		
setRouteSetting = This method	d gets the global route preferen	ce settings
Parameter Type Description		

responseGetRouteSettings			
setRouteSetting = This method gets the global route preference settings			
Parameter Type Description			
getRouteSettings_settings	RouteSettings		

5.5.12 getSupportedCostModels

requestGetSupportedCostModels
This method retrieves a list of supported cost models



requestGetSupportedCostModels		
Parameter	Туре	Description

responseGetSupportedCostModels			
This method retrieves a list of supported cost models			
Parameter	Туре	Description	
getSupportedCostModels_cos	t Md&e/scist r_CostModel_		

5.5.13 getSupportedRoutePreferences

requestGetSupportedRoutePreferences		
This method retrieves a list of supported route preferences		
Parameter Type Description		

responseGetSupportedRoutePreferences			
This method retrieves a list of supported route preferences			
Parameter Type Description			
getSupportedRoutePreferenceSI_http://dePreferenceStrissterence_			
getSupportedRoutePreference	s <u>T⊦dBN/dititomP@ferieiticelPse</u> ferer	ice_	

5.5.14 getWaypoints

requestGetWaypoints		
getWaypoints = This method retrieves a list of waypoints		
Parameter	Туре	Description
getWaypoints_R_routeHandle	Handle	routeHandle = Route handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value

responseGetWaypoints		
getWaypoints = This method retrieves a list of waypoints		
Parameter Type Description		Description



responseGetWaypoints		
getWaypoints_startFromCurre tbPolsition	startFromCurrentPosition = flag indicating if the current position is used as starting point	
getWaypoints_waypointsList		

5.5.15 setBlockedRouteStretch

requestSetBlockedRouteStretch		
setBlockedRouteStretches = This method sets blocked streches on a given route		
Parameter Type Description		
setBlockedRouteStretch_R_ro	utterhaltedle	routeHandle = Route handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
setBlockedRouteStretch_R_le	nlgtht32	Length in meters, from the current car position, to be blocked.

responseSetBlockedRouteStretch		
setBlockedRouteStretches = This method sets blocked streches on a given route		
Parameter Type Description		

5.5.16 setCostModel

requestSetCostModel		!	
This method sets the cost mod	lel		
Parameter	Туре	Description	
setCostModel_R_routeHandle	Handle	Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value	
setCostModel_R_costModel	CostModel	enum(INVALID,FASTEST,SHORTEST,E)	COLOGICAL,

responseSetCostModel		
This method sets the cost mod		
Parameter Type Description		



5.5.17 setRoutePreferences

requestSetRoutePreferences		
This method sets a list of route preferences		
Parameter Type Description		
setRoutePreferences_R_route	HH-bearrod lee	Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
setRoutePreferences_R_roadl	Teferénciel : is Route Preference	
setRoutePreferences_R_cond	tTothPvefetren_CoolristitionPreferer	rce_

responseSetRoutePreferences		
This method sets a list of route	preferences	
Parameter Type Description		

5.5.18 setRouteSchedule

requestSetRouteSchedule		
This method sets the time schedule for the route to be calculated		
Parameter Type Description		Description
setRouteSchedule_R_routeHa	rh dlie dle	Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
setRouteSchedule_R_routeSc	redule Schedule	

responseSetRouteSchedule		
This method sets the time schedule for the route to be calculated		
Parameter Type Description		

5.5.19 setRouteSettings

requestSetRouteSettings		
setRouteSetting = This method sets global route preference settings		
Parameter	Туре	Description
setRouteSettings_R_settings	RouteSettings	



responseSetRouteSettings		
setRouteSetting = This method sets global route preference settings		
Parameter Type Description		

5.5.20 setWaypoints

requestSetWaypoints setWaypoints = This method sets a list of waypoints		
setWaypoints_R_routeHandle	Handle	routeHandle = Route handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
setWaypoints_R_startFromCu	rbeotleasition	startFromCurrentPosition = flag indicating if the current position is used as starting point
setWaypoints_R_waypointsLis	tTHBVector_WayPoint_	

responseSetWaypoints		
setWaypoints = This method sets a list of waypoints		
Parameter Type Description		

5.5.21 alternativeRoutesAvailable

informationAlternativeRoutesAvailable		
alternativeRoutesAvailable = This signal is emitted when alternative routes have been computed in the background and are available for guidance.		
Parameter Type Description		
alternativeRoutesAvailable_rou	u TellBandtest_ist andle_	

5.5.22 routeCalculationCancelled

informationRouteCalculationCancelled		
routeCalculationCancelled = This signal informs a client that a route calculation was cancelled		
Parameter Type Description		



informationRouteCalculationCancelled		
routeCalculationCancelled_routehaladle	routeHandle = Route handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value	

5.5.23 routeCalculationFailed

informationRouteCalculation	nFailed		
routeCalculationFailed = This	signal informs a client th	at a route calculation failed	
Parameter	Туре	Description	
routeCalculationFailed_Handle	aHandle	routeHandle = Route handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value	
routeCalculationFailed_errorC	odelculationError	errorCode = enum(INVALID,UNMATCHED_POSITIO))	N,UNREACHA
routeCalculationFailed_unfullfi	illedPreferencesce		

5.5.24 routeCalculationProgressUpdate

informationRouteCalculationProgressUpdate		
routeCalculationProgressUpdate = This signal informs a client about a route calculation progress		
Parameter Type Description		
routeCalculationProgressUpda	t <mark>elaroukt</mark> eHandle	routeHandle = Route handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
routeCalculationProgressUpda	tle <u>t</u> βpercentage	percentage = progress status. Range [0:100]

5.5.25 routeCalculationSuccessful

informationRouteCalculationSuccessful		
routeCalculationSuccessful = This signal informs a client that a route calculation was successful		
Parameter Type Description		Description
routeCalculationSuccessful_ro	u tleiridis dle	routeHandle = Route handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
routeCalculationSuccessful_ui	Rudtilled Perferences	



5.5.26 routeDeleted

informationRouteDeleted		
routeDeleted = This signal is emitted to inform clients that the current route has been deleted		
Parameter Type Description		Description
routeDeleted_routeHandle	Handle	routeHandle = Route handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value

5.5.27 routeSettingsChanged

informationRouteSettingsChanged		
routeSettingsChanged = This signal is emitted to inform clients that the global route settings has been changed.		
Parameter Type Description		
routeSettingsChanged_setting	sTHBVector_RouteSettingType	

5.5.28 THBVector_ConiditionPreference_

Vector of element type ConiditionPreference

Referenced by : org_harman_nav_ctrl_Routing::setRoutePreferences, org_harman_nav_ctrl_Routing::getRoutePreferences, org_harman_nav_ctrl_Routing::getSupportedRoutePreferences

5.5.29 THBVector CostModel

Vector of element type CostModel

Referenced by: org_harman_nav_ctrl_Routing::getSupportedCostModels

5.5.30 THBVector_Handle_

Vector of element type Handle

Referenced by: org_harman_nav_ctrl_Routing::calculateAlternateRoute, org_harman_nav_ctrl_Routing::getAllRoutes, org_harman_nav_ctrl_Routing::alternativeRoutesAvailable



5.5.31 THBVector_RouteOverviewType_

Vector of element type RouteOverviewType

Referenced by : org_harman_nav_ctrl_Routing::getRouteOverview

5.5.32 THBVector_RoutePreference_

Vector of element type RoutePreference

Referenced by: org_harman_nav_ctrl_Routing::setRoutePreferences, org_harman_nav_ctrl_Routing::getRoutePreferences, org_harman_nav_ctrl_Routing::getSupportedRoutePreferences

5.5.33 THBVector_RouteSettingType_

Vector of element type RouteSettingType

Referenced by: org_harman_nav_ctrl_Routing::routeSettingsChanged

5.5.34 THBVector_Schedule_

Vector of element type **Schedule**

Referenced by : org_harman_nav_ctrl_Routing::getRouteSchedule

5.5.35 THBVector_WayPoint_

Vector of element type WayPoint

Referenced by : org_harman_nav_ctrl_Routing::setWaypoints, org_harman_nav_ctrl_Routing::getWaypoints

5.6 org_harman_nav_ctrl_RoutingTypes

Interface Version: 1.2

5.6.1 CalculationError

CalculationError	
Literal	Description



CalculationError	
CalculationError_BasicEnum_INVALID	
CalculationError_UNREACHABLE_DESTINATION	
CalculationError_UNFULFILLED_PREFERENCE_I	MODE

 $Referenced\ by: org_harman_nav_ctrl_Routing::routeCalculationFailed$

5.6.2 ConditionPreferenceSource

ConditionPreferenceSource	
Literal	Description
ConditionPreferenceSource_BasicEnum_INVALID	
ConditionPreferenceSource_TRAFFIC_REALTIME	

 $Referenced\ by: org_harman_nav_ctrl_RoutingTypes::ConiditionPreference$

5.6.3 ConiditionPreference

ConiditionPreference		
struct generated for DBus argument SetRoutePreferences_conditionPreferenceList		
Structure Element	Туре	Description
mode PreferenceMode		
source	ConditionPreferenceSource	

Referenced by: org_harman_nav_ctrl_Routing::THBVector_ConiditionPreference_

5.6.4 CostModel

CostModel		
Literal	Description	
CostModel_BasicEnum_INVALID		
CostModel_FASTEST		
CostModel_SHORTEST		



CostModel	
CostModel_ECOLOGICAL	
CostModel_SCENIC	
CostModel_EASY	
CostModel_OFF_ROAD	
CostModel_BALANCED	
CostModel_CHEAPEST	

Referenced by: org_harman_nav_ctrl_Routing::setCostModel, org_harman_nav_ctrl_Routing::getCostModel, org_harman_nav_ctrl_Routing::THBVector_CostModel_, org_harman_nav_ctrl_RoutingTypes::RouteSettingItem

5.6.5 IntermediatePoint

IntermediatePoint			
Structure Element	Туре	Description	
_base	Coordinate2D		
type	IntermediatePointType		

5.6.6 IntermediatePointType

IntermediatePointType		
Literal	Description	
IntermediatePointType_HARD_POINT		
IntermediatePointType_SOFT_POINT		

Referenced by : org_harman_nav_ctrl_RoutingTypes::WayPointItem, org_harman_nav_ctrl_RoutingTypes::IntermediatePoint

5.6.7 PreferenceMode

PreferenceMode	
Literal	Description



PreferenceMode	
PreferenceMode_BasicEnum_INVALID	
PreferenceMode_PROHIBIT	
PreferenceMode_AVOID	
PreferenceMode_USE	
PreferenceMode_PREFER	
PreferenceMode_IGNORE	

Referenced by : org_harman_nav_ctrl_RoutingTypes::ConiditionPreference, org_harman_nav_ctrl_RoutingTypes::RoutePreference

5.6.8 RouteOverview

RouteOverview			
Map Element	Туре	Description	
keyType	RouteOverviewType		
valueType	RouteOverviewItem		

Referenced by : org_harman_nav_ctrl_Routing::getRouteOverview

5.6.9 RouteOverviewItem

RouteOverviewItem		
Variant Element	Туре	Description
uValue	UInt32	

5.6.10 RouteOverviewType

RouteOverviewType	
Literal	Description
RouteOverviewType_Schedule_ARRIVAL_TIME	
RouteOverviewType_Schedule_ARRIVAL_DATE	
RouteOverviewType_Schedule_DEPARTURE_TIME	IE .



RouteOverviewType	
RouteOverviewType_Schedule_DEPARTURE_DA	ГЕ
RouteOverviewType_TOTAL_DISTANCE	
RouteOverviewType_TOTAL_TIME	
RouteOverviewType_FUEL_CONSUMPTION	

Referenced by: org_harman_nav_ctrl_Routing::THBVector_RouteOverviewType_

5.6.11 RoutePreference

RoutePreference		
struct generated for DBus	argument SetRoutePreferences_	roadPreferenceList
Structure Element	Туре	Description
mode	PreferenceMode	
source	RoutePreferenceSource	

Referenced by: org_harman_nav_ctrl_Routing::routeCalculationSuccessful, org_harman_nav_ctrl_Routing::routeCalculationFailed, org_harman_nav_ctrl_Routing::THBVector_RoutePreference_, org_harman_nav_ctrl_RoutingTypes::RoutePreferences

5.6.12 RoutePreferenceSource

RoutePreferenceSource		
Literal	Description	
RoutePreferenceSource_BasicEnum_INVALID		
RoutePreferenceSource_FERRY		
RoutePreferenceSource_TOLL_ROADS		
RoutePreferenceSource_TUNNELS		
RoutePreferenceSource_HIGHWAYS_MOTORWA	YS	
RoutePreferenceSource_VEHICLE_SIZE_LIMIT		
RoutePreferenceSource_CRIME_AREAS		
RoutePreferenceSource_U_TURNS		
RoutePreferenceSource_UNPAVED		
RoutePreferenceSource_HOV		



Referenced by : org_harman_nav_ctrl_RoutingTypes::RoutePreference

5.6.13 RoutePreferences

Vector of element type RoutePreference

Referenced by : org_harman_nav_ctrl_RoutingTypes::RouteSettingItem

5.6.14 RouteSchedule

RouteSchedule			
Map Element	Туре	Description	
keyType	Schedule		
valueType	UInt32		

Referenced by : org_harman_nav_ctrl_Routing::setRouteSchedule, org_harman_nav_ctrl_Routing::getRouteSchedule

5.6.15 RouteSettingItem

RouteSettingItem			
Variant Element	Туре	Description	
costModelValue	CostModel		
boolValue	boolean		
routePreferencesValue	RoutePreferences		

5.6.16 RouteSettingType

RouteSettingType		
Literal	Description	
RouteSettingType_BasicEnum_INVALID		
RouteSettingType_COST_MODEL		
RouteSettingType_USE_TRAFFIC_PATTERNS		
RouteSettingType_SHOW_ALTERNATIVES		



RouteSettingType	
RouteSettingType_ROUTE_PREFERENCES	

Referenced by : org_harman_nav_ctrl_Routing::THBVector_RouteSettingType_

5.6.17 RouteSettings

RouteSettings			
Map Element	Туре	Description	
keyType	RouteSettingType		
valueType	RouteSettingItem		

Referenced by : org_harman_nav_ctrl_Routing::setRouteSettings, org_harman_nav_ctrl_Routing::getRouteSettings

5.6.18 Schedule

Schedule		
Literal	Description	
Schedule_BasicEnum_INVALID		
Schedule_ARRIVAL_TIME		
Schedule_ARRIVAL_DATE		
Schedule_DEPARTURE_TIME		
Schedule_DEPARTURE_DATE		

Referenced by: org_harman_nav_ctrl_Routing::THBVector_Schedule_

5.6.19 WapointElementType

WapointElementType	
Literal	Description
WapointElementType_BasicEnum_INVALID	
WapointElementType_WAYPOINT_TYPE	



WapointElementType	
WapointElementType_LOCATION_INPUT	
WapointElementType_LATITUDE	
WapointElementType_LONGITUDE	
WapointElementType_ALTITUDE	

5.6.20 WayPoint

WayPoint			
Map Element	Туре	Description	
keyType	WapointElementType		
valueType	WayPointItem		

Referenced by: org_harman_nav_ctrl_Routing::THBVector_WayPoint_

5.6.21 WayPointItem

WayPointItem			
Variant Element	Туре	Description	
coordinateValue	double		
altitudeValue	Int32		
wayPointValue	IntermediatePointType		
metaData	Buffer		

5.7 org_harman_nav_ctrl_highwaymode_HighwayMo

Interface Version: 2.2

5.7.1 createView

requestCreateView

create a new view to the mother array. This view will be maintained until the client uses destroyView, unsubscribes or service/proxy exit. After creating a view the client must receive an update. Only one



requestCreateView			
created view is allowed to modify the list entries. Please note: a valid usecase is to specify a viewSize which is bigger than the inital list size			
Parameter	Туре	Description	
createView_R_list	ListId	list to create the view upon.	
createView_R_viewsize	ViewSize	individual size of the requested view.	

responseCreateView

create a new view to the mother array. This view will be maintained until the client uses destroyView, unsubscribes or service/proxy exit. After creating a view the client must receive an update. Only one created view is allowed to modify the list entries. Please note: a valid usecase is to specify a viewSize which is bigger than the inital list size

Parameter	Туре	Description
createView_view	ViewId	view identification used to distinguish several instances of a view for one client. It is never changed by the service nor the client. This id is unique!

5.7.2 deleteView

requestDeleteView		
delete the given view instance		
Parameter	Туре	Description
deleteView_R_view	ViewId	identifies the view to apply this operation upon.

responseDeleteView		
delete the given view instance		
Parameter Type Description		

5.7.3 getListSize

requestGetListSize		
get the current number of contained elements in the given list.		
Parameter Type Descri		Description
getListSize_R_list	ListId	



responseGetListSize				
get the current number of contained elements in the given list.				
Parameter Type Description				
getListSize_size	ListSize			

5.7.4 getMessageDetails

requestGetMessageDetails			
get the details of a road junction	get the details of a road junction, interchange, POI or traffic incident		
Parameter Type Description			
getMessageDetails_R_view	ViewId	Identifies the view this result list is applied for.	
getMessageDetails_R_itemId	HighwayItemId		

responseGetMessageDetails		
get the details of a road junction, interchange, POI or traffic incident		
Parameter Type Description		Description
getMessageDetails_messageDetails		

5.7.5 getResultList

requestGetResultList		
getResultList		
Parameter	Туре	Description
getResultList_R_view	ViewId	Identifies the view this result list is applied for.

responseGetResultList getResultList		
getResultList_resultPosition	ListKey	list key of the first entry into the received result list.
getResultList_items	HighwayItemArray	result items based on the requested position and key what is related to the given view id.



5.7.6 setEnable

requestSetEnable			
turn on/off highway mode			
Parameter	Туре	Description	
setEnable_R_enabled	boolean		

responseSetEnable		
turn on/off highway mode		
Parameter Type Description		Description

5.7.7 setViewAnchor

requestSetViewAnchor

set a stable element inside the current view snapshot. The client should use an available snapshot of a view to maintain focused elements within the view if possible, and change the view position only if an element to be focused is outside of the given view. A snapshot is generated whenever querying the data contained in a view. Together with that data, the ViewSnapshotPosition is provided. The initial snapshot of the view is always [0, min(viewSize-1, listSize-1)] with anchor offset 0. When creating a new view snapshot, the last call of setViewPosition or setViewAnchor (whichever was the last one) will be the relevant information to reposition the new view snapshot. If setViewAnchor was the last call, the anchor element of the old view snapshot is used for repositioning. (This method only needs to be used if the current view snapshot is outdated because the list has been updated.)

The following rules are applied to set the position of the new view snapshot [newFrom, newTo], given a snapshot [from, to] and anchor offset aOff: Let elem(k) denote the element at key k in the old snapshot and new(e) denote the key the element e will have (would have if deleted) in the new snapshot (see also examples below). newFrom is set to new(elem(from+aOff)) - aOff. If any of these calculated values are out of the range of the list [0, listSize-1], they will be truncated to fit into the list. As a consequence, whenever possible, the anchor element of the old snapshot will be at the same offset within the new snapshot.

As an example for the case in which the data was updated: old list {"a", "b", "c", "d", "e", "f"} with view snapshot ["c", "d"] with viewSize 2 and viewKey 2 new list {"b", "d", "f", "h", "j", "l"} setViewAnchor(0) => elem(from+aOff) is "c", new(elem(from+aOff)) is 1 ("c" would be inserted at index 1) => ["d", "f"] with ViewSnapshotPosition 6, listKey=1, anchorOffset=0. setViewAnchor(1) => elem(from+aOff) is "d", new(elem(from+aOff)) is 1 => ["b", "d"] with ViewSnapshotPosition 6, listKey=0, anchorOffset=1.

Parameter	Туре	Description
setViewAnchor_R_view	ViewId	identifies the view to apply this operation upon.
setViewAnchor_R_anchor	AnchorOffset	relative anchor position in the view, referenced from ListKey Please note: only positive values and 0 are allowed



5.7.8 setViewPosition

requestSetViewPosition

set the absolute view position to element key. The client should use an available snapshot of a view to maintain focused elements within the view if possible, and change the view position only if an element to be focused is outside of the given view. A snapshot is generated whenever querying the data contained in a view. Together with that data, the ViewSnapshotPosition is provided. The initial snapshot of the view is always [0, min(viewSize-1, listSize-1)]. When creating a new view snapshot, the last call of setViewPosition or setViewAnchor (whichever was the last one) will be the relevant information to reposition the new view snapshot. If setViewPosition was the last call, the view is moved such that the provided key refers to the absolute position on the current snapshot of the view. (This becomes important if the current view snapshot is outdated because the list has been updated.)

The following rules are applied to set the position of the new view snapshot [newFrom, newTo], given a snapshot [from, to]: Let elem(k) denote the element at key k in the old snapshot and new(e) denote the key the element e will have (would have if deleted) in the new snapshot (see also examples (1)-(3) below). (1) If key is less than from, then newFrom will be set to new(elem(from)) - (from-key). (2) If key is contained in [from, to], then newKey will be set to new(elem(key)). (3) If key is greater than to, then newFrom will be set to new(elem(to)) + (key-to). If any of these calculated values are out of the range of the list [0, listSize-1], they will be truncated to fit into the list. (Note that the resulting newFrom is always equal to key if the data wasn't updated, but it doesn't have to be equal to key if the data was updated.) After setting the view position the anchor offset will automatically be set to 0. There are two special key values to allow scrolling to the top/bottom of the list, independently from the above rules: The key value 0xFFFE always positions the view to the bottom of the list.

As an example for the case in which the data was updated: old list {"a", "b", "c", "d", "e", "f"} with view snapshot ["c", "d"] with viewSize 2 and viewKey 2 new list {"b", "d", "f", "h", "j", "l"} (1) setViewPosition(0) => [from, to] is [2, 3], elem(from) is "c", new(elem(from)) is 1 => ["b", "d"] with ViewSnapshotPosition 6, listKey=0, anchorOffset=0. (2) setViewPosition(3) => [from, to] is [2, 3], elem(key) is "d", new(elem(key)) is 1 => ["d", "f"] with ViewSnapshotPosition 6, listKey=1, anchorOffset=0. (3) setViewPosition(4) => [from, to] is [2, 3], elem(to) is "d", new(elem(d)) is 1 => ["f", "h"] with ViewSnapshotPosition 6, listKey=2, anchorOffset=0.

Parameter	Туре	Description
setViewPosition_R_view	ViewId	identifies the view to apply this operation upon.
setViewPosition_R_key	ListKey	element to position the view upon, according to view policy.

5.7.9 setViewSize

requestSetViewSize

adjust the view size. It is allowed to set view size to a larger value than the actual size of the list, but less or equal than the maximum size of the list. The implementation may limit the maximum view size for resource reasons. After adjusting the window size the client must receive an update.



requestSetViewSize		
Parameter Type Description		
setViewSize_R_view	ViewId	identifies the view to apply this operation upon.
setViewSize_R_new_size	ViewSize	new view size

responseSetViewSize

adjust the view size. It is allowed to set view size to a larger value than the actual size of the list, but less or equal than the maximum size of the list. The implementation may limit the maximum view size for resource reasons. After adjusting the window size the client must receive an update.

Parameter	Туре	Description

5.7.10 listSize

informationListSize			
informs the client about changes of the list size.			
Parameter Type Description			
listSize_id	ListId	list id related to the list size update	
listSize_size	ListSize	changed list size information	

5.7.11 viewUpdate

informationViewUpdate

indicate to the client that the underlying list of a certain view has changed Whenever elements get inserted/removed or the content of element gets changed, the size or the sorting order of a list might change. This might influence the current view and especially the position of the anchor element in the list. To allow a client to react on such changes in an approapriate manner, the viewUpdate broadcast will provide all necessary information to its client. It is up to the client to reposition the view to its needs based on the provided information, using the methods setViewPosition or setViewAnchor.

Parameter	Туре	Description
viewUpdate_view	ViewId	unique identifier of a view
viewUpdate_size	ListSize	current size of the underlying list
viewUpdate_viewChanged	boolean	at least one element of the currently active view snapshot has changed
viewUpdate_listChanged	boolean	at least one element of the list has changed (this might lead to a different new view snapshot)



5.7.12 astatus

Attribute astatus	
indicate the statuses of Highway Mode	
Туре	Notification Type
HighWayStatus	ON_CHANGE

5.7.13 Error

Error	
This is the type for error responses.	
Literal	Description
ERROR_ListError_INVALID	
ERROR_ListError_INVALID_LIST_ID	
ERROR_ListError_INVALID_VIEW	
ERROR_ListError_INVALID_PARAMETER	
ERROR_ListError_SIZE_LIMIT_EXCEEDED	
ERROR_ListError_OUT_OF_RESSOURCES	
ERROR_ListError_OUT_OF_RANGE_POSITION	
ERROR_ListError_POLICY_DENIED	

5.8 org_harman_nav_ctrl_highwaymode_HighwayMo

Interface Version: 2.2

5.8.1 Addresses

Vector of element type Address

Referenced by : org_harman_nav_ctrl_highwaymode_HighwayModeTypes::InterchangeDetails, org_harman_nav_ctrl_highwaymode_HighwayModeTypes::JunctionDetails

5.8.2 Distance_m

Alias of actual type: UInt32



5.8.3 HighWayStatus

HighWayStatus		
Literal	Description	
HighWayStatus_BasicEnum_INVALID		
HighWayStatus_DISABLED		
HighWayStatus_ACTIVE		
HighWayStatus_INACTIVE		

Referenced by: org_harman_nav_ctrl_highwaymode_HighwayMode::astatus

5.8.4 Highwayltem

Highwayltem			
generalized representation of a junction, interchange, POI, and traffic incident			
Structure Element Type Description			
id	HighwayltemId		
messageType	ItemType		
icondId	SIcon		
descriptions	String		
distance	Distance_m		

Referenced by: org_harman_nav_ctrl_highwaymode_HighwayModeTypes::HighwayItemArray

5.8.5 HighwayltemArray

a list of highway items Vector of element type Highwayltem

 $Referenced\ by: org_harman_nav_ctrl_highwaymode_HighwayMode::getResultList$

5.8.6 HighwayltemDetails

HighwayltemDetails
union of highway features and event



HighwayltemDetails			
Variant Element	Туре	Description	
poiDetails	SearchResultDetails		
serviceAreaDetailes	POIDetailsArray		
trafficIncidentDetails	SMessage		
junctionDetails	JunctionDetails		
interchangeDetails	InterchangeDetails		

Referenced by: org_harman_nav_ctrl_highwaymode_HighwayModeTypes::MessageDetails

5.8.7 HighwayltemId

Alias of actual type: UInt32

Referenced by: org_harman_nav_ctrl_highwaymode_HighwayMode::getMessageDetails, org_harman_nav_ctrl_highwaymode_HighwayModeTypes::HighwayItem, org_harman_nav_ctrl_highwaymode_HighwayModeTypes::POIInformation

5.8.8 InterchangeDetails

InterchangeDetails		
Structure Element	Туре	Description
address	Addresses	

Referenced by: org_harman_nav_ctrl_highwaymode_HighwayModeTypes::HighwayItemDetails

5.8.9 ItemDetailsType

ItemDetailsType		
Literal	Description	
ItemDetailsType_BasicEnum_INVALID		
ItemDetailsType_DTYPE_Poi		
ItemDetailsType_DTYPE_TrafficIncident		
ItemDetailsType_DTYPE_Junction		
ItemDetailsType_DTYPE_Interchange		



Referenced by: org_harman_nav_ctrl_highwaymode_HighwayModeTypes::MessageDetails

5.8.10 ItemType

ItemType		
Literal	Description	
ItemType_BasicEnum_INVALID		
ItemType_TYPE_ServiceArea		
ItemType_TYPE_Fuel		
ItemType_TYPE_Parking		
ItemType_TYPE_Junction		
ItemType_TYPE_Interchange		
ItemType_TYPE_POI		
ItemType_TYPE_TrafficIncident		

Referenced by: org_harman_nav_ctrl_highwaymode_HighwayModeTypes::HighwayItem

5.8.11 JunctionDetails

JunctionDetails			
Structure Element	Туре	Description	
address	Addresses		

 $Referenced\ by: org_harman_nav_ctrl_highwaymode_HighwayModeTypes:: HighwayItemDetails$

5.8.12 MessageDetails

MessageDetails		
highway feature or event details and its type.		
type DTYPE_Poi is paired with POIDetails type DTYPE_TrafficIncident is paired with TrafficIncidentDetails		
TBD: How to represent junctionDetails and InterchangeDetails		
Structure Element	Туре	Description



MessageDetails		
type	ItemDetailsType	
details	HighwayItemDetails	
distance	Distance_m	

Referenced by: org_harman_nav_ctrl_highwaymode_HighwayMode::getMessageDetails

5.8.13 POIDetailsArray

Vector of element type SearchResultDetails

Referenced by: org_harman_nav_ctrl_highwaymode_HighwayModeTypes::HighwayItemDetails

5.8.14 POlInformation

POlInformation			
representation of a POI in the service area			
Structure Element	Туре	Description	
description	String		
poild	POI_ID		
icondId	ResourceID		
parent	HighwayltemId		

5.8.15 Resourceld

Alias of actual type: UInt64

5.8.16 Time_ms

Alias of actual type: UInt32

5.8.17 UpdateReason

UpdateReason	
Literal	Description



UpdateReason	
UpdateReason_BasicEnum_INVALID	
UpdateReason_REASON_TimerTimedout	
UpdateReason_REASON_DistanceChanged	
UpdateReason_REASON_ElementAdded	
UpdateReason_REASON_ElementRemoved	



6 MapControl Service

6.1 org_harman_nav_ctrl_mapv_MapViewControl

Interface Version: 1.2

6.1.1 addKml

requestAddKml			
addKml = add Kml Content to MapViewer			
Parameter	Туре	Description	
addKml_R_sessionHandle	Handle	sessionHandle = Session handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value	
addKml_R_mapViewInstance	eH landid e	mapViewInstanceHandle = Map instance handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value	
addKml_R_kmlType	KmlType	defines if kml is of KmlType:(KML_URL/KML_CONTENT)	
addKml_R_kml	String	is either the kml-url or a kml-content	
addKml_R_show	boolean	show if TRUE then kmlContent is shown on MapViewer	

responseAddKml		
addKml = add Kml Content to MapViewer		
Parameter	Туре	Description
addKml_kmlHandle	Handle	kmlHandle = NAV2010-kmlHandle

6.1.2 addMapViewScaleChangedListener

requestAddMapViewScaleChangedListener		
addMapViewScaleChangedListener = This method adds a listener which is notified when map view scale changes.		
Parameter Type Description		Description



responseAddMapViewScaleChangedListener		
addMapViewScaleChangedListener = This method adds a listener which is notified when map view scale changes.		
Parameter	Туре	Description

6.1.3 centerOnObjectListItems

requestCenterOnObjectListItems			
centerOnObjectListItems = This method shows an overview map with the current route in the center			
Parameter Type Description			
centerOnObjectListItems	s_R_s <mark>elssiodilel</mark> andle	sessionHandle = Session handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value	
centerOnObjectListItems	s_R_m ap√idw InstanceHandle	mapViewInstanceHandle = Map instance handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value	
centerOnObjectListItems	s_R_objed#ListItem_DbjectListItem_	objectListItems = list of ObjectListItmes to center on (if 1 element is in list, don't change scale)	

responseCenterOnObjectListItems		
centerOnObjectListItems = This method shows an overview map with the current route in the center		
Parameter Type Description		

6.1.4 convertGeoCoordsToPixelCoords

requestConvertGeoCoordsToPixelCoords		
convertGeoCoordsToPixelCoords = This method converts geographical coordinates into pixel coordinates		
Parameter Type Description		
convertGeoCoordsToPixelCoo	r <mark>ids<u>n</u>Rl<u>e</u>sessionHandle</mark>	sessionHandle = Session handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
convertGeoCoordsToPixelCoordsnapViewInstanceHand		enapViewInstanceHandle = Map instance handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
convertGeoCoordsToPixelCoordsPegeoCoordidatese2D_		



responseConvertGeoCoordsToPixelCoords		
convertGeoCoordsToPixelCoords = This method converts geographical coordinates into pixel coordinates		
Parameter Type Description		Description
convertGeoCoordsToPixelCoo	rds Bàinel Codroin ates	

6.1.5 convertPixelCoordsToGeoCoords

requestConvertPixelCoordsToGeoCoords		
convertPixelCoordsToGeoCoords = This method converts pixel coordinates to geographical coordinates		
Parameter	Туре	Description
convertPixelCoordsToGeoCoo	<mark>rlda<u>n</u>Rl<u>e</u>sessionHandle</mark>	sessionHandle = Session handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
convertPixelCoordsToGeoCoo <mark>rdsnRle</mark> mapViewInstanceHand		enapViewInstanceHandle = Map instance handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
convertPixelCoordsToGeoCoo	rds <u>ER/e</u> pixe <u>rCoinedi</u> nates	

responseConvertPixelCoordsToGeoCoords		
convertPixelCoordsToGeoCoords = This method converts pixel coordinates to geographical coordinates		
Parameter Type Description		
convertPixelCoordsToGeoCoordsleadentoordinatesate2D_		

6.1.6 createMapViewInstance

requestCreateMapViewInsta	nce	
createMapViewInstance = This method creates a new map instance		
Parameter Type Description		Description
createMapViewInstance_R_se	ssionHandle	sessionHandle = Session handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
createMapViewInstance_R_m	ap Wiiew Size	
createMapViewInstance_R_m	ар⁄мі<u>е</u>м⁄∓ууГе уре	mapViewType = enum(INVALID,MAIN_MAP,SPLIT_SCREE)



responseCreateMapViewInstance		
createMapViewInstance = This method creates a new map instance		
Parameter Type Description		Description
createMapViewInstance_map\	/iewldstanceHandle	mapViewInstanceHandle = Map instance handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value

6.1.7 deleteKml

requestDeleteKml deleteKml = deletes (and hides) Kml Content to MapViewer		
deleteKml_R_sessionHandle	Handle	sessionHandle = Session handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
deleteKml_R_mapViewInstand	c é l d iandid l e	mapViewInstanceHandle = Map instance handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
deleteKml_R_kmlHandle	Handle	kmlHandle = NAV2010-kmlHandle

responseDeleteKml		
deleteKml = deletes (and hides) Kml Content to MapViewer		
Parameter Type		Description

6.1.8 displayCustomElements

requestDisplayCustomElements		
displayCustomElements = This method visualizes a set of custom elements on the map		
Parameter	Туре	Description
displayCustomElements_R_se	ssiont tandle	sessionHandle = Session handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
displayCustomElements_R_m	a <mark>p∖viielwi</mark> nstanceHandle	mapViewInstanceHandle = Map instance handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value



requestDisplayCustomElements	
displayCustomElements_R_customElement_	

responseDisplayCustomElements		
displayCustomElements = This method visualizes a set of custom elements on the map		
Parameter	Туре	Description
displayCustomElements_customElevisenthiahdlesle_		

6.1.9 displayObjectList

requestDisplayObjectList		
displayObjectList = This method visualizes a list of objects, created in another domain		
Parameter Type Description		Description
displayObjectList_R_session	nHainhadhadle	sessionHandle = Session handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
displayObjectList_R_mapVie	wI hstadic eHandle	mapViewInstanceHandle = Map instance handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
displayObjectList_R_objectL	ist ObjectList	contains enum to other domain + session-id of other domain

responseDisplayObjectList		
displayObjectList = This method visualizes a list of objects, created in another domain		
Parameter Type Description		

6.1.10 displayRoute

requestDisplayRoute		
displayRoute = This method visualizes one of the calculated routes		
Parameter Type Description		
displayRoute_R_sessionHand	e landle	sessionHandle = Session handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
displayRoute_R_mapViewInst	a <mark>rleebla</mark> ndle	mapViewInstanceHandle = Map instance handle. Range[0x0:0x7fffffff].



requestDisplayRoute		
		0x0 is reserved as an invalid handle value
displayRoute_R_routeHandle	Handle	routeHandle = Route handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
displayRoute_R_highlighted	boolean	highlighted = flag. TRUE means highlighted, FALSE means not highlighted

responseDisplayRoute		
displayRoute = This method visualizes one of the calculated routes		
Parameter Type Description		Description

6.1.11 getAutozoomEnabled

requestGetAutozoomEnabled			
Parameter	Туре	Description	
getAutozoomEnabled_R_sess	i bhthain dle	sessionHandle = Session handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value	
getAutozoomEnabled_R_map	V ilewblist anceHandle	mapViewInstanceHandle = Map instance handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value	

responseGetAutozoomEnabled			
Parameter Type Description			
getAutozoomEnabled_enabled	boolean	enabled	

6.1.12 getAutozoomSetting

requestGetAutozoomSetting			
Parameter Type Description			
getAutozoomSetting_R_session	o hlda nlüle	sessionHandle = Session handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value	



requestGetAutozoomSetting		
getAutozoomSetting_R_mapV	elulnsta nceHandle	mapViewInstanceHandle = Map instance handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value

responseGetAutozoomSetting			
Parameter Type Description			
getAutozoomSetting_autozoon	n Settiing omSetting	autozoomSetting (NEAR / NORMAL / FAR)	

6.1.13 getCameraDistanceFromTargetPoint

requestGetCameraDistanceFromTargetPoint				
getCameraDistanceFromTargetPoint = This method gets the mode and the camera distance from the target point				
Parameter	Type Description			
getCameraDistanceFromTarge	t Roidt eR_mapViewInstanceHa	indto ViewInstanceHandle = Map instance handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value		

responseGetCameraDistanceFromTargetPoint			
getCameraDistanceFromTargetPoint = This method gets the mode and the camera distance from the target point			
Parameter Type Description			
getCameraDistanceFromTarge	ቲ ቡot β2_distance	distance = distance from the view point in meters	

6.1.14 getCameraHeading

requestGetCameraHeading			
getCameraHeading = This method returns the current camera heading			
Parameter Type Description			
getCameraHeading_R_mapVio	e <mark>wansta</mark> nceHandle	mapViewInstanceHandle = Map instance handle. Range[0x0:0x7fffffff].	



requestGetCameraHeading			
	0x0	0 is reserved as an invalid handle	
	val	alue	

responseGetCameraHeading	g		
getCameraHeading = This me	thod returns the curren	nt camera heading	
Parameter	Туре	Description	
getCameraHeading_headingT	yplent16	headingType = enum(INVALID,CONSTANT_ANGLE,TR)	ACK_UP,TOW
getCameraHeading_headingA	ngt82	headingAngle = heading angle in degrees measured from the North axis clockwise. Range[0:360]	
getCameraHeading_target	Coordinate2D		

6.1.15 getCameraHeight

requestGetCameraHeight			
getCameraHeight = This meth	getCameraHeight = This method gets the camera height		
Parameter	Туре	Description	
getCameraHeight_R_mapViev	v I-hatathe eHandle	mapViewInstanceHandle = Map instance handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value	

responseGetCameraHeight		
getCameraHeight = This method gets the camera height		
Parameter	Туре	Description
getCameraHeight_height	UInt32	height = height from the ground in meters

6.1.16 getCameraPosition

requestGetCameraPosition		
getCameraPosition = This method returns the coordinates of the point at which the camera is positioned		
Parameter Type Description		



requestGetCameraPosition		
getCameraPosition_R_mapViewInstanceHandle	mapViewInstanceHandle = Map instance handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value	

responseGetCameraPosition		
getCameraPosition = This method returns the coordinates of the point at which the camera is positioned		
Parameter Type Description		
getCameraPosition_position	Coordinate3D	

6.1.17 getCameraRollAngle

requestGetCameraRollAngle		
getCameraRollAngle = This method returns the camera roll angle		
Parameter	Type Description	
getCameraRollAngle_R_map\	/i d whostanceHandle	mapViewInstanceHandle = Map instance handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value

responseGetCameraRollAngle		
getCameraRollAngle = This method returns the camera roll angle		
Parameter Type Description		
getCameraRollAngle_roll	Int32	roll = roll angle in degrees. Range [-180:180]

6.1.18 getCameraTiltAngle

requestGetCameraTiltAngle		
getCameraTiltAngle = This method returns the camera tilt angle		
Parameter Type Description		
getCameraTiltAngle_R_mapV	evandtanceHandle	mapViewInstanceHandle = Map instance handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value



responseGetCameraTiltAngle		
getCameraTiltAngle = This method returns the camera tilt angle		
Parameter	Type Description	
getCameraTiltAngle_tilt	Int32	tilt = tilt angle in degrees. Range [-180:180]

6.1.19 getDisplayedCustomElements

requestGetDisplayedCustomElements			
getDisplayedCustomElements = This method retrieves the visualized custom elements on the map			
Parameter	rameter Type Description		
getDisplayedCustomElements	<u>IRamdap</u> ViewInstanceHandle	mapViewInstanceHandle = Map instance handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value	

responseGetDisplayedCustomElements		
getDisplayedCustomElements = This method retrieves the visualized custom elements on the map		
Parameter Type Description		Description
getDisplayedCustomElements	<u>tCustom⊞terments</u> Dict	

6.1.20 getDisplayedRoutes

requestGetDisplayedRoutes		
getDisplayedRoutes = This method returns a list of displayed routes		
Parameter Type Description		Description
getDisplayedRoutes_R_mapV	evalmsta nceHandle	mapViewInstanceHandle = Map instance handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value

responseGetDisplayedRoutes		
getDisplayedRoutes = This method returns a list of displayed routes		
Parameter Type Description		



responseGetDisplayedRoutes	
getDisplayedRoutes_displayedRld@tesctor_DisplayedRoute_	

6.1.21 getFollowCarMode

requestGetFollowCarMode		
getFollowCarMode = This method returns the current FollowCar-mode		
Parameter Type Description		Description
getFollowCarMode_R_mapVie	wilanstäenceHandle	mapViewInstanceHandle = Map instance handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value

responseGetFollowCarMode		
getFollowCarMode = This met	getFollowCarMode = This method returns the current FollowCar-mode	
Parameter	Type Description	
getFollowCarMode_followCarM	/tootel ean	followCarMode = flag. If true, the current car position is interpreted as position of the point the camera must look at

6.1.22 getMapMode

requestGetMapMode		
Parameter	Туре	Description
getMapMode_R_sessionHand	l e landle	sessionHandle = Session handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
getMapMode_R_mapViewInst	a ricetia ndle	mapViewInstanceHandle = Map instance handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value

responseGetMapMode		
Parameter	Туре	Description
getMapMode_mapMode	String	mapMode



6.1.23 getMapModeList

requestGetMapModeList			
getMapModeList = This metho	getMapModeList = This method returns a list of supported map modes		
Parameter	Type Description		
getMapModeList_R_mapView	instanteHandle	mapViewInstanceHandle = Map instance handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value	

responseGetMapModeList		
getMapModeList = This method returns a list of supported map modes		
Parameter Type Description		Description
getMapModeList_mapModeListTHBVector_CHBString_		mapMode-List (string-based)

6.1.24 getMapViewBoundingBox

requestGetMapViewBoundingBox		
getMapViewBoundingBox = This method returns the bounding box of a given map instance		
Parameter	Туре	Description
getMapViewBoundingBox_R_i	nhap \dewlnstanceHandle	mapViewInstanceHandle = Map instance handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value

responseGetMapViewBoundingBox		
getMapViewBoundingBox = This method returns the bounding box of a given map instance		
Parameter Type Description		Description
getMapViewBoundingBox_bou	®diregB®e ctangle	

6.1.25 getMapViewObjectVisibility

requestGetMapViewObjectVisibility	
getMapViewObjectVisibility = This method gets the type of objects shown on the map.	



requestGetMapViewObjectVisibility		
Parameter	Туре	Description
getMapViewObjectVisibility_R	<u>rhæpd∕ie</u> wInstanceHandle	mapViewInstanceHandle = Map instance handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value

responseGetMapViewObjectVisibility		
getMapViewObjectVisibility = This method gets the type of objects shown on the map.		
Parameter	Туре	Description
getMapViewObjectVisibility_ob	je/ct/v@tibelitt/vLissi bility	

6.1.26 getMapViewPerformanceLevel

requestGetMapViewPerformanceLevel			
getMapViewPerformanceLevel = This method returns the perfomance level of a given map instance			
Parameter	Parameter Type Description		
getMapViewPerformanceLeve	<u>Handia</u> pViewInstanceHandle	mapViewInstanceHandle = Map instance handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value	

responseGetMapViewPerformanceLevel			
getMapViewPerformanceLeve	I = This method returns the per	fomance level of a given map instance	
Parameter	Type Description		
getMapViewPerformanceLeve	LperfbrmanceLevel	performanceLevel = enum(INVALID,LEVEL1,LEVEL2,LEVEL)	3,LEVEL4,LEV

6.1.27 getMapViewPerspective

requestGetMapViewPerspective		
getMapViewPerspective = This method returns the current map perspective		
Parameter Type Description		



requestGetMapViewPerspective		
getMapViewPerspective_R_mathMielManstanceHandle	mapViewInstanceHandle = Map instance handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value	

responseGetMapViewPerspective		
getMapViewPerspective = This method returns the current map perspective		
Parameter	Туре	Description
getMapViewPerspective_perspective_perspective	Matiweerspective	perspective = enum(INVALID,2D,3D,)

6.1.28 getMapViewRotation

requestGetMapViewRotation		
getMapViewRotation = This method is particularly interesting for debugging purposes		
Parameter	Type Description	
getMapViewRotation_R_map\	/idwholstanceHandle	mapViewInstanceHandle = Map instance handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value

responseGetMapViewRotation		
getMapViewRotation = This method is particularly interesting for debugging purposes		
Parameter	Туре	Description
getMapViewRotation_rotationA	AlmgB2	rotationAngle = rotation angle in degrees measured from the North axis clockwise. Range[0:360]
getMapViewRotation_rotationA	AngtaPerFrame	rotationAnglePerFrame = partial rotation for each map frame in degrees

6.1.29 getMapViewSaveArea

requestGetMapViewSaveArea

SetMapViewSaveArea = This methods defines the area that the HMI guarantees not to cover with other getMapViewSaveArea or user interface elements



requestGetMapViewSaveArea		
Parameter	Туре	Description
getMapViewSaveArea_R_map	ViæwIts tanceHandle	mapViewInstanceHandle = Map instance handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value

responseGetMapViewSaveArea		
SetMapViewSaveArea = This methods defines the area that the HMI guarantees not to cover with other getMapViewSaveArea or user interface elements		
Parameter	Туре	Description
getMapViewSaveArea_saveAr	e acreenRectangle	

6.1.30 getMapViewScale

requestGetMapViewScale			
getMapViewScale = This meth	getMapViewScale = This method returns the currently used map scale		
Parameter	Type Description		
getMapViewScale_R_mapVie	WHastahaceHandle	mapViewInstanceHandle = Map instance handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value	

responseGetMapViewScale		
getMapViewScale = This method returns the currently used map scale		
Parameter	Туре	Description
getMapViewScale_scaleID	Int8	scaleID = scale identifier. Range[0:256]
getMapViewScale_isMinMax	MapScaleType	isMinMax = enum(INVALID,MIN,MAX,MID,)

6.1.31 getMapViewScaleMode

requestGetMapViewScaleMode		
getMapViewScaleMode = This method gets the scaling mode.		
Parameter Type Description		



requestGetMapViewScaleMode		
getMapViewScaleMode_R_mapMiedWanstanceHandle	mapViewInstanceHandle = Map instance handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value	

responseGetMapViewScaleMode		
getMapViewScaleMode = This method gets the scaling mode.		
Parameter	Туре	Description
getMapViewScaleMode_scale		scaleMode = enum(AUTOMATIC,MANUAL,HYBRID)

6.1.32 getMapViewTheme

requestGetMapViewTheme		
getMapViewTheme = This method returns the current theme of a given map view instance		
Parameter Type Description		Description
getMapViewTheme_R_mapV	i eWamsta nceHandle	mapViewInstanceHandle = Map instance handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value

responseGetMapViewTheme)		
getMapViewTheme = This method returns the current theme of a given map view instance			
Parameter	Type Description		
getMapViewTheme_mapView	Tiklerpoēheme	mapViewTheme = enum(INVALID,THEME_1,THEME_2,TH)	EME_3

6.1.33 getMapViewType

requestGetMapViewType		
getMapViewType = This method returns the map type of a map instance as it was set using CreateMapViewInstance		
Parameter Type Description		



requestGetMapViewType	
getMapViewType_R_mapViewInataticeHandle	mapViewInstanceHandle = Map instance handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value

responseGetMapViewType		
getMapViewType = This method returns the map type of a map instance as it was set using CreateMapViewInstance		
Parameter Type Description		
getMapViewType_mapViewTy	pe apViewType	mapViewType = enum(INVALID,MAIN_MAP,SPLIT_SCREE)

6.1.34 getMapViewVisibilityMode

requestGetMapViewVisibilityMode		
getMapViewVisibilityMode = This method returns the current visibility mode		
Parameter Type Description		Description
getMapViewVisibilityMode_R_	rhlap\vlie wInstanceHandle	mapViewInstanceHandle = Map instance handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value

responseGetMapViewVisibilityMode		
getMapViewVisibilityMode = This method returns the current visibility mode		
Parameter	Type Description	
getMapViewVisibilityMode_vis	bilitjt M io _j de	visibilityMode = enum(INVALID,VISIBLE,INVISIBLE,FROZ

6.1.35 getPoiCategoriesVisible

requestGetPoiCategoriesVisible		
getPoiCategoriesVisible = Get the set of POI categories displayed on the map.		
Parameter Type Description		



requestGetPoiCategoriesVisible		
getPoiCategoriesVisible_R_map\viewnstanceHandle	mapViewInstanceHandle = Map instance handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value	

responseGetPoiCategoriesVisible		
getPoiCategoriesVisible = Get the set of POI categories displayed on the map.		
Parameter Type Description		Description
getPoiCategoriesVisible_poiCa	aTelgiBityelotsor_UInt32_	

6.1.36 getScaleList

requestGetScaleList			
getScaleList = This method returns a list of supported map scales			
Parameter	arameter Type Description		
getScaleList_R_mapViewInsta	a ntæhtäe dle	mapViewInstanceHandle = Map instance handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value	

responseGetScaleList			
getScaleList = This method returns a list of supported map scales			
Parameter Type Description			
getScaleList_scaleList	THBVector_MapScale_		

6.1.37 getSupportedMapViewObjectVisibilities

requestGetSupportedMapViewObjectVisibilities			
getSupportedMapViewObjectVisibilities = This method gets the supported object visibilities.			
Parameter	Type Description		
getSupportedMapViewObjectV	/isibilitle s_R_mapViewInstance	htaaplleewInstanceHandle = Map instance handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value	



responseGetSupportedMapViewObjectVisibilities		
getSupportedMapViewObjectVisibilities = This method gets the supported object visibilities.		
Parameter Type Description		Description
getSupportedMapViewObjectVislbbitiestoobjecttvislbbitiestoobjecttvislbbitiestoobjectvislb		

6.1.38 getSupportedMapViewPerformanceLevels

requestGetSupportedMapViewPerformanceLevels		
getSupportedMapViewPerformanceLevels = This method retrieves the supported performance levels		
Parameter Type Description		

responseGetSupportedMapViewPerformanceLevels		
getSupportedMapViewPerformanceLevels = This method retrieves the supported perfomance levels		
Parameter Type Description		
getSupportedMapViewPerformandelLevels_performanceLevelList		

6.1.39 getSupportedMapViewPerspectives

requestGetSupportedMapViewPerspectives		
getSupportedMapViewPerspectives = This method retrieves the supported mapview perspectives		
Parameter Type Description		

responseGetSupportedMapViewPerspectives		
getSupportedMapViewPerspectives = This method retrieves the supported mapview perspectives		
Parameter Type Description		Description
getSupportedMapViewPerspec	TīvesvpetspedtiveLesspective_	

6.1.40 getSupportedMapViewScaleModes

requestGetSupportedMapViewScaleModes
getSupportedMapViewScaleModes = This method gets the supported scaling modes.



requestGetSupportedMapViewScaleModes		
Parameter Type Description		
getSupportedMapViewScaleMddlasdR_mapViewInstanceHandle=Map instance handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value		

responseGetSupportedMapViewScaleModes		
getSupportedMapViewScaleModes = This method gets the supported scaling modes.		
Parameter Type Description		Description
getSupportedMapViewScaleM	odeB_\scateMode_StaleMode_	

6.1.41 getSupportedMapViewThemes

requestGetSupportedMapViewThemes		
getSupportedMapViewThemes = This method retrieves the supported mapview themes		
Parameter Type Description		

responseGetSupportedMapViewThemes		
getSupportedMapViewThemes = This method retrieves the supported mapview themes		
Parameter	Туре	Description
getSupportedMapViewThemes	<u>TIMBIDVéictourTINéappēllietme</u>	

6.1.42 getSupportedMapViewTypes

requestGetSupportedMapViewTypes		
getSupportedMapViewTypes = This method retrieves the supported map view types		
Parameter Type Description		

responseGetSupportedMapViewTypes		
getSupportedMapViewTypes = This method retrieves the supported map view types		
Parameter	Туре	Description
getSupportedMapViewTypes_mapBi/ewtbypeMastviewType_		



6.1.43 getSupportedMapViewVisibilityModes

requestGetSupportedMapViewVisibilityModes		
getSupportedMapViewVisibilityModes = This method retrieves the supported mapview visibility modes		
Parameter Type Description		

responseGetSupportedMapViewVisibilityModes		
getSupportedMapViewVisibilityModes = This method retrieves the supported mapview visibility modes		
Parameter	Туре	Description
getSupportedMapViewVisibility	/ <mark>MolBe∕se_ctricsi_b`l/lits</mark> /iMoltogle_List	

6.1.44 getTargetPoint

requestGetTargetPoint		
getTargetPoint = This method retrieves the target point position		
Parameter Type Description		Description
getTargetPoint_R_mapViewIn	sitamodelandle	mapViewInstanceHandle = Map instance handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value

responseGetTargetPoint			
getTargetPoint = This method retrieves the target point position			
Parameter	Туре	Description	
getTargetPoint_targetPoint	Coordinate3D		

6.1.45 getVersion

requestGetVersion		
GetVersion = This method returns the API version implemented by the server application		
Parameter Type Description		

responseGetVersion
GetVersion = This method returns the API version implemented by the server application



responseGetVersion		
Parameter	Туре	Description
getVersion_version	Version	

6.1.46 hideCustomElements

requestHideCustomElements		
hideCustomElements = This method hides a set of custom elements which were visualized by DisplayCustomElements		
Parameter Type Description		Description
hideCustomElements_R_sess	onanaine lle	sessionHandle = Session handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
hideCustomElements_R_map	Vii t exwlutIstanceHandle	mapViewInstanceHandle = Map instance handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
hideCustomElements_R_custo	nnementaliandiesie_	

responseHideCustomElements		
hideCustomElements = This method hides a set of custom elements which were visualized by DisplayCustomElements		
Parameter Type Description		

6.1.47 hideObjectList

requestHideObjectList		
hideObjectList = This method hides a list of objects, created in another domain		
Parameter	Туре	Description
hideObjectList_R_sessionHan	dle andle	sessionHandle = Session handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
hideObjectList_R_mapViewIns	tanodit andle	mapViewInstanceHandle = Map instance handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
hideObjectList_R_objectList	ObjectList	contains enum to other domain + session-id of other domain



responseHideObjectList		
hideObjectList = This method hides a list of objects, created in another domain		
Parameter Type Description		

6.1.48 hideRoute

requestHideRoute		
hideRoute = This method hides one of the visible routes		
Parameter	Туре	Description
hideRoute_R_sessionHandle	Handle	sessionHandle = Session handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
hideRoute_R_mapViewInstand	c <mark>eldaddd</mark> e	mapViewInstanceHandle = Map instance handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
hideRoute_R_routeHandle	Handle	routeHandle = Route handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value

responseHideRoute		
hideRoute = This method hides one of the visible routes		
Parameter Type Description		Description

6.1.49 highlightObjectListItem

requestHighlightObjectListItem		
highlightObjectListItem = highlights exclusively a various number of items within an objectList. For unhighlight all, objectListItems is empty		
Parameter	Туре	Description
highlightObjectListItem_R_ses	s ilanda ndle	sessionHandle = Session handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
highlightObjectListItem_R_ma	p Vævlle stanceHandle	mapViewInstanceHandle = Map instance handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
highlightObjectListItem_R_obj	ectlestitemos_ObjectListItem_	contains enum to other domain, contains session-id of other domain



responseHighlightObjectListItem		
highlightObjectListItem = highlights exclusively a various number of items within an objectList. For unhighlight all, objectListItems is empty		
Parameter Type Description		

6.1.50 mapSetStyle

requestMapSetStyle		
mapSetStyle = Changes the StyleSet of the MapViewer. e.g. day/night switch		
Parameter	Туре	Description
mapSetStyle_R_sessionHa	andl <mark>e</mark> Handle	sessionHandle = Session handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
mapSetStyle_R_mapViewInstahlændle		mapViewInstanceHandle = Map instance handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
mapSetStyle_R_styleSet	MapViewStyleSet	styleSet = StyleSet enum. {DAY, NIGHT}

responseMapSetStyle		
mapSetStyle = Changes the StyleSet of the MapViewer. e.g. day/night switch		
Parameter Type Description		

6.1.51 mapShowRouteOverview

requestMapShowRouteOverview		
mapShowRouteOverview = This method shows an overview map with the current route in the center		
Parameter	Туре	Description
mapShowRouteOverview_R_s	etssiothetandle	sessionHandle = Session handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
mapShowRouteOverview_R_r	ndap Wittow Instance Handle	mapViewInstanceHandle = Map instance handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value



requestMapShowRouteOverview	
mapShowRouteOverview_R_rdullett8t2	Route-Id
mapShowRouteOverview_R_onemation	orientation = orientation of mapViewer during route-overview

responseMapShowRouteOverview		
mapShowRouteOverview = This method shows an overview map with the current route in the center		
Parameter Type Description		

6.1.52 mapViewGesture

requestMapViewGesture mapViewGesture = This method is a compound gesture command		
mapViewGesture_R_session	nH ahadie lle	sessionHandle = Session handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
mapViewGesture_R_mapVie	ew <mark>Irlatatile</mark> eHandle	mapViewInstanceHandle = Map instance handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
mapViewGesture_R_system	Mi lista 2ondsTime	any internal time of system-HMI-clock in ms. This timestamp should be used for smoothing the movement within controller
mapViewGesture_R_isFinge	erD bao lean	while gesture is running, set to true if gesture ends (last finger lifted from touchscreen) set to false. in case of false, anchorScreen, scrollOffset, zoomFactor, rorationAngle and pitchAngle are ignored
mapViewGesture_R_anchor	Scare en Coordinate	anchorScreen = center "pixels" of gesture to have a rotation axis and scrolling-center
mapViewGesture_R_scrollO	ffsetcreenCoordinate	scrollOffset = scrolling in pixels to a direction. 0/0 = default (no scroll)
mapViewGesture_R_zoomF	ac tdo uble	zoomFactor = changing scale. 1.0 = no change
mapViewGesture_R_rotation	n Andglable	rotationAngle = rotate in degree 0.0 = no change 90.0 = 90 degree



requestMapViewGesture		
mapViewGesture_R_pitchAng	d ouble	pitchAngle = pitch the view. 0.0 = no change, positive values goto birdview, negative-values goto 2D

responseMapViewGesture		
mapViewGesture = This method is a compound gesture command		
Parameter	Туре	Description

6.1.53 popSettings

requestPopSettings		
popSettings = re-stores the current map-ctrl setting (scale, orientation, visible objects) from the stack (called after pushSetting)		
Parameter	Туре	Description
popSettings_R_sessionHandle	Handle	sessionHandle = Session handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
popSettings_R_mapViewInsta	n de hlale dle	mapViewInstanceHandle = Map instance handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value

responsePopSettings		
popSettings = re-stores the current map-ctrl setting (scale, orientation, visible objects) from the stack (called after pushSetting)		
Parameter	Туре	Description

6.1.54 pushSettings

requestPushSettings		
pushSettings = stores the current map-ctrl setting (scale, orientation, visible objects) to an internal stack		
Parameter	Туре	Description
pushSettings_R_sessionHand	e landle	sessionHandle = Session handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value



requestPushSettings	
pushSettings_R_mapViewInstarleeLlandle	mapViewInstanceHandle = Map instance handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value

responsePushSettings		
pushSettings = stores the curre stack	ent map-ctrl setting (scale, oriel	ntation, visible objects) to an internal
Parameter Type Description		

6.1.55 releaseMapViewInstance

requestReleaseMapViewInst	tance	
releaseMapViewInstance = This method releases (i.e. destroys) a given map instance. Only invisible map instances can be released		
Parameter	Туре	Description
releaseMapViewInstance_R_s	e <mark>ssione</mark> landle	sessionHandle = Session handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
releaseMapViewInstance_R_r	ท อ_่คุฬเช็พ InstanceHandle	mapViewInstanceHandle = Map instance handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value

responseReleaseMapViewInstance	
releaseMapViewInstance = This method releases (i.e. destroys) a given map instance. Only invisible map instances can be released	
Parameter Type Description	

6.1.56 removeMapViewScaleChangedListener

requestRemoveMapViewScaleChangedListener		
removeMapViewScaleChange view scale changes.	dListener = This method remov	es a listener which is notified when map
Parameter Type Description		



responseRemoveMapViewScaleChangedListener	
removeMapViewScaleChangedListener = This method removes a listener which is notified when map view scale changes.	
Parameter Type Description	

6.1.57 resetSettings

requestResetSettings		
resetSettings = resets the mapInstance to a dedicated state (same as startup)		same as startup)
Parameter	Туре	Description
resetSettings_R_sessionHand	e landle	sessionHandle = Session handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
resetSettings_R_mapViewInst	a <mark>rleetile</mark> ndle	mapViewInstanceHandle = Map instance handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value

responseResetSettings		
resetSettings = resets the map	Instance to a dedicated state (s	same as startup)
Parameter Type Description		

6.1.58 selectElementsOnMap

requestSelectElementsOnMap		
selectElementsOnMap = This method selects elements on the map view which are at the position specified by user input		
Parameter	Туре	Description
selectElementsOnMap_R_map	o lþwlle stanceHandle	mapViewInstanceHandle = Map instance handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
selectElementsOnMap_R_pixe	®oe rdinate	
selectElementsOnMap_R_sele	ctaBleeype sSelectableMapTyp	e_
selectElementsOnMap_R_max	k Nlmf1l6 erOfSelectedElements	maxNumberOfSelectedElements = maximum number of selected elements to return. If 0, all possible elements which can be selected will be returned



responseSelectElementsOnMap		
selectElementsOnMap = This method selects elements on the map view which are at the position specified by user input		
Parameter Type Description		
selectElementsOnMap_selecte	ed Elekhertts _SelectedMapElem	ent_

6.1.59 setAutozoomEnabled

requestSetAutozoomEnabled		
Parameter	Туре	Description
setAutozoomEnabled_R_sess	onthal nelle	sessionHandle = Session handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
setAutozoomEnabled_R_map\	ditemblistanceHandle	mapViewInstanceHandle = Map instance handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
setAutozoomEnabled_R_enab	l ed olean	enabled

responseSetAutozoomEnabled		
Parameter	Туре	Description

6.1.60 setAutozoomSetting

requestSetAutozoomSetting		
Parameter	Туре	Description
setAutozoomSetting_R_session	i h I sla nd di e	sessionHandle = Session handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
setAutozoomSetting_R_mapV	evalmsta nceHandle	mapViewInstanceHandle = Map instance handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
setAutozoomSetting_R_autozo	AntSettingSetting	autozoomSetting (NEAR / NORMAL / FAR)

responseSetAutozoomSetting	



responseSetAutozoomSetting		
Parameter	Туре	Description

6.1.61 setCameraDistanceFromTargetPoint

requestSetCameraDistanceFromTargetPoint		
setCameraDistanceFromTargetPoint = This method sets the mode and the camera distance from the target point		
Parameter	Туре	Description
setCameraDistanceFromTarge	tRointeR_sessionHandle	sessionHandle = Session handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
setCameraDistanceFromTargetRoindleR_mapViewInstanceHamodapViewInstanceHandle = Map instance handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value		
setCameraDistanceFromTarge	t ⊮oti3 2_R_distance	distance = distance from the view point in meters

responseSetCameraDistanceFromTargetPoint	
setCameraDistanceFromTargetPoint = This method sets the mode and the camera distance from the target point	
Parameter Type Description	

6.1.62 setCameraHeadingAngle

requestSetCameraHeadingAngle		
setCameraHeadingAngle = This method sets the map view heading angle		
Parameter	Туре	Description
setCameraHeadingA	ngle_R_s essionle landle	sessionHandle = Session handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
setCameraHeadingA	ngle_R_m <mark>lalpWid⊎w</mark> InstanceHandle	mapViewInstanceHandle = Map instance handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
setCameraHeadingA	ngle_R_h elat©i i2ig	heading = heading angle in degrees. Range [0:360]



responseSetCameraHeadingAngle		
setCameraHeadingAngle = This method sets the map view heading angle		
Parameter Type Description		

6.1.63 setCameraHeadingToTarget

requestSetCameraHeadingToTarget		
setCameraHeadingToTarget = This method sets the camera heading in such a way, that the camera always looks at a given target		
Parameter Type Description		
setCameraHeadingToTarget_l	R <u>I</u> sessionHandle	sessionHandle = Session handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
setCameraHeadingToTarget_l	R <u>-I</u> anaptviewInstanceHandle	mapViewInstanceHandle = Map instance handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
setCameraHeadingToTarget_I	C_tangënate2D	

responseSetCameraHeadingToTarget		
setCameraHeadingToTarget = This method sets the camera heading in such a way, that the camera always looks at a given target		
Parameter Type Description		

6.1.64 setCameraHeadingTrackUp

requestSetCameraHeadingTrackUp		
setCameraHeadingTrackUp = This method sets the camera heading in such a way, that the camera always looks in the direction in which the car is moving		
Parameter	Туре	Description
setCameraHeadingTrackUp_R	<u>⊦</u> sæs slienHandle	sessionHandle = Session handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
setCameraHeadingTrackUp_R	<u>Haa</u> d∕eiewInstanceHandle	mapViewInstanceHandle = Map instance handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value



responseSetCameraHeadingTrackUp		
setCameraHeadingTrackUp = This method sets the camera heading in such a way, that the camera always looks in the direction in which the car is moving		
Parameter Type Description		

6.1.65 setCameraHeight

requestSetCameraHeight setCameraHeight = This method sets the camera height		
setCameraHeight_R_session	nH atadie le	sessionHandle = Session handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
setCameraHeight_R_mapVio	ew l_mstatic eHandle	mapViewInstanceHandle = Map instance handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
setCameraHeight_R_height	UInt32	height = height from the ground in meters

responseSetCameraHeight		
setCameraHeight = This method sets the camera height		
Parameter Type Description		

6.1.66 setCameraPosition

requestSetCameraPosition		
setCameraPosition = This method sets the coordinates of the point at which the camera must be positioned		
Parameter Type Description		
setCameraPosition_R_session	Handle	sessionHandle = Session handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
setCameraPosition_R_mapVie	whatenceHandle	mapViewInstanceHandle = Map instance handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
setCameraPosition_R_position	Coordinate3D	



responseSetCameraPosition		
setCameraPosition = This method sets the coordinates of the point at which the camera must be positioned		
Parameter Type Description		

6.1.67 setCameraRollAngle

requestSetCameraRollAngle setCameraRollAngle = This method sets the camera roll angle		
setCameraRollAngle_R_sess	io <mark>nleladiel</mark> e	sessionHandle = Session handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
setCameraRollAngle_R_map	VilelwhostanceHandle	mapViewInstanceHandle = Map instance handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
setCameraRollAngle_R_roll	Int32	roll = roll angle in degrees. Range [-180:180]

responseSetCameraRollAngle		
setCameraRollAngle = This method sets the camera roll angle		
Parameter Type Description		

6.1.68 setCameraTiltAngle

requestSetCameraTiltAngle setCameraTiltAngle = This method sets the camera tilt angle		
setCameraTiltAngle_R_set	ssio rl#kandlte	sessionHandle = Session handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
setCameraTiltAngle_R_ma	pVi ewinsta nceHandle	mapViewInstanceHandle = Map instance handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
setCameraTiltAngle_R_tilt	Int32	tilt = tilt angle in degrees. Range [-180:180]



responseSetCameraTiltAngle		
setCameraTiltAngle = This method sets the camera tilt angle		
Parameter Type Description		

6.1.69 setFollowCarMode

requestSetFollowCarMode			
setFollowCarMode = This met	setFollowCarMode = This method sets the FollowCar mode		
Parameter	Туре	Description	
setFollowCarMode_R_session	HHamdle:	sessionHandle = Session handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value	
setFollowCarMode_R_mapVie	w laståe ceHandle	mapViewInstanceHandle = Map instance handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value	
setFollowCarMode_R_followC	atr ivitolela n	followCarMode = flag. If true, the current car position is interpreted as position of the point the camera must look at	

responseSetFollowCarMode		
setFollowCarMode = This method sets the FollowCar mode		
Parameter Type Description		Description

6.1.70 setKmlVisibility

requestSetKmlVisibility		
setKmlVisibility = shows/hides a kmlFile (without deleting it actually)		
Parameter	Туре	Description
setKmlVisibility_R_sessionHa	idle ndle	sessionHandle = Session handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
setKmlVisibility_R_mapViewIn	stancë e landle	mapViewInstanceHandle = Map instance handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
setKmlVisibility_R_kmlHandle	Handle	kmlHandle = NAV2010-kmlHandle



requestSetKmlVisibility	
setKmlVisibility_R_show	show if TRUE then kmlContent is shown on MapViewer

responseSetKmlVisibility		
setKmlVisibility = shows/hides a kmlFile (without deleting it actually)		
Parameter Type Description		

6.1.71 setMapMode

requestSetMapMode			
setMapMode = This method sets the map mode (String-datatype, could be hard-coded in HMI if controller is known)			
Parameter Type Description			
setMapMode_R_sessionHand	e landle	sessionHandle = Session handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value	
setMapMode_R_mapViewInst	a <mark>riaelda</mark> ndle	mapViewInstanceHandle = Map instance handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value	
setMapMode_R_mapMode	String	mapMode	

responseSetMapMode			
setMapMode = This method sets the map mode (String-datatype, could be hard-coded in HMI if controller is known)			
Parameter Type Description			

6.1.72 setMapViewBoundingBox

requestSetMapViewBoundingBox		
setMapViewBoundingBox = This method sets the map bounding box		
Parameter	Type Description	
setMapViewBoundingBox_R_s	s elssidht Handle	sessionHandle = Session handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value



requestSetMapViewBoundingBox	
setMapViewBoundingBox_R_mapViewInstanceHandle	mapViewInstanceHandle = Map instance handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
setMapViewBoundingBox_R_boundingBoxangle	

responseSetMapViewBoundingBox		
setMapViewBoundingBox = This method sets the map bounding box		
Parameter Type Description		

6.1.73 setMapViewObjectVisibility

requestSetMapViewObjectVisibility		
setMapViewObjectVisibility = This method specifies the type of objects to show on the map.		
Parameter Type Description		
setMapViewObjectVisibility_R	slessilo nHandle	sessionHandle = Session handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
setMapViewObjectVisibility_R	hhap://iewInstanceHandle	mapViewInstanceHandle = Map instance handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
setMapViewObjectVisibility_R	b/bajp@l/jisidaWitylbiisity	

responseSetMapViewObjectVisibility			
setMapViewObjectVisibility = This method specifies the type of objects to show on the map.			
Parameter Type Description			

6.1.74 setMapViewPan

requestSetMapViewPan		
setMapViewPan = This method pans a given map instance		
Parameter	Туре	Description
setMapViewPan_R_sessionHa	a hdie dle	sessionHandle = Session handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value



requestSetMapViewPan	
setMapViewPan_R_mapViewInstanteHandle	mapViewInstanceHandle = Map instance handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
setMapViewPan_R_systemMiliset32ndsTime	any internal time of system-HMI-clock in ms. This timestamp should be used for smoothing the movement within controller
setMapViewPan_R_panningAction	panningAction = enum(PAN_START,PAN_TO,PAN_END Whenever a finger is start to touch the screen: PAN_START, whenever a finger leaves the screen: PAN_END
setMapViewPan_R_pixelCoordinatesector_ScreenC	ordinate array of currently touching finger. If this array is emtpy, all fingers have been removed from screen. A flic can start

responseSetMapViewPan		
setMapViewPan = This method pans a given map instance		
Parameter	Туре	Description

6.1.75 setMapViewPerformanceLevel

requestSetMapViewPerformanceLevel			
setMapViewPerformanceLevel = This method sets the perfomance level of a given map instance			
Parameter	arameter Type Description		
setMapViewPerformanceLevel	<u>⊦Rars#s</u> sionHandle	sessionHandle = Session handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value	
setMapViewPerformanceLevel	<u>Handla</u> pViewInstanceHandle	mapViewInstanceHandle = Map instance handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value	
setMapViewPerformanceLevel	<u>LRv</u> performanceLevel	performanceLevel = enum(INVALID,LEVEL1,LEVEL2,LEVEL)	3,LEVEL4,LE\

responseSetMapViewPerformanceLevel
setMapViewPerformanceLevel = This method sets the perfomance level of a given map instance



responseSetMapViewPerformanceLevel		
Parameter	Туре	Description

6.1.76 setMapViewPerspective

requestSetMapViewPerspective		
setMapViewPerspective = This method sets the map perspective		
Parameter	Туре	Description
setMapViewPerspective_R_s	e \$\$ionHa ndle	sessionHandle = Session handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
setMapViewPerspective_R_m	a <mark>p Miælld</mark> nstanceHandle	mapViewInstanceHandle = Map instance handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
setMapViewPerspective_R_p	elspective	perspective = enum(INVALID,2D,3D,)

responseSetMapViewPerspective	
setMapViewPerspective = This method sets the map perspective	
Parameter Type Description	

6.1.77 setMapViewRotation

requestSetMapViewRotation		
setMapViewRotation = This method rotates the map		
Parameter	Туре	Description
setMapViewRotation_R_session	o <mark>irl<i>e</i>ladid</mark> le	sessionHandle = Session handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
setMapViewRotation_R_mapV	ilelwhustanceHandle	mapViewInstanceHandle = Map instance handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
setMapViewRotation_R_rotation	ohnASi@le	rotationAngle = rotation angle in degrees measured from the North axis clockwise. Range[0:360]
setMapViewRotation_R_rotation	om/ManglePerSecond	rotationAnglePerSecond = partial rotation for each second



responseSetMapViewRotation		
setMapViewRotation = This method rotates the map		
Parameter	Туре	Description

6.1.78 setMapViewSaveArea

requestSetMapViewSaveAre	a	
setMapViewSaveArea = This methods defines the area that the HMI guarantees not to cover with other windows or user interface elements		
Parameter	Туре	Description
setMapViewSaveArea_R_sess	i daht aadle	sessionHandle = Session handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
setMapViewSaveArea_R_map	Viewlits tanceHandle	mapViewInstanceHandle = Map instance handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
setMapViewSaveArea_R_save	&cea enRectangle	

responseSetMapViewSaveArea		
setMapViewSaveArea = This methods defines the area that the HMI guarantees not to cover with other windows or user interface elements		
Parameter	Туре	Description

6.1.79 setMapViewScale

requestSetMapViewScale		
setMapViewScale = This method sets the map scale by specifying a ScaleID		
Parameter	Туре	Description
setMapViewScale_R_sessionI	Haladle e	sessionHandle = Session handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
setMapViewScale_R_mapViev	Mhatain ceHandle	mapViewInstanceHandle = Map instance handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
setMapViewScale_R_scaleID	UInt16	scaleID = scale identifier. Range[0:256]



responseSetMapViewScale		
setMapViewScale = This method sets the map scale by specifying a ScaleID		
Parameter	Туре	Description

6.1.80 setMapViewScaleByDelta

requestSetMapViewSo	requestSetMapViewScaleByDelta	
setMapViewScaleByDelta = This method sets the map scale by specifying a delta value with respect to the currently set ScaleID		
Parameter	Туре	Description
setMapViewScaleByDe	lta_R_s elssidh Handle	sessionHandle = Session handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
setMapViewScaleByDe	lta_R_m hap\dle wInstanceHandle	mapViewInstanceHandle = Map instance handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
setMapViewScaleByDe	lta_R_s tratite Delta	scaleDelta = This parameter can have either positive or negative values. '0' means no change. Positive values indicate larger scales

responseSetMapViewScaleByDelta		
setMapViewScaleByDelta = This method sets the map scale by specifying a delta value with respect to the currently set ScaleID		
Parameter	Туре	Description

6.1.81 setMapViewScaleByMetersPerPixel

requestSetMapViewScaleBy	MetersPerPixel	
setMapViewScaleByMetersPerPixel = This method sets the map scale by specifying the number of meters that a pixel represents		
Parameter	Туре	Description
setMapViewScaleByMetersPe	rPixœt <u>ll</u> &_sessionHandle	sessionHandle = Session handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
setMapViewScaleByMetersPe	r <mark>Pixœt∐</mark> &_mapViewInstanceHai	ndlapViewInstanceHandle = Map instance handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value



requestSetMapViewScaleByMetersPerPixel	
setMapViewScaleByMetersPerPixel	metersPerPixel = meters per pixel

responseSetMapViewScaleByMetersPerPixel		
setMapViewScaleByMetersPerPixel = This method sets the map scale by specifying the number of meters that a pixel represents		
Parameter	Туре	Description

6.1.82 setMapViewScaleMode

requestSetMapViewScaleMode		
setMapViewScaleMode = This method sets the scaling mode.		
Parameter Type Description		Description
setMapViewScaleMode_	R_se ssiontHa ndle	sessionHandle = Session handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
setMapViewScaleMode_	R_malph/iledh/trnstanceHandle	mapViewInstanceHandle = Map instance handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
setMapViewScaleMode_	R_sca leM ostealeMode	scaleMode = enum(AUTOMATIC,MANUAL,HYBRID)

responseSetMapViewScaleMode		
setMapViewScaleMode = This method sets the scaling mode.		
Parameter Type Description		

6.1.83 setMapViewTheme

requestSetMapViewTheme		
setMapViewTheme = This method configures the theme of a given map view instance		
Parameter Type Description		
setMapViewTheme_R_session	Handle	sessionHandle = Session handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
setMapViewTheme_R_mapVie	wanstanceHandle	mapViewInstanceHandle = Map instance handle. Range[0x0:0x7fffffff].



requestSetMapViewTheme	
	0x0 is reserved as an invalid handle value
setMapViewTheme_R_mapViewTheme	mapViewTheme = enum(DAY / NIGHT)

responseSetMapViewTheme		
setMapViewTheme = This method configures the theme of a given map view instance		
Parameter Type Description		

6.1.84 setMapViewVisibilityMode

requestSetMapViewVisibilityMode		
setMapViewVisibilityMode = This method sets the current visibility mode		
Parameter Type Description		Description
setMapViewVisibilityMode_R_	s <mark>essiole</mark> Handle	sessionHandle = Session handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
setMapViewVisibilityMode_R_	<mark>ாக்ஸி∕ile</mark> wInstanceHandle	mapViewInstanceHandle = Map instance handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
setMapViewVisibilityMode_R_	višititititMode	visibilityMode = enum(INVALID,VISIBLE,INVISIBLE,FROZ

responseSetMapViewVisibilityMode		
setMapViewVisibilityMode = This method sets the current visibility mode		
Parameter Type Description		

6.1.85 setPoiCategoriesNotVisible

requestSetPoiCategoriesNotVisible		
setPoiCategoriesNotVisible = Remove POI categories from the set of POI categories displayed on the map.		
Parameter	Туре	Description
setPoiCategoriesNotVisible_R	<u>Islessilo</u> nHandle	sessionHandle = Session handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value



requestSetPoiCategoriesNotVisible		
setPoiCategoriesNotVisible_R	<u>Irraap</u> WiewInstanceHandle	mapViewInstanceHandle = Map instance handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
setPoiCategoriesNotVisible_R	Tidistategorylldat32_	poiCategorylds = list of POI-categories

responseSetPoiCategoriesNotVisible		
setPoiCategoriesNotVisible = Remove POI categories from the set of POI categories displayed on the map.		
Parameter Type Description		

6.1.86 setPoiCategoriesVisible

requestSetPoiCategoriesVisible		
setPoiCategoriesVisible = Add POI categories to the set of POI categories displayed on the map. Any specified category that until now was displayed with scale limits is now displayed without limits.		
Parameter Type Description		
setPoiCategoriesVisible_R_se	s <mark>sion#la</mark> ndle	sessionHandle = Session handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
setPoiCategoriesVisible_R_ma	a pl vdiedwhstanceHandle	mapViewInstanceHandle = Map instance handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
setPoiCategoriesVisible_R_po	i Cate gerytot <u>s</u> UInt32_	poiCategoryIds = list of POI-categories

responseSetPoiCategoriesVisible			
setPoiCategoriesVisible = Add POI categories to the set of POI categories displayed on the map. Any specified category that until now was displayed with scale limits is now displayed without limits.			
Parameter Type Description			

6.1.87 setPoiCategoriesVisibleMode

requestSetPoiCategoriesVisibleMode

setPoiCategoriesVisibleMode = gives the possibility to show or hide all POI categories regardsless of of which one are enabled with setPoiCategoriesVisible/setPoiCategoriesNotVisible. The selection



requestSetPoiCategoriesVisibleMode		
which is done with setPoiCategoriesVisible/setPoiCategoriesNotVisible is not changed by this command.		
Parameter Type Description		
setPoiCategoriesVisibleMode_	RasessionHandle	sessionHandle = Session handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
setPoiCategoriesVisibleMode_	Ramalp ViewInstance Handle	mapViewInstanceHandle = Map instance handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
setPoiCategoriesVisibleMode_	RojtGitCatjegerie/st/lisitNetMede	poiCategoriesVisibleMode = {SELECTED(default) / ALL / NONE}

responseSetPoiCategoriesVisibleMode

setPoiCategoriesVisibleMode = gives the possibility to show or hide all POI categories regardsless of of which one are enabled with setPoiCategoriesVisible/setPoiCategoriesNotVisible. The selection which is done with setPoiCategoriesVisible/setPoiCategoriesNotVisible is not changed by this command.

Parameter	Туре	Description

6.1.88 setPoiCategoriesVisibleWithinLimits

requestSetPoiCategoriesVisibleWithinLimits

setPoiCategoriesVisible = Add POI categories to the set of POI categories displayed on the map, where the POI's are only displayed in a specific range of scales. Any specified category that until now was displayed without scale limits is now displayed with limits.

Parameter	Туре	Description
setPoiCategoriesVisibleWithin	Linaits <u>ll</u> eR_sessionHandle	sessionHandle = Session handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
setPoiCategoriesVisibleWithin	Lirhaitts∐∉ R_mapViewInstanceHar	ndlapViewInstanceHandle = Map instance handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
setPoiCategoriesVisibleWithin	_TrhiBs<u>√</u>ectpoiOate⊗or ylds	
setPoiCategoriesVisibleWithin	Limt&s_R_minScaleID	minScaleID = minimun scale on which the POI categories are displayed
setPoiCategoriesVisibleWithin	Llimt&ts_R_maxScaleID	maxScaleID = maximum scale on which the POI categories are displayed



responseSetPoiCategoriesVisibleWithinLimits

setPoiCategoriesVisible = Add POI categories to the set of POI categories displayed on the map, where the POI's are only displayed in a specific range of scales. Any specified category that until now was displayed without scale limits is now displayed with limits.

6.1.89 setTargetPoint

requestSetTargetPoint		
setTargetPoint = This method sets the position of the point the camera is always aimed at		
Parameter Type Description		
setTargetPoint_R_sessionHar	dle ndle	sessionHandle = Session handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
setTargetPoint_R_mapViewIn	stamodie and le	mapViewInstanceHandle = Map instance handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
setTargetPoint_R_targetPoint	Coordinate3D	

responseSetTargetPoint		
setTargetPoint = This method sets the position of the point the camera is always aimed at		
Parameter Type Description		

6.1.90 setTrafficIncidentsVisibility

requestSetTrafficIncidentsVisibility		
setTrafficIncidentsVisibility = Set the visibility of Traffic Incidents on the map.		
Parameter	Туре	Description
setTrafficIncidentsVisibility_R_	s ėssiöe Handle	sessionHandle = Session handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
setTrafficIncidentsVisibility_R_	r <mark>riap∀ie</mark> wInstanceHandle	mapViewInstanceHandle = Map instance handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
setTrafficIncidentsVisibility_R_	vioible an	visible = If true, Traffic Incidents are shown on the map, else they are not shown.



responseSetTrafficIncidentsVisibility		
setTrafficIncidentsVisibility = Set the visibility of Traffic Incidents on the map.		
Parameter Type Description		

6.1.91 displayedRoutes

informationDisplayedRoutes		
displayedRoutes = This signal is emitted when the list of displayed routes change		
Parameter Type Description		Description
displayedRoutes_mapViewIns	t ahwellla ndle	mapViewInstanceHandle = Map instance handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value
displayedRoutes_displayedRo	ultesBVector_DisplayedRoute_	-

6.1.92 mapViewScaleChanged

informationMapViewScaleChanged			
mapViewScaleChanged = This signal is emitted when the mapview scale changes			
Parameter	Parameter Type Description		
mapViewScaleChanged_map\	/iewldstanceHandle	mapViewInstanceHandle = Map instance handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value	
mapViewScaleChanged_scale	IIDt8	scaleID = scale identifier. Range[0:256]	
mapViewScaleChanged_isMin	Max pScaleType	isMinMax = enum(INVALID,MIN,MAX,MID,)	

6.1.93 mapViewVisibilityChanged

informationMapViewVisibilityChanged		
mapViewVisibilityChanged = This signal is emitted when the MapView visibility changes		
Parameter Type Description		
mapViewVisibilityChanged_map	a <mark>bMiesWe</mark> nstanceHandle	mapViewInstanceHandle = Map instance handle. Range[0x0:0x7fffffff]. 0x0 is reserved as an invalid handle value



informationMapViewVisibilityChanged	
mapViewVisibilityChanged_visibilityMtgde	visibilityMode = enum(INVALID,VISIBLE,INVISIBLE,FROZE)

6.1.94 astatus

Attribute astatus		
Туре	Notification Type	
Status	ON_CHANGE	

6.1.95 THBVector_CHBString_

mapMode-List (string-based) Vector of element type String

Referenced by: org_harman_nav_ctrl_mapv_MapViewControl::getMapModeList

6.1.96 THBVector_Coordinate2D_

Vector of element type Coordinate2D

Referenced by: org_harman_nav_ctrl_mapv_MapViewControl::convertPixelCoordsToGeoCoords, org_harman_nav_ctrl_mapv_MapViewControl::convertGeoCoordsToPixelCoords

6.1.97 THBVector_CustomElement_

Vector of element type CustomElement

Referenced by : org_harman_nav_ctrl_mapv_MapViewControl::displayCustomElements

6.1.98 THBVector_DisplayedRoute_

Vector of element type **DisplayedRoute**

Referenced by : org_harman_nav_ctrl_mapv_MapViewControl::getDisplayedRoutes, org_harman_nav_ctrl_mapv_MapViewControl::displayedRoutes

6.1.99 THBVector_Handle_

Vector of element type Handle



Referenced by : org_harman_nav_ctrl_mapv_MapViewControl::displayCustomElements, org_harman_nav_ctrl_mapv_MapViewControl::hideCustomElements

6.1.100 THBVector_Level_

Vector of element type Level

Referenced by:

org_harman_nav_ctrl_mapv_MapViewControl::getSupportedMapViewPerformanceLevels

6.1.101 THBVector_MapObject_

Vector of element type MapObject

Referenced by: org_harman_nav_ctrl_mapv_MapViewControl::getSupportedMapViewObjectVisibilities

6.1.102 THBVector_MapPerspective_

Vector of element type MapPerspective

Referenced by: org_harman_nav_ctrl_mapv_MapViewControl::getSupportedMapViewPerspectives

6.1.103 THBVector_MapScaleMode_

Vector of element type MapScaleMode

Referenced by : org_harman_nav_ctrl_mapv_MapViewControl::getSupportedMapViewScaleModes

6.1.104 THBVector_MapScale_

Vector of element type MapScale

Referenced by: org_harman_nav_ctrl_mapv_MapViewControl::getScaleList

6.1.105 THBVector_MapTheme_

Vector of element type MapTheme

Referenced by : org_harman_nav_ctrl_mapv_MapViewControl::getSupportedMapViewThemes

6.1.106 THBVector_MapViewType_

Vector of element type MapViewType



Referenced by: org_harman_nav_ctrl_mapv_MapViewControl::getSupportedMapViewTypes

6.1.107 THBVector_ObjectListItem_

contains enum to other domain, contains session-id of other domain Vector of element type **ObjectListItem**

Referenced by: org_harman_nav_ctrl_mapv_MapViewControl::highlightObjectListItem, org_harman_nav_ctrl_mapv_MapViewControl::centerOnObjectListItems

6.1.108 THBVector_Pixel_

Vector of element type Pixel

Referenced by: org_harman_nav_ctrl_mapv_MapViewControl::convertPixelCoordsToGeoCoords, org_harman_nav_ctrl_mapv_MapViewControl::convertGeoCoordsToPixelCoords

6.1.109 THBVector_ScreenCoordinate_

array of currently touching finger. If this array is emtpy, all fingers have been removed from screen. A flic can start Vector of element type **ScreenCoordinate**

Referenced by: org_harman_nav_ctrl_mapv_MapViewControl::setMapViewPan

6.1.110 THBVector_SelectableMapType_

Vector of element type SelectableMapType

Referenced by : org_harman_nav_ctrl_mapv_MapViewControl::selectElementsOnMap

6.1.111 THBVector_SelectedMapElement_

Vector of element type SelectedMapElement

Referenced by : org_harman_nav_ctrl_mapv_MapViewControl::selectElementsOnMap

6.1.112 THBVector_UInt32_

Vector of element type UInt32

Referenced by: org_harman_nav_ctrl_mapv_MapViewControl::getPoiCategoriesVisible, org_harman_nav_ctrl_mapv_MapViewControl::setPoiCategoriesVisible, org_harman_nav_ctrl_mapv_MapViewControl::setPoiCategoriesVisibleWithinLimits, org_harman_nav_ctrl_mapv_MapViewControl::setPoiCategoriesNotVisible



6.1.113 THBVector_Visibility_

Vector of element type Visibility

Referenced by: org_harman_nav_ctrl_mapv_MapViewControl::getSupportedMapViewVisibilityModes

6.2 org_harman_nav_ctrl_mapv_MapViewControlTyp

Interface Version: 1.1

6.2.1 AnchorPoint

AnchorPoint		
struct generated for DBus argument DisplayCustomElements_customElementsElem4		
Structure Element	Туре	Description
X	Int16	
у	Int16	

Referenced by : org_harman_nav_ctrl_mapv_MapViewControlTypes::CustomElement

6.2.2 AutozoomSetting

AutozoomSetting		
Literal Description		
AutozoomSetting_NEAR		
AutozoomSetting_NORMAL		
AutozoomSetting_FAR		

Referenced by: org_harman_nav_ctrl_mapv_MapViewControl::setAutozoomSetting, org_harman_nav_ctrl_mapv_MapViewControl::getAutozoomSetting, org_harman_nav_ctrl_mapv_MapViewControlTypes::ScreenStatus

6.2.3 CustomElement

CustomElement
struct generated for DBus argument DisplayCustomElements_customElements



CustomElement		
Structure Element	Туре	Description
name	String	
iconUri	String	
coordinate	Coordinate2D	
elem4	AnchorPoint	

Referenced by: org_harman_nav_ctrl_mapv_MapViewControl::THBVector_CustomElement_, org_harman_nav_ctrl_mapv_MapViewControlTypes::ElementValue

6.2.4 Dimension

Dimension		
struct generated for DBus argument CreateMapViewInstance_mapViewSize		
Structure Element	Туре	Description
horizontalSize	UInt16	
verticalSize	UInt16	

Referenced by : org_harman_nav_ctrl_mapv_MapViewControl::createMapViewInstance, org_harman_nav_ctrl_mapv_MapViewControlTypes::ScreenStatus

6.2.5 DisplayedRoute

DisplayedRoute		
struct generated for DBus argument GetDisplayedRoutes_displayedRoutes		
Structure Element	Туре	Description
routeHandle	Handle	
highlighted	boolean	

Referenced by: org_harman_nav_ctrl_mapv_MapViewControl::THBVector_DisplayedRoute_, org_harman_nav_ctrl_mapv_MapViewControlTypes::DisplayedRoutes

6.2.6 DisplayedRoutes

Vector of element type **DisplayedRoute**

Referenced by: org_harman_nav_ctrl_mapv_MapViewControlTypes::ScreenStatus



6.2.7 EObjectListDomain

EObjectListDomain	
Literal	Description
EObjectListDomain_POI_SERVICE	

Referenced by : org_harman_nav_ctrl_mapv_MapViewControlTypes::ObjectList

6.2.8 ElementValue

ElementValue			
Variant Element	Туре	Description	
trafficIncident	Int32		
handle	Handle		
element	CustomElement		
objectListItem	ObjectListItem		

Referenced by: org_harman_nav_ctrl_mapv_MapViewControlTypes::SelectedMapElement

6.2.9 KmlType

KmlType	
Literal	Description
KmlType_KML_URL	KML_URL: the string paramater is a URL (filename)
KmlType_KML_CONTENT	KML_CONTENT: the paramater contains the kml-content directly (file inside big-string)

 $Referenced\ by: org_harman_nav_ctrl_mapv_MapViewControl::addKml$

6.2.10 Level

Level	
Literal	Description



Level	
Level_BasicEnum_INVALID	
Level_LEVEL_1	
Level_LEVEL_2	
Level_LEVEL_3	
Level_LEVEL_4	
Level_LEVEL_5	

Referenced by: org_harman_nav_ctrl_mapv_MapViewControl::setMapViewPerformanceLevel, org_harman_nav_ctrl_mapv_MapViewControl::getMapViewPerformanceLevel, org_harman_nav_ctrl_mapv_MapViewControl::THBVector_Level_

6.2.11 MapObject

MapObject		
Literal	Description	
MapObject_BasicEnum_INVALID		
MapObject_BUILDINGS		
MapObject_TERRAIN		

Referenced by: org_harman_nav_ctrl_mapv_MapViewControl::THBVector_MapObject_

6.2.12 MapObjectVisibility

MapObjectVisibility			
Map Element	Туре	Description	
keyType	MapObject		
valueType	boolean		

Referenced by : org_harman_nav_ctrl_mapv_MapViewControl::setMapViewObjectVisibility, org_harman_nav_ctrl_mapv_MapViewControl::getMapViewObjectVisibility

6.2.13 MapPerspective

MapPerspective	



MapPerspective		
Literal	Description	
MapPerspective_BasicEnum_INVALID		
MapPerspective_PERSPECTIVE_2D		
MapPerspective_PERSPECTIVE_3D		

Referenced by: org_harman_nav_ctrl_mapv_MapViewControl::setMapViewPerspective, org_harman_nav_ctrl_mapv_MapViewControl::getMapViewPerspective, org_harman_nav_ctrl_mapv_MapViewControl::THBVector_MapPerspective_, org_harman_nav_ctrl_mapv_MapViewControlTypes::ScreenStatus

6.2.14 MapScale

MapScale			
struct generated for DBus	argument GetScaleList_sca	aleList	
Structure Element	Туре	Description	
scaleId	UInt16		
scaleValue	UInt16		
unit	MapScaleUnit		
millimetersPerPixel	UInt32		

Referenced by : org_harman_nav_ctrl_mapv_MapViewControl::THBVector_MapScale_, org_harman_nav_ctrl_mapv_MapViewControlTypes::ScreenStatus

6.2.15 MapScaleMode

MapScaleMode		
Literal	Description	
MapScaleMode_BasicEnum_INVALID		
MapScaleMode_AUTOMATIC		
MapScaleMode_MANUAL		
MapScaleMode_HYBRID		



org_harman_nav_ctrl_mapv_MapViewControl::THBVector_MapScaleMode_, org_harman_nav_ctrl_mapv_MapViewControlTypes::ScreenStatus

6.2.16 MapScaleType

MapScaleType		
Literal	Description	
MapScaleType_BasicEnum_INVALID		
MapScaleType_MIN		
MapScaleType_MAX		
MapScaleType_MID		

Referenced by: org_harman_nav_ctrl_mapv_MapViewControl::getMapViewScale, org_harman_nav_ctrl_mapv_MapViewControl::mapViewScaleChanged

6.2.17 MapScaleUnit

MapScaleUnit		
Literal	Description	
MapScaleUnit_BasicEnum_INVALID		
MapScaleUnit_METER		
MapScaleUnit_MILE		
MapScaleUnit_KM		
MapScaleUnit_YARD		
MapScaleUnit_FOOT		

Referenced by: org_harman_nav_ctrl_mapv_MapViewControlTypes::MapScale

6.2.18 MapTheme

MapTheme		
Literal	Description	
MapTheme_BasicEnum_INVALID		
MapTheme_DAY		
MapTheme_NIGHT		



Referenced by: org_harman_nav_ctrl_mapv_MapViewControl::setMapViewTheme, org_harman_nav_ctrl_mapv_MapViewControl::getMapViewTheme, org_harman_nav_ctrl_mapv_MapViewControl::THBVector_MapTheme_, org_harman_nav_ctrl_mapv_MapViewControlTypes::ScreenStatus

6.2.19 MapViewOrientation

MapViewOrientation		
Literal	Description	
MapViewOrientation_NORTH_UP		
MapViewOrientation_HEADING_UP		
MapViewOrientation_MANEUVER_UP		
MapViewOrientation_DESTINATION_UP		
MapViewOrientation_FIXED_ANGLE		

Referenced by : org_harman_nav_ctrl_mapv_MapViewControl::mapShowRouteOverview, org_harman_nav_ctrl_mapv_MapViewControlTypes::ScreenStatus

6.2.20 MapViewStyleSet

MapViewStyleSet	
Literal	Description
MapViewStyleSet_DAY	
MapViewStyleSet_NIGHT	

Referenced by : org_harman_nav_ctrl_mapv_MapViewControl::mapSetStyle, org_harman_nav_ctrl_mapv_MapViewControlTypes::ScreenStatus

6.2.21 MapViewType

MapViewType		
Literal	Description	
MapViewType_BasicEnum_INVALID		
MapViewType_MAIN_MAP		
MapViewType_SPLIT_SCREEN		



Referenced by: org_harman_nav_ctrl_mapv_MapViewControl::createMapViewInstance, org_harman_nav_ctrl_mapv_MapViewControl::getMapViewType, org_harman_nav_ctrl_mapv_MapViewControl::THBVector_MapViewType_, org_harman_nav_ctrl_mapv_MapViewControlTypes::ScreenStatus

6.2.22 ObjectList

ObjectList			
ObjectList, used in displayObjectList/hideObjectList			
Structure Element	Туре	Description	
domain	EObjectListDomain		
domainHandle	Handle		

Referenced by : org_harman_nav_ctrl_mapv_MapViewControl::displayObjectList, org_harman_nav_ctrl_mapv_MapViewControl::hideObjectList, org_harman_nav_ctrl_mapv_MapViewControlTypes::ObjectListItem

6.2.23 ObjectListItem

ObjectListItem			
ObjectListItem, used in highlightObjectListItem			
Structure Element Type Description			
objectList	ObjectList		
domainIndex	UInt32		

Referenced by : org_harman_nav_ctrl_mapv_MapViewControl::THBVector_ObjectListItem_, org_harman_nav_ctrl_mapv_MapViewControlTypes::ElementValue

6.2.24 PanAction

PanAction		
Literal	Description	
PanAction_BasicEnum_INVALID		
PanAction_PAN_START		
PanAction_PAN_TO		



PanAction	
PanAction_PAN_END	

Referenced by : org_harman_nav_ctrl_mapv_MapViewControl::setMapViewPan

6.2.25 Pixel

Pixel		
struct generated for DBus argument SetMapViewPan_pixelCoordinates		
Structure Element	Туре	Description
х	UInt16	
у	UInt16	

Referenced by : org_harman_nav_ctrl_mapv_MapViewControl::selectElementsOnMap, org_harman_nav_ctrl_mapv_MapViewControl::THBVector_Pixel_

6.2.26 PoiCategoriesVisibleMode

PoiCategoriesVisibleMode		
Literal	Description	
PoiCategoriesVisibleMode_SELECTED		
PoiCategoriesVisibleMode_ALL		
PoiCategoriesVisibleMode_NONE		

 $Referenced\ by: org_harman_nav_ctrl_mapv_MapViewControl::setPoiCategoriesVisibleMode$

6.2.27 Poild

Poild			
compound POI-id			
Structure Element	Туре	Description	
databaseld	UInt32		
poild	UInt64		



6.2.28 ScreenCoordinate

ScreenCoordinate			
struct pixel-coordinate			
Structure Element	Туре	Description	
Х	Int32		
у	Int32		

Referenced by: org_harman_nav_ctrl_mapv_MapViewControl::mapViewGesture, org_harman_nav_ctrl_mapv_MapViewControl::mapViewGesture, org_harman_nav_ctrl_mapv_MapViewControl::THBVector_ScreenCoordinate_

6.2.29 ScreenRectangle

ScreenRectangle struct pixel-coordinate			
Structure Element	Туре	Description	
left	Int32		
top	Int32		
width	UInt32		
height	UInt32		

Referenced by: org_harman_nav_ctrl_mapv_MapViewControl::setMapViewBoundingBox, org_harman_nav_ctrl_mapv_MapViewControl::getMapViewBoundingBox, org_harman_nav_ctrl_mapv_MapViewControl::setMapViewSaveArea, org_harman_nav_ctrl_mapv_MapViewControl::getMapViewSaveArea

6.2.30 ScreenStatus

ScreenStatus			
Settings per map view instance.			
Structure Element	Туре	Description	
mapViewInstanceHandle	Handle		
mapMode	String		
visibility	Visibility		



ScreenStatus		
viewType	MapViewType	
style	MapViewStyleSet	
theme	MapTheme	
orientation	MapViewOrientation	
perspective	MapPerspective	
displayedRoutes	DisplayedRoutes	
scaleMode	MapScaleMode	
scale	MapScale	
autozoomEnabled	boolean	
autozoomSetting	AutozoomSetting	
followCarMode	boolean	
cameraHeadingAngle	Int32	
cameraPosition	Coordinate3D	
screenDimensions	Dimension	

 $Referenced\ by: org_harman_nav_ctrl_mapv_MapViewControlTypes::ScreenStatusList$

6.2.31 ScreenStatusList

Vector of element type **ScreenStatus**

Referenced by : org_harman_nav_ctrl_mapv_MapViewControlTypes::Status

6.2.32 SelectableMapType

SelectableMapType		
Literal	Description	
SelectableMapType_BasicEnum_INVALID		
SelectableMapType_CUSTOM_ELEMENT		
SelectableMapType_CURRENT_POSITION		
SelectableMapType_WAYPOINT		
SelectableMapType_POI		
SelectableMapType_TRAFFIC_INCIDENT		
SelectableMapType_ROUTE		
SelectableMapType_GEOCOORDINATES		
SelectableMapType_OBJECT_LIST_ITEM		



Referenced by : org_harman_nav_ctrl_mapv_MapViewControl::THBVector_SelectableMapType_, org_harman_nav_ctrl_mapv_MapViewControlTypes::SelectedMapElement

6.2.33 SelectedMapElement

SelectedMapElement			
struct generated for DBus argument SelectElementsOnMap_selectedElements			
Structure Element	Туре	Description	
type	SelectableMapType		
position	Coordinate2D		
value	ElementValue		

Referenced by : org_harman_nav_ctrl_mapv_MapViewControl::THBVector_SelectedMapElement_

6.2.34 Status

Status			
Settings for map viewer.			
Structure Element	Туре	Description	
statusList	ScreenStatusList		

Referenced by : org_harman_nav_ctrl_mapv_MapViewControl::astatus

6.2.35 Visibility

Visibility		
Literal	Description	
Visibility_BasicEnum_INVALID		
Visibility_VISIBLE		
Visibility_INVISIBLE		
Visibility_FROZEN		



org_harman_nav_ctrl_mapv_MapViewControl::mapViewVisibilityChanged, org_harman_nav_ctrl_mapv_MapViewControl::THBVector_Visibility_, org_harman_nav_ctrl_mapv_MapViewControlTypes::ScreenStatus

6.2.36 tCustomElementDict

tCustomElementDict			
Map Element	Туре	Description	
keyType	Handle		
valueType	CustomElement	struct generated for DBus argument DisplayCustomElements_customElemen	

 $Referenced\ by: org_harman_nav_ctrl_mapv_MapViewControl::getDisplayedCustomElements$



7 LearningNav Service

7.1 org_harman_nav_ctrl_ln_Trails

Interface Version: 1.0

7.1.1 createView

requestCreateView

create a new view to the mother array. This view will be maintained until the client uses destroyView, unsubscribes or service/proxy exit. After creating a view the client must receive an update. Only one created view is allowed to modify the list entries. Please note: a valid usecase is to specify a viewSize which is bigger than the inital list size

Parameter	Туре	Description
createView_R_list	ListId	list to create the view upon.
createView_R_viewsize	ViewSize	individual size of the requested view.

responseCreateView

create a new view to the mother array. This view will be maintained until the client uses destroyView, unsubscribes or service/proxy exit. After creating a view the client must receive an update. Only one created view is allowed to modify the list entries. Please note: a valid usecase is to specify a viewSize which is bigger than the inital list size

Parameter	Туре	Description
createView_view		view identification used to distinguish several instances of a view for one client. It is never changed by the service nor the client. This id is unique!

7.1.2 deleteView

requestDeleteView		
delete the given view instance		
Parameter	Туре	Description
deleteView_R_view	ViewId	identifies the view to apply this operation upon.



responseDeleteView		
delete the given view instance		
Parameter Type Description		

7.1.3 getDetails

requestGetDetails			
Returns trail objects for the given handles.			
Parameter	Туре	Description	
getDetails_R_handles	TrailHandles		

responseGetDetails		
Returns trail objects for the given handles.		
Parameter Type		Description
getDetails_trails	Trails	

7.1.4 getListSize

requestGetListSize		
get the current number of contained elements in the given list.		
Parameter Type Description		Description
getListSize_R_list	ListId	

responseGetListSize			
get the current number of contained elements in the given list.			
Parameter Type Description			
getListSize_size	ListSize		

7.1.5 getSettings

requestGetSettings		
Set trail settings.		
Parameter	Туре	Description



requestGetSettings		
getSettings_R_keys	SettingKeys	

responseGetSettings		
Set trail settings.		
Parameter	Туре	Description
getSettings_settings	Settings	

7.1.6 getViewData

requestGetViewData		
Returns a snapshot of the current view and returns contained data.		
Parameter Type Description		
getViewData_R_view	ViewId	identifies the view to apply this operation upon.

responseGetViewData			
Returns a snapshot of the current view and returns contained data.			
Parameter Type Description			
getViewData_trailDescriptions	TrailDescriptions	Descriptions in order of the current view	
getViewData_snapshotPos	ViewSnapshotPosition	information how the message view snapshot is positioned within the list	

7.1.7 setSettings

requestSetSettings			
Get trail settings.			
Parameter	Туре	Description	
setSettings_R_settings	Settings		

responseSetSettings		
Get trail settings.		
Parameter	Туре	Description



7.1.8 setViewAnchor

requestSetViewAnchor

set a stable element inside the current view snapshot. The client should use an available snapshot of a view to maintain focused elements within the view if possible, and change the view position only if an element to be focused is outside of the given view. A snapshot is generated whenever querying the data contained in a view. Together with that data, the ViewSnapshotPosition is provided. The initial snapshot of the view is always [0, min(viewSize-1, listSize-1)] with anchor offset 0. When creating a new view snapshot, the last call of setViewPosition or setViewAnchor (whichever was the last one) will be the relevant information to reposition the new view snapshot. If setViewAnchor was the last call, the anchor element of the old view snapshot is used for repositioning. (This method only needs to be used if the current view snapshot is outdated because the list has been updated.)

The following rules are applied to set the position of the new view snapshot [newFrom, newTo], given a snapshot [from, to] and anchor offset aOff: Let elem(k) denote the element at key k in the old snapshot and new(e) denote the key the element e will have (would have if deleted) in the new snapshot (see also examples below). newFrom is set to new(elem(from+aOff)) - aOff. If any of these calculated values are out of the range of the list [0, listSize-1], they will be truncated to fit into the list. As a consequence, whenever possible, the anchor element of the old snapshot will be at the same offset within the new snapshot.

As an example for the case in which the data was updated: old list {"a", "b", "c", "d", "e", "f"} with view snapshot ["c", "d"] with viewSize 2 and viewKey 2 new list {"b", "d", "f", "h", "j", "l"} setViewAnchor(0) => elem(from+aOff) is "c", new(elem(from+aOff)) is 1 ("c" would be inserted at index 1) => ["d", "f"] with ViewSnapshotPosition 6, listKey=1, anchorOffset=0. setViewAnchor(1) => elem(from+aOff) is "d", new(elem(from+aOff)) is 1 => ["b", "d"] with ViewSnapshotPosition 6, listKey=0, anchorOffset=1.

	,	
Parameter	Туре	Description
setViewAnchor_R_view	ViewId	identifies the view to apply this operation upon.
setViewAnchor_R_anchor	AnchorOffset	relative anchor position in the view, referenced from ListKey Please note: only positive values and 0 are allowed

7.1.9 setViewPosition

requestSetViewPosition

set the absolute view position to element key. The client should use an available snapshot of a view to maintain focused elements within the view if possible, and change the view position only if an element to be focused is outside of the given view. A snapshot is generated whenever querying the data contained in a view. Together with that data, the ViewSnapshotPosition is provided. The initial snapshot of the view is always [0, min(viewSize-1, listSize-1)]. When creating a new view snapshot, the last call of setViewPosition or setViewAnchor (whichever was the last one) will be the relevant information to reposition the new view snapshot. If setViewPosition was the last call, the view is moved such that the provided key refers to the absolute position on the current snapshot of the view. (This becomes important if the current view snapshot is outdated because the list has been updated.)



requestSetViewPosition

The following rules are applied to set the position of the new view snapshot [newFrom, newTo], given a snapshot [from, to]: Let elem(k) denote the element at key k in the old snapshot and new(e) denote the key the element e will have (would have if deleted) in the new snapshot (see also examples (1)-(3) below). (1) If key is less than from, then newFrom will be set to new(elem(from)) - (from-key). (2) If key is contained in [from, to], then newKey will be set to new(elem(key)). (3) If key is greater than to, then newFrom will be set to new(elem(to)) + (key-to). If any of these calculated values are out of the range of the list [0, listSize-1], they will be truncated to fit into the list. (Note that the resulting newFrom is always equal to key if the data wasn't updated, but it doesn't have to be equal to key if the data was updated.) After setting the view position the anchor offset will automatically be set to 0. There are two special key values to allow scrolling to the top/bottom of the list, independently from the above rules: The key value 0xFFFE always positions the view to the top of the list. The key value 0xFFFF always positions the view to the bottom of the list.

As an example for the case in which the data was updated: old list {"a", "b", "c", "d", "e", "f"} with view snapshot ["c", "d"] with viewSize 2 and viewKey 2 new list {"b", "d", "f", "h", "j", "l"} (1) setViewPosition(0) => [from, to] is [2, 3], elem(from) is "c", new(elem(from)) is 1 => ["b", "d"] with ViewSnapshotPosition 6, listKey=0, anchorOffset=0. (2) setViewPosition(3) => [from, to] is [2, 3], elem(key) is "d", new(elem(key)) is 1 => ["d", "f"] with ViewSnapshotPosition 6, listKey=1, anchorOffset=0. (3) setViewPosition(4) => [from, to] is [2, 3], elem(to) is "d", new(elem(d)) is 1 => ["f", "h"] with ViewSnapshotPosition 6, listKey=2, anchorOffset=0.

Parameter	Туре	Description
setViewPosition_R_view	ViewId	identifies the view to apply this operation upon.
setViewPosition_R_key	ListKey	element to position the view upon, according to view policy.

7.1.10 setViewSize

requestSetViewSize

adjust the view size. It is allowed to set view size to a larger value than the actual size of the list, but less or equal than the maximum size of the list. The implementation may limit the maximum view size for resource reasons. After adjusting the window size the client must receive an update.

Parameter	Туре	Description
setViewSize_R_view	ViewId	identifies the view to apply this operation upon.
setViewSize_R_new_size	ViewSize	new view size

responseSetViewSize

adjust the view size. It is allowed to set view size to a larger value than the actual size of the list, but less or equal than the maximum size of the list. The implementation may limit the maximum view size for resource reasons. After adjusting the window size the client must receive an update.

Parameter Type Description



7.1.11 listSize

informationListSize		
informs the client abo	out changes of the list size.	
Parameter	Туре	Description
listSize_id	ListId	list id related to the list size update
listSize_size	ListSize	changed list size information

7.1.12 viewUpdate

informationViewUpdate

indicate to the client that the underlying list of a certain view has changed Whenever elements get inserted/removed or the content of element gets changed, the size or the sorting order of a list might change. This might influence the current view and especially the position of the anchor element in the list. To allow a client to react on such changes in an approapriate manner, the viewUpdate broadcast will provide all necessary information to its client. It is up to the client to reposition the view to its needs based on the provided information, using the methods setViewPosition or setViewAnchor.

Parameter	Туре	Description
viewUpdate_view	ViewId	unique identifier of a view
viewUpdate_size	ListSize	current size of the underlying list
viewUpdate_viewChanged	boolean	at least one element of the currently active view snapshot has changed
viewUpdate_listChanged	boolean	at least one element of the list has changed (this might lead to a different new view snapshot)

7.1.13 Error

Error	
This is the type for error responses.	
Literal	Description
ERROR_TrailError_INVALID	
ERROR_TrailError_GET_SETTINGS_ERROR	
ERROR_TrailError_SET_SETTINGS_ERROR	
ERROR_TrailError_GET_DETAILS_ERROR	
ERROR_ListError_INVALID	



Error	
ERROR_ListError_INVALID_LIST_ID	
ERROR_ListError_INVALID_VIEW	
ERROR_ListError_INVALID_PARAMETER	
ERROR_ListError_SIZE_LIMIT_EXCEEDED	
ERROR_ListError_OUT_OF_RESSOURCES	
ERROR_ListError_OUT_OF_RANGE_POSITION	
ERROR_ListError_POLICY_DENIED	

7.2 org_harman_nav_ctrl_ln_TrailTypes

Interface Version: 1.0

7.2.1 SettingKey

SettingKey		
Literal	Description	
SettingKey_RECORDING_ENABLED		
SettingKey_MAX_TRAIL_LENGTH		

Referenced by: org_harman_nav_ctrl_ln_TrailTypes::SettingKeys

7.2.2 SettingKeys

Vector of element type SettingKey

Referenced by : org_harman_nav_ctrl_ln_Trails::getSettings

7.2.3 SettingValue

SettingValue			
Variant Element	Туре	Description	
boolValue	boolean		
distance	Distance		



7.2.4 Settings

Settings			
Map between settings and values.			
Map Element Type		Description	
keyType	SettingKey		
valueType	SettingValue		

Referenced by : org_harman_nav_ctrl_ln_Trails::getSettings, org_harman_nav_ctrl_ln_Trails::setSettings

7.2.5 TrailDescription

TrailDescription			
Structure Element	Туре	Description	
handle	TrailHandle		
description	String		

Referenced by: org_harman_nav_ctrl_ln_TrailTypes::TrailDescriptions

7.2.6 TrailDescriptions

Vector of element type TrailDescription

Referenced by : org_harman_nav_ctrl_ln_Trails::getViewData

7.2.7 TrailDetails

TrailDetails			
Trail object.			
Structure Element	Туре	Description	
handle	TrailHandle		
timeStart	Timestamp		
timeEnd	Timestamp		
posStart	Coordinate3D		



TrailDetails		
posEnd	Coordinate3D	
length	Distance	

7.2.8 TrailError

TrailError		
Literal	Description	
TrailError_BasicEnum_INVALID		
TrailError_GET_SETTINGS_ERROR		
TrailError_SET_SETTINGS_ERROR		
TrailError_GET_DETAILS_ERROR		

7.2.9 TrailHandle

Alias of actual type: UInt32

Referenced by: org_harman_nav_ctrl_ln_TrailTypes::TrailDescription, org_harman_nav_ctrl_ln_TrailTypes::TrailDetails, org_harman_nav_ctrl_ln_TrailDetails, org_harman_nav_ctrl_ln_TrailDetails, org_harman_nav_ctrl_ln_TrailDetails, org_h

7.2.10 TrailHandles

Vector of element type TrailHandle

Referenced by: org_harman_nav_ctrl_ln_Trails::getDetails

7.2.11 Trails

Trails			
Map between trail handle and its object.			
Map Element Type Description			
keyType	TrailHandle		
valueType	TrailDetails	Trail object.	

Referenced by : org_harman_nav_ctrl_ln_Trails::getDetails



8 LocationMemory Service

8.1 org_harman_nav_ctrl_memory_LocationMemory

Interface Version: 5.0

8.1.1 addltem

requestAddItem		
add a exsisting Location Memory Item to another list.		
Parameter	Туре	Description
addItem_R_sourceViewId	ViewId	source view id which is where this source item comes from.
addItem_R_sourceItemKey	ViewKey	source item key which has to be added
addItem_R_destinationListId	ListId	destination list where this item place to

responseAddItem			
add a exsisting Location Memory Item to another list.			
Parameter Type Description		Description	
addItem_itemId	Titemid	Item id	

8.1.2 addItemLocation

requestAddItemLocation		
add a new Location Memory Item to a list. If a new item is created a name for the item is created.		
Parameter Type Description		
addItemLocation_R_listId	ListId	list to add the item to.
addItemLocation_R_location	LocationItem	location to add

responseAddItemLocation		
add a new Location Memory Item to a list. If a new item is created a name for the item is created.		
Parameter Type Description		
addItemLocation_itemId	Titemid	Item id



8.1.3 createSpeechFile

requestCreateSpeechFile		
create an ECO file with the list entries The file is saved as path/listname.eco		
Parameter Type Description		
createSpeechFile_R_listId	ListId	Identifies the list the file should be generated for.
createSpeechFile_R_path	String	path where the file should be saved

responseCreateSpeechFile		
create an ECO file with the list entries The file is saved as path/listname.eco		
Parameter Type Description		

8.1.4 createView

requestCreateView

create a new view to the mother array. This view will be maintained until the client uses destroyView, unsubscribes or service/proxy exit. After creating a view the client must receive an update. Only one created view is allowed to modify the list entries.

Parameter	Туре	Description
createView_R_list	ListId	list to create the view upon.
createView_R_viewsize	ViewSize	individual size of the requested view. The max size could be smaller or equal than max list size
createView_R_position	ListKey	element to position the view upon, according to view policy.

responseCreateView

create a new view to the mother array. This view will be maintained until the client uses destroyView, unsubscribes or service/proxy exit. After creating a view the client must receive an update. Only one created view is allowed to modify the list entries.

Parameter	Туре	Description
createView_view		view identification used to distinguish several instances of a view for one client. It is never changed by the service nor the client.



8.1.5 deleteView

requestDeleteView		
delete the given view inst	ance	
Parameter	Туре	Description
deleteView_R_view	ViewId	identifies the view to apply this operation upon.

responseDeleteView		
delete the given view instance		
Parameter	Туре	Description

8.1.6 exportFullList

requestExportFullList		
export the entire list to an external source		
Parameter	Туре	Description
exportFullList_R_source	EExternalSources	where to store the export

responseExportFullList		
export the entire list to an external source		
Parameter	Туре	Description
exportFullList_success	boolean	successfull export.
exportFullList_message	String	a message to help identify the particular error type which can be used for the HMI.

8.1.7 filterView

requestFilterView

The items of the given view is filtered by the string input. As this funcationality was not designed in ListViewBase, the first version implementation is to response the items. Future, the funcationality will be updated with the view data updated .. i.e. the view is updated and only matching items remain in the view. If no match is found then the result will be an empty view. An empty searchString will restore the view.

Parameter	Туре	Description



requestFilterView		
filterView_R_view	ViewId	view identification
filterView_R_pattern	String	pattern to match the items
filterView_R_deepMatch	boolean	Extension to match item internal data (currently not supported)

responseFilterView

The items of the given view is filtered by the string input. As this funcationality was not designed in ListViewBase, the first version implementation is to response the items. Future, the funcationality will be updated with the view data updated .. i.e. the view is updated and only matching items remain in the view. If no match is found then the result will be an empty view. An empty searchString will restore the view.

Parameter	Туре	Description
filterView_listItems	THBVector_Item_	result items based on the search string

8.1.8 getActiveAutoNavItems

requestGetActiveAutoNavItems getActiveAutoNavItems for the Fixed_Favorite list to check which items are at the current time in an auto-navigate timeslot (i.e. return list of keys). Parameter getActiveAutoNavItems_R_viewiewId Type Description Identifies the view this result list is applied for.

responseGetActiveAutoNavItems		
getActiveAutoNavItems for the Fixed_Favorite list to check which items are at the current time in an auto-navigate timeslot (i.e. return list of keys).		
Parameter	Туре	Description
getActiveAutoNavItems_result	RósiKeny	list key of the first entry into the received result list.
getActiveAutoNavItems_listIte	ms-IBVector_Item_	result items based on the requested position and key what is related to the given view id.

8.1.9 getActiveItems

requestGetActiveItems

return all items with matching timeslot (to current time) Empty list is returned if none match.



requestGetActiveItems		
Parameter	Туре	Description
getActiveItems_R_view	ViewId	view identification

responseGetActiveItems		
return all items with matching timeslot (to current time) Empty list is returned if none match.		
Parameter	Туре	Description
getActiveItems_itemKeys	THBVector_ViewKey_	items which are currently active

8.1.10 getItemDetails

requestGetItemDetails		
return all data for a Location Memory Item.		
Parameter Type Description		
getItemDetails_R_view	ViewId	view identification
getItemDetails_R_itemKey	ViewKey	item key to retrieve the details for

responseGetItemDetails			
return all data for a Location Memory Item.			
Parameter	Туре	Description	
getItemDetails_location	LocationItem	location details	

8.1.11 getItemDetailsExt

requestGetItemDetailsExt			
return all data for a Location Memory items.			
Parameter	Туре	Description	
getItemDetailsExt_R_items	UniqueItemIdList		

responseGetItemDetailsExt			
return all data for a Location Memory items.			
Parameter	Туре	Description	
getItemDetailsExt_locations	LocationList	location details	



8.1.12 getListSize

requestGetListSize		
get the current number of contained elements in the given list. This should be used create a view with a view size which has to be smaller or equal then size of the resulted list size. @see createView		
Parameter Type Description		
getListSize_R_list	ListId	

responseGetListSize		
get the current number of contained elements in the given list. This should be used create a view with a view size which has to be smaller or equal then size of the resulted list size. @see createView		
Parameter Type Description		
getListSize_size	ListSize	

8.1.13 getResultList

requestGetResultList		
getResultList		
Parameter	Туре	Description
getResultList_R_view	ViewId	Identifies the view this result list is applied for.

responseGetResultList		
getResultList		
Parameter	Туре	Description
getResultList_snapshotPos	ViewSnapshotPosition	information how the item view snapshot is positioned within the list
getResultList_listItems	THBVector_Item_	result items based on the requested position and key what is related to the given view id.

8.1.14 getSortOrder

requestGetSortOrder	
retrieve the sort order of a view instance	



requestGetSortOrder		
Parameter Type Description		
getSortOrder_R_view	ViewId	identifies the view to apply this operation upon.

responseGetSortOrder		
retrieve the sort order of a view instance		
Parameter	Туре	Description
getSortOrder_order	SortOption	the sort order currently used for this view instance.

8.1.15 importFullList

requestImportFullList		
import the entire list from an external source		
Parameter	Туре	Description
importFullList_R_source	EExternalSources	where to initiate the import from

responselmportFullList		
import the entire list from a	n external source	
Parameter	Туре	Description
importFullList_success	boolean	successfull import.
importFullList_message	String	a message to help identify the particular error type which can be used for the HMI.

8.1.16 importLocationItemList

requestImportLocationItemList		
importa given list of tuples (name, location) into a destination list. Typical use-case download of POIs from a server, or USB stick bulk import.		
Parameter	Туре	Description
importLocationItemList_R_des	t lnatio nListId	the destination list, see availableLists attribute, for example "FAVORITES"
importLocationItemList_R_item	nElsBVector_NameLocationIten	nlist of of tuples (name, location) to be imported



response Import Location Item List

importa given list of tuples (name, location) into a destination list. Typical use-case download of POIs from a server, or USB stick bulk import.

Parameter	Туре	Description
	1 .	•

8.1.17 removeAll

requestRemoveAll		
remove all items which are related to the given List id.		
Parameter	Туре	Description
removeAll_R_list	ListId	list to create the view upon.

responseRemoveAll	
remove all items which are related to the given List id.	
Parameter Type Description	

8.1.18 removeltem

requestRemoveItem

remove one Item which is based on the given itemKey and a given list id. If the item is available in the given list it is removed from that list. If it is only available in that list it is completely removed(set listId with invalid value).

Parameter	Туре	Description
removeItem_R_view	ViewId	Identifies the list the item is removed from.
removeItem_R_itemKey	ViewKey	item key which is used
removeItem_R_listId	ListId	list the item is removed from

responseRemoveItem

remove one Item which is based on the given itemKey and a given list id. If the item is available in the given list it is removed from that list. If it is only available in that list it is completely removed(set listId with invalid value).

,		
Parameter	Туре	Description



8.1.19 setItemName

requestSetItemName		
set the name of an item.		
Parameter	Туре	Description
setItemName_R_listId	ListId	list to set the name for the item to.
setItemName_R_itemId	Titemid	Item id(uniq during LC)
setItemName_R_name	TItemName	new name to use

responseSetItemName		
set the name of an item.		
Parameter	Туре	Description

8.1.20 setLocationItem

requestSetLocationItem			
change the item			
Parameter	Туре	Description	
setLocationItem_R_view	ViewId	view identification	
setLocationItem_R_itemKey	ViewKey	Item to manipulate	
setLocationItem_R_location	LocationItem	location to add	

responseSetLocationIte	n	
change the item		
Parameter	Туре	Description
setLocationItem_item	Item	basic data of item (with proposed name)

8.1.21 setSortOrder

requestSetSortOrder

configure the sort order of a view instance. Changing the sort order of a view may trigger a view update.



requestSetSortOrder		
Parameter	Туре	Description
setSortOrder_R_view	ViewId	identifies the view to apply this operation upon.
setSortOrder_R_order	SortOption	the sort order to use for this view instance.

responseSetSortOrder		
configure the sort order of a vieupdate.	ew instance. Changing the sort	order of a view may trigger a view
Parameter Type Description		Description

8.1.22 setTimeslot

requestSetTimeslot		
change the timeslot of an item		
Parameter	Туре	Description
setTimeslot_R_view	ViewId	view identification
setTimeslot_R_itemKey	ViewKey	Item to manipulate
setTimeslot_R_timeslot	Timeslot	new timeslot to set

responseSetTimeslot		
change the timeslot of an item		
Parameter Type Description		

8.1.23 setViewAnchor

requestSetViewAnchor

set a stable element inside the current view snapshot. The client should use an available snapshot of a view to maintain focused elements within the view if possible, and change the view position only if an element to be focused is outside of the given view. A snapshot is generated whenever querying the data contained in a view. Together with that data, the ViewSnapshotPosition is provided. The initial snapshot of the view is always [0, min(viewSize-1, listSize-1)] with anchor offset 0. When creating a new view snapshot, the last call of setViewPosition or setViewAnchor (whichever was the last one) will be the relevant information to reposition the new view snapshot. If setViewAnchor was the last call, the



requestSetViewAnchor

anchor element of the old view snapshot is used for repositioning. (This method only needs to be used if the current view snapshot is outdated because the list has been updated.)

The following rules are applied to set the position of the new view snapshot [newFrom, newTo], given a snapshot [from, to] and anchor offset aOff: Let elem(k) denote the element at key k in the old snapshot and new(e) denote the key the element e will have (would have if deleted) in the new snapshot (see also examples below). newFrom is set to new(elem(from+aOff)) - aOff. If any of these calculated values are out of the range of the list [0, listSize-1], they will be truncated to fit into the list. As a consequence, whenever possible, the anchor element of the old snapshot will be at the same offset within the new snapshot.

As an example for the case in which the data was updated: old list {"a", "b", "c", "d", "e", "f"} with view snapshot ["c", "d"] with viewSize 2 and viewKey 2 new list {"b", "d", "f", "h", "j", "l"} setViewAnchor(0) => elem(from+aOff) is "c", new(elem(from+aOff)) is 1 ("c" would be inserted at index 1) => ["d", "f"] with ViewSnapshotPosition 6, listKey=1, anchorOffset=0. setViewAnchor(1) => elem(from+aOff) is "d", new(elem(from+aOff)) is 1 => ["b", "d"] with ViewSnapshotPosition 6, listKey=0, anchorOffset=1.

Parameter	Туре	Description
setViewAnchor_R_view	ViewId	identifies the view to apply this operation upon.
setViewAnchor_R_anchor	AnchorOffset	relative anchor position in the view, referenced from ListKey Please note: only positive values and 0 are allowed

8.1.24 setViewPosition

requestSetViewPosition

set the absolute view position to element key. The client should use an available snapshot of a view to maintain focused elements within the view if possible, and change the view position only if an element to be focused is outside of the given view. A snapshot is generated whenever querying the data contained in a view. Together with that data, the ViewSnapshotPosition is provided. The initial snapshot of the view is always [0, min(viewSize-1, listSize-1)]. When creating a new view snapshot, the last call of setViewPosition or setViewAnchor (whichever was the last one) will be the relevant information to reposition the new view snapshot. If setViewPosition was the last call, the view is moved such that the provided key refers to the absolute position on the current snapshot of the view. (This becomes important if the current view snapshot is outdated because the list has been updated.)

The following rules are applied to set the position of the new view snapshot [newFrom, newTo], given a snapshot [from, to]: Let elem(k) denote the element at key k in the old snapshot and new(e) denote the key the element e will have (would have if deleted) in the new snapshot (see also examples (1)-(3) below). (1) If key is less than from, then newFrom will be set to new(elem(from)) - (from-key). (2) If key is contained in [from, to], then newKey will be set to new(elem(key)). (3) If key is greater than to, then newFrom will be set to new(elem(to)) + (key-to). If any of these calculated values are out of the range of the list [0, listSize-1], they will be truncated to fit into the list. (Note that the resulting newFrom is always equal to key if the data wasn't updated, but it doesn't have to be equal to key if the data was updated.) After setting the view position the anchor offset will automatically be set to 0. There are two special key values to allow scrolling to the top/bottom of the list, independently from the above rules:



requestSetViewPosition

The key value 0xFFFE always positions the view to the top of the list. The key value 0xFFFF always positions the view to the bottom of the list.

As an example for the case in which the data was updated: old list {"a", "b", "c", "d", "e", "f"} with view snapshot ["c", "d"] with viewSize 2 and viewKey 2 new list {"b", "d", "f", "h", "j", "l"} (1) setViewPosition(0) => [from, to] is [2, 3], elem(from) is "c", new(elem(from)) is 1 => ["b", "d"] with ViewSnapshotPosition 6, listKey=0, anchorOffset=0. (2) setViewPosition(3) => [from, to] is [2, 3], elem(key) is "d", new(elem(key)) is 1 => ["d", "f"] with ViewSnapshotPosition 6, listKey=1, anchorOffset=0. (3) setViewPosition(4) => [from, to] is [2, 3], elem(to) is "d", new(elem(d)) is 1 => ["f", "h"] with ViewSnapshotPosition 6, listKey=2, anchorOffset=0.

Parameter	Туре	Description
setViewPosition_R_view	ViewId	identifies the view to apply this operation upon.
setViewPosition_R_key	ListKey	element to position the view upon, according to view policy.

8.1.25 setViewSize

requestSetViewSize

adjust the view size. It is allowed to set view size to a larger value than the actual size of the list, but less or equal than the maximum size of the list. The implementation may limit the maximum view size for resource reasons. After adjusting the window size the client must receive an update.

Parameter	Туре	Description
setViewSize_R_view	ViewId	identifies the view to apply this operation upon.
setViewSize_R_new_size	ViewSize	new view size

responseSetViewSize

adjust the view size. It is allowed to set view size to a larger value than the actual size of the list, but less or equal than the maximum size of the list. The implementation may limit the maximum view size for resource reasons. After adjusting the window size the client must receive an update.

Parameter	Туре	Description
	3.	•

8.1.26 listSize

informationListSize

informs the client about changes of the list size.



informationListSize		
Parameter	Туре	Description
listSize_id	ListId	list id related to the list size update
listSize_size	ListSize	changed list size information

8.1.27 viewUpdate

informationViewUpdate

indicate to the client that the underlying list of a certain view has changed Whenever elements get inserted/removed or the content of element gets changed, the size or the sorting order of a list might change. This might influence the current view and especially the position of the anchor element in the list. To allow a client to react on such changes in an approapriate manner, the viewUpdate broadcast will provide all necessary information to its client. It is up to the client to reposition the view to its needs based on the provided information, using the methods setViewPosition or setViewAnchor.

Parameter	Туре	Description
viewUpdate_view	ViewId	unique identifier of a view
viewUpdate_size	ListSize	current size of the underlying list
viewUpdate_viewChanged	boolean	at least one element of the currently active view snapshot has changed
viewUpdate_listChanged	boolean	at least one element of the list has changed (this might lead to a different new view snapshot)

8.1.28 aavailableConfiguration

Attribute aavailableConfiguration	
contains all available View Configuration to create view instances upon	
Type Notification Type	
Configurations	ON_CHANGE

8.1.29 aavailableLists

Attribute aavailableLists	
The list ids which can be queried from this interface	
Type Notification Type	
THBVector_ListId_	ON_CHANGE



8.1.30 Error

Error		
This is the type for error responses.		
Literal	Description	
ERROR_ListError_INVALID		
ERROR_ListError_INVALID_LIST_ID		
ERROR_ListError_INVALID_VIEW		
ERROR_ListError_INVALID_PARAMETER		
ERROR_ListError_SIZE_LIMIT_EXCEEDED		
ERROR_ListError_OUT_OF_RESSOURCES		
ERROR_ListError_OUT_OF_RANGE_POSITION		
ERROR_ListError_POLICY_DENIED		
ERROR_LocationMemoryError_INVALID		
ERROR_LocationMemoryError_INVALID_LIST_ID		
ERROR_LocationMemoryError_INVALID_VIEW		
ERROR_LocationMemoryError_INVALID_PARAME	TER	
ERROR_LocationMemoryError_SIZE_LIMIT_EXCE	EDED	
ERROR_LocationMemoryError_OUT_OF_RESSO	URCES	
ERROR_LocationMemoryError_OUT_OF_RANGE	POSITION	
ERROR_LocationMemoryError_POLICY_DENIED		
ERROR_LocationMemoryError_INVALID_PATH		
ERROR_LocationMemoryError_PATH_NOT_WRIT	ABLE	
ERROR_LocationMemoryError_EMPTY_LIST		

8.1.31 THBVector_Item_

result items based on the requested position and key what is related to the given view id. Vector of element type **Item**

Referenced by: org_harman_nav_ctrl_memory_LocationMemory::getResultList, org_harman_nav_ctrl_memory_LocationMemory::getActiveAutoNavItems, org_harman_nav_ctrl_memory_LocationMemory::filterView

8.1.32 THBVector_ListId_

The list ids which can be queried from this interface Vector of element type ListId

Referenced by : org_harman_nav_ctrl_memory_LocationMemory::aavailableLists



8.1.33 THBVector_NameLocationItem_

list of of tuples (name, location) to be imported Vector of element type NameLocationItem

Referenced by: org_harman_nav_ctrl_memory_LocationMemory::importLocationItemList

8.1.34 THBVector_ViewKey_

items which are currently active Vector of element type ViewKey

Referenced by: org_harman_nav_ctrl_memory_LocationMemory::getActiveItems

8.2 org_harman_nav_ctrl_memory_LocationMemory

Interface Version: 3.4

8.2.1 Configurations

Configurations		
Configuration settings		
Map Element	Туре	Description
keyType	EProvidedListTypes	
valueType	ListSetting	supported Location Memory Listsettings

Referenced by: org_harman_nav_ctrl_memory_LocationMemory::aavailableConfiguration

8.2.2 Dayslot

Dayslot		
Definition of a dayslot. User must ensure that start is less than end (Otherwise it would be undefined if previous/next day is meant)		
Structure Element Type Description		
active	boolean	if slot is active
start_min	UInt16	start time in minutes since midnight, hour = start_min / 60 , min = start_min % 60
end_min	UInt16	end time in minutes since midnight



Referenced by: org_harman_nav_ctrl_memory_LocationMemoryTypes::DayslotList

8.2.3 DayslotList

Array for the timeslot for each day, 7 slots starting with monday. Vector of element type Dayslot

Referenced by: org_harman_nav_ctrl_memory_LocationMemoryTypes::Timeslot

8.2.4 EExternalSources

EExternalSources	
Literal	Description
EExternalSources_E_EXTERNAL_MEDIA	media storage

Referenced by : org_harman_nav_ctrl_memory_LocationMemory::importFullList, org_harman_nav_ctrl_memory_LocationMemory::exportFullList

8.2.5 EltemType

EltemType		
Literal	Description	
EltemType_E_LM_TYPE_POI		
EltemType_E_LM_TYPE_ADDRESS		
EltemType_E_LM_TYPE_CONTACT		
EltemType_E_LM_TYPE_TOUR		
EltemType_E_LM_TYPE_EMPTY		

Referenced by : org_harman_nav_ctrl_memory_LocationMemoryTypes::Location, org_harman_nav_ctrl_memory_LocationMemoryTypes::LocationItem, org_harman_nav_ctrl_memory_LocationMemoryTypes::Item

8.2.6 EProvidedListTypes

EProvidedListTypes	



EProvidedListTypes		
Literal	Description	
EProvidedListTypes_E_LIST_RECENT	recent list, only fifo sorting	
EProvidedListTypes_E_LIST_FAVOURITES	favorite list, alphabetical	
EProvidedListTypes_E_LIST_FIXED_FAVOURITE	Sixed favorites, only custom sorted (fixed)	
EProvidedListTypes_E_LIST_WEATHER		

 $Referenced\ by: org_harman_nav_ctrl_memory_Location Memory Types:: Tltem Membership$

8.2.7 Item

short item data			
Structure Element	Туре	Description	
id	Titemid		
name	TItemName		
type	EltemType		
lists	TItemMembership		

Referenced by: org_harman_nav_ctrl_memory_LocationMemory::setLocationItem, org_harman_nav_ctrl_memory_LocationMemory::THBVector_Item_, org_harman_nav_ctrl_memory_LocationMemoryTypes::ItemList

8.2.8 ItemList

List of Item. Vector of element type Item

8.2.9 ListSetting

ListSetting		
supported Location Memory Listsettings		
Structure Element Type Description		
listId	ListId	
availableSortings	THBVector_SortOption_	
policy	ModificationPolicy	



ListSetting		
maxListSize	UInt32	

8.2.10 Location

Location Description of a single location enriched with a type.		
type	EltemType	Type as tour can consist of Poi,Contact,Address
address	Address	Location from LocationInputTypes
poiDetails	SearchResultDetails	details for POIs

Referenced by : org_harman_nav_ctrl_di_OneBoxSearch::getEntry, org_harman_nav_ctrl_memory_LocationMemoryTypes::LocationList

8.2.11 LocationItem

All data for a location		
type	EltemType	type of location
locations	LocationList	list of locations
time	Timeslot	used timeslot, used only for fixed favorite list

Referenced by: org_harman_nav_ctrl_memory_LocationMemory::addItemLocation, org_harman_nav_ctrl_memory_LocationMemory::getItemDetails, org_harman_nav_ctrl_memory_LocationMemory::setLocationItem, org_harman_nav_ctrl_memory_LocationMemoryTypes::LocationItemList, org_harman_nav_ctrl_memory_LocationMemoryTypes::NameLocationItem

8.2.12 LocationItemList

List of LocationItem. Vector of element type LocationItem



8.2.13 LocationList

List of destinations. A regular address will be a single entry, a contact can consist of home and office address, a poi of postal and entry address, a tour of several (concrete) destinations. Vector of element type **Location**

Referenced by : org_harman_nav_ctrl_di_OneBoxSearch::requestResultList, org_harman_nav_ctrl_memory_LocationMemory::getItemDetailsExt, org_harman_nav_ctrl_memory_LocationMemoryTypes::LocationItem

8.2.14 LocationMemoryError

LocationMemoryError		
Literal	Description	
LocationMemoryError_ListError_INVALID_LIST_ID	occurs if the list id was invalid.	
LocationMemoryError_ListError_INVALID_VIEW	view identification used to distinguish several instances of a view for one client. It is never changed by the service nor the client.	
LocationMemoryError_ListError_INVALID_PARAM	TOTOTE Birs if one of the provided parameters was not acceptable.	
LocationMemoryError_ListError_SIZE_LIMIT_EXCI	বৈটেটাড়ি if the implementation can not provide such large views.	
LocationMemoryError_ListError_OUT_OF_RESSO	becares if there are not enough resources available to create another view (e.g. memory).	
LocationMemoryError_ListError_OUT_OF_RANGE	ୁଜ୍ୟୁ:TiਿOthere is request a position which is not available	
LocationMemoryError_ListError_POLICY_DENIED	Some policy could not be executed.	
LocationMemoryError_INVALID_PATH	path is not existing.	
LocationMemoryError_PATH_NOT_WRITABLE	path is not writable.	
LocationMemoryError_EMPTY_LIST	occurs if the list was empty.	

8.2.15 NameLocationItem

NameLocationItem		
A tuple containing the user define name in the list. Example: location = POI "Pasing Arcaden" with address: Josef-Felder-Strae 53, 81241 Mnchen, Deutschland name = a user given name like "Mein Lieblingsplatz"		
Structure Element Type Description		
name	TItemName	User given name for a location in the list
location	LocationItem	the location saved in the list



Referenced by: org_harman_nav_ctrl_memory_LocationMemory::THBVector_NameLocationItem_

8.2.16 THBVector_SortOption_

Vector of element type SortOption

Referenced by: org_harman_nav_ctrl_memory_LocationMemoryTypes::ListSetting

8.2.17 Titemid

Unick Alias of actual type: UInt16

Referenced by: org_harman_nav_ctrl_memory_LocationMemory::addItem, org_harman_nav_ctrl_memory_LocationMemory::addItemLocation, org_harman_nav_ctrl_memory_LocationMemory::setItemName, org_harman_nav_ctrl_memory_LocationMemoryTypes::Item

8.2.18 TltemMembership

shows on which lists an item is present Vector of element type EProvidedListTypes

Referenced by : org_harman_nav_ctrl_memory_LocationMemoryTypes::Item

8.2.19 TitemName

Alias of actual type: String

Referenced by: org_harman_nav_ctrl_memory_LocationMemory::setItemName, org_harman_nav_ctrl_memory_LocationMemoryTypes::NameLocationItem, org_harman_nav_ctrl_memory_LocationMemoryTypes::Item

8.2.20 Timeslot

Timeslot		
Definition of a timeslot		
Structure Element	Туре	Description
active	boolean	if timeslot is currently active
dayslots	DayslotList	slots for each day, 0 = Monday

Referenced by : org_harman_nav_ctrl_memory_LocationMemory::setTimeslot, org_harman_nav_ctrl_memory_LocationMemoryTypes::LocationItem



8.2.21 UniqueltemId

Absolute unique (list independent) item ID, blackbox for the client Alias of actual type: Buffer

8.2.22 UniqueltemIdList

List of item ids Vector of element type UniqueItemId

 $Referenced\ by: org_harman_nav_ctrl_memory_LocationMemory::getItemDetailsExt$

8.2.23 ViewKeyList

List of Item. Vector of element type ViewKey



9 Positioning Service

9.1 org_harman_nav_ctrl_Positioning

Interface Version: 0.2

9.1.1 getAddress

requestGetAddress		
getAddress = This method returns the current address		
Parameter	Туре	Description
getAddress_R_valuesToRetur	nTHBVector_AddressItemKey_	

responseGetAddress			
getAddress = This method	d returns the current address		
Parameter	Туре	Description	
getAddress_address	AddressItemDict		

9.1.2 getCurrentRoadAttributes

requestGetCurrentRoadAttributes		
getCurrentRoadAttributes = This method returns the current road attributes.		
Parameter Type Description		Description
getCurrentRoadAttributes_R_k	Rys adAttributeKeys	

responseGetCurrentRoadAttributes			
getCurrentRoadAttributes = This method returns the current road attributes.			
Parameter Type Description			
getCurrentRoadAttributes_dict	RoadAttributeDict		

9.1.3 getPosition

requestGetPosition
getPosition = This method returns the current position



requestGetPosition		
Parameter	Туре	Description
getPosition_R_valuesToReturn	THBVector_PositionItemKey_	

responseGetPosition		
getPosition = This method returns the current position		
Parameter	Туре	Description
getPosition_position	PositionItemDict	

9.1.4 getStatus

requestGetStatus		
getStatus = This method return	ns the current status	
Parameter	Туре	Description
getStatus_R_valuesToReturn	THBVector_PositionStatus_	

responseGetStatus		
getStatus = This method returns the current status		
Parameter	Туре	Description
getStatus_status	PositionStatusDict	

9.1.5 addressUpdate

informationAddressUpdate		
addressUpdate = This signal is called to notify a client application that the current address changed		
Parameter Type Description		
addressUpdate_changedValue	AddressItemDict	

9.1.6 currentRoadAttributesChanged

informationCurrentRoadAttributesChanged		
currentRoadAttributesChanged changed.	d = This signal is emitted when	the current road attributes have
Parameter	Туре	Description



informationCurrentRoadAttributesChanged	
currentRoadAttributesChangedRchat/AgedVattlest	

9.1.7 offRoadPositionChanged

informationOffRoadPosition	Changed	
offroadPositionChanged = This signal is emitted when the heading and the distance to the closest point on the road network changes		
Parameter	Туре	Description
offRoadPositionChanged_dista	ablomet32	distance = distance in meters to the closest point on the road network
offRoadPositionChanged_dire	chird/8/2	direction = direction in degrees relatively to the closest point on the road network. Range [0:360]

9.1.8 positionUpdate

informationPositionUpdate			
positionUpdate = This signal is called to notify a client application of a position change. The update frequency is implementation specific. The maximal allowed frequency is 10Hz			
Parameter Type Description			
positionUpdate_changedValue	₽ ositionItemDict		

9.1.9 statusUpdate

informationStatusUpdate		
statusUpdate = This signal is emitted to notify a client application that the current status changed		
Parameter Type		Description
statusUpdate_changedValues	PositionStatusDict	

9.1.10 agpsRTC

Attribute agpsRTC	
Real-time GPS clock corrected by leap-seconds.	
Туре	Notification Type



Attribute agpsRTC	
GpsTime	ON_CHANGE

9.1.11 THBVector_AddressItemKey_

Vector of element type AddressItemKey

Referenced by : org_harman_nav_ctrl_Positioning::getAddress

9.1.12 THBVector_PositionItemKey_

Vector of element type PositionItemKey

Referenced by : org_harman_nav_ctrl_Positioning::getPosition

9.1.13 THBVector_PositionStatus_

Vector of element type PositionStatus

Referenced by : org_harman_nav_ctrl_Positioning::getStatus

9.2 org_harman_nav_ctrl_PositioningTypes

Interface Version: 1.2

9.2.1 AddressItemDict

AddressItemDict			
Map Element	Туре	Description	
keyType	AddressItemKey		
valueType	AddressItemValue		

Referenced by : org_harman_nav_ctrl_Positioning::getAddress, org_harman_nav_ctrl_Positioning::addressUpdate

9.2.2 AddressItemKey

AddressItemKey	



AddressItemKey	
Literal	Description
AddressItemKey_BasicEnum_INVALID	
AddressItemKey_TIMESTAMP	TIMESTAMP type is CommonTypes.Timestamp.
AddressItemKey_COUNTRY	COUNTRY type is String.
AddressItemKey_COUNTRYCODE	COUNTRYCODE type is String.
AddressItemKey_STATE	STATE type is String.
AddressItemKey_CITY	CITY type is String.
AddressItemKey_STREET	STREET type is String.
AddressItemKey_ROAD_NUMBER	ROAD_NUMBER type is String.
AddressItemKey_HOUSENUMBER	HOUSENUMBER type is String.
AddressItemKey_HOUSENAME	HOUSENAME type is String.
AddressItemKey_CROSSING	CROSSING type is String.
AddressItemKey_DISTRICT	DISTRICT type is String.
AddressItemKey_TIMEZONE_OFFSET	TIMEZONE_OFFSET type is Int16.
AddressItemKey_DAYLIGHT_OFFSET	DAYLIGHT_OFFSET type is Int16.
AddressItemKey_MATCH_TYPE	MATCH_TYPE type is PositioningTypes.MatchMode.

Referenced by: org_harman_nav_ctrl_Positioning::THBVector_AddressItemKey_

9.2.3 AddressItemValue

AddressItemValue			
Variant Element	Туре	Description	
addressField	String		
offset	Int16		
timestamp	Timestamp		
matchMode	MatchMode		

9.2.4 EIntersection

Elntersection	
Literal	Description



EIntersection	
EIntersection_INTERSECT_NA	
EIntersection_INTERSECTION_JUNCTION	

 $Referenced\ by: org_harman_nav_ctrl_PositioningTypes::RoadAttributeValue$

9.2.5 ERoadClass

ERoadClass		
Literal	Description	
ERoadClass_BasicEnum_INVALID		
ERoadClass_ROADCLASS_GLOBAL		
ERoadClass_ROADCLASS_MAIN		
ERoadClass_ROADCLASS_REGIONAL		
ERoadClass_ROADCLASS_LOCAL		
ERoadClass_ROADCLASS_PRIVATE		

Referenced by : org_harman_nav_ctrl_PositioningTypes::RoadAttributeValue, org_harman_nav_ctrl_GuidanceTypes::ManeuverDetails, org_harman_nav_ctrl_GuidanceTypes::RoadInfo

9.2.6 ERoadType

ERoadType	
Literal	Description
ERoadType_ROADTYPE_NONE	
ERoadType_ROADTYPE_RAMP	
ERoadType_ROADTYPE_ROUNDABOUT	
ERoadType_ROADTYPE_PARALLEL	
ERoadType_ROADTYPE_SERVICE	
ERoadType_ROADTYPE_MAIN	
ERoadType_ROADTYPE_SQUARE	
ERoadType_ROADTYPE_PARKING	
ERoadType_ROADTYPE_PEDESTRIAN	



ERoadType	
ERoadType_ROADTYPE_CONTROLLED	

Referenced by : org_harman_nav_ctrl_PositioningTypes::RoadAttributeValue

9.2.7 ESpeedLimitStatus

ESpeedLimitStatus		
Literal	Description	
ESpeedLimitStatus_AVAILABLE		
ESpeedLimitStatus_NOT_AVAILABLE		
ESpeedLimitStatus_NO_LIMIT		

Referenced by : org_harman_nav_ctrl_PositioningTypes::SpeedLimit

9.2.8 ExitInfo

ExitInfo		
Structure Element	Туре	Description
present	boolean	

Referenced by: org_harman_nav_ctrl_PositioningTypes::RoadAttributeValue

9.2.9 GnnsFixStatus

GnnsFixStatus		
Literal	Description	
GnnsFixStatus_BasicEnum_INVALID		
GnnsFixStatus_NO_FIX		
GnnsFixStatus_TIME_FIX		
GnnsFixStatus_FIX_2D		



GnnsFixStatus	
GnnsFixStatus_FIX_3D	

9.2.10 GpsTime

GpsTime			
Structure Element	Туре	Description	
time	Timestamp		
quality	GpsTimeQuality		

Referenced by : org_harman_nav_ctrl_Positioning::agpsRTC

9.2.11 **GpsTimeQuality**

GpsTimeQuality		
Literal	Description	
GpsTimeQuality_GOOD		
GpsTimeQuality_POOR		

Referenced by : org_harman_nav_ctrl_PositioningTypes::GpsTime

9.2.12 MatchMode

MatchMode		
Literal	Description	
MatchMode_INVALID		
MatchMode_ON_ROAD		
MatchMode_OFF_ROAD		
MatchMode_ON_FERRY		
MatchMode_IN_TUNNEL		



MatchMode	
MatchMode_ON_CARPARK	

Referenced by: org_harman_nav_ctrl_PositioningTypes::AddressItemValue

9.2.13 PositionItemDict

PositionItemDict			
Map Element	Туре	Description	
keyType	PositionItemKey		
valueType	PositionItemValue		

Referenced by : org_harman_nav_ctrl_Positioning::getPosition, org_harman_nav_ctrl_Positioning::positionUpdate, org_harman_nav_ctrl_Simulation::setPosition

9.2.14 PositionItemKey

PositionItemKey		
Literal	Description	
PositionItemKey_PositionStatus_TIMESTAMP	TIMESTAMP type is CommonTypes.Timestamp.	
PositionItemKey_PositionStatus_GNSS_FIX_STAT	GSISS_FIX_STATUS type is PositioninTypes.GnnsFixStatus.	
PositionItemKey_PositionStatus_DR_STATUS	DR_STATUS type is Boolean.	
PositionItemKey_PositionStatus_MM_STATUS	MM_STATUS type is Boolean.	
PositionItemKey_PositionStatus_SIMULATION_MC	SIMULATION_MODE type is Boolean.	
PositionItemKey_LATITUDE	LATITUDE type is Double.	
PositionItemKey_LONGITUDE	LONGITUDE type is Double.	
PositionItemKey_ALTITUDE	ALTITUDE type is Double.	
PositionItemKey_HEADING	HEADING type is Double.	
PositionItemKey_SPEED	SPEED type is Double.	
PositionItemKey_CLIMB	CLIMB type is Double.	
PositionItemKey_NUM_SATELLITES_VISIBLE	NUM_SATELLITES_VISIBLE type is Int32.	
PositionItemKey_NUM_SATELLITES_USED	NUM_SATELLITES_USED type is Int32.	

Referenced by: org_harman_nav_ctrl_Positioning::THBVector_PositionItemKey_



9.2.15 PositionItemValue

PositionItemValue			
Variant Element	Туре	Description	
timestamp	Timestamp		
status	boolean		
fix	GnnsFixStatus		
doubleValue	double		
intValue	Int32		
measurement	UnitOfMeasurement		

9.2.16 PositionStatus

PositionStatus		
Literal	Description	
PositionStatus_BasicEnum_INVALID		
PositionStatus_TIMESTAMP	TIMESTAMP type is CommonTypes.Timestamp.	
PositionStatus_GNSS_FIX_STATUS	GNSS_FIX_STATUS type is PositioninTypes.GnnsFixStatus.	
PositionStatus_DR_STATUS	DR_STATUS type is Boolean.	
PositionStatus_MM_STATUS	MM_STATUS type is Boolean.	
PositionStatus_SIMULATION_MODE	SIMULATION_MODE type is Boolean.	

Referenced by : org_harman_nav_ctrl_Positioning::THBVector_PositionStatus_

9.2.17 PositionStatusDict

PositionStatusDict			
Map Element	Туре	Description	
keyType	PositionStatus		
valueType	PositionStatusValue		

Referenced by : org_harman_nav_ctrl_Positioning::getStatus, org_harman_nav_ctrl_Positioning::statusUpdate



9.2.18 PositionStatusValue

PositionStatusValue			
Variant Element	Туре	Description	
statusValue	boolean		
fixStatus	GnnsFixStatus		
timestanp	Timestamp		

9.2.19 RoadAttributeDict

RoadAttributeDict			
Map Element	Туре	Description	
keyType	RoadAttributeKey		
valueType	RoadAttributeValue		

 $\label{lem:condition} Referenced\ by: org_harman_nav_ctrl_Positioning::getCurrentRoadAttributes, org_harman_nav_ctrl_Positioning::currentRoadAttributesChanged$

9.2.20 RoadAttributeKey

RoadAttributeKey		
Literal	Description	
RoadAttributeKey_BasicEnum_INVALID		
RoadAttributeKey_ROAD_CLASS	ROAD_CLASS type is PositioningTypes.ERoadClass.	
RoadAttributeKey_ROAD_TYPE	ROAD_TYPE type is PositioningTypes.ERoadType.	
RoadAttributeKey_CONTROLLED_ACCESS	CONTROLLED_ACCESS type is Boolean.	
RoadAttributeKey_URBAN	URBAN type is Boolean.	
RoadAttributeKey_SPEED_LIMIT	SPEED_LIMIT type is Float with speed in km per hour.	
RoadAttributeKey_LEFT_HAND_TRAFFIC	LEFT_HAND_TRAFFIC type is Boolean.	
RoadAttributeKey_INTERSECTION_TYPE	INTERSECTION_TYPE type is PositioningTypes.EIntersection.	
RoadAttributeKey_EXIT_INFO	EXIT_INFO type is PositioningTypes.ExitInfo.	



Referenced by : org_harman_nav_ctrl_PositioningTypes::RoadAttributeKeys

9.2.21 RoadAttributeKeys

Vector of element type RoadAttributeKey

 $Referenced\ by: org_harman_nav_ctrl_Positioning::getCurrentRoadAttributes$

9.2.22 RoadAttributeValue

RoadAttributeValue			
Variant Element	Туре	Description	
boolValue	boolean		
floatValue	float		
intersectionValue	EIntersection		
roadclassValue	ERoadClass		
roadValue	ERoadType		
exitInfoValue	ExitInfo		
speedLimitValue	SpeedLimit		

9.2.23 SpeedLimit

SpeedLimit			
Structure Element	Туре	Description	
status	ESpeedLimitStatus		
speedLimit	UInt32		

 $Referenced\ by: org_harman_nav_ctrl_PositioningTypes::RoadAttributeValue$



10 Traffic Service

10.1 org_harman_nav_ctrl_traffic_TrafficInformation

Interface Version: 2.1

requestSetConfiguration

10.1.1 SetConfiguration

3

configuration attribute of the TrafficInformation interface

this attribute must be set by client/hmi at startup and everytime a basic configuration (e.g. language selection) has changed.

Parameter	Туре	Description
s_Configuration	SConfig	configuration attribute of the TrafficInformation interface this attribute must be set by client/hmi at startup and everytime a basic configuration (e.g. language selection) has changed.

responseSetConfiguration

configuration attribute of the TrafficInformation interface

this attribute must be set by client/hmi at startup and everytime a basic configuration (e.g. language selection) has changed.

Parameter	Туре	Description
s_Configuration	SConfig	configuration attribute of the TrafficInformation interface this attribute must be set by client/ hmi at startup and everytime a basic configuration (e.g. language selection) has changed.

10.1.2 createView

requestCreateView

create a new view to the mother array. This view will be maintained until the client uses destroyView, unsubscribes or service/proxy exit. After creating a view the client must receive an update. Only one



requestCreateView		
created view is allowed to modify the list entries. Please note: a valid usecase is to specify a viewSize which is bigger than the inital list size		
Parameter	Туре	Description
createView_R_list	ListId	list to create the view upon.
createView_R_viewsize	ViewSize	individual size of the requested view.

responseCreateView		
create a new view to the mother array. This view will be maintained until the client uses destroyView, unsubscribes or service/proxy exit. After creating a view the client must receive an update. Only one created view is allowed to modify the list entries. Please note: a valid usecase is to specify a viewSize which is bigger than the inital list size		
Parameter	Туре	Description
createView_view	ViewId	view identification used to distinguish several instances of a view for one client. It is never changed by the service nor the client. This id is unique!

10.1.3 deleteView

requestDeleteView		
delete the given view insta	ince	
Parameter	Туре	Description
deleteView_R_view	ViewId	identifies the view to apply this operation upon.

responseDeleteView		
delete the given view instance		
Parameter Type Description		Description

10.1.4 getAvailableTmcStations

requestGetAvailableTmcStations
get a list of all TMC stations, which are currently available in the tuner



requestGetAvailableTmcStations		
Parameter	Туре	Description

responseGetAvailableTmcStations		
get a list of all TMC stations, which are currently available in the tuner		
Parameter	Туре	Description
getAvailableTmcStations_avail		list of all TMC stations, which are currently available in the tuner

10.1.5 getListSize

requestGetListSize		
get the current number of contained elements in the given list.		
Parameter Type		Description
getListSize_R_list	ListId	

responseGetListSize			
get the current number of contained elements in the given list.			
Parameter Type		Description	
getListSize_size	ListSize		

10.1.6 getMessageData

requestGetMessageData			
gets the message information associated with one message identifier			
Parameter	neter Type Description		
getMessageData_R_message	dMessageId	identifier of the message for which data shall be retrieved	

responseGetMessageData		
gets the message information associated with one message identifier		
Parameter	Туре	Description
getMessageData_message	SMessage	information about the traffic event or flow



10.1.7 getSupportedOnlineFallbackSources

requestGetSupportedOnlineFallbackSources		
get a list of all supported fallback sources for traffic data if online data cannot be retreived (e.g., no connection, no roaming allowed)		
Parameter	Туре	Description

responseGetSupportedOnlineFallbackSources		
get a list of all supported fallback sources for traffic data if online data cannot be retreived (e.g., no connection, no roaming allowed)		
Parameter Type Description		
getSupportedOnlineFallbackSo	p urdes<u>e</u>fallba6kSour6es ection_	list of all supported fallback sources for traffic data

10.1.8 getSupportedSources

requestGetSupportedSources		
get a list of all supported sources for traffic data		
Parameter	Туре	Description

responseGetSupportedSources		
get a list of all supported source	es for traffic data	
Parameter	Туре	Description
getSupportedSources_sources	THBVector_SourceSelection_	list of all supported sources for traffic data

10.1.9 getViewData

requestGetViewData

creates a snapshot of the current view of the traffic message list and returns the contained messages' data. Using the set view position or set view anchor (whichever was set last), the view snapshot is positioned within the list. The information about the snapshot position and the traffic messages contained in the view snapshot are returned to the client.

|--|



requestGetViewData		
getViewData_R_view	ViewId	identifies the view to apply this operation upon.

responseGetViewData

creates a snapshot of the current view of the traffic message list and returns the contained messages' data. Using the set view position or set view anchor (whichever was set last), the view snapshot is positioned within the list. The information about the snapshot position and the traffic messages contained in the view snapshot are returned to the client.

Parameter	Туре	Description
getViewData_messages	TMessages	the messages contained in the current view snapshot
getViewData_snapshotPos	ViewSnapshotPosition	information how the message view snapshot is positioned within the list

10.1.10 refreshOnlineTrafficData

requestRefreshOnlineTrafficData

Triggers a new query for traffic data from the online traffic data provider. This call will only have an effect if the currently selected source is Online (see attribute source) and if Manual refresh mode was configured (see attribute configuration.refreshSetting.mode).

Parameter	Туре	Description

10.1.11 setViewAnchor

requestSetViewAnchor

set a stable element inside the current view snapshot. The client should use an available snapshot of a view to maintain focused elements within the view if possible, and change the view position only if an element to be focused is outside of the given view. A snapshot is generated whenever querying the data contained in a view. Together with that data, the ViewSnapshotPosition is provided. The initial snapshot of the view is always [0, min(viewSize-1, listSize-1)] with anchor offset 0. When creating a new view snapshot, the last call of setViewPosition or setViewAnchor (whichever was the last one) will be the relevant information to reposition the new view snapshot. If setViewAnchor was the last call, the anchor element of the old view snapshot is used for repositioning. (This method only needs to be used if the current view snapshot is outdated because the list has been updated.)

The following rules are applied to set the position of the new view snapshot [newFrom, newTo], given a snapshot [from, to] and anchor offset aOff: Let elem(k) denote the element at key k in the old snapshot and new(e) denote the key the element e will have (would have if deleted) in the new



requestSetViewAnchor

snapshot (see also examples below). newFrom is set to new(elem(from+aOff)) - aOff. If any of these calculated values are out of the range of the list [0, listSize-1], they will be truncated to fit into the list. As a consequence, whenever possible, the anchor element of the old snapshot will be at the same offset within the new snapshot.

As an example for the case in which the data was updated: old list {"a", "b", "c", "d", "e", "f"} with view snapshot ["c", "d"] with viewSize 2 and viewKey 2 new list {"b", "d", "f", "h", "j", "l"} setViewAnchor(0) => elem(from+aOff) is "c", new(elem(from+aOff)) is 1 ("c" would be inserted at index 1) => ["d", "f"] with ViewSnapshotPosition 6, listKey=1, anchorOffset=0. setViewAnchor(1) => elem(from+aOff) is "d", new(elem(from+aOff)) is 1 => ["b", "d"] with ViewSnapshotPosition 6, listKey=0, anchorOffset=1.

Parameter	Туре	Description
setViewAnchor_R_view	ViewId	identifies the view to apply this operation upon.
setViewAnchor_R_anchor	AnchorOffset	relative anchor position in the view, referenced from ListKey Please note: only positive values and 0 are allowed

10.1.12 setViewPosition

requestSetViewPosition

set the absolute view position to element key. The client should use an available snapshot of a view to maintain focused elements within the view if possible, and change the view position only if an element to be focused is outside of the given view. A snapshot is generated whenever querying the data contained in a view. Together with that data, the ViewSnapshotPosition is provided. The initial snapshot of the view is always [0, min(viewSize-1, listSize-1)]. When creating a new view snapshot, the last call of setViewPosition or setViewAnchor (whichever was the last one) will be the relevant information to reposition the new view snapshot. If setViewPosition was the last call, the view is moved such that the provided key refers to the absolute position on the current snapshot of the view. (This becomes important if the current view snapshot is outdated because the list has been updated.)

The following rules are applied to set the position of the new view snapshot [newFrom, newTo], given a snapshot [from, to]: Let elem(k) denote the element at key k in the old snapshot and new(e) denote the key the element e will have (would have if deleted) in the new snapshot (see also examples (1)-(3) below). (1) If key is less than from, then newFrom will be set to new(elem(from)) - (from-key). (2) If key is contained in [from, to], then newKey will be set to new(elem(key)). (3) If key is greater than to, then newFrom will be set to new(elem(to)) + (key-to). If any of these calculated values are out of the range of the list [0, listSize-1], they will be truncated to fit into the list. (Note that the resulting newFrom is always equal to key if the data wasn't updated, but it doesn't have to be equal to key if the data was updated.) After setting the view position the anchor offset will automatically be set to 0. There are two special key values to allow scrolling to the top/bottom of the list, independently from the above rules: The key value 0xFFFE always positions the view to the bottom of the list.

As an example for the case in which the data was updated: old list {"a", "b", "c", "d", "e", "f"} with view snapshot ["c", "d"] with viewSize 2 and viewKey 2 new list {"b", "d", "f", "h", "j", "l"} (1) e^{-t} setViewPosition(0) => [from, to] is [2, 3], elem(from) is "c", new(elem(from)) is 1 => ["b", "d"] with



requestSetViewPosition

ViewSnapshotPosition 6, listKey=0, anchorOffset=0. (2) setViewPosition(3) => [from, to] is [2, 3], elem(key) is "d", new(elem(key)) is 1 => ["d", "f"] with ViewSnapshotPosition 6, listKey=1, anchorOffset=0. (3) setViewPosition(4) => [from, to] is [2, 3], elem(to) is "d", new(elem(d)) is 1 => ["f", "h"] with ViewSnapshotPosition 6, listKey=2, anchorOffset=0.

Parameter	Туре	Description
setViewPosition_R_view	ViewId	identifies the view to apply this operation upon.
setViewPosition_R_key	ListKey	element to position the view upon, according to view policy.

10.1.13 setViewSize

requestSetViewSize

adjust the view size. It is allowed to set view size to a larger value than the actual size of the list, but less or equal than the maximum size of the list. The implementation may limit the maximum view size for resource reasons. After adjusting the window size the client must receive an update.

Parameter	Туре	Description
setViewSize_R_view	ViewId	identifies the view to apply this operation upon.
setViewSize_R_new_size	ViewSize	new view size

responseSetViewSize

adjust the view size. It is allowed to set view size to a larger value than the actual size of the list, but less or equal than the maximum size of the list. The implementation may limit the maximum view size for resource reasons. After adjusting the window size the client must receive an update.

Parameter	Туре	Description

10.1.14 toggleDetourStatus

requestToggleDetourStatus

toggle the detour status of a certain ti message

according to the toyota specification a user can select a certain message for detour. With this request the client/hmi can switch the detour flag of a certain TI message.

Parameter	Туре	Description
toggleDetourStatus_R_id	TMessageId	unique identifier of the message, for which the detour status shall be toggled



responseToggleDetourStatus

toggle the detour status of a certain ti message

according to the toyota specification a user can select a certain message for detour. With this request the client/hmi can switch the detour flag of a certain TI message.

Parameter	Туре	Description
toggleDetourStatus_message	SMessage	resulting message (with toggled detour flag and possibly updated content, e.g., updated icons)

10.1.15 listSize

informationListSize		
informs the client about changes of the list size.		
Parameter	Туре	Description
listSize_id	ListId	list id related to the list size update
listSize_size	ListSize	changed list size information

10.1.16 popUpIndication

informationPopUpIndication

indicate a popup caused by TI-messages to the customer

This broadcast is used to indicate any kind of popup that is caused by one or more TI messages (according to spec, a single message is trigger condition). There are two kind of popups: dynamic reroute suggestion caused by TI-delay and emergency noticiation Furhtermore we've added an additional popup type MISC which can be used to indicate any other type of popup (not yet specified nor used)

Parameter	Туре	Description
popUpIndication_type	PopupType	reason for the popup
popUpIndication_responsibleN	l ēššagas ges	messages, which have caused the popup

10.1.17 viewUpdate

informationViewUpdate

indicate to the client that the underlying list of a certain view has changed. Whenever elements get inserted/removed or the content of element gets changed, the size or the sorting order of a list might



informationViewUpdate

change. This might influence the current view and especially the position of the anchor element in the list. To allow a client to react on such changes in an approapriate manner, the viewUpdate broadcast will provide all necessary information to its client. It is up to the client to reposition the view to its needs based on the provided information, using the methods setViewPosition or setViewAnchor.

Parameter	Туре	Description
viewUpdate_view	ViewId	unique identifier of a view
viewUpdate_size	ListSize	current size of the underlying list
viewUpdate_viewChanged	boolean	at least one element of the currently active view snapshot has changed
viewUpdate_listChanged	boolean	at least one element of the list has changed (this might lead to a different new view snapshot)

10.1.18 aavailableLists

Attribute aavailableLists		
The list ids which can be queried from	om this interface	
Type Notification Type		
THBVector_ListId_	ON_CHANGE	

10.1.19 aconfiguration

Attribute aconfiguration

configuration attribute of the TrafficInformation interface

this attribute must be set by client/hmi at startup and everytime a basic configuration (e.g. language selection) has changed.

Туре	Notification Type
SConfig	ON_CHANGE

10.1.20 acurrentTmcStation

Attribute acurrentTmcStation		
the tmc station to which the radio is currently tuned (or empty string if no reception)		
Type Notification Type		



Attribute acurrentTmcStation	
String	ON_CHANGE

10.1.21 asource

Attribute asource		
indicator of currently available TrafficInformation source		
Type Notification Type		
SourceSelection	ON_CHANGE	

10.1.22 Error

Error		
This is the type for error responses.		
Literal	Description	
ERROR_ListError_INVALID		
ERROR_ListError_INVALID_LIST_ID		
ERROR_ListError_INVALID_VIEW		
ERROR_ListError_INVALID_PARAMETER		
ERROR_ListError_SIZE_LIMIT_EXCEEDED		
ERROR_ListError_OUT_OF_RESSOURCES		
ERROR_ListError_OUT_OF_RANGE_POSITION		
ERROR_ListError_POLICY_DENIED		
ERROR_TrafficInformationError_MESSAGE_NOT_AVAILABLE		
ERROR_TrafficInformationError_FAILED		

10.1.23 THBVector_CHBString_

list of all TMC stations, which are currently available in the tuner Vector of element type String

 $Referenced\ by: org_harman_nav_ctrl_traffic_TrafficInformation::getAvailableTmcStations$

10.1.24 THBVector_ListId_

The list ids which can be queried from this interface Vector of element type ListId

Referenced by : org_harman_nav_ctrl_traffic_TrafficInformation::aavailableLists



10.1.25 THBVector_SourceSelection_

list of all supported sources for traffic data Vector of element type SourceSelection

Referenced by: org_harman_nav_ctrl_traffic_TrafficInformation::getSupportedSources, org_harman_nav_ctrl_traffic_TrafficInformation::getSupportedOnlineFallbackSources

10.2 org_harman_nav_ctrl_traffic_TrafficInformation

Interface Version: 2.1

10.2.1 Direction

Direction		
Literal	Description	
Direction_North		
Direction_NorthWest		
Direction_West		
Direction_SouthWest		
Direction_South		
Direction_SouthEast		
Direction_East		
Direction_NorthEast		

Referenced by: org_harman_nav_ctrl_traffic_TrafficInformationTypes::SBaseMessage

10.2.2 OnlineRefreshMode

OnlineRefreshMode		
Literal	Description	
OnlineRefreshMode_Auto	set to automodus, frequency specifies high (!=0) or low (0) frequency	
OnlineRefreshMode_Manual	refresh frequency will be provided explicitly, the frequency 0 will be interpreted as "only on explicit request"	

Referenced by: org_harman_nav_ctrl_traffic_TrafficInformationTypes::SOnlineRefreshSetting



10.2.3 PopupType

PopupType		
Literal	Description	
PopupType_Misc	a generic popup caused by a ti-message	
PopupType_Emergency	a ti emergency message is received	
PopupType_Reroute	a dynamic detour/reroute suggestion (because of ti message)	

Referenced by : org_harman_nav_ctrl_traffic_TrafficInformation::popUpIndication

10.2.4 RouteDynamics

RouteDynamics		
Literal	Description	
RouteDynamics_Off	no route dynamics	
RouteDynamics_Automatic	automatic rerouting in case of message-on-route	
RouteDynamics_Manual	user will get informed and decides if a new route will be guided	

 $Referenced\ by: org_harman_nav_ctrl_traffic_TrafficInformationTypes::SConfig$

10.2.5 SBaseMessage

SBaseMessage		
representation of a ba	ase TI message	
	uniquely identified by it's id. According	essages as it is expected in the overviewng to spec, we suggest to use the
Roadlcon	routeSegmentFrom - routeSegmentTo	eventlcon
distance	headinglcon	
	/ routeSegmentDesc	



SBaseMessage		
Structure Element	Туре	Description
id	TMessageId	unique identifier of the traffic message
roadlcon	SIcon	icon, which indicates the road on which the traffic event is located (e.g., road number sign)
routeSegmentFrom	String	name of the route segment, at which the traffic event starts
routeSegmentTo	String	name of the route segment, at which the traffic event ends
routeSegmentDesc	String	description of the route segment, on which the traffic event is located
eventicon	Sicon	icon, which indicates the incident associated with the traffic event
direction	Direction	value, which indicates the cardinal direction, in which the event is located
distance	TDistance_dm	distance (in decimeters) to the traffic event
isOnroute	boolean	flag, which indicates whether the traffic event is located on the guided route
isDetoured	boolean	flag, which indicates whether the traffic event is actively detoured (see toggleDetourStatus)
hasRouteFromTo	boolean	tbc

 $\label{lem:condition} Referenced\ by: org_harman_nav_ctrl_traffic_TrafficInformationTypes::SMessage, org_harman_nav_ctrl_traffic_TrafficInformationTypes::TBaseMessages$

10.2.6 SConfig

SConfig			
configuration structure to s	configuration structure to set customer related settings for traffic messages		
Structure Element Type Description			
source	SourceSelection	selected TI source	
roamingAllowed	boolean	flag, which indicates whether online is allowed as source in roaming state	
refreshSetting	SOnlineRefreshSetting	refresh setting for online ti data	
onlineFallbackSource	SourceSelection	source selection if online cannot be used (e.g., no connection, no roaming desired)	



SConfig		
selectedTmcStation	String	manual selection of TMC station (empty string indicates that the system shall automatically tune to a suitable station)
radiusFilter_km	UInt8	only TI messages in this radius are shown
routesettings	RouteDynamics	dynamic route behaviour (off/auto/ manual)

Referenced by: org_harman_nav_ctrl_traffic_TrafficInformation::SetConfiguration, org_harman_nav_ctrl_traffic_TrafficInformation::SetConfiguration, org_harman_nav_ctrl_traffic_TrafficInformation::aconfiguration

10.2.7 SMessage

SMessage

representation of a TI message

this struct will be used in order to display the details of a certain TI message. It contains a nested SBaseMessage which is used to identify the basic credentials of the TI messages. Furthermore it provides a lenght of the incident, followed by a description. The description is given in the language selected via config or - if no appropriate translation is available - in the fallback language. Please note: the description is a list of strings in which each entry represents a description of one event/incident (imagine multi-events). In other words: an entry does not represent a textline in the HMI!

Structure Element	Туре	Description
indexInList	Int32	index of the traffic message within the message list
base	SBaseMessage	basic credentials of traffic message
length	TDistance_dm	length on guided route, which is affected by the traffic message
delay	TTime_sec	delay caused on the guided route by this traffic message
fromLocation	String	location, at which the traffic event starts
toLocation	String	location, at which the traffic event ends
description	THBVector_CHBString_	textual description of the traffic event (multi-events: each entry represents the description of one event/indcident)

Referenced by: org_harman_nav_ctrl_highwaymode_HighwayModeTypes::HighwayItemDetails, org_harman_nav_ctrl_traffic_TrafficInformation::getMessageData, org_harman_nav_ctrl_traffic_TrafficInformation::toggleDetourStatus, org_harman_nav_ctrl_traffic_TrafficInformationTypes::TMessages



10.2.8 SOnlineRefreshSetting

SOnlineRefreshSetting

describes the refresh settings for online connection This struct is used the specify the frequency in which ti online data will be fetched from server. Currently there are two modes available. With auto modus the refresh rate is specified by server. The client can select between high and low frequency by setting the frequency to 0 - low and !=0 - high. In manual mode the frequency specifies an interval in seconds in which new online ti data is requested from server, if the value 0 is set, traffic data will only be refreshed on explicit request.

Structure Element	Туре	Description
mode	OnlineRefreshMode	refresh setting (auto, manual,)
frequency	UInt16	frequency in seconds, in which the online data shall be queried In auto mode only values "!=0"=>"high" and "==0"=>"low" will be distinguished. In manual mode, values "!=0"=>"frequency in seconds" and "==0"=>"only on explicit request" will be distinguished.

Referenced by: org_harman_nav_ctrl_traffic_TrafficInformationTypes::SConfig

10.2.9 SourceSelection

SourceSelection		
Literal	Description	
SourceSelection_Off	TI is disabled	
SourceSelection_RDS	radio reception e.g. TMC	
SourceSelection_Digital	digital radio reception e.g. TMC	
SourceSelection_Satellite	digital satellite reception e.g. TMC-SiriusXM	
SourceSelection_Online	point-2-point online reception e.g. TPEG	

Referenced by: org_harman_nav_ctrl_traffic_TrafficInformation::asource, org_harman_nav_ctrl_traffic_TrafficInformation::THBVector_SourceSelection_, org_harman_nav_ctrl_traffic_TrafficInformationTypes::SConfig, org_harman_nav_ctrl_traffic_TrafficInformationTypes::SConfig

10.2.10 TBaseMessages

a list of basemessages - used e.g. for the sorted list of TI-messages Vector of element type **SBaseMessage**



10.2.11 THBVector_CHBString_

textual description of the traffic event (multi-events: each entry represents the description of one event/indcident) Vector of element type **String**

Referenced by: org_harman_nav_ctrl_traffic_TrafficInformationTypes::SMessage

10.2.12 TMessageId

unique identifier of a certain TI message Alias of actual type: UInt64

Referenced by: org_harman_nav_ctrl_traffic_TrafficInformation::getMessageData, org_harman_nav_ctrl_traffic_TrafficInformation::toggleDetourStatus, org_harman_nav_ctrl_traffic_TrafficInformationTypes::SBaseMessage, org_harman_nav_ctrl_traffic_TrafficInformationTypes::TMessageIds

10.2.13 TMessageIds

Vector of element type TMessageId

Referenced by: org_harman_nav_ctrl_Guidance::alternativeTIRouteAvailable

10.2.14 TMessages

list of ti messages Vector of element type SMessage

Referenced by : org_harman_nav_ctrl_traffic_TrafficInformation::getViewData, org_harman_nav_ctrl_traffic_TrafficInformation::popUpIndication

10.2.15 TrafficInformationError

TrafficInformationError		
Literal Description		
TrafficInformationError_MESSAGE_NOT_AVAILAB	ILE message for which the request was triggered is not available	
TrafficInformationError_FAILED	Unspecified error	

10.3 org_harman_nav_ctrl_speedcam_SpeedCamOn

Interface Version: 1.0



10.3.1 createSession

requestCreateSession

Each client (online service) must establish a session to the speedcam service to send data. The session should be deleted if service gets unavailable. In this case all client related data gets removed from the service. As input parameter the service expects a source enumartion which identifies the camera service. Furthermore it expects a boolean which tells the service if feedback loop is supported or not (see broadcast feedback for further details) Please note: during shutdown all existing sessions will get deleted automatically

Parameter	Туре	Description
createSession_R_source	EDataSource	Source identifier of provider
createSession_R_isFeedback		True, if provider supports custom cam reports, false otherwise

responseCreateSession

Each client (online service) must establish a session to the speedcam service to send data. The session should be deleted if service gets unavailable. In this case all client related data gets removed from the service. As input parameter the service expects a source enumartion which identifies the camera service. Furthermore it expects a boolean which tells the service if feedback loop is supported or not (see broadcast feedback for further details) Please note: during shutdown all existing sessions will get deleted automatically

Parameter	Туре	Description
createSession_session	Handle	Handle to the new session

10.3.2 deleteSession

requestDeleteSession

Delete session and release data. This method should be called whenever an online client gets unavailable. The retrieved data of the corresponding client gets removed from service. Please note: During shutdown, all existing sessions will get removed automatically

Parameter	Туре	Description
deleteSession_R_session	Handle	Handle to the session to close

10.3.3 push

requestPush

Push speedcam data The online client will use this method to push speedcam data to the service. As parameter a SDataUpdate strucuture is expected which contains a bytebuffer and the update type



requestPush

(update or delete). The format stored in the bytebuffer depends on the registered datasource (see createSession) and the project-specific format agreements. The response of the method will indicate as soon as the service is ready to accept more data.

Parameter	Туре	Description
push_R_session	Handle	Handle to the open client session
push_R_data	SDataUpdate	Structure holding the raw data

responsePush

Push speedcam data The online client will use this method to push speedcam data to the service. As parameter a SDataUpdate strucuture is expected which contains a bytebuffer and the update type (update or delete). The format stored in the bytebuffer depends on the registered datasource (see createSession) and the project-specific format agreements. The response of the method will indicate as soon as the service is ready to accept more data.

·	·	
Parameter	Туре	Description

10.3.4 feedback

informationFeedback

Provide feedback about existing or new speedcameras. The scs supports a feedback loop which allows a customer to report new cameras or confirm/ revoke existing cameras. The SSpeedCamFeedback structure describes the position as well as some characteristics of the reported cam. The service will trigger the feedback broadcast only if the supportFeedback flag was set during create session call.

Parameter	Туре	Description
feedback_session	Handle	Handle to the open client session
feedback_speedcam		Feedback about reported/confirmed/ revoked cams

10.4 org_harman_nav_ctrl_speedcam_SpeedCamOn

Interface Version: 1.0

10.4.1 Countrylso

Country code (ISO 3166-1 alpha-3) Alias of actual type: String

Referenced by:

org_harman_nav_ctrl_speedcam_SpeedCamOnlineServiceTypes::SSpeedCamFeedback



10.4.2 EDataSource

EDataSource EDataSource		
Literal Description		
EDataSource_AHA	Data from the online service of AHA radio (Cyclopse)	
EDataSource_Coyote	Data from the Coyote app	
EDataSource_Onboard	Data from onboard database	
EDataSource_Custom	Pending data reported by the Hmi	

Referenced by: org_harman_nav_ctrl_speedcam_SpeedCamOnlineService::createSession

10.4.3 EDataUpdate

EDataUpdate	
Literal	Description
EDataUpdate_Update	Data tile is to be updated
EDataUpdate_Delete	Data tile is to be removed

 $Referenced\ by: org_harman_nav_ctrl_speedcam_SpeedCamOnlineServiceTypes::SDataUpdate$

10.4.4 EFeedback

EFeedback		
Literal Description		
EFeedback_New	New speed cam is reported	
EFeedback_Confirmation	Existing speed cam is confirmed	
EFeedback_Revocation	Existing speed cam is revoked	

Referenced by:

 $org_harman_nav_ctrl_speedcam_SpeedCamOnlineServiceTypes::SSpeedCamFeedback$

10.4.5 Handle

Used to identify a session Alias of actual type: UInt16



Referenced by: org_harman_nav_ctrl_speedcam_SpeedCamOnlineService::createSession, org_harman_nav_ctrl_speedcam_SpeedCamOnlineService::deleteSession, org_harman_nav_ctrl_speedcam_SpeedCamOnlineService::push, org_harman_nav_ctrl_speedcam_SpeedCamOnlineService::feedback

10.4.6 Heading

Geographic heading in degree Alias of actual type: UInt16

Referenced by: org_harman_nav_ctrl_speedcam_SpeedCamOnlineServiceTypes::SDirectedPosition

10.4.7 Id

Generic id. concrete format of the data is agreed between service and client: AHA: string, Coyote: UInt32 Alias of actual type: **Buffer**

Referenced by:

org_harman_nav_ctrl_speedcam_SpeedCamOnlineServiceTypes::SSpeedCamFeedback

10.4.8 Latitude

Latitude in degree Alias of actual type: double

Referenced by: org_harman_nav_ctrl_speedcam_SpeedCamOnlineServiceTypes::SDirectedPosition

10.4.9 Longitude

Longitude in degree Alias of actual type: double

Referenced by: org_harman_nav_ctrl_speedcam_SpeedCamOnlineServiceTypes::SDirectedPosition

10.4.10 RawData

All incoming data is stored as a bytebuffer. The concrete format of the data is agreed between service and client: AHA: KML-format as string, Coyote: Serialized HBTD as binary Alias of actual type: **Buffer**

Referenced by: org_harman_nav_ctrl_speedcam_SpeedCamOnlineServiceTypes::SDataUpdate

10.4.11 SDataUpdate

SDataUpdate		
Update data structure contains update type (update/insert or delete) and generic raw-data bytebuffer		
Structure Element	Туре	Description



SDataUpdate		
type	EDataUpdate	Data update operation type
tile	TileId	Tile identifier (in case of delete)
data	RawData	Tile raw data (in case of update)

Referenced by: org_harman_nav_ctrl_speedcam_SpeedCamOnlineService::push

10.4.12 SDirectedPosition

SDirectedPosition		
Detailed position of a speedcam		
Structure Element	Туре	Description
latitude	Latitude	Latitude in degree
longitude	Longitude	Longitude in degree
heading	Heading	Geographic heading in degree

Referenced by:

 $org_harman_nav_ctrl_speedcam_SpeedCamOnlineServiceTypes::SSpeedCamFeedback$

10.4.13 SSpeedCamFeedback

SSpeedCamFeedback			
Feedback data for speed cams. For new reported cams, the speed cam identifier is empty.			
Structure Element Type Description		Description	
type	EFeedback	Type of feedback	
id	ld	Speed cam identifier	
pos	SDirectedPosition	Speed cam location	
limit	Speed	Speed cam speed limit	
country	CountryIso	Country code (ISO 3166-1 alpha-3)	
timeStamp	Timestamp	Time stamp (seconds, Unix time)	

Referenced by: org_harman_nav_ctrl_speedcam_SpeedCamOnlineService::feedback

10.4.14 Speed

Speed in km/h Alias of actual type: UInt16



Referenced by:

 $org_harman_nav_ctrl_speedcam_SpeedCamOnlineServiceTypes::SSpeedCamFeedback$

10.4.15 Tileld

Tile id Alias of actual type: Int32

Referenced by: org_harman_nav_ctrl_speedcam_SpeedCamOnlineServiceTypes::SDataUpdate

10.5 org_harman_nav_ctrl_speedcam_SpeedCamSe

Interface Version: 3.0

10.5.1 confirmExistingSpeedCam

requestConfirmExistingSpeedCam		
Confirms an existing speedcam instance.		
Parameter	Туре	Description
confirmExistingSpeedCam_R_	sesiba	Handle to the open client session
confirmExistingSpeedCam_R_	<mark>spe</mark> edCamId	Identifier of the existing cam

10.5.2 confirmSpeedCam

requestConfirmSpeedCam		
Confirms a previously reported speedcam location. This method should be called by the client, if the driver reports an entirely new speed cam. The attributes of the new speed cam have to be added to the report.		
Parameter	Туре	Description
confirmSpeedCam_R_session	Handle	Handle to the open client session
confirmSpeedCam_R_reportId	SReportId	Identifier of the report to confirm
confirmSpeedCam_R_data	SSpeedCamConfirmationData	Confirmation data for new cam

10.5.3 createSession

requestCreateSession
Opens a new session on the speedcam controller



requestCreateSession		
Parameter	Туре	Description

responseCreateSession		
Opens a new session on the speedcam controller		
Parameter	Туре	Description
createSession_session	Handle	Handle to the new session

10.5.4 declineExistingSpeedCam

requestDeclineExistingSpeedCam		
Declines an existing speedcam instance.		
Parameter	Туре	Description
declineExistingSpeedCam_R_	s es side	Handle to the open client session
declineExistingSpeedCam_R_	s <mark>pe</mark> edCamId	Identifier of the existing cam

10.5.5 declineSpeedCam

requestDeclineSpeedCam		
Declines a previously reported speedcam location This method should be called by the client, if the driver cancels the dialog for reporting a cam.		
Parameter	Туре	Description
declineSpeedCam_R_session	Handle	Handle to the open client session
declineSpeedCam_R_reportId	SReportId	Identifier of the report to decline

10.5.6 deleteSession

requestDeleteSession		
Closes an existing session on the speedcam controller		
Parameter	Туре	Description
deleteSession_R_session	Handle	Handle to the session to close



10.5.7 reportSpeedcam

requestReportSpeedcam

Reports the location of a potential speedcam This method allows the driver to report an either new or existing speedcam spot. As a result the caller will get a report identifier which may be used to decline or to confirm the report with additional information later

Parameter	Туре	Description
reportSpeedcam_R_session	Handle	Handle to the open client session

responseReportSpeedcam

Reports the location of a potential speedcam This method allows the driver to report an either new or existing speedcam spot. As a result the caller will get a report identifier which may be used to decline or to confirm the report with additional information later

Parameter	Туре	Description
reportSpeedcam_reportId	SReportId	Report identifier

10.5.8 forthcomingEvent

informationForthcomingEvent

Informs the client about the closest forthcoming speedcam within the configured range. If guidance is running, the look-ahead is based on the guided route, otherwise it is based on the predicted driving path.

Parameter	Туре	Description
forthcomingEvent_session	Handle	Handle to the open client session
forthcomingEvent_event	SSpeedCamEvent	Event information associated to closest cam

10.6 org_harman_nav_ctrl_speedcam_SpeedCamSe

Interface Version: 3.0

10.6.1 EDirection

EDirection	
Literal	Description



EDirection	
EDirection_DRIVING_DIRECTION	Speed cam is measuring in driving direction
EDirection_AGAINST_DRIVING_DIRECTION	Speed cam is measuring against driving direction
EDirection_BOTH_DIRECTIONS	Speed cam is measuring in both directions

Referenced by:

 $org_harman_nav_ctrl_speedcam_SpeedCamServiceTypes::SSpeedCamConfirmationData$

10.6.2 ESpeedCamProvider

ESpeedCamProvider		
Literal	Description	
ESpeedCamProvider_AHA_CYCLOPSE	Data from the online service of AHA radio (Cyclopse)	
ESpeedCamProvider_COYOTE	Data from the Coyote app	
ESpeedCamProvider_ONBOARD	Data from onboard database	
ESpeedCamProvider_CUSTOMER	Pending data reported by the Hmi	

 $Referenced\ by: org_harman_nav_ctrl_speedcam_SpeedCamServiceTypes::SSpeedCamEvent$

10.6.3 ESpeedCamType

ESpeedCamType		
Literal	Description	
ESpeedCamType_UNKNOWN_SPEEDCAM	Type of speed cam not supported or unknown	
ESpeedCamType_FIXED_SPEEDCAM_POINT	A single speed cam installed at a fixed location	
ESpeedCamType_FIXED_TRAFFIC_LIGHT_CAM_	₽©ЫПght cam mounted to a fixed location	
ESpeedCamType_FIXED_TRAFFIC_LIGHT_AND_	_\$R5EnDiQAM re ROight cam + speed cam mounted to a fixed location	
ESpeedCamType_MOBILE_SPEEDCAM_POINT	A mobile speed cam, temporarily operated at one location	
ESpeedCamType_FIXED_DANGER_ZONE	A fixed risk zone (e.g. accident zone, black spot)	
ESpeedCamType_FIXED_AVERAGE_SPEED_ZO	MEne, where average speed between begin and end location is evaluated	
ESpeedCamType_MOBILE_RISK_ZONE	Risk zone with frequent mobile speed cam operations within	



Referenced by:

org_harman_nav_ctrl_speedcam_SpeedCamServiceTypes::SSpeedCamConfirmationData, org_harman_nav_ctrl_speedcam_SpeedCamServiceTypes::SSpeedCamEvent

10.6.4 SReportId

SReportId		
Speed cam report identifier. This identifier is unique within the set of newly reported and not yet confirmed speed cameras.		
Structure Element Type Description		
id	UInt64	Inner report identifier.

Referenced by: org_harman_nav_ctrl_speedcam_SpeedCamService::reportSpeedcam, org_harman_nav_ctrl_speedcam_SpeedCamService::declineSpeedCam, org_harman_nav_ctrl_speedcam_SpeedCamService::confirmSpeedCam

10.6.5 SSpeedCamConfirmationData

SpeedCamConfirmationData Speedcam feedback confirmation. This structure contains the required information for confirming a new speed cam. Beneath the direction indication, this involves an optional speedlimit information (use 0 to let engine determine speed limit) and the type of cam Structure Element Type Description direction The road orientation of the speed cam

direction

EDirection

The road orientation of the speed cam
speedlimit

TSpeed_kmh

The speed limit of the speed cam in km/h

camType

ESpeedCamType

The type of the speed cam

 $Referenced\ by: org_harman_nav_ctrl_speedCamService::confirmSpeedCamService:$

10.6.6 SSpeedCamEvent

SSpeedCamEvent		
Forthcoming speedcam event. Beneath the unique identifier of the cam and the remanining distance to it, this event also holds a wide range of attributes associated to the cam itself		
Structure Element Type Description		



SSpeedCamEvent		
distanceTo	TDistance_dm	Distance indication to forthcoming speed cam
isDistanceToZoneEnd	boolean	True, if distance is related to the end of a speed cam zone, false in any other case
speedCam	Tld	Unique identifier of the speed cam (used for feedback loop)
camProvider	ESpeedCamProvider	The provider of the speed cam data
camType	ESpeedCamType	The type of the speed cam
camlcon	Sicon	Map icon of the speed cam
camSpeedlimit	TSpeed_kmh	Speed limit of the speed cam in km/h
isSpeedlimitExceeded	boolean	True, if the cam speed limit is currently being exceeded by own speed, false otherwise

Referenced by: org_harman_nav_ctrl_speedcam_SpeedCamService::forthcomingEvent

10.6.7 Tld

Alias of actual type: UInt64

Referenced by: org_harman_nav_ctrl_speedcam_SpeedCamService::declineExistingSpeedCam, org_harman_nav_ctrl_speedcam_SpeedCamService::confirmExistingSpeedCam, org_harman_nav_ctrl_speedcam_SpeedCamServiceTypes::SSpeedCamEvent

10.6.8 TSpeed_kmh

Alias of actual type: UInt16

Referenced by:

 $org_harman_nav_ctrl_speedcam_SpeedCamServiceTypes::SSpeedCamConfirmationData, \\org_harman_nav_ctrl_speedcam_SpeedCamServiceTypes::SSpeedCamEvent$



11 Icon Service

11.1 org_harman_nav_ctrl_icon_lconProvider

Interface Version: 0.2

11.1.1 createSession

requestCreateSession			
initialize an icon session. Prerequiste and mandatory to any other IconProvider call. The client need to specify an iconFilePath, where all requested resources can be copied to.			
Parameter Type Description			
createSession_R_iconFilePath	String	writeable and accessable file path	

responseCreateSession		
initialize an icon session. Prerequiste and mandatory to any other IconProvider call. The client need to specify an iconFilePath, where all requested resources can be copied to.		
Parameter Type Description		
createSession_iconSessionHandle icon session handle		

11.1.2 deleteSession

requestDeleteSession		
deletes an icon session and all assiociated resources which were requested		
Parameter	Туре	Description
deleteSession_R_iconSession	HHazmodlee	

responseDeleteSession		
deletes an icon session and all assiociated resources which were requested		
Parameter Type Description		

11.1.3 getIconResource

requestGetIconResource	
generic icon request call to get a navigation based icon	



requestGetIconResource		
Parameter	Туре	Description
getIconResource_R_iconSess	i bhahlaha dle	mandatory icon session handle
getlconResource_R_iconReso	urcellesourceSetId	icon resource id which is provided by other navigation domains and is used to address one dedicated icon resource set
getIconResource_R_iconDesignation	D esignParameters	description of the requested icon design

responseGetIconResource		
generic icon request call to get a navigation based icon		
Parameter	Туре	Description
getIconResource_icon	IconResponseData	

11.2 org_harman_nav_ctrl_icon_lconProviderTypes

Interface Version: 1.0

11.2.1 DesignParameters

DesignParameters		
describes the desired icon design		
Structure Element	Туре	Description
imageEncoding	ImageEncoding	
displayRepresentation	IconDisplayRepresentation	
dayNightRepresentation	IconDayNightRepresentation	
isHighlighted	boolean	

Referenced by: org_harman_nav_ctrl_icon_lconProvider::getlconResource

11.2.2 ErrorCode

ErrorCode	
Literal	Description
ErrorCode_NO_ERROR	



ErrorCode	
ErrorCode_ERROR_UNSPECIFIED	
ErrorCode_ERROR_ICONRESOURCE_NOT_AVA	ILABLE
ErrorCode_ERROR_ICON_FILE_PATH_INVALID	

 $Referenced\ by: org_harman_nav_ctrl_icon_lconProviderTypes::lconResponseData$

11.2.3 IconDayNightRepresentation

IconDayNightRepresentation		
Literal	Description	
IconDayNightRepresentation_DAY		
IconDayNightRepresentation_NIGHT		

Referenced by : org_harman_nav_ctrl_icon_lconProviderTypes::DesignParameters

11.2.4 IconDisplayRepresentation

IconDisplayRepresentation		
Literal	Description	
IconDisplayRepresentation_DEFAULT		
IconDisplayRepresentation_MAP		
IconDisplayRepresentation_HMI		
IconDisplayRepresentation_GUIDANCE		
IconDisplayRepresentation_ICD		
IconDisplayRepresentation_HEAD_UP_DISPLAY		

 $Referenced\ by: org_harman_nav_ctrl_icon_lconProviderTypes::DesignParameters$

11.2.5 IconResourceSetId

Alias of actual type: UInt32

 $Referenced\ by: org_harman_nav_ctrl_icon_lconProvider::getlconResource$



11.2.6 IconResponseData

IconResponseData			
contains icon response information			
Structure Element	Туре	Description	
url	String		
iconType	IconType		
iconWidthInPixel	UInt32		
iconHeightInPixel	UInt32		
errorCode	ErrorCode		

Referenced by: org_harman_nav_ctrl_icon_lconProvider::getlconResource

11.2.7 IconType

IconType	
Literal	Description
IconType_POI	
IconType_TRAFFIC_EVENT	
IconType_TRAFFIC_ROAD_NUMBER	
IconType_ROAD_SIGN	
IconType_SIGN_POST	
IconType_COUNTRY_FLAG	

 $Referenced\ by: org_harman_nav_ctrl_icon_lconProviderTypes::lconResponseData$

11.2.8 ImageEncoding

ImageEncoding		
Literal	Description	
ImageEncoding_RAW_RGBA8888		
ImageEncoding_PNG		

 $Referenced\ by: org_harman_nav_ctrl_icon_lconProviderTypes::DesignParameters$



12 Common Types

12.1 org_harman_nav_ctrl_CommonTypes

Interface Version: 1.0

12.1.1 Area

Alias of actual type: Polygon

12.1.2 BasicEnum

BasicEnum	
Literal	Description
BasicEnum_INVALID	

12.1.3 Coordinate2D

Coordinate2D			
Structure Element	Туре	Description	
latitude	double		
longitude	double		

```
Referenced by: org_harman_nav_ctrl_CommonTypes::Rectangle, org_harman_nav_ctrl_CommonTypes::Rectangle, org_harman_nav_ctrl_CommonTypes::Polygon, org_harman_nav_ctrl_CommonTypes::Coordinate3D, org_harman_nav_ctrl_di_LocationInput::reverseGeocode, org_harman_nav_ctrl_di_POIServiceTypes::THBVector_Coordinate2D_, org_harman_nav_ctrl_mapv_MapViewControl::setCameraHeadingToTarget, org_harman_nav_ctrl_mapv_MapViewControl::getCameraHeading,
```



```
org_harman_nav_ctrl_mapv_MapViewControl::THBVector_Coordinate2D_, org_harman_nav_ctrl_mapv_MapViewControlTypes::CustomElement, org_harman_nav_ctrl_mapv_MapViewControlTypes::SelectedMapElement, org_harman_nav_ctrl_GuidanceTypes::LaneGuidanceInfo, org_harman_nav_ctrl_GuidanceTypes::ManeuverInfo, org_harman_nav_ctrl_RoutingTypes::IntermediatePoint
```

12.1.4 Coordinate3D

Coordinate3D			
Structure Element	Туре	Description	
_base	Coordinate2D		
altitude	Int32		

```
Referenced by: org_harman_nav_ctrl_di_LocationInputTypes::AddressValue,
org_harman_nav_ctrl_di_POIContentAccessModule::THBVector_Coordinate3D_,
org_harman_nav_ctrl_di_POISearch::setCenter,
org_harman_nav_ctrl_di_POIServiceTypes::PoiDetails,
org_harman_nav_ctrl_di_POIServiceTypes::PoiAddedDetails,
org_harman_nav_ctrl_di_POIServiceTypes::PoiCAMDetails,
org_harman_nav_ctrl_di_POIServiceTypes::PreviewDetails,
org_harman_nav_ctrl_ln_TrailTypes::TrailDetails, org_harman_nav_ctrl_ln_TrailTypes::TrailDetails,
org_harman_nav_ctrl_mapv_MapViewControl::setTargetPoint,
org_harman_nav_ctrl_mapv_MapViewControl::getTargetPoint,
org_harman_nav_ctrl_mapv_MapViewControl::setCameraPosition,
org_harman_nav_ctrl_mapv_MapViewControl::getCameraPosition,
org_harman_nav_ctrl_mapv_MapViewControlTypes::ScreenStatus,
org_harman_nav_ctrl_GuidanceTypes::WaypointInfo,
org harman nav ctrl RouteInfoTypes::SegmentDetails.
org_harman_nav_ctrl_RouteInfoTypes::SegmentDetails
```

12.1.5 Distance

Alias of actual type: double

```
Referenced by: org_harman_nav_ctrl_In_TrailTypes::TrailDetails, org_harman_nav_ctrl_In_TrailTypes::SettingValue, org_harman_nav_ctrl_GuidanceTypes::LaneGuidanceInfo, org_harman_nav_ctrl_GuidanceTypes::TravelCosts, org_harman_nav_ctrl_GuidanceTypes::ManeuverInfo, org_harman_nav_ctrl_GuidanceTypes::ManeuverInfo, org_harman_nav_ctrl_RouteInfoTypes::SegmentItem
```



12.1.6 Handle

Alias of actual type: UInt32

```
Referenced by : org harman nay ctrl di LocationInput::createLocationInput.
org harman nav ctrl di LocationInput::deleteLocationInput,
org harman nav ctrl di LocationInput::setAddress,
org harman nav ctrl di LocationInput::setSelectionCriterion,
org harman nav ctrl di LocationInput::spell, org harman nav ctrl di LocationInput::search,
org_harman_nav_ctrl_di_LocationInput::requestListUpdate,
org_harman_nav_ctrl_di_LocationInput::selectEntry, org_harman_nav_ctrl_di_LocationInput::getEntry,
org harman nav ctrl di LocationInput::validateAddress,
org_harman_nav_ctrl_di_LocationInput::reverseGeocode,
org_harman_nav_ctrl_di_LocationInput::currentSelectionCriterion,
org harman nav ctrl di LocationInput::spellResult,
org harman nav ctrl di LocationInput::searchResultList,
org_harman_nav_ctrl_di_LocationInput::searchResultListSizeChanged,
org_harman_nav_ctrl_di_LocationInput::contentUpdated,
org harman nav ctrl di LocationInput::addressValidationResult,
org harman nav ctrl di OneBoxSearch::createOneBoxSearch,
org_harman_nav_ctrl_di_OneBoxSearch::deleteOneBoxSearch,
org_harman_nav_ctrl_di_OneBoxSearch::setSearchCountry,
org_harman_nav_ctrl_di_OneBoxSearch::setSearchLanguage,
org_harman_nav_ctrl_di_OneBoxSearch::setSearchParameters,
org harman nav ctrl di OneBoxSearch::startOneBoxSearch,
org harman nav ctrl di OneBoxSearch::cancelOneBoxSearch,
org harman nav ctrl di OneBoxSearch::requestResultList,
org_harman_nav_ctrl_di_OneBoxSearch::selectEntry,
org_harman_nav_ctrl_di_OneBoxSearch::getEntry,
org harman nav ctrl di OneBoxSearch::searchStatus,
org_harman_nav_ctrl_di_OneBoxSearch::searchResultList,
org_harman_nav_ctrl_di_OneBoxSearch::searchResultListSizeChanged,
org_harman_nav_ctrl_di_POIContentAccessModule::poiSearchStarted,
org harman nav ctrl di POIContentAccessModule::poiSearchCanceled,
org_harman_nav_ctrl_di_POIContentAccessModule::resultListRequested.
org harman nav ctrl di POIContentAccessModule::searchStatus,
org harman nav ctrl di POISearch::createPoiSearchHandle,
org_harman_nav_ctrl_di_POISearch::deletePoiSearchHandle,
org_harman_nav_ctrl_di_POISearch::setCenter,
org_harman_nav_ctrl_di_POISearch::setRouteHandle,
org harman nav ctrl di POISearch::setRouteHandle,
org_harman_nav_ctrl_di_POISearch::setCategories,
org_harman_nav_ctrl_di_POISearch::setSearchRadius,
org_harman_nav_ctrl_di_POISearch::setMaximumResults,
org_harman_nav_ctrl_di_POISearch::setAttributes,
org_harman_nav_ctrl_di_POISearch::startPoiSearch,
org harman nav ctrl di POISearch::cancelPoiSearch,
org harman nav ctrl di POISearch::requestResultList,
org harman nav ctrl di POISearch::poiStatus,
org_harman_nav_ctrl_di_POISearch::resultListChanged,
org_harman_nav_ctrl_di_POISearch::getPoiData,
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org_harman_nav_ctrl_di_SpeechLocationInput::getSpeechModesList,
org_harman_nav_ctrl_di_SpeechLocationInput::getSpeechList,
org_harman_nav_ctrl_di_SpeechLocationInput::getSpeechOrtographies,
org_harman_nav_ctrl_icon_lconProvider::createSession,
org_harman_nav_ctrl_icon_lconProvider::deleteSession,
org_harman_nav_ctrl_icon_lconProvider::getlconResource,
org_harman_nav_ctrl_mapv_MapViewControl::createMapViewInstance,
org_harman_nav_ctrl_mapv_MapViewControl::createMapViewInstance,
org_harman_nav_ctrl_mapv_MapViewControl::releaseMapViewInstance,
org_harman_nav_ctrl_mapv_MapViewControl::releaseMapViewInstance,
org_harman_nav_ctrl_mapv_MapViewControl::getMapViewType,
org_harman_nav_ctrl_mapv_MapViewControl::setTargetPoint,
org_harman_nav_ctrl_mapv_MapViewControl::setTargetPoint,
org_harman_nav_ctrl_mapv_MapViewControl::getTargetPoint,
org_harman_nav_ctrl_mapv_MapViewControl::setFollowCarMode,
org harman nav ctrl mapv MapViewControl::setFollowCarMode,
org_harman_nav_ctrl_mapv_MapViewControl::getFollowCarMode,
org_harman_nav_ctrl_mapv_MapViewControl::setCameraPosition,
org_harman_nav_ctrl_mapv_MapViewControl::setCameraPosition,
org_harman_nav_ctrl_mapv_MapViewControl::getCameraPosition,
org_harman_nav_ctrl_mapv_MapViewControl::setCameraHeadingAngle,
org_harman_nav_ctrl_mapv_MapViewControl::setCameraHeadingAngle,
org harman nav ctrl mapv MapViewControl::setCameraHeadingToTarget,
org_harman_nav_ctrl_mapv_MapViewControl::setCameraHeadingToTarget,
org_harman_nav_ctrl_mapv_MapViewControl::setCameraHeadingTrackUp,
org_harman_nav_ctrl_mapv_MapViewControl::setCameraHeadingTrackUp,
org_harman_nav_ctrl_mapv_MapViewControl::getCameraHeading,
org_harman_nav_ctrl_mapv_MapViewControl::setCameraTiltAngle,
org_harman_nav_ctrl_mapv_MapViewControl::setCameraTiltAngle,
org_harman_nav_ctrl_mapv_MapViewControl::getCameraTiltAngle,
org_harman_nav_ctrl_mapv_MapViewControl::setCameraRollAngle,
org_harman_nav_ctrl_mapv_MapViewControl::setCameraRollAngle,
org_harman_nav_ctrl_mapv_MapViewControl::getCameraRollAngle,
org_harman_nav_ctrl_mapv_MapViewControl::setCameraDistanceFromTargetPoint,
org_harman_nav_ctrl_mapv_MapViewControl::setCameraDistanceFromTargetPoint,
org_harman_nav_ctrl_mapv_MapViewControl::getCameraDistanceFromTargetPoint,
org_harman_nav_ctrl_mapv_MapViewControl::setMapViewScaleMode,
org_harman_nav_ctrl_mapv_MapViewControl::setMapViewScaleMode,
org_harman_nav_ctrl_mapv_MapViewControl::getMapViewScaleMode,
org_harman_nav_ctrl_mapv_MapViewControl::getSupportedMapViewScaleModes,
org_harman_nav_ctrl_mapv_MapViewControl::setCameraHeight,
org_harman_nav_ctrl_mapv_MapViewControl::setCameraHeight,
org_harman_nav_ctrl_mapv_MapViewControl::getCameraHeight,
org_harman_nav_ctrl_mapv_MapViewControl::setMapViewPerspective,
org harman nav ctrl mapv MapViewControl::setMapViewPerspective,
org_harman_nav_ctrl_mapv_MapViewControl::getMapViewPerspective.
org_harman_nav_ctrl_mapv_MapViewControl::setMapViewObjectVisibility,
org_harman_nav_ctrl_mapv_MapViewControl::setMapViewObjectVisibility,
org_harman_nav_ctrl_mapv_MapViewControl::getMapViewObjectVisibility,
org_harman_nav_ctrl_mapv_MapViewControl::getSupportedMapViewObjectVisibilities,
org_harman_nav_ctrl_mapv_MapViewControl::getScaleList,
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org_harman_nav_ctrl_mapv_MapViewControl::setMapViewScale,
org_harman_nav_ctrl_mapv_MapViewControl::setMapViewScale,
org_harman_nav_ctrl_mapv_MapViewControl::setMapViewScaleByDelta,
org_harman_nav_ctrl_mapv_MapViewControl::setMapViewScaleByDelta,
org_harman_nav_ctrl_mapv_MapViewControl::setMapViewScaleByMetersPerPixel,
org_harman_nav_ctrl_mapv_MapViewControl::setMapViewScaleByMetersPerPixel,
org_harman_nav_ctrl_mapv_MapViewControl::getMapViewScale,
org_harman_nav_ctrl_mapv_MapViewControl::setMapViewBoundingBox,
org_harman_nav_ctrl_mapv_MapViewControl::setMapViewBoundingBox,
org_harman_nav_ctrl_mapv_MapViewControl::getMapViewBoundingBox,
org_harman_nav_ctrl_mapv_MapViewControl::setMapViewSaveArea,
org_harman_nav_ctrl_mapv_MapViewControl::setMapViewSaveArea,
org_harman_nav_ctrl_mapv_MapViewControl::getMapViewSaveArea,
org_harman_nav_ctrl_mapv_MapViewControl::setMapViewPan,
org_harman_nav_ctrl_mapv_MapViewControl::setMapViewPan,
org harman nav ctrl mapv MapViewControl::setMapViewRotation.
org_harman_nav_ctrl_mapv_MapViewControl::setMapViewRotation,
org_harman_nav_ctrl_mapv_MapViewControl::getMapViewRotation,
org_harman_nav_ctrl_mapv_MapViewControl::setMapViewVisibilityMode,
org_harman_nav_ctrl_mapv_MapViewControl::setMapViewVisibilityMode,
org_harman_nav_ctrl_mapv_MapViewControl::getMapViewVisibilityMode,
org_harman_nav_ctrl_mapv_MapViewControl::setMapViewPerformanceLevel,
org harman nav ctrl mapv MapViewControl::setMapViewPerformanceLevel.
org_harman_nav_ctrl_mapv_MapViewControl::getMapViewPerformanceLevel,
org_harman_nav_ctrl_mapv_MapViewControl::displayRoute,
org_harman_nav_ctrl_mapv_MapViewControl::displayRoute,
org_harman_nav_ctrl_mapv_MapViewControl::displayRoute,
org_harman_nav_ctrl_mapv_MapViewControl::hideRoute,
org_harman_nav_ctrl_mapv_MapViewControl::hideRoute,
org_harman_nav_ctrl_mapv_MapViewControl::hideRoute,
org_harman_nav_ctrl_mapv_MapViewControl::getDisplayedRoutes,
org_harman_nav_ctrl_mapv_MapViewControl::addKml,
org_harman_nav_ctrl_mapv_MapViewControl::addKml,
org_harman_nav_ctrl_mapv_MapViewControl::addKml,
org_harman_nav_ctrl_mapv_MapViewControl::deleteKml,
org_harman_nav_ctrl_mapv_MapViewControl::deleteKml,
org_harman_nav_ctrl_mapv_MapViewControl::deleteKml,
org_harman_nav_ctrl_mapv_MapViewControl::setKmlVisibility,
org_harman_nav_ctrl_mapv_MapViewControl::setKmlVisibility,
org_harman_nav_ctrl_mapv_MapViewControl::setKmlVisibility,
org_harman_nav_ctrl_mapv_MapViewControl::pushSettings,
org_harman_nav_ctrl_mapv_MapViewControl::pushSettings,
org_harman_nav_ctrl_mapv_MapViewControl::popSettings,
org_harman_nav_ctrl_mapv_MapViewControl::popSettings,
org harman nav ctrl mapv MapViewControl::resetSettings.
org_harman_nav_ctrl_mapv_MapViewControl::resetSettings,
org_harman_nav_ctrl_mapv_MapViewControl::displayObjectList,
org_harman_nav_ctrl_mapv_MapViewControl::displayObjectList,
org_harman_nav_ctrl_mapv_MapViewControl::hideObjectList,
org_harman_nav_ctrl_mapv_MapViewControl::hideObjectList,
org_harman_nav_ctrl_mapv_MapViewControl::highlightObjectListItem,
```



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org_harman_nav_ctrl_mapv_MapViewControl::highlightObjectListItem,
org_harman_nav_ctrl_mapv_MapViewControl::centerOnObjectListItems,
org_harman_nav_ctrl_mapv_MapViewControl::centerOnObjectListItems,
org_harman_nav_ctrl_mapv_MapViewControl::getPoiCategoriesVisible,
org_harman_nav_ctrl_mapv_MapViewControl::setPoiCategoriesVisible,
org_harman_nav_ctrl_mapv_MapViewControl::setPoiCategoriesVisible,
org_harman_nav_ctrl_mapv_MapViewControl::setPoiCategoriesVisibleMode,
org_harman_nav_ctrl_mapv_MapViewControl::setPoiCategoriesVisibleMode,
org_harman_nav_ctrl_mapv_MapViewControl::setPoiCategoriesVisibleWithinLimits,
org_harman_nav_ctrl_mapv_MapViewControl::setPoiCategoriesVisibleWithinLimits,
org_harman_nav_ctrl_mapv_MapViewControl::setPoiCategoriesNotVisible,
org_harman_nav_ctrl_mapv_MapViewControl::setPoiCategoriesNotVisible,
org_harman_nav_ctrl_mapv_MapViewControl::setTrafficIncidentsVisibility,
org_harman_nav_ctrl_mapv_MapViewControl::setTrafficIncidentsVisibility,
org_harman_nav_ctrl_mapv_MapViewControl::setMapViewTheme,
org harman nav ctrl mapv MapViewControl::setMapViewTheme,
org_harman_nav_ctrl_mapv_MapViewControl::getMapViewTheme,
org_harman_nav_ctrl_mapv_MapViewControl::convertPixelCoordsToGeoCoords,
org_harman_nav_ctrl_mapv_MapViewControl::convertPixelCoordsToGeoCoords,
org_harman_nav_ctrl_mapv_MapViewControl::convertGeoCoordsToPixelCoords,
org_harman_nav_ctrl_mapv_MapViewControl::convertGeoCoordsToPixelCoords,
org_harman_nav_ctrl_mapv_MapViewControl::displayCustomElements,
org harman nav ctrl mapv MapViewControl::displayCustomElements,
org_harman_nav_ctrl_mapv_MapViewControl::hideCustomElements,
org_harman_nav_ctrl_mapv_MapViewControl::hideCustomElements,
org_harman_nav_ctrl_mapv_MapViewControl::getDisplayedCustomElements,
org_harman_nav_ctrl_mapv_MapViewControl::selectElementsOnMap,
org_harman_nav_ctrl_mapv_MapViewControl::mapViewGesture,
org_harman_nav_ctrl_mapv_MapViewControl::mapViewGesture,
org_harman_nav_ctrl_mapv_MapViewControl::mapShowRouteOverview,
org_harman_nav_ctrl_mapv_MapViewControl::mapShowRouteOverview,
org_harman_nav_ctrl_mapv_MapViewControl::mapSetStyle,
org_harman_nav_ctrl_mapv_MapViewControl::mapSetStyle,
org_harman_nav_ctrl_mapv_MapViewControl::getMapModeList,
org_harman_nav_ctrl_mapv_MapViewControl::setMapMode,
org_harman_nav_ctrl_mapv_MapViewControl::setMapMode,
org_harman_nav_ctrl_mapv_MapViewControl::getMapMode,
org_harman_nav_ctrl_mapv_MapViewControl::getMapMode,
org_harman_nav_ctrl_mapv_MapViewControl::setAutozoomSetting,
org_harman_nav_ctrl_mapv_MapViewControl::setAutozoomSetting,
org_harman_nav_ctrl_mapv_MapViewControl::getAutozoomSetting,
org_harman_nav_ctrl_mapv_MapViewControl::getAutozoomSetting,
org_harman_nav_ctrl_mapv_MapViewControl::setAutozoomEnabled,
org_harman_nav_ctrl_mapv_MapViewControl::setAutozoomEnabled,
org harman nav ctrl mapv MapViewControl::getAutozoomEnabled,
org_harman_nav_ctrl_mapv_MapViewControl::getAutozoomEnabled,
org_harman_nav_ctrl_mapv_MapViewControl::mapViewScaleChanged,
org_harman_nav_ctrl_mapv_MapViewControl::mapViewVisibilityChanged,
org_harman_nav_ctrl_mapv_MapViewControl::displayedRoutes,
org_harman_nav_ctrl_mapv_MapViewControl::THBVector_Handle_,
org_harman_nav_ctrl_mapv_MapViewControlTypes::ObjectList,
```



```
org_harman_nav_ctrl_mapv_MapViewControlTypes::ElementValue,
org harman nav ctrl mapv MapViewControlTypes::DisplayedRoute,
org_harman_nav_ctrl_mapv_MapViewControlTypes::ScreenStatus,
org_harman_nav_ctrl_Guidance::startGuidance, org_harman_nav_ctrl_Guidance::getGuidanceStatus,
org harman nav ctrl Guidance::selectAlternativeTIRoute,
org_harman_nav_ctrl_Guidance::guidanceStatusChanged,
org_harman_nav_ctrl_Guidance::alternativeTIRouteInvalidated,
org_harman_nav_ctrl_GuidanceTypes::RouteCostData, org_harman_nav_ctrl_Routing::createRoute,
org_harman_nav_ctrl_Routing::deleteRoute, org_harman_nav_ctrl_Routing::setCostModel,
org_harman_nav_ctrl_Routing::getCostModel, org_harman_nav_ctrl_Routing::setRoutePreferences,
org_harman_nav_ctrl_Routing::getRoutePreferences,
org_harman_nav_ctrl_Routing::setRouteSchedule, org_harman_nav_ctrl_Routing::getRouteSchedule,
org_harman_nav_ctrl_Routing::setWaypoints, org_harman_nav_ctrl_Routing::getWaypoints,
org_harman_nav_ctrl_Routing::calculateRoute,
org_harman_nav_ctrl_Routing::cancelRouteCalculation,
org harman nav ctrl Routing::calculateAlternateRoute,
org_harman_nav_ctrl_Routing::getRouteOverview,
org_harman_nav_ctrl_Routing::setBlockedRouteStretch, org_harman_nav_ctrl_Routing::routeDeleted,
org_harman_nav_ctrl_Routing::routeCalculationCancelled,
org_harman_nav_ctrl_Routing::routeCalculationSuccessful,
org_harman_nav_ctrl_Routing::routeCalculationFailed,
org_harman_nav_ctrl_Routing::routeCalculationProgressUpdate,
org harman nav ctrl Routing::THBVector Handle,
org harman nav ctrl speedcam SpeedCamService::createSession,
org_harman_nav_ctrl_speedcam_SpeedCamService::deleteSession,
org_harman_nav_ctrl_speedcam_SpeedCamService::reportSpeedcam,
org_harman_nav_ctrl_speedcam_SpeedCamService::declineSpeedCam,
org_harman_nav_ctrl_speedcam_SpeedCamService::confirmSpeedCam,
org_harman_nav_ctrl_speedcam_SpeedCamService::declineExistingSpeedCam,
org_harman_nav_ctrl_speedcam_SpeedCamService::confirmExistingSpeedCam,
org_harman_nav_ctrl_speedcam_SpeedCamService::forthcomingEvent
```

12.1.7 Linkld

Alias of actual type: Buffer

12.1.8 Polygon

Vector of element type Coordinate2D

12.1.9 Rectangle

Rectangle			
Structure Element	Туре	Description	
topLeft	Coordinate2D		



Rectangle		
bottomRight	Coordinate2D	

12.1.10 Slcon

Sicon			
Structure Element	Туре	Description	
dummy	Int32		

Referenced by: org_harman_nav_ctrl_highwaymode_HighwayModeTypes::HighwayItem, org_harman_nav_ctrl_speedcam_SpeedCamServiceTypes::SSpeedCamEvent, org_harman_nav_ctrl_traffic_TrafficInformationTypes::SBaseMessage, org_harman_nav_ctrl_traffic_TrafficInformationTypes::SBaseMessage

12.1.11 TDistance_dm

Type to represent distances and lengths. Unit is decimeter (=0.1 m = 10 cm). This unit was chosen because: - it is small enough to represent "feet" distances in a unique way (e.g. when distances to maneuver points are displayed in feet units), and - for smaller units, like cm or mm, the maximum 32 bit value would be close to possible route lengths ($2^32 \, \text{dm} \sim 400,000 \, \text{km}$, which is 10 times around the world). This type was chosen to be "unsigned" because no use case with negative distances was found. Alias of actual type: **UInt32**

Referenced by : org_harman_nav_ctrl_speedcam_SpeedCamServiceTypes::SSpeedCamEvent, org_harman_nav_ctrl_traffic_TrafficInformationTypes::SBaseMessage, org_harman_nav_ctrl_traffic_TrafficInformationTypes::SMessage

12.1.12 TTime sec

Alias of actual type: UInt32

Referenced by: org_harman_nav_ctrl_traffic_TrafficInformationTypes::SMessage

12.1.13 Timestamp

Alias of actual type: UInt64

Referenced by: org_harman_nav_ctrl_ln_TrailTypes::TrailDetails, org_harman_nav_ctrl_ln_TrailTypes::TrailDetails, org_harman_nav_ctrl_PositioningTypes::GpsTime, org_harman_nav_ctrl_PositioningTypes::AddressItemValue, org_harman_nav_ctrl_PositioningTypes::PositionStatusValue,



org_harman_nav_ctrl_PositioningTypes::PositionItemValue, org_harman_nav_ctrl_speedcam_SpeedCamOnlineServiceTypes::SSpeedCamFeedback

12.1.14 Version

Version		
version.		
Structure Element	Туре	Description
versionMajor	UInt16	when the major changes, then backward compatibility with previous releases is not granted.
versionMinor	UInt16	when the minor changes, then backward compatibility with previous releases is granted, but something changed in the implementation of the API (e.g. new methods may have been added).
versionMicro	UInt16	when the micro changes, then backward compatibility with previous releases is granted (bug fixes or documentation modifications).
date	String	release date (e.g. 21-06-2011).

Referenced by : org_harman_nav_ctrl_di_LocationInput::getVersion,

org_harman_nav_ctrl_di_OneBoxSearch::getVersion,

org_harman_nav_ctrl_di_POIContentAccessModule::getVersion,

org_harman_nav_ctrl_di_POISearch::getVersion,

org_harman_nav_ctrl_mapv_MapViewControl::getVersion

12.2 org_harman_nav_ctrl_common_list_ListTypes

Interface Version: 1.0

12.2.1 AnchorOffset

the relative view anchor based on position ListKey Alias of actual type: UInt16

Referenced by: org_harman_nav_ctrl_common_list_ListTypes::ViewSnapshotPosition,

org_harman_nav_ctrl_highwaymode_HighwayMode::setViewAnchor,

org harman nav ctrl In Trails::setViewAnchor,

org_harman_nav_ctrl_memory_LocationMemory::setViewAnchor,

org_harman_nav_ctrl_RouteInfo::setViewAnchor,

org_harman_nav_ctrl_traffic_TrafficInformation::setViewAnchor



12.2.2 ListError

ListError	
Literal	Description
ListError_BasicEnum_INVALID	
ListError_INVALID_LIST_ID	occurs if the list id was invalid.
ListError_INVALID_VIEW	view identification used to distinguish several instances of a view for one client. It is never changed by the service nor the client.
ListError_INVALID_PARAMETER	occurs if one of the provided parameters was not acceptable.
ListError_SIZE_LIMIT_EXCEEDED	occurs if the implementation can not provide such large views.
ListError_OUT_OF_RESSOURCES	occurs if there are not enough resources available to create another view (e.g. memory).
ListError_OUT_OF_RANGE_POSITION	occurs if there is request a position which is not available
ListError_POLICY_DENIED	Some policy could not be executed.

12.2.3 ListId

ListId			
The ListId is the name of a list.			
Structure Element	Туре	Description	
listname	String		

```
Referenced by: org_harman_nav_ctrl_highwaymode_HighwayMode::getListSize, org_harman_nav_ctrl_highwaymode_HighwayMode::createView, org_harman_nav_ctrl_highwaymode_HighwayMode::listSize, org_harman_nav_ctrl_ln_Trails::getListSize, org_harman_nav_ctrl_ln_Trails::createView, org_harman_nav_ctrl_ln_Trails::listSize, org_harman_nav_ctrl_memory_LocationMemory::getListSize, org_harman_nav_ctrl_memory_LocationMemory::removeAll, org_harman_nav_ctrl_memory_LocationMemory::removeItem, org_harman_nav_ctrl_memory_LocationMemory::addItem, org_harman_nav_ctrl_memory_LocationMemory::addItemLocation, org_harman_nav_ctrl_memory_LocationMemory::setItemName, org_harman_nav_ctrl_memory_LocationMemory::createSpeechFile, org_harman_nav_ctrl_memory_LocationMemory::importLocationItemList, org_harman_nav_ctrl_memory_LocationMemory::listSize, org_harman_nav_ctrl_memory_LocationMemory::THBVector_ListId_,
```



```
org_harman_nav_ctrl_memory_LocationMemoryTypes::ListSetting,
org_harman_nav_ctrl_RouteInfo::getListSize, org_harman_nav_ctrl_RouteInfo::createView,
org_harman_nav_ctrl_RouteInfo::listSize, org_harman_nav_ctrl_RouteInfo::THBVector_ListId_,
org_harman_nav_ctrl_traffic_TrafficInformation::getListSize,
org_harman_nav_ctrl_traffic_TrafficInformation::createView,
org_harman_nav_ctrl_traffic_TrafficInformation::listSize,
org_harman_nav_ctrl_traffic_TrafficInformation::THBVector_ListId_
```

12.2.4 ListKey

Absolute position within the whole list Alias of actual type: UInt16

```
Referenced by: org_harman_nav_ctrl_common_list_ListTypes::ViewSnapshotPosition, org_harman_nav_ctrl_highwaymode_HighwayMode::setViewPosition, org_harman_nav_ctrl_highwaymode_HighwayMode::getResultList, org_harman_nav_ctrl_ln_Trails::setViewPosition, org_harman_nav_ctrl_memory_LocationMemory::createView, org_harman_nav_ctrl_memory_LocationMemory::setViewPosition, org_harman_nav_ctrl_memory_LocationMemory::getActiveAutoNavItems, org_harman_nav_ctrl_RouteInfo::setViewPosition, org_harman_nav_ctrl_traffic_TrafficInformation::setViewPosition
```

12.2.5 ListSize

total size of the whole list Alias of actual type: UInt16

```
Referenced by: org_harman_nav_ctrl_common_list_ListTypes::ViewSnapshotPosition, org_harman_nav_ctrl_highwaymode_HighwayMode::getListSize, org_harman_nav_ctrl_highwaymode_HighwayMode::viewUpdate, org_harman_nav_ctrl_highwaymode_HighwayMode::listSize, org_harman_nav_ctrl_ln_Trails::getListSize, org_harman_nav_ctrl_ln_Trails::getListSize, org_harman_nav_ctrl_memory_LocationMemory::getListSize, org_harman_nav_ctrl_memory_LocationMemory::listSize, org_harman_nav_ctrl_memory_LocationMemory::viewUpdate, org_harman_nav_ctrl_RouteInfo::getListSize, org_harman_nav_ctrl_RouteInfo::viewUpdate, org_harman_nav_ctrl_RouteInfo::listSize, org_harman_nav_ctrl_traffic_TrafficInformation::viewUpdate, org_harman_nav_ctrl_traffic_TrafficI
```

12.2.6 ModificationPolicy

ModificationPolicy		
Literal	Description	
ModificationPolicy_E_POLLICY_ADD		
ModificationPolicy_E_POLICY_REMOVE		



ModificationPolicy	
ModificationPolicy_E_POLICY_REMOVE_ALL	

Referenced by: org_harman_nav_ctrl_memory_LocationMemoryTypes::ListSetting

12.2.7 SortOption

SortOption		
Literal	Description	
SortOption_BasicEnum_INVALID		
SortOption_TYPE		
SortOption_NAME		
SortOption_TIME		
SortOption_CUSTOM_SORT_1		
SortOption_CUSTOM_SORT_2		
SortOption_CUSTOM_SORT_3		
SortOption_CUSTOM_SORT_4		
SortOption_CUSTOM_SORT_5		
SortOption_CUSTOM_SORT_6		
SortOption_CUSTOM_SORT_7		
SortOption_CUSTOM_SORT_8		

Referenced by: org_harman_nav_ctrl_common_list_ListTypes::SortOptionList, org_harman_nav_ctrl_memory_LocationMemory::setSortOrder, org_harman_nav_ctrl_memory_LocationMemory::getSortOrder, org_harman_nav_ctrl_memory_LocationMemoryTypes::THBVector_SortOption_

12.2.8 SortOptionList

Vector of element type **SortOption**

12.2.9 ViewId

every create view is assigned to one view id Alias of actual type: UInt16

Referenced by : org_harman_nav_ctrl_highwaymode_HighwayMode::createView, org_harman_nav_ctrl_highwaymode_HighwayMode::deleteView,



```
org_harman_nav_ctrl_highwaymode_HighwayMode::setViewSize,
org_harman_nav_ctrl_highwaymode_HighwayMode::setViewPosition,
org_harman_nav_ctrl_highwaymode_HighwayMode::setViewAnchor,
org_harman_nav_ctrl_highwaymode_HighwayMode::getResultList,
org_harman_nav_ctrl_highwaymode_HighwayMode::getMessageDetails,
org_harman_nav_ctrl_highwaymode_HighwayMode::viewUpdate,
org_harman_nav_ctrl_ln_Trails::createView, org_harman_nav_ctrl_ln_Trails::deleteView,
org_harman_nav_ctrl_ln_Trails::setViewSize, org_harman_nav_ctrl_ln_Trails::setViewPosition,
org_harman_nav_ctrl_ln_Trails::setViewAnchor, org_harman_nav_ctrl_ln_Trails::getViewData,
org_harman_nav_ctrl_ln_Trails::viewUpdate,
org_harman_nav_ctrl_memory_LocationMemory::createView,
org_harman_nav_ctrl_memory_LocationMemory::deleteView,
org_harman_nav_ctrl_memory_LocationMemory::setViewSize,
org_harman_nav_ctrl_memory_LocationMemory::setViewPosition,
org_harman_nav_ctrl_memory_LocationMemory::setViewAnchor,
org harman nav ctrl memory LocationMemory::setSortOrder,
org_harman_nav_ctrl_memory_LocationMemory::getSortOrder,
org_harman_nav_ctrl_memory_LocationMemory::removeItem,
org_harman_nav_ctrl_memory_LocationMemory::getResultList,
org_harman_nav_ctrl_memory_LocationMemory::getActiveAutoNavItems,
org_harman_nav_ctrl_memory_LocationMemory::addItem,
org_harman_nav_ctrl_memory_LocationMemory::getItemDetails,
org harman nav ctrl memory LocationMemory::getActiveItems,
org_harman_nav_ctrl_memory_LocationMemory::setTimeslot,
org_harman_nav_ctrl_memory_LocationMemory::filterView,
org_harman_nav_ctrl_memory_LocationMemory::setLocationItem,
org_harman_nav_ctrl_memory_LocationMemory::viewUpdate,
org_harman_nav_ctrl_RouteInfo::createView, org_harman_nav_ctrl_RouteInfo::deleteView,
org_harman_nav_ctrl_RouteInfo::setViewSize, org_harman_nav_ctrl_RouteInfo::setViewPosition,
org_harman_nav_ctrl_RouteInfo::setViewAnchor, org_harman_nav_ctrl_RouteInfo::getResultList,
org_harman_nav_ctrl_RouteInfo::getItemDetails, org_harman_nav_ctrl_RouteInfo::viewUpdate,
org_harman_nav_ctrl_traffic_TrafficInformation::createView,
org_harman_nav_ctrl_traffic_TrafficInformation::deleteView,
org_harman_nav_ctrl_traffic_TrafficInformation::setViewSize,
org_harman_nav_ctrl_traffic_TrafficInformation::setViewPosition,
org_harman_nav_ctrl_traffic_TrafficInformation::setViewAnchor,
org_harman_nav_ctrl_traffic_TrafficInformation::getViewData,
org_harman_nav_ctrl_traffic_TrafficInformation::viewUpdate
```

12.2.10 ViewKey

relative position within the view window only starting from the first view element Alias of actual type: **UInt16**

```
Referenced by: org_harman_nav_ctrl_common_list_ListTypes::ViewKeyList, org_harman_nav_ctrl_memory_LocationMemory::removeItem, org_harman_nav_ctrl_memory_LocationMemory::addItem, org_harman_nav_ctrl_memory_LocationMemory::getItemDetails, org_harman_nav_ctrl_memory_LocationMemory::setTimeslot, org_harman_nav_ctrl_memory_LocationMemory::setLocationItem, org_harman_nav_ctrl_memory_LocationMemory::THBVector_ViewKey_,
```



org_harman_nav_ctrl_memory_LocationMemoryTypes::ViewKeyList, org_harman_nav_ctrl_RouteInfo::getItemDetails

12.2.11 ViewKeyList

Vector of element type ViewKey

12.2.12 **ViewSize**

size related to the created view only Alias of actual type: ListSize

```
Referenced by: org_harman_nav_ctrl_highwaymode_HighwayMode::createView, org_harman_nav_ctrl_highwaymode_HighwayMode::setViewSize, org_harman_nav_ctrl_ln_Trails::createView, org_harman_nav_ctrl_ln_Trails::setViewSize, org_harman_nav_ctrl_memory_LocationMemory::createView, org_harman_nav_ctrl_memory_LocationMemory::setViewSize, org_harman_nav_ctrl_RouteInfo::createView, org_harman_nav_ctrl_RouteInfo::setViewSize, org_harman_nav_ctrl_traffic_TrafficInformation::createView, org_harman_nav_ctrl_traffic_TrafficInformation::setViewSize
```

12.2.13 ViewSnapshotPosition

ViewSnapshotPosition			
description of how the snapshot of a view was positioned when querying the data contained in a view			
Structure Element	Туре	Description	
listSize	ListSize	size of the underlying list	
listKey	ListKey	key of the first element of the view snapshot	
anchorOffset	AnchorOffset	offset of the anchor element within the view snapshot	

```
Referenced by: org_harman_nav_ctrl_ln_Trails::getViewData, org_harman_nav_ctrl_memory_LocationMemory::getResultList, org_harman_nav_ctrl_RouteInfo::getResultList, org_harman_nav_ctrl_traffic_TrafficInformation::getViewData
```