

Front End Design Group  
System Level Design Team

# Internal Training

## TLM 2.0 Library

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Design Engineering Division

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**v1.2**

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Confidential

# Outline

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1. Transaction Level Modeling (TLM)
2. Objects in TLM2.0
3. TLM2.0 library
4. Connection
5. Communication
6. TLM2.0 with Forest
7. Topics

# Outline

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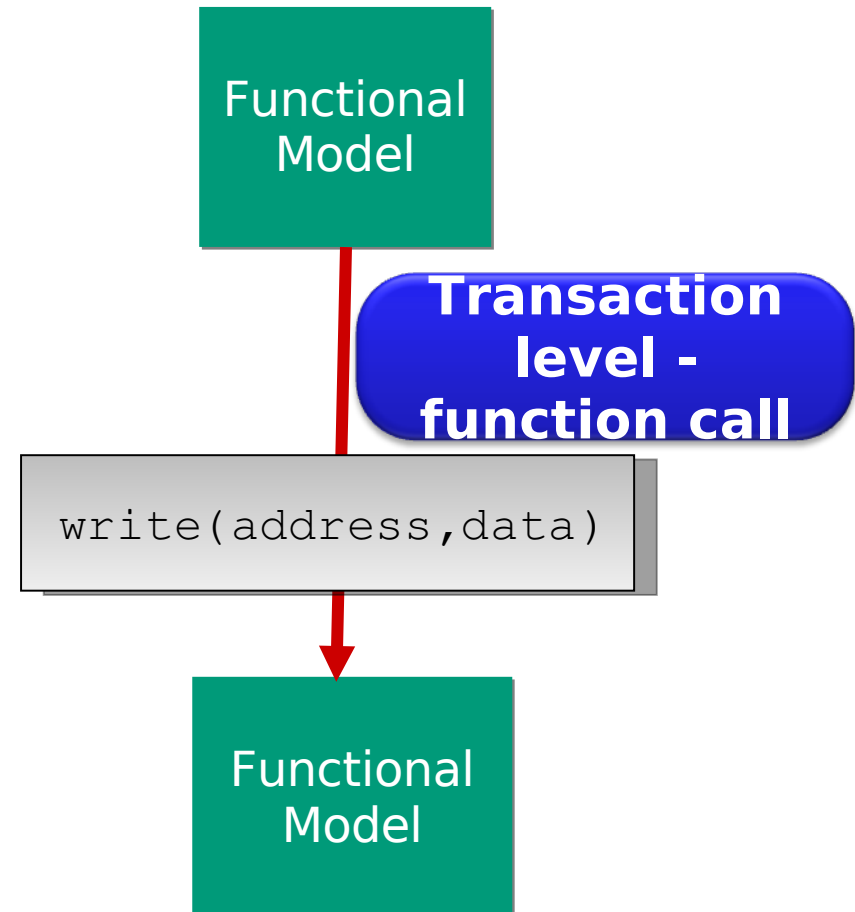
1. Transaction Level Modeling (TLM)
2. Objects in TLM2.0
3. TLM2.0 library
4. Connection
5. Communication
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7. Topics

# 1. Transaction Level Modeling (TLM) (1/3)

**TLM** is a concept without precise definition. A working group of **Open SystemC Initiative** (OSCI) is currently defining a set of terminology for TLM and developing TLM standards.

**TLM** is used to solve these problems:

- Providing an early platform for software development.
- Aiding software/hardware integration.
- Enabling software performance analysis.
- System Level Design architecture analysis.
- Functional hardware verification.



# 1. Transaction Level Modeling (TLM) (2/3)

## Reasons of using TLM

- Architectural exploration, performance modelling
- Software execution on virtual model of hardware platform
- Golden model for hardware functional verification
- Available before RTL
- Simulation much faster than RTL (100-10.000 times)



Earlier

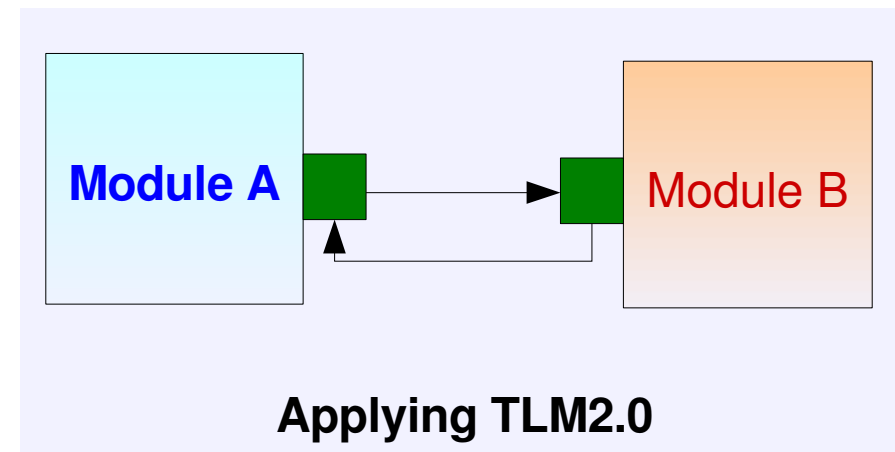
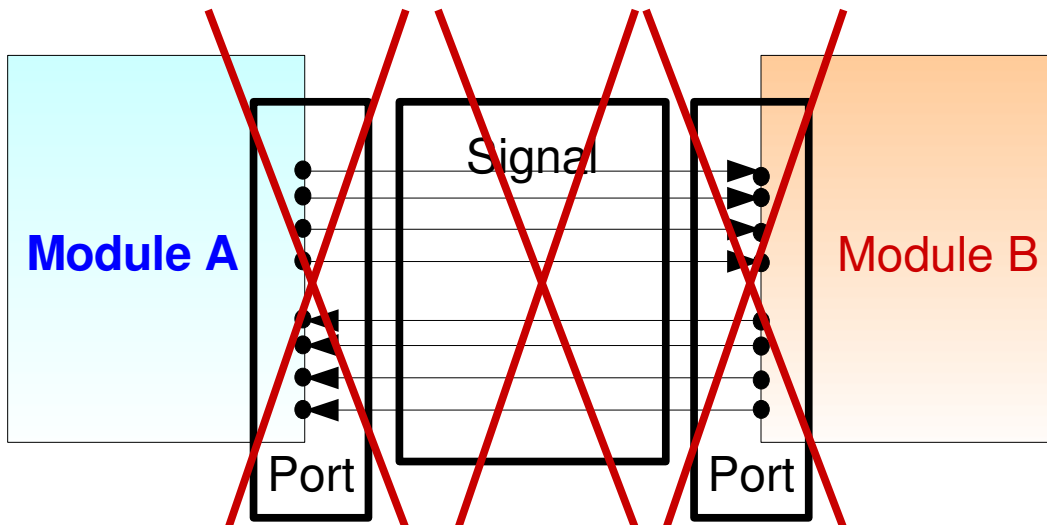
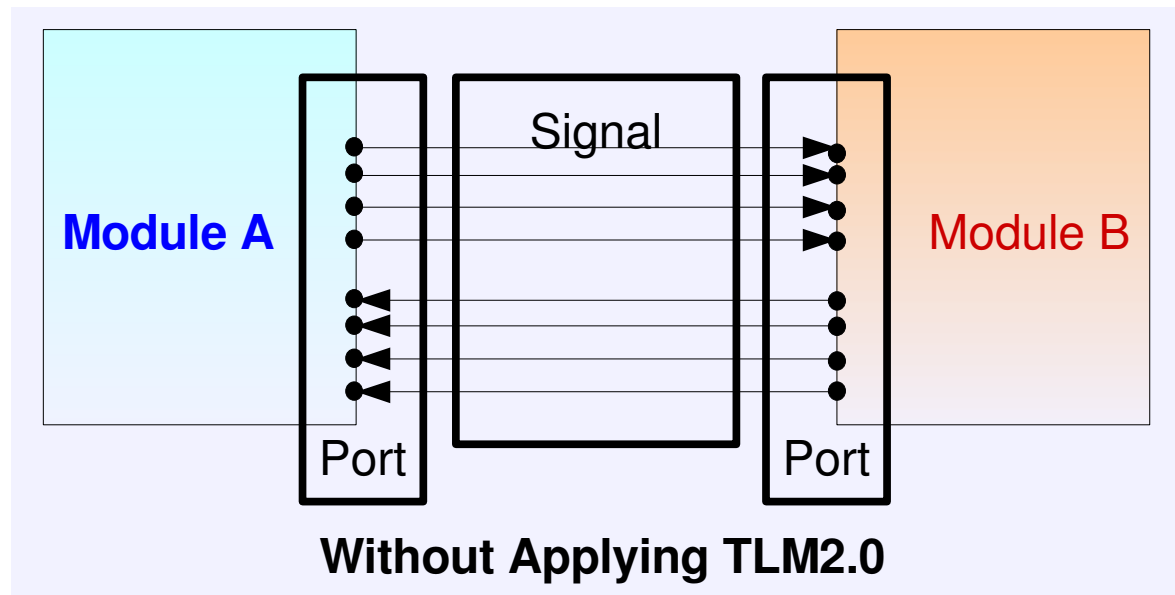


Faster

## TLM 2.0

- A library which built on SystemC library
- Consists of a set of core interfaces, objects and base protocol, and utilities to enable TLM concept

# 1. Transaction Level Modeling (TLM) (3/3)

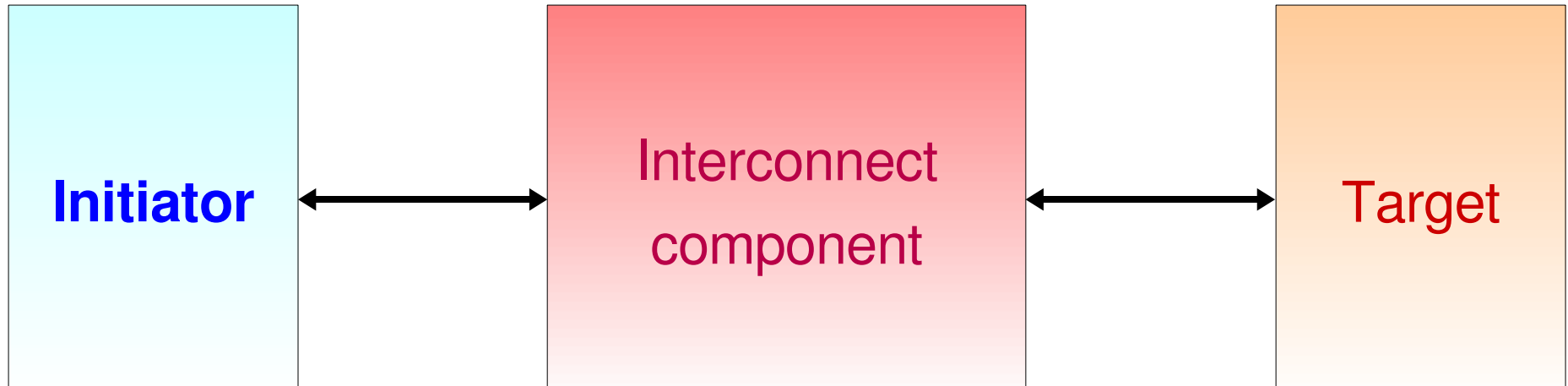


# Outline

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1. Transaction Level Modeling (TLM)
2. Basic Objects in TLM2.0
  - 2.1. Initiator/Target
  - 2.2. Socket
  - 2.3. Path
  - 2.4. Interface
3. TLM2.0 library
4. Connection
5. Communication
6. TLM2.0 with Forest
7. Topics

## 2.1 Initiator/Target



Module that can **initiate** transactions, create transaction objects

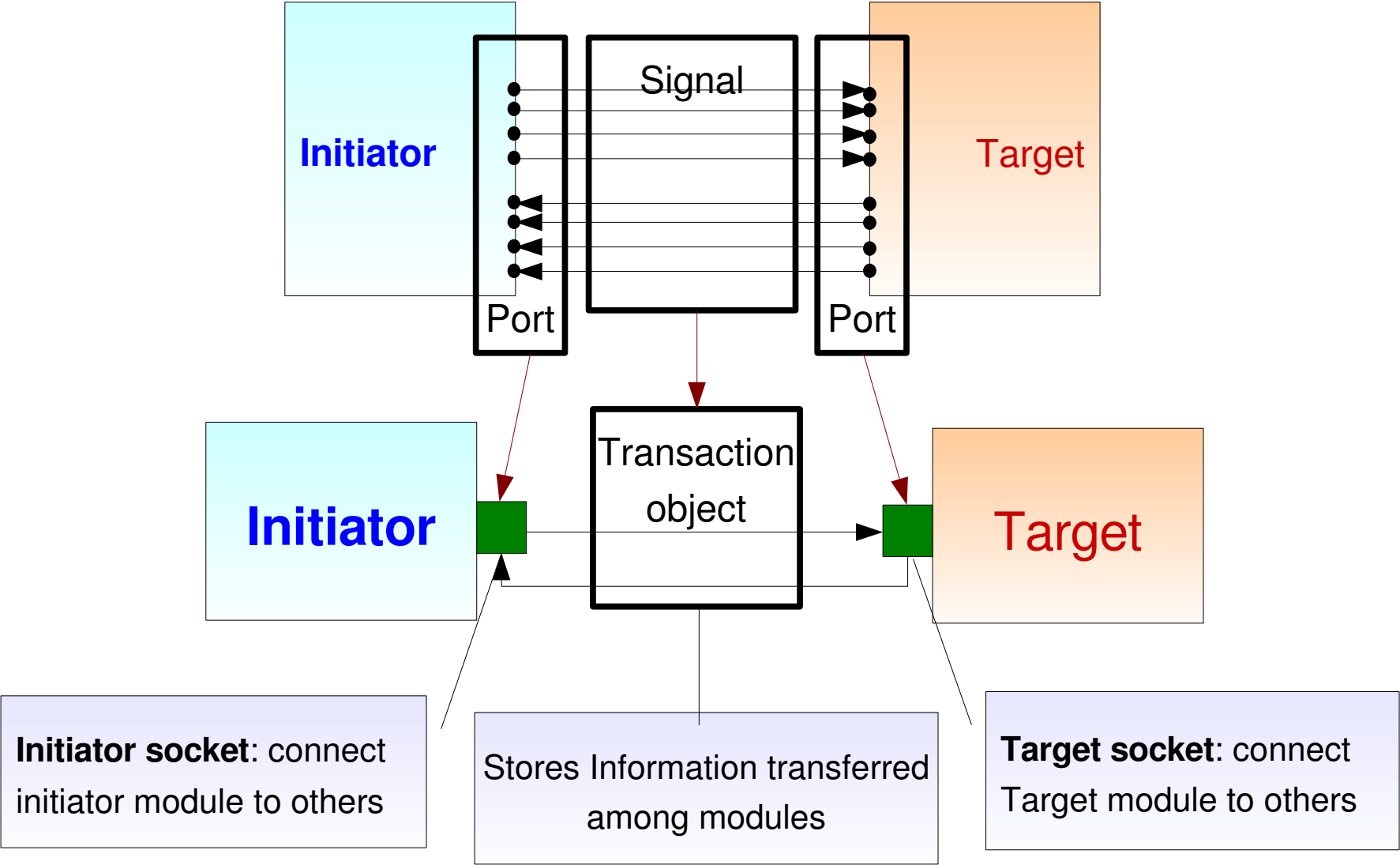
Module that accesses a transaction but does **act as an initiator or a target** for that transaction

Module that acts as the **final destination** for a transaction

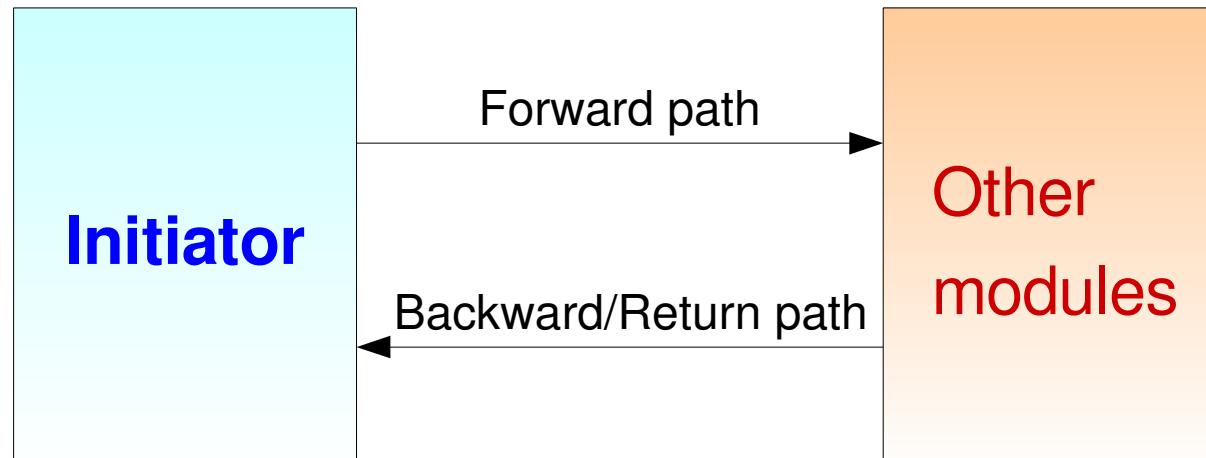
*A module applied TLM2.0 must be the one of three above types. DON'T apply TLM2.0 if you don't know this important information*



# 2.2 Socket



## 2.3 Path



**Forward path:** transaction object is created by an initiator and passed to other modules

**Backward/Return path:** transaction object is returned to Initiator by two ways:

1. ***Return path:*** Transaction object is returned automatically. Other modules don't send transaction object back to Initiator by calling certain methods
2. ***Backward path:*** Other modules send transaction object back to Initiator by calling certain methods

## 2.3 Interfaces (1/3)

- Direct access (read or write) to an area of memory owned by a target by using a direct pointer
- Speed up simulation time for memory access.

Direct memory  
interface  
(DMI)

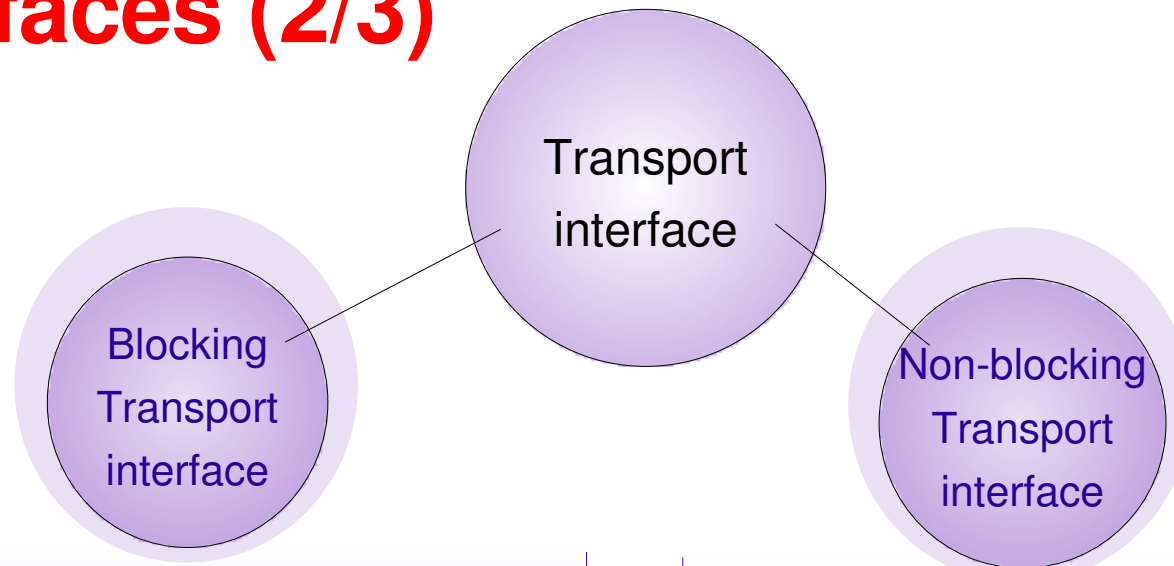
Debug  
transport  
interface

Debug access (read or write) to an area of memory owned by a target. *Forward path only*

Transport  
interface

Transport transactions between  
initiators, targets and  
interconnect components

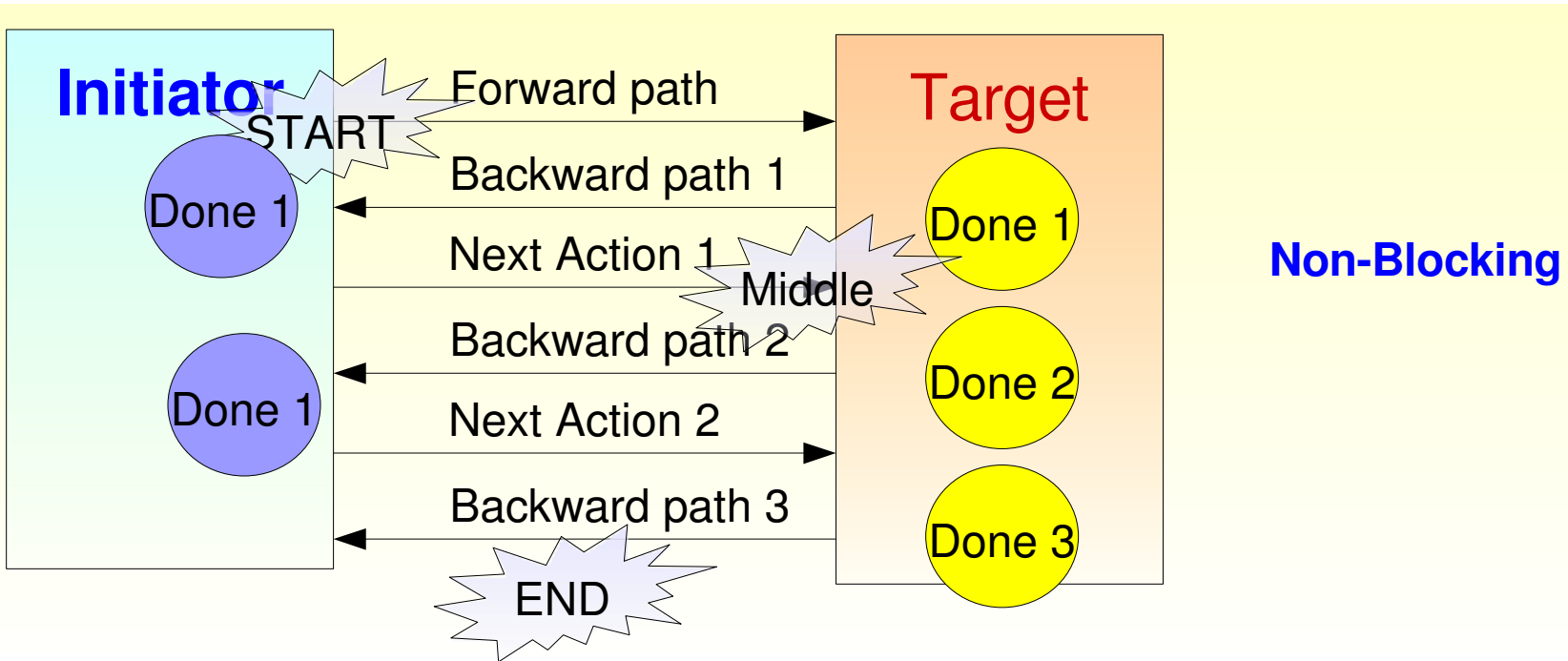
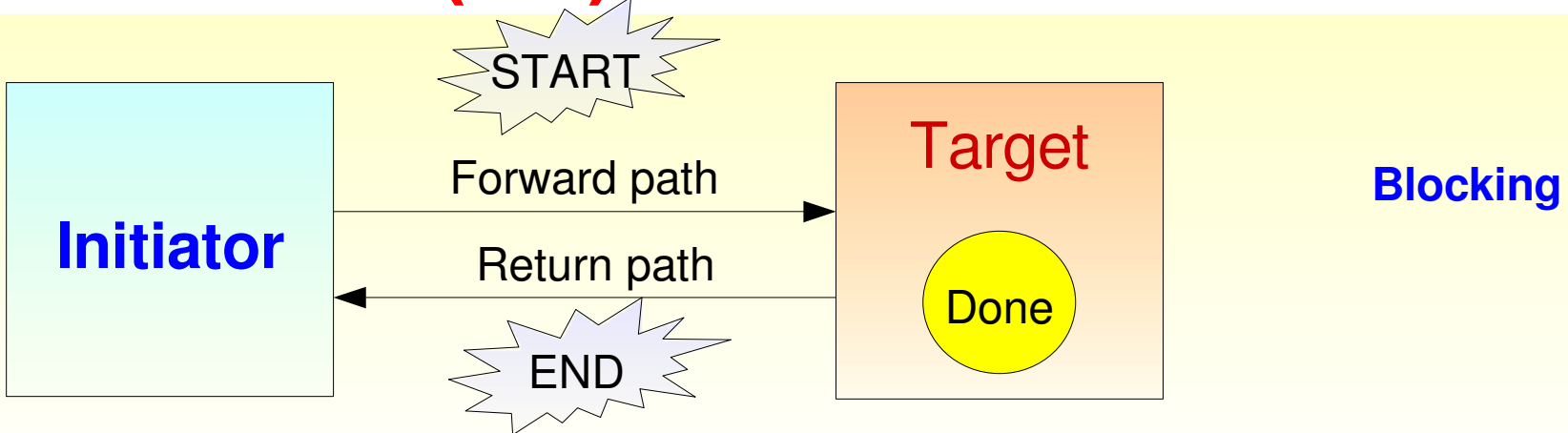
## 2.3 Interfaces (2/3)



- Each transaction has 2 timing points: START and END of a transaction
- Use Forward path and Return Path only
- “Blocking”: Initiator wishes to complete a transaction with a target by a single call

- Each transaction has multiple timing points
- Use Forward path, Backward/Return Path
- Express the **detailed sequence of interactions** between Initiator and target.
- “Non-Blocking”: transaction is finished through multi calls or single call

# 2.3 Interfaces (3/3)

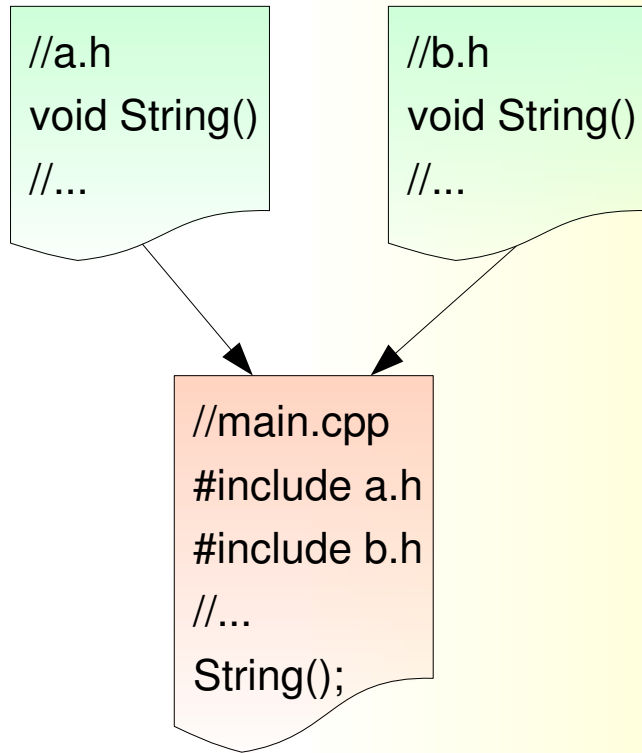


# Outline

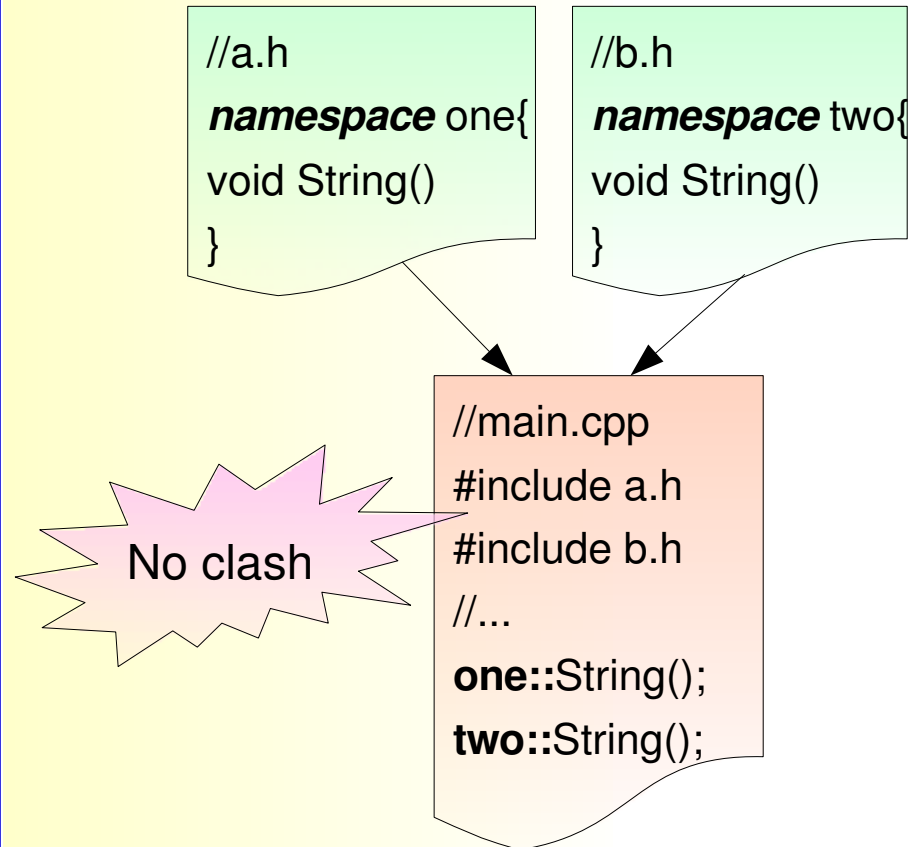
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1. Transaction Level Modeling (TLM)
2. Basic Objects in TLM2.0
3. TLM2.0 library
  - 3.1. Overview
  - 3.2. Some main classes in TLM2.0
    - 3.2. Transport interface classes
  - 3.3. Forward/backward interfaces
  - 3.4. Socket classes
4. Connection
5. Communication
6. TLM2.0 with Forest
7. Topics

# 3.1 Overview (1/2)



The `String()` functions clash  
=> It is impossible to use both header files  
in a single program



A **namespace** is a 'region' that attaches an additional identifier to any names declared inside it

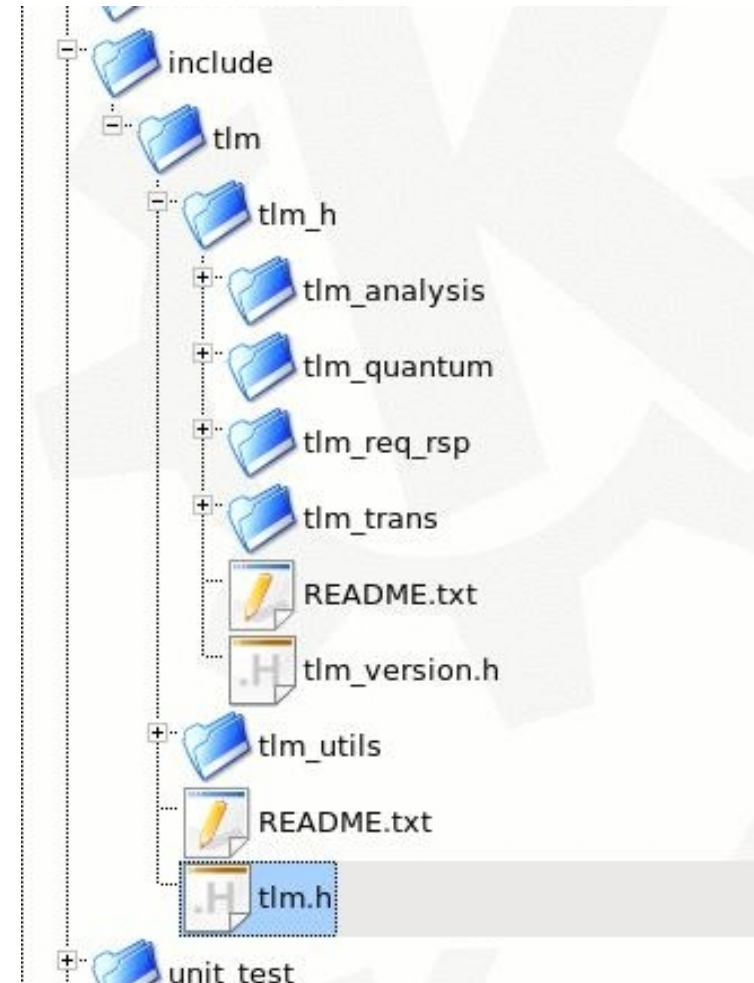
# 3.1 Overview (2/2)

**TLM2.0 library** includes many header files (.h). Basically, it consists of two main parts corresponding to two top-level C++ namespaces, **tlm** and **tlm\_utils**.

Namespace **tlm**: contains the core classes

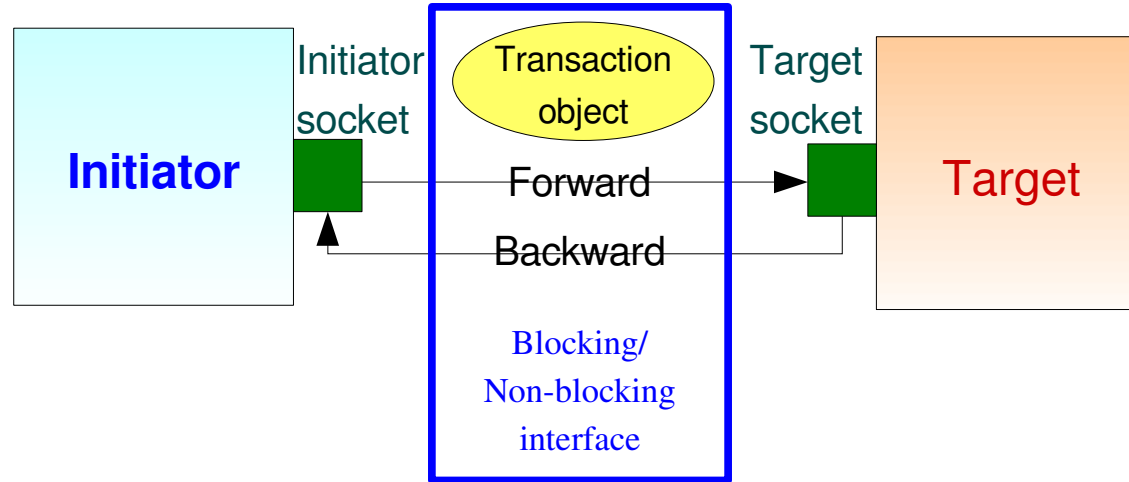
Namespace **tlm\_utils**: contains the additional classes that inherit from core classes for some certain purposes. It helps users use TLM2.0 more easily

*All classes mentioned in this presentation are in **tlm** namespace*



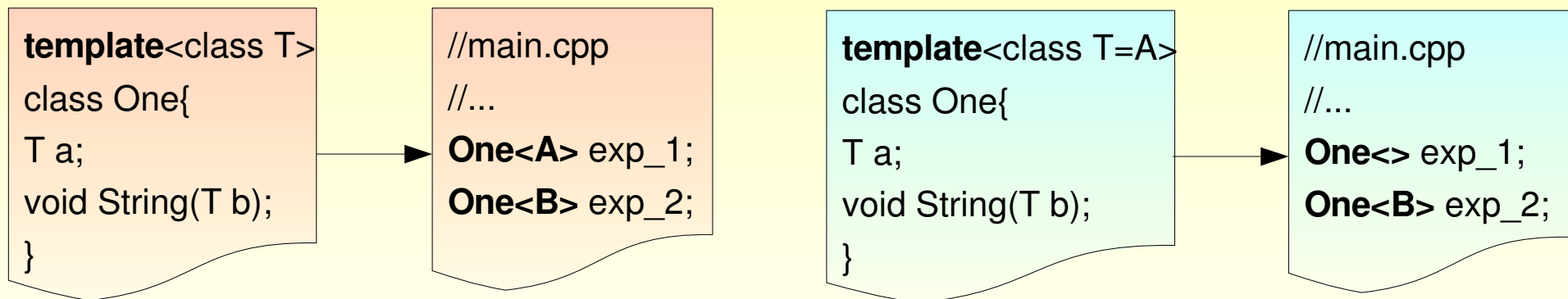
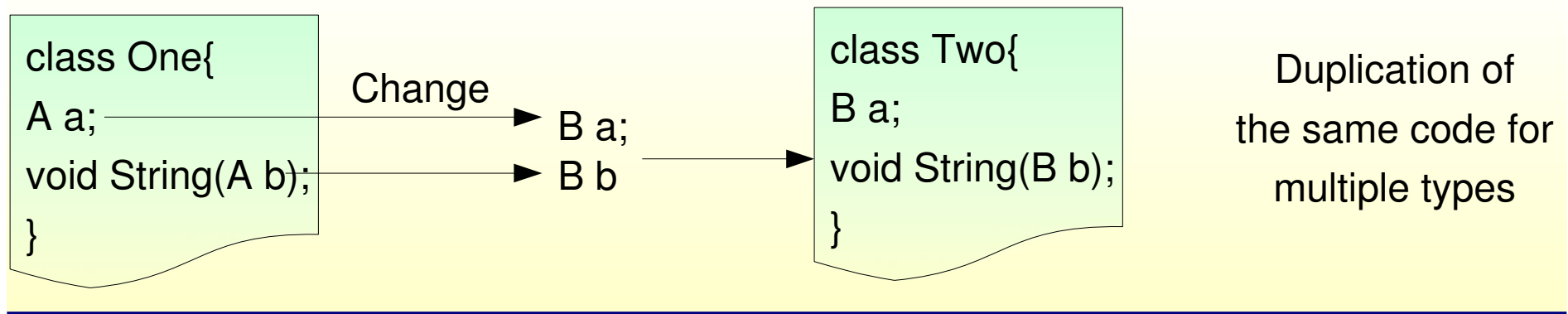


## 3.2 Some main classes in TLM2.0



- Initiator socket: *tlm\_initiator\_socket* class / Target socket: *tlm\_target\_socket* class
- Transaction object: *tlm\_generic\_payload* class (generic payload object)
- Blocking transport interface: *tlm\_blocking\_transport\_if* class
- Non-blocking transport interface: *tlm\_fw\_nonblocking\_transport\_if* class  
*tlm\_bw\_nonblocking\_transport\_if* class
- Forward transport interface: *tlm\_fw\_transport\_if* class
- Backward transport interface: *tlm\_bw\_transport\_if* class

# 3.3 Transport interface classes (1/3)



**C++ templates** enable you to define a family of functions or classes that can operate on different types of information

## 3.3 Transport interface classes (2/3)

```
template <typename TRANS = tlm_generic_payload>
class tlm_blocking_transport_if : public virtual sc_core::sc_interface {
public:
virtual void b_transport (TRANS& trans, sc_core::sc_time& t) = 0;
};
```

Blocking transport  
interface

```
template <typename TRANS = tlm_generic_payload, typename PHASE = tlm_phase>
class tlm_fw_nonblocking_transport_if : public virtual sc_core::sc_interface {
public:
virtual tlm_sync_enum nb_transport_fw (TRANS& trans, PHASE& phase, sc_core::sc_time& t) = 0;
};
```

Non-Blocking  
transport interface

```
template <typename TRANS = tlm_generic_payload, typename PHASE = tlm_phase>
class tlm_bw_nonblocking_transport_if : public virtual sc_core::sc_interface {
public:
virtual tlm_sync_enum nb_transport_bw (TRANS& trans, PHASE& phase, sc_core::sc_time& t) = 0;
```

## 3.3 Transport interface classes (3/3)

**tlm\_phase:** this is a class that shows PHASE information between initiator and target. This class contains tlm\_phase\_enum enum to indicate phases

```
enum tlm_phase_enum {  
    UNINITIALIZED_PHASE=0,  
    BEGIN_REQ=1,  
    END_REQ,  
    BEGIN_RESP,  
    END_RESP  
};
```

**tlm\_sync\_enum:** used for synchronizing between Initiator and Target

```
enum tlm_sync_enum { TLM_ACCEPTED, TLM_UPDATED, TLM_COMPLETED };
```

TLM\_ACCEPTED: the call has been accepted

TLM\_UPDATED: The transaction object has been updated

TLM\_COMPLETED: The transaction object has been updated, and the transaction is complete

# 3.4 Forward/Backward interface

*Revised in v1.2*

class **tlm\_fw\_transport\_if**:

Forward interface

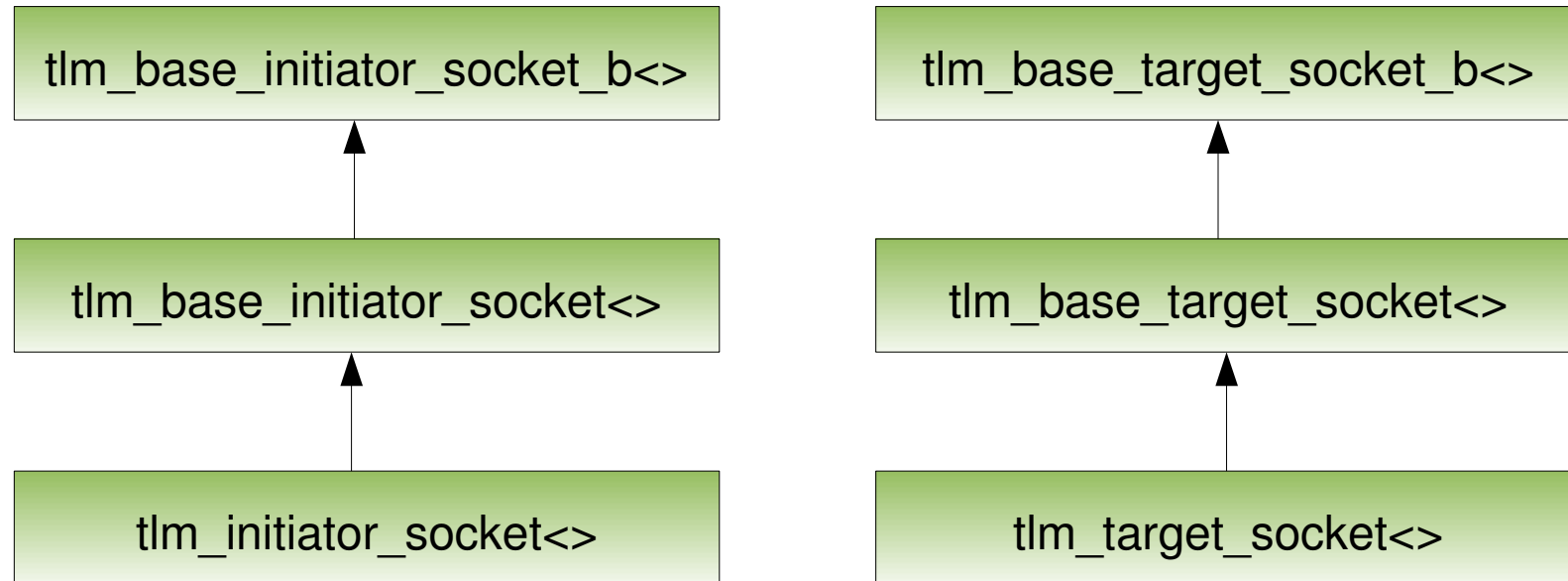
```
    public virtual tlm_fw_nonblocking_transport_if<typename TYPES::tlm_payload_type,  
                                                    typename TYPES::tlm_phase_type>  
    , public virtual tlm_blocking_transport_if<typename TYPES::tlm_payload_type>  
    , public virtual tlm_fw_direct_mem_if<typename TYPES::tlm_payload_type>  
    , public virtual tlm_transport_dbg_if<typename TYPES::tlm_payload_type>  
    {};
```

class **tlm\_bw\_transport\_if**:

Backward interface

```
    public virtual tlm_bw_nonblocking_transport_if<typename TYPES::tlm_payload_type,  
                                                    typename TYPES::tlm_phase_type>  
    , public virtual tlm_bw_direct_mem_if  
    {};
```

## 3.4 Socket classes (1/2)



We use **tlm\_initiator\_socket** and **tlm\_target\_socket**, but the main functions of socket are defined in **tlm\_base\_initiator\_socket** and **tlm\_base\_target\_socket**

## 3.4 Socket classes (2/2)

*Revised in v1.2*

**The main methods:** bind and operation() are to connect socket to another socket and backward/forward interface

### Initiator socket class

```
void bind (tlm_base_target_socket_b & s);  
  
void operator() (tlm_base_target_socket_b & s);  
  
void bind (tlm_base_initiator_socket_b& s);  
  
void operator() (tlm_base_initiator_socket_b& s);  
  
void bind (tlm_bw_transport_if& ifs);  
  
void operator() (tlm_bw_transport_if& s);
```

### Target socket class

```
void bind (tlm_base_initiator_socket_b & s);  
  
void operator() (tlm_base_initiator_socket_b & s);  
  
void bind (tlm_base_target_socket_b& s);  
  
void operator() (tlm_base_target_socket_b& s);  
  
void bind (tlm_fw_transport_if& ifs);  
  
void operator() (tlm_fw_transport_if& s);
```

# Outline

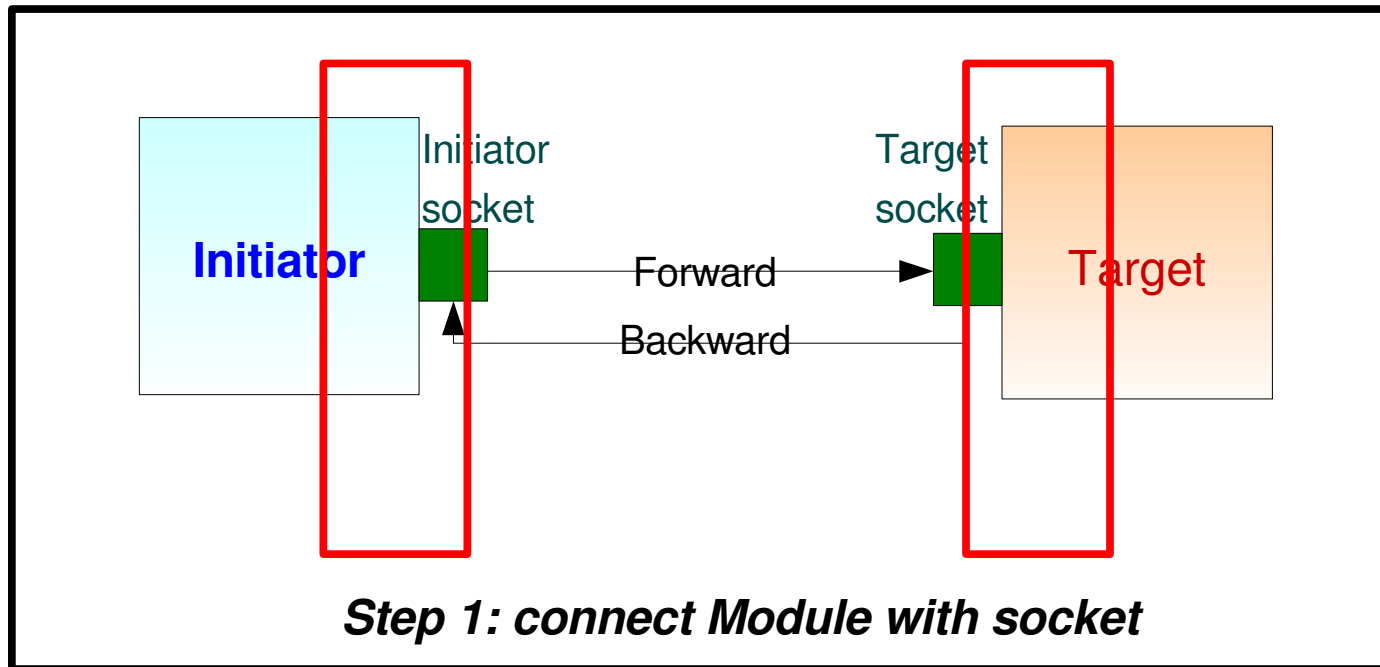
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1. Transaction Level Modeling (TLM)
2. Basic Objects in TLM2.0
3. TLM2.0 library
4. Connection
  - 4.1. Module and socket
  - 4.2. Socket and another socket
5. Communication
6. TLM2.0 with Forest
7. Topics



# 4. Connection

*Revised in v1.2*



# 4.1 Module and socket (1/3)

## *Step 1: Choose Path type*

Based on **Destination point**.

## *Step 2: Declare module with chosen path*

Inherit from `tlm::tlm_bw_transport_if<>` for Backward/Return path

Inherit from `tlm::tlm_fw_transport_if<>` for Forward path

## *Step 3: Declare corresponding socket*

`tlm::tlm_initiator_socket<>` for initiator socket

`tlm::tlm_target_socket<>` for target socket

## *Step 4: Connect module to socket*

Using operator () in constructor of module

# 4.1 Module and socket (2/3)

*Revised in v1.2*

## Example:

### HPB Master (Initiator) <-> initiator socket

This module is Initiator -> Destination of Backward path

```
class Chpbc: public sc_module, public tlm::tlm_bw_transport_if<>{  
  
    //Declare Initiator socket  
  
    tlm::tlm_initiator_socket<> ini_socket;  
  
    SC_CTOR(Chpbc){  
  
        ini_socket(*this);    //Connect initiator socket to module  
  
    }  
  
}
```

# 4.1 Module and socket (3/3)

## Example:

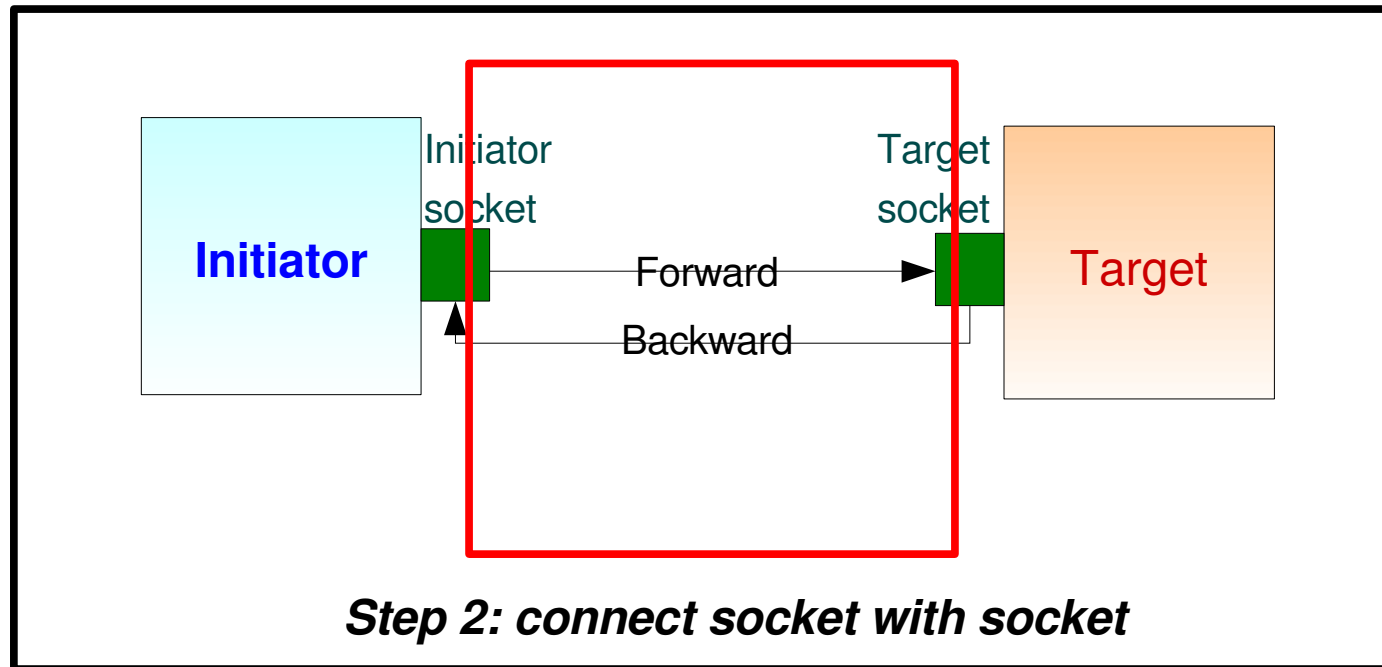
**TMU (target) <-> target socket**

This module is target -> Destination of Forward path

```
class Ctmu: public sc_module, public tlm::tlm_fw_transport_if<>{  
  
    //Declare Target socket  
  
    tlm::tlm_target_socket<> tgt_socket;  
  
    SC_CTOR(Chpbc){  
  
        tgt_socket(*this);    //Connect initiator socket to module  
  
    }  
  
}
```

# 4. Connection

*Revised in v1.2*



## 4.2 Socket and another socket (1/2)

### **Single socket:**

Connect initiator socket to target socket

Connect initiator socket to another initiator socket

Connect target socket to another target socket

### **Multi socket:**

Connect multi initiator socket to many target socket

Connect multi initiator socket to many initiator socket

Connect multi target socket to many target socket

## 4.2 Socket and another socket (2/2)

Revised in v1.2

### Example:

Initiator socket of Master HPB <-> Target socket of TMU

```
class Chpbc: public sc_module, public tlm::tlm_bw_transport_if<>{  
  
    tlm::tlm_initiator_socket<> ini_socket;  
  
    Ctmu *tmu;  
  
    SC_CTOR(Chpbc){  
  
        ini_socket(*this);    //Connect initiator socket to module  
  
        tmu = new Ctmu("tmu");  
  
        ini_socket(tmu->tgt_socket); //Connect initiator socket to target socket  
  
    }  
}
```

# Outline

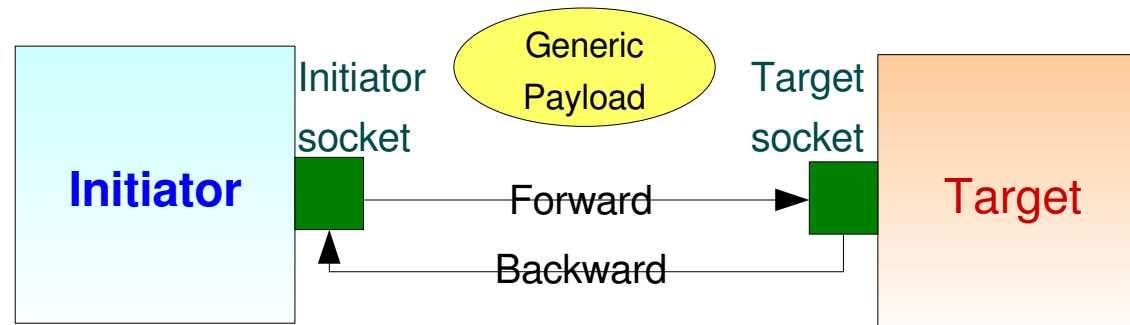
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1. Transaction Level Modeling (TLM)
2. Basic Objects in TLM2.0
3. TLM2.0 library
4. Connection
5. Communication
  - 5.1. Generic Payload
  - 5.2. Preparation
  - 5.3. Block communication
  - 5.4. Non-Blocking communication (Not Yet)
6. TLM2.0 with Forest
7. Topics



# 5. Communication

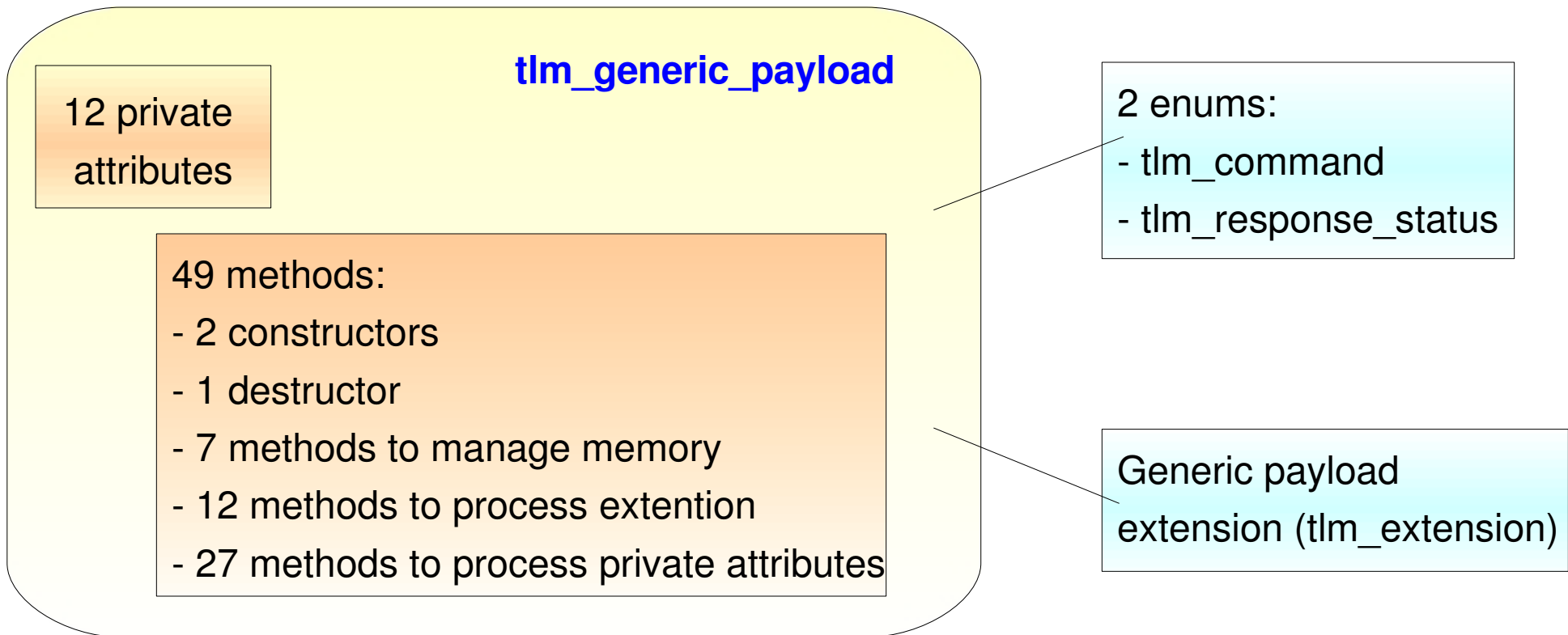
*Revised in v1.2*



***Step 2: communication through Generic payload***

# 5.1 Generic payload (1/6)

**Generic payload (tlm\_generic\_payload class)** is a very important object in TLM2.0. It includes all information of transaction transferred among modules.



# 5.1 Generic payload (2/6)

## Some main Attributes

No.	Data type	Name	Explanation
1	sc_dt::unit64	m_address	- Address value. The <b>start address</b> on the system memory map of the contiguous block of data begin read or written - Need not be word-aligned
2	tlm_command	m_command	Command value: enum <b>tlm_command</b> { TLM_READ_COMMAND, TLM_WRITE_COMMAND, TLM_IGNORE_COMMAND};
3	unsigned char*	m_data	Data pointer
4	unsigned int	m_length	- The number of bytes to be copied to or from the data array, inclusive of any bytes disabled by the byte enable attribute
5	tlm_response_status	m_response_status	- Indicate whether an error has occurred during the transaction enum <b>tlm_response_status</b> { TLM_OK_RESPONSE = 1, TLM_INCOMPLETE_RESPONSE = 0, TLM_GENERIC_ERROR_RESPONSE = -1, TLM_ADDRESS_ERROR_RESPONSE = -2, TLM_COMMAND_ERROR_RESPONSE = -3, TLM_BURST_ERROR_RESPONSE = -4, TLM_BYTE_ENABLE_ERROR_RESPONSE = -5 }; (-4): the target is unable to execute the transaction with the given streaming width in case that initiator supports it (-1): Any other error

# 5.1 Generic payload (3/6)

## Some main Attributes

No.	Data type	Name	Explanation
7	unsigned char*	m_byte_enable	Byte enable pointer. Macro TLM_BYTE_DISABLED (0): this byte is disabled Macro TLM_BYTE_ENABLED (0xFF): this byte is enabled
8	unsigned int	m_byte_enable_length	Byte enable length
9	tlm_array<tlm_extension_base*>	m_extensions	Extension array

# 5.1 Generic payload (4/6)

## Some main methods

No.	Prototype	Explanation
1	bool <b>is_read</b> ()	Return true if command attribute is TLM_READ_COMMAND
2	void <b>set_read</b> ()	Set the command attribute to TLM_READ_COMMAND
3	bool <b>is_write</b> ()	Return true if command attribute is TLM_WRITE_COMMAND
4	void <b>set_write</b> ()	Set the command attribute to TLM_WRITE_COMMAND
5	tlm_command <b>get_command</b> ()	Get the current command value
6	void <b>set_command</b> (const tlm_command command)	Set the command value to command attribute
7	sc_dt::unit64 <b>get_address</b> ()	Return the current value of the address attribute
8	void <b>set_address</b> (const sc_dt::unit64 address)	Set the address attribute to the value passed as an argument The value of the address attribute need not be word-aligned
9	unsigned char* <b>get_data_ptr</b> ()	Return the current value of the data pointer attribute
10	void <b>set_data_ptr</b> (unsigned char* data)	Set the data pointer attribute to the value passed as an argument. For the read command, the contents of the data array will be overwritten by the target

# 5.1 Generic payload (5/6)

## Some main methods

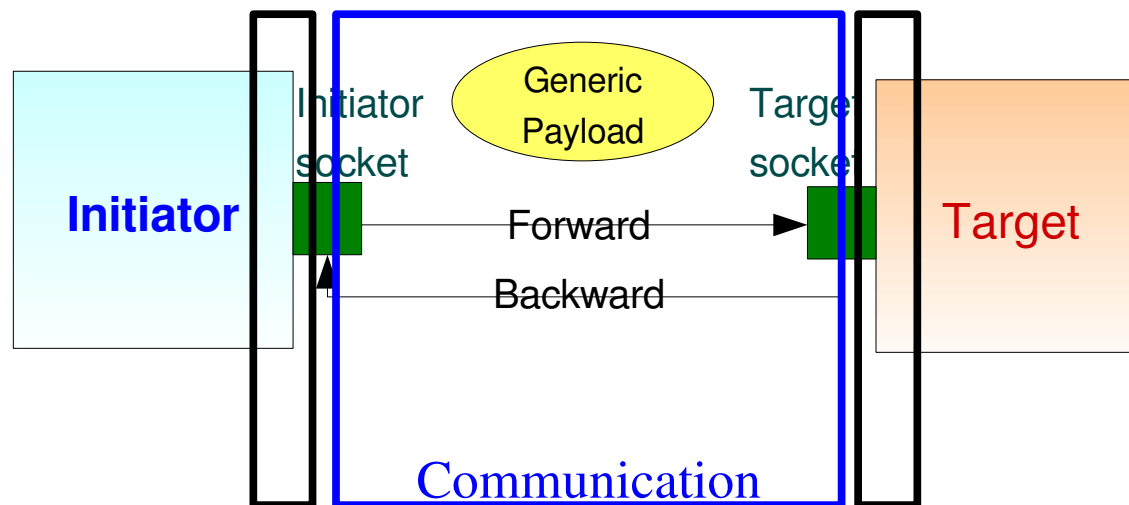
No.	Prototype	Explanation
11	unsigned int <b>get_data_length()</b>	Return the current value of the data length attribute. The data length attribute as <i>the number of bytes</i> to be copied to or from the data array
12	void <b>set_data_length</b> (const unsigned int length)	Set the data length attribute to the value passed as an argument
13	bool <b>is_response_ok()</b>	Return <b>true</b> if an only if the current value of the response status attribute is TLM_OK_RESPONSE
14	bool <b>is_response_error()</b>	Return <b>true</b> if an only if the current value of the response status attribute is NOT TLM_OK_RESPONSE
15	tlm_response_status <b>get_response_status()</b>	Return the current value of the response status attribute
16	void <b>set_response_status</b> (const tlm_response_status)	Set the response status attribute
17	std::string <b>get_response_string()</b>	Return the current value of the response status attribute as a text string
18	unsigned char* <b>get_byte_enable_ptr()</b>	Return the current value of the byte enable pointer attribute
19	void <b>set_byte_enable_ptr</b> (unsigned char* byte_enable)	Set the pointer to the byte enable array to the value passed as an argument

# 5.1 Generic payload (6/6)

## Some main methods

No.	Prototype	Explanation
20	unsigned int <b>get_byte_enable_length()</b>	Return the current value of the byte enable length attribute
21	void <b>set_byte_enable_length</b> (const unsigned int byte_enable_length)	Set the byte enable length attribute

## 5.2 Preparation (1/6)



Initiator and target communicate together by **calling functions**. All function must be defined in Initiator module and target module before communication.



## 5.2 Preparation (2/6)

**Initiator module:** inherit from *tlm::tlm\_bw\_transport\_if<>*

Moreover, *tlm::tlm\_bw\_transport\_if<>* inherit publicly and virtually from:

*tlm::tlm\_bw\_non\_blocking\_transport\_if<>*

*tlm::tlm\_sync\_enum* **nb\_transport\_bw** (*tlm::tlm\_generic\_payload* & trans, *tlm::tlm\_phase* & phase, *sc\_time* & delay)

*tlm::tlm\_bw\_direct\_mem\_if*

void **invalidate\_direct\_mem\_ptr**(*sc\_dt::uint64* start\_range, *sc\_dt::uint64* end\_range)

=> Initiator module MUST define both of two methods:

*nb\_transport\_bw*

*invalidate\_direct\_mem\_ptr*

## 5.2 Preparation (3/6)

```
class Chpbc: public sc_module, public tlm::tlm_bw_transport_if<>{
    //Declare Initiator socket
    tlm::tlm_initiator_socket<> hpb_master;
    SC_CTOR(Chpbc){
        ini_socket(*this);    //Connect initiator socket to module
    }
    tlm::tlm_sync_enum nb_transport_bw (tlm::tlm_generic_payload & trans, tlm::tlm_phase&
                                        phase, sc_time& delay)
    {
        //Do something
    }
    void invalidate_direct_mem_ptr(sc_dt::uint64 start_range, sc_dt::uint64 end_range)
    {
        //Do something
    }
}
```

## 5.2 Preparation (4/6)

**Target module:** inherit from *tlm::tlm\_fw\_transport\_if<>*.

Moreover, *tlm::tlm\_fw\_transport\_if<>* inherit publicly and virtually from:

*tlm::tlm\_fw\_non\_blocking\_transport\_if<>*

*tlm::tlm\_sync\_enum nb\_transport\_fw* (*tlm::tlm\_generic\_payload* & trans, *tlm::tlm\_phase*& phase, *sc\_time*& delay)

*tlm::tlm\_fw\_direct\_mem\_if*

bool **get\_direct\_mem\_ptr**(*tlm::tlm\_generic\_payload* & trans, *tlm::tlm\_dmi*& dmi\_data)

*tlm::tlm\_blocking\_transport\_if<>*

void **b\_transport**(*tlm::tlm\_generic\_payload*& trans, *sc\_core::sc\_time*& t)

*tlm::tlm\_transport\_dbg\_if<>*

unsigned int **transport\_dbg**(*tlm::tlm\_generic\_payload*& trans)

=> Target module MUST define four above functions

## 5.2 Preparation (5/6)

```
class Ctmu: public sc_module, public tlm::tlm_fw_transport_if<>{  
    //Declare Target socket  
    tlm::tlm_target_socket<> tgt_socket;  
    SC_CTOR(Chpbc){  
        tgt_socket(*this);    //Connect initiator socket to module  
    }  
    tlm::tlm_sync_enum nb_transport_fw (tlm::tlm_generic_payload & trans, tlm::tlm_phase&  
                                        phase, sc_time& delay){ }  
    bool get_direct_mem_ptr(tlm::tlm_generic_payload & trans, tlm::tlm_dmi& dmi_data){ }  
    void b_transport(tlm::tlm_generic_payload& trans, sc_core::sc_time& t){ }  
    unsigned int transport_dbg(tlm::tlm_generic_payload& trans)  
}
```

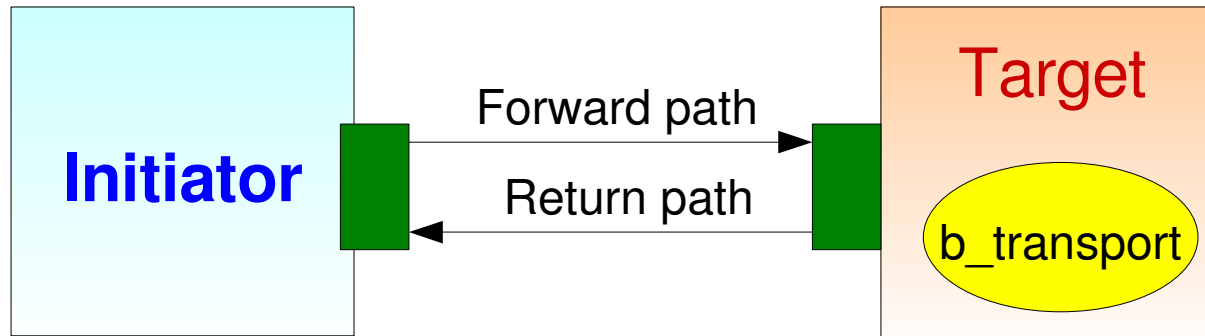
# 5.2 Preparation (6/6)

## Summary

Function	Where to be defined	Explanation
nb_transport_bw	Initiator	- Called by Target Module - Main function of Non-Blocking transaction
nb_transport_fw	Target	- Called by Initiator Module - Main function of Non-Blocking transaction
b_transport	Target	- Called by Initiator - Main function of Blocking transaction
invalidate_direct_mem_ptr	Target	- Called by Initiator - Used in Direct memory interface
get_direct_mem_ptr	Initiator	- Called by Target - Used in Direct memory interface
transport_dbg	Target	- Called by Target - Used in Debug interface

**TLM2.0 provide us these pure virtual functions, attributes, methods. *The contents of each function is depended on us***

## 5.3 Block communication (1/3)



**Blocking interface:** Initiator module -> Target module  
(Initiator socket -> Target socket)

**Step 1:** Create transaction object (tlm::tlm\_generic\_payload object)

**Step 2:** Set values or information for transaction object by using methods of tlm::tlm\_generic\_payload

**Step 3:** From Initiator socket call b\_transport function

## 5.3 Block communication (2/3)

*Revised in v1.2*

### **Example:**

```
void HPB_Thread(){  
    //Create transaction object  
    tlm::tlm_generic_payload hpb_transport;  
  
    //Set information for Generic payload  
    hpb_transport.set_address(addr);  
    hpb_transport.set_command(tlm::TLM_READ_COMMAND);  
    hpb_transport.set_data_length(dsize);  
    hpb_transport.set_response_status(tlm::TLM_INCOMPLETE_RESPONSE);  
  
    // Call b_transport  
    sc_time delay_time = SC_ZERO_TIME;  
    ini_socket->b_transport(hpb_transport, delay_time);  
}
```

## 5.3 Block communication (3/3)

**void b\_transport(tlm::tlm\_generic\_payload & trans, sc\_core::sc\_time& t)**

- Defined in target module
- We can use event, wait of SystemC in b\_transport
- The call to b\_transport will mark the first timing point. The return from b\_transport will mark the final timing point
- *sc\_time t*: delay time. How it affects our modules is depended on how we implement it.
- Get information/values of generic payload by methods of tlm\_generic\_payload



# Outline

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1. Transaction Level Modeling (TLM)
2. Basic Objects in TLM2.0
3. TLM2.0 library
4. Connection
5. Communication
6. TLM2.0 with Forest
7. Topics

# 6. TLM2.0 with Forest

## Modify Makefile:

Add path of TLM2.0 library:

`TLM = /shsv/sld/Common/Lib/04_TLM/TLM2.0-2008-06-09`

*(This path is according to where you store TLM2.0 library)*

Add define option:

`DEFS = -DSHX2 ..... -DSC_INCLUDE_DYNAMIC_PROCESSES $(FOREST_TYPE) $(FOREST_SNC_TYPE) $(FOREST_SHWY_WIDTH)`

## Modify Makefile.defs:

`INCDIRS = $(INCDIR) -I. -I$(SYSTEMC)/include -I$(TLM)/include/tlm $(addprefix -I, $(SEARCH_DIR))`

# 6. TLM2.0 with Forest

TLM2.0 has two namespace:

Namespace **tlm**: contains main classes

=> #include <tlm.h>

Namespace **tlm\_utils**: contains utility classes

=> Include file according to which class to use

For example, #include "tlm\_utils/simple\_initiator\_socket.h"

(Use tlm\_simple\_initiator\_socket class)

## Always declare namespace

Example:

```
tlm::tlm_initiator_socket<>
```

```
tlm::tlm_fw_transport_if<>
```

# Outline

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1. Transaction Level Modeling (TLM)
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# Topics

1. Research transaction object (tlm::tlm\_generic\_payload class), especially extension class (tlm::tlm\_extension)
2. Research non-blocking transport interface, applied for complicated module/bus/bridge
3. Research Direct Memory interface: a method to increase simulation speed of memory access between Initiator and target
4. Connect multi-sockets – Use initiator socket or target socket complicatedly
5. Timing in TLM2.0: apply temporal decoupling, quantum and quantum keeper in loosely-timed coding style



**Thank you for your attention**

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