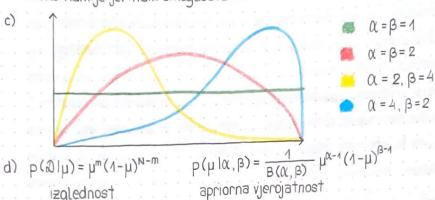
SU1: 9. DOMACA ZADACA

V14 - Zadaci za učenje

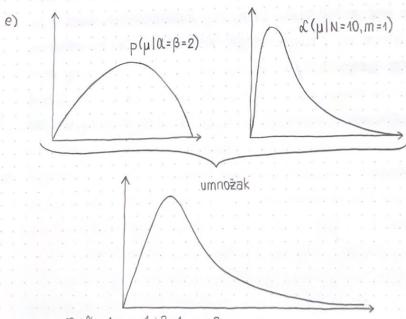
- 5. a) $\hat{\theta}_{MAP}$ = argmax p(010) = argmax p(010) p(0)

 Procjenitelj MAP bolji je od procjenitelja MLE jer kombinira apriorno znanje i informacije dobivene iz podataka.
 - b) Da su dvije distribucije konjugatne znači da su iste vrste, a konjugatna apriorna distribucija je ona koja, kada se pomnoži izglednošću, daje distribuciju koja je iste vrste kao i aposteriorna distribucija. Svojstvo konjugatnosti bitno nam je jer nam omogućava da radimo tzv. "online" učenje.



izglednost apriorna vjerojatnost
$$p(\mu \mid \emptyset, \alpha, \beta) = p(\mu \mid N, m, \alpha, \beta) = \mu^{m} (1 - \mu)^{N-m} \frac{1}{B(\alpha, \beta)} \mu^{\alpha-1} (1 - \mu)^{\beta-1} \frac{1}{P(\emptyset)}$$

$$=\mu^{m+\alpha-1}\left(1-\mu\right)^{N-m+\beta-1}\frac{1}{B(\alpha,\beta)\,p(\mathfrak{D})}$$



f)
$$\hat{\mu}_{MAP} = \frac{m + \alpha - 1}{\alpha + N + \beta - 2} = \frac{1 + 2 - 1}{2 + 10 + 2 - 2} = \frac{2}{12} = 0.167$$

$$\hat{\mu}_{MLE} = \frac{1}{10} = 0.1$$

Porastom broja primjera N, razlika između $\hat{\mu}_{\text{MAP}}$ i $\hat{\mu}_{\text{MLE}}$ se smanjuje jer sve vise vjerujemo podacima.

g) Ako za parametre beta distribucije odaberemo α=β=2, MAP procjenitelj svodi se na $\hat{\mu}_{\text{MAP}} = \frac{m+1}{N+2}$, što zovemo Laplaceovim procjeniteljem.

 $h_1(x) = P(x|y=1)P(y=1) = 0.16$

 $h_2(x) = P(x|y=2)P(y=2) = 0.025$

 $P(x) = \sum_{y=1}^{3} P(x|y) P(y) = 0.56$

 $h_3(x) = P(x|y=3)P(y=3) = 0.375 \Rightarrow MAP hipoteza$

V15 - Zadaci za učenje

2.
$$P(y=1) = 0.2$$
 $P(x|y=1) = 0.8$

$$P(y=2) = 0.05$$
 $P(x|y=2) = 0.5$

$$P(y=3) = 0.75$$
 $P(x|y=3) = 0.5$

$$(y=3)=0.75$$
 $P(x|y=3)=0.9$

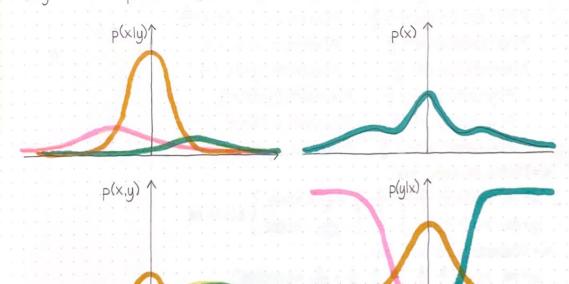
$$P(y=1|x) = \frac{h_1(x)}{P(x)} = 0.286$$

 $P(y=2|x) = \frac{h_2(x)}{P(x)} = 0.446$

$$P(y=3|x) = \frac{h_3(x)}{P(x)} = 0.670$$

3.
$$P(y=1)=0.3$$
 $\mu_1=-5$ $\sigma_1^2=5$

$$P(y=2)=0.2$$
 $\mu_2=0$ $\sigma_2^2=1$ $\mu_3=5$ $\sigma_3^2=10$



V16 - Zadaci za učenje

2.a)
$$P(x_1 = Istraly = ne) = 0$$
 $P(x_1 = Istraly = da) = \frac{1}{2}$

$$P(x_1 = Dalmacijaly = ne) = \frac{1}{3}$$
 $P(x_1 = Dalmacijaly = da) = \frac{1}{2}$

$$P(x_1 = \text{Kvarnerl } y = \text{ne}) = \frac{2}{3}$$
 $P(x_1 = \text{Kvarnerl } y = \text{da}) = 0$

$$P(x_2 = ne | y = ne) = 1$$

$$P(x_0=da|u=ne)=0$$

$$P(x_2 = a_0|y = h_0) = \frac{4}{a}$$

$$P(x_3 = kamp|y=ne) = \frac{2}{3}$$

$$P(x_1 = Istraly = da) = \frac{1}{2}$$

$$P(x_1 = Dalmacijaly = da) = \frac{1}{2}$$

$$P(x_1 = Kvarner | y = da) = 0$$

$$P(x_2 = ne|y=ne) = 1$$
 $P(x_2 = ne|y=da) = \frac{1}{4}$

$$P(x_2=da|y=ne)=0$$
 $P(x_2=da|y=da)=\frac{3}{4}$

P(x3=privatnily=ne)=
$$\frac{4}{3}$$
 P(x3=privatnily=da)= $\frac{4}{2}$

$$P(x_3 = kamp|y=da) = 0$$

$$P(x_3=hotelly=da)=\frac{1}{2}$$

```
P(x_4 = autoly = ne) = 0 P(x_4 = autoly = da) = \frac{3}{4}
                           P(x_4 = busly = ne) = \frac{2}{3}  P(x_4 = busly = da) = 0
                          P(x_4 = avion|y=ne) = \frac{1}{3} P(x_4 = avion|y=da) = \frac{1}{4}
                 h (Istra, ne, kamp, bus) = argmax P(y) Tr P(xkly)
                    y = ne: h = \frac{3}{4} \cdot 0 \cdot 1 \cdot \frac{2}{3} \cdot \frac{2}{3} = 0
                                                                ne možemo klasificirati primjer na ovaj način
                    y = da: h = \frac{41}{2} \cdot \frac{1}{4} \cdot 0.0 = 0
                h (Dalmacija, da, hotel, bus) = argmax P(y) The P(xkly)
                   y = ne: h = \frac{1}{3} \cdot 0 \cdot 0 \cdot \frac{2}{3} = 0
                                                              ne možemo klasificirati primjer na ovaj način
                   y = da \cdot h = \frac{1}{2} \cdot \frac{3}{4} \cdot \frac{1}{2} \cdot 0 = \int
         b) P(x_1 = Istraly = ne) = \frac{1}{6}
                                                                 P(x_1=Istraly=da)=\frac{3}{7}
               P(x_4 = Dalmacijaly = ne) = \frac{2}{6}
                                                                 P(x_1 = Dalmacija | y = da) = \frac{3}{7}
               P(X_1 = Kvarner | y = ne) = \frac{3}{6}
                                                                 P(x_1 = Kvarner | y = da) = \frac{1}{7}
                  P(x_2 = ne | y = ne) = \frac{4}{5}
                                                          P(x_2 = nely = da) = \frac{2}{6}
                  P(x_2=daly=ne) = \frac{1}{5}
                                                          P(x_2 = daly = da) = \frac{4}{6}
                     P(X_3 = privatnily = ne) = \frac{2}{6}
                                                                   P(x3=privatnily=da)=3
                    P(x_3 = kamply = ne) = \frac{3}{6} P(x_3 = kamply = da) = \frac{1}{7}
                    P(x3=hotelly=ne)=\frac{4}{6} P(x3=hotelly=da)=\frac{3}{7}
                       P(x_4 = autoly = ne) = \frac{1}{6} P(x_4 = autoly = da) = \frac{4}{7}
                       P(x_4 = bus | y = ne) = \frac{3}{6} P(x_4 = bus | y = da) = \frac{1}{7}
                      P(X_4=avion | y=ne)=\frac{2}{6}
                                                             P(x_4=avion|y=da)=\frac{2}{3}
            x = (Istra, ne, kamp, bus)
               y = ne: h(x) = \frac{3}{7} \cdot \frac{1}{6} \cdot \frac{4}{5} \cdot \frac{3}{6} \cdot \frac{3}{6} = \frac{1}{70} \approx 0.0143

y = da: h(x) = \frac{4}{7} \cdot \frac{3}{7} \cdot \frac{2}{6} \cdot \frac{1}{7} \cdot \frac{1}{7} = \frac{4}{2401} \approx 0.0002 h(x) = ne
           x = (Dalmacija, da, hotel, bus)
              y = ne: h(x) = \frac{3}{7} \cdot \frac{2}{6} \cdot \frac{1}{5} \cdot \frac{1}{6} \cdot \frac{3}{6} = \frac{1}{420} \approx 0.000238

y = da: h(x) = \frac{4}{7} \cdot \frac{3}{7} \cdot \frac{4}{6} \cdot \frac{3}{7} \cdot \frac{1}{7} = \frac{96}{2401} \approx 0.039983 h(x) = da
3. a) ENTROPIJA: H(P)=-\(\Sigma\) P(x) LnP(x) UNAKRSNA ENTROPIJA: H(P,Q)=-\(\Sigma\) P(x) LnQ(x)
         RELATIVNA ENTROPIJA: H(P,Q)-H(P) = - \( P(x) \lnQ(x)-(-\( \Sigma \) P(x) \lnP(x))
                                                                       = -\sum_{x} P(x) \ln Q(x) + \sum_{x} P(x) \ln P(x)
                                                                       = \sum_{k} P(x) \ln \frac{P(x)}{Q(x)} = D_{kL}(P|Q)
       D_{KL}(P(x,y)||P(x)P(y)) = \sum_{x,y} P(x,y) \ln \frac{P(x,y)}{P(x)P(y)} = I(x,y) \quad \text{UZAJAMNA INFORMACIJA}
 b) P(1,1) = 0.2 P(1,2) = 0.05 P(1,3) = 0.3 I(x,y) = P(1,1) \ln \frac{P(1,1)}{P(x=1) P(y=1)}
                                                                                                     + P(2,3) \ln \frac{P(2,3)}{P(x=2) P(y=3)}
       P(2,1)=0.05 P(2,2)=0.3 P(2,3)=0.1
          P(x=1)=0.55 P(x=2)=0.45
                                                                                                   = 0.194563
         P(y=1) = 0.25 P(y=2) = 0.35 P(y=3) = 0.4
```

Varijable nisu nezavisne.