## 0.1 Configuration

The Hardware Emulator and the Emulator Manager support a simple fail-safe way of configuring them and making queries to them. A message is made of a String where each line (separated by a newline character) is a name followed by optional parameters.

The syntax is whitespace insensitive and as follows:

```
name = param1, param2, param...
or
name
```

Whitespace is optional, and the only separating characters are the equal sign (=), the comma (,) and the newline character  $(\n)$ .

## 0.1.1 Configuration

The current settings supported when allocating an emulator are shown in Table 1.

```
autopilot=name
```

Name of the autopilot program file, without extension.

os=name

Name of the operating system used. Currently linux or windows. This implies the extension of the autopilot file searched. If the os command is not given, the Emulator will search for any autopilot with the given name in the search folder.

```
debug=flag1, flag2, ...
```

Enable the debugging outputs for the specified flags, where the flags are any of mem, regs, requipdate, syscalls, unsupported syscalls, code or call.

cpu\_frequency=value

The CPU frequency in Hertz used to evaluate the computation time.

memory\_frequency=value

The RAM frequency in Hertz used to evaluate the computation time.

cache\_name=size, read\_ticks, write\_ticks

Where name is IL1, DL1, L2 or L3. This setting enables and sets the parameters of the named cache layer. Set size to 0 to disable this cache level. The ticks refer to the CPU ticks.

no\_time

Disables the delaying of the autopilot in the simulation.

test\_real

If the RMIModelServer and the autopilot are of the same operating system type, this flag makes the emulator load the autopilot directly as a library (not emulated) and uses its outputs to validate those of the emulated instance.

export

Enables the HardwareEmulator to export the deviation from the planned trajectory and the evaluated execution time of the autopilot. Data is currently exported for the first 60 seconds of the simulation. The output files are autopilot\_dist.txt and autopilot\_time.txt.

Table 1: HardwareEmulator Configuration

The EmulatorManager itself also supports a config string on initialization. Table 2 shows the supported config.

```
autopilots_folder=folder
Sets the folder in which to look for autopilot programs.
```

Table 2: EmulatorManager Configuration

## 0.1.2 Queries

The query system uses the same presented syntax, but also sends a response for every query, using the same syntax.

Queries supported by the EmulatorManager are shown in Table 3.

Query	get_error_msg
Response	error_msg=msg
	Returns the last error message that occurred while allocating an autopilot
	emulator.
Query	get_available_autopilots
Response	available_autopilots=autopilot1, autopilot2,
	Returns the list of autopilot files available in the autopilot folder.
Query	get_available_threads
Response	available_threads=thread_count
	Returns the number of concurrent threads the machine running the RMI-
	ModelServer supports.
Query	get_autopilots_folder
Response	autopilots_folder=folder
	Returns the current autopilots folder.

 ${\bf Table~3:~Emulator Manager~queries.}$ 

Queries supported by querying a specific emulator are shown in Table 4.

Query	get_avg_runtime
Response	avg_runtime=time
	Returns the mean average time of autopilot execution.
Query	is_computing
Response	computing=1 or 0
	Returns 1 if the computer is considered to be computing in simulation time.
Query	get_computer_time
Response	computer_time=time
	Returns the time counter of the computer, in microseconds.

Table 4: HardwareEmulator queries.