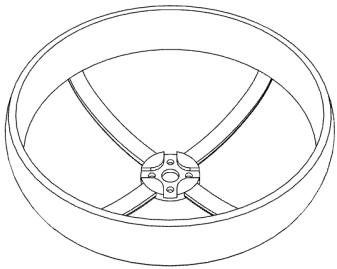
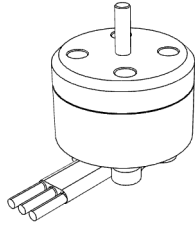


Motor Assembly

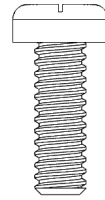
Parts



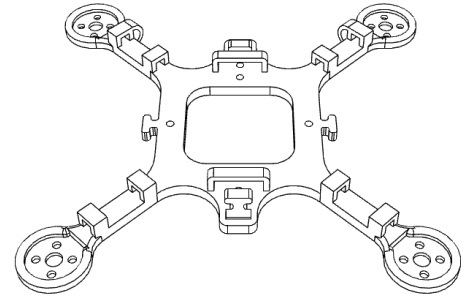
Ducts
X4



Motor
X4



4mm
Screw
X16

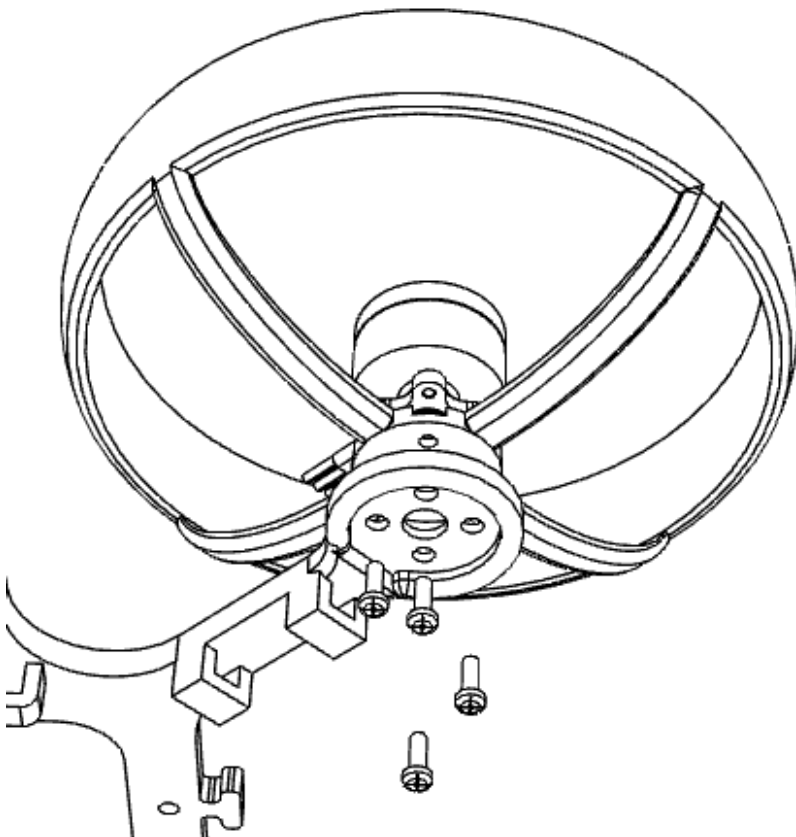
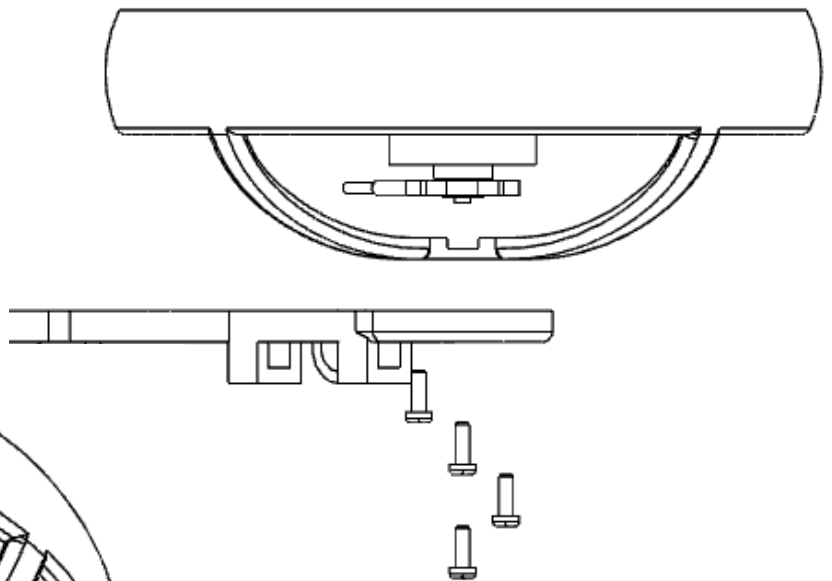


Frame
X1

Tools



Philips Screwdriver



Motor
▼
Duct
▼
Frame
▲
Screws

TIP

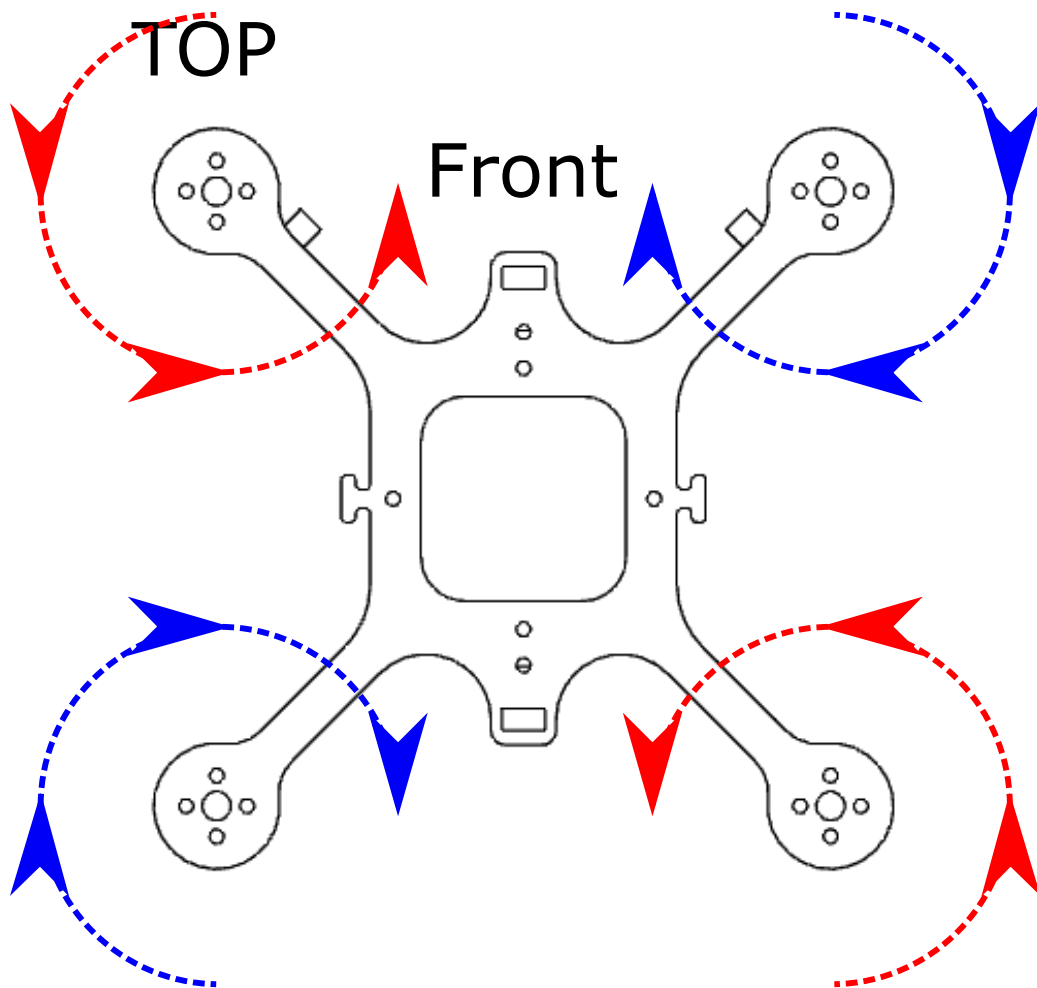
Use one screw to hold the parts together while adding the others.

Motor Layout

Layout:

To identify the clockwise and counterclockwise motors look for the motors wires that do not match these are the clockwise motors.

Arrange your motors as so:



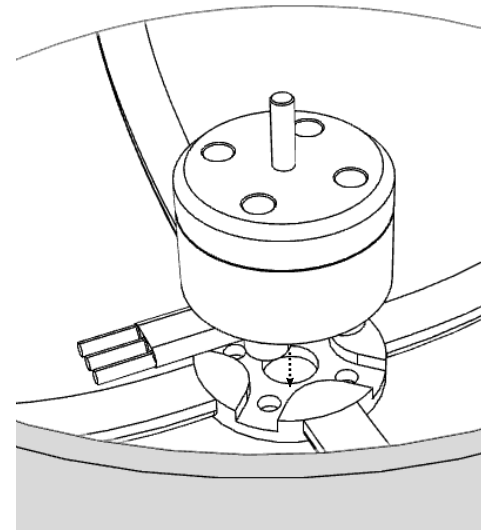
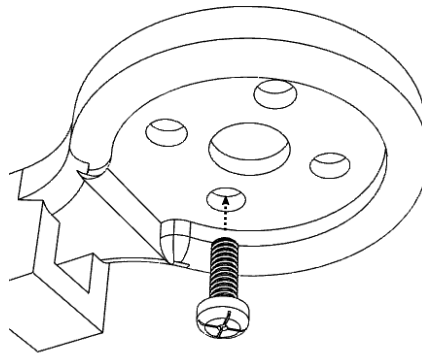
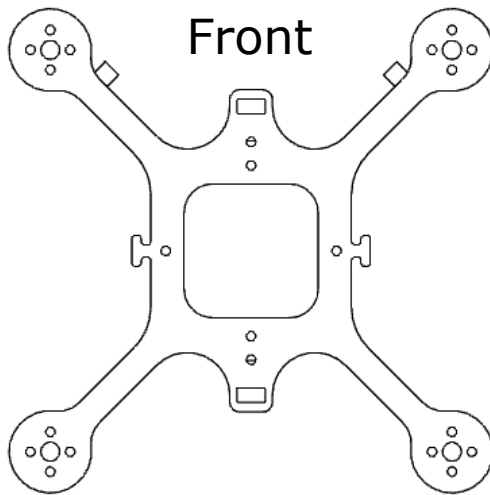
Motor Guide

Step 1:

Start with the front left motor
(SEE MOTOR LAYOUT)

Insert 1 screw through the bottom of the frame arm(The non-flat side).
Key the motor into the sunken part of the duct.

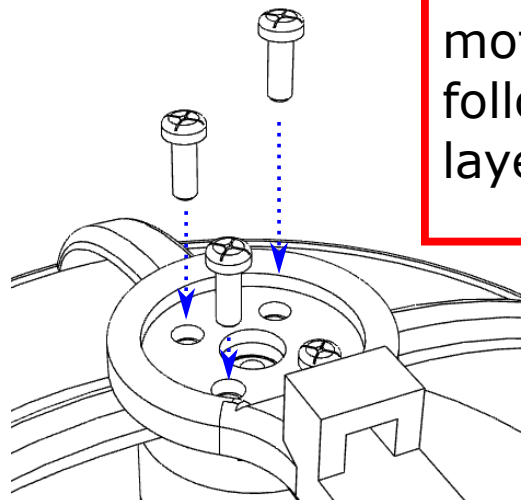
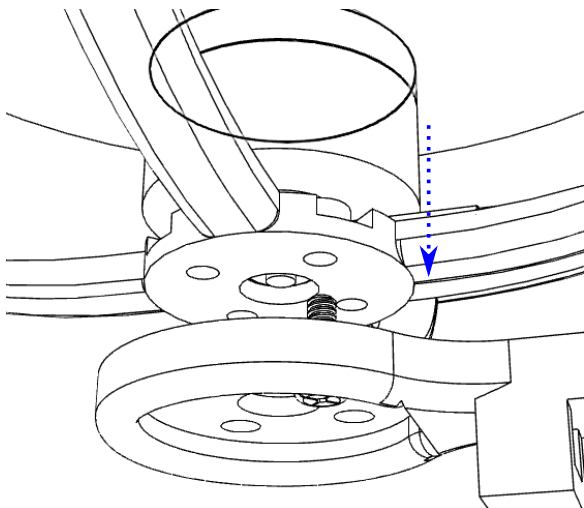
TOP



Step 2:

Place the motor and duct onto the drone frame.
Make sure that the motor wires are pointing towards
the middle of the drone. Bolt the screw into the motor.

Then bolt in the other 3 screws.



Repeat Process
for other
motors
following motor
layerout.