## HASH TABLES

## 1. Introduction

## 2. DICTIONARY DATA TYPE

**Definition 2.1.** Let  $\mathcal{X}$  be a set of *items* and let  $\mathcal{U}$  be a set of *keys*. Consider an abstract data type D which dynamically stores a collection of pairs (k, x) where  $k \in \mathcal{U}$  and  $x \in \mathcal{X}$  in such a way that D does not store two pairs having the same key at the same time. Moreover, we assume that D supports the following operations.

INSERT(D,(k,x))

Adds pair (k, x) into D if there is no other pair stored in D with k as a first entry.

DELETE(D,k)

Removes a pair with *k* as a first entry from *D* if such pair is stored in *D*.

SEARCH(D,k)

Returns x if a pair (k, x) is stored in D. Otherwise returns nil.

An abstract data type with these properties and interface is called *an associative array* or *a dictionary*.

**Definition 2.2.** Let  $\mathcal{X}$  and  $\mathcal{U}$  be sets. *Dictionary problem for*  $\mathcal{X}$  *and*  $\mathcal{U}$  is the task of designing a dictionary with  $\mathcal{X}$  as the set of items and  $\mathcal{U}$  as the set of keys.

## 3. HASH FUNCTIONS

In this section we introduce the important notion of a hash function and we discuss some probabilistic properties of it.

**Definition 3.1.** Let  $\mathcal{U}$  be a set. A hash function is a mapping  $h : \mathcal{U} \to \{0, 1, ..., m-1\}$  where  $m \in \mathbb{N}_+$ . Given a has function h a collision is a pair of keys  $k_1, k_2 \in \mathcal{U}$  such that  $k(k_1) = h(k_2)$ .

**Definition 3.2.** Let *X* be a set and let  $n \in \mathbb{N}_+$ . Then a set

$$X^{\wedge n} = \left\{ \left(x_1, ..., x_n\right) \in X^n \,\middle|\, \forall_{1 \leq i < j \leq n} \, x_i \neq x_j \right\}$$

is called *antisymmetric cartesian power of X*.

**Definition 3.3.** Let  $\mathcal{U}$  be a measurable space. We consider  $\mathcal{U}^{\wedge n}$  as the measurable subspace of a product space  $\mathcal{U}^n$ . Suppose that P is a probability distribution on  $\mathcal{U}^{\wedge n}$ . Let  $h: \mathcal{U} \to \{0, 1, ..., m-1\}$  be a hash function for some  $m \in \mathbb{N}_+$ . Suppose that

$$P(h(k_i) = h(k_j) \mid (k_1, ..., k_n) \in \mathcal{U}^{\wedge n}) = \frac{1}{m}$$

for every pair of distinct elements  $i, j \in \{1, ..., n\}$ . Then h is a simple uniform hashing with respect to P.

**Example 3.4.** Let  $\mathcal{U} = [0, m]$  for some  $m \in \mathbb{N}_+$ . Then  $\mathcal{U}$  is a measurable space with respect to Borel algebra  $\mathcal{B}([0, m])$ . We define a hash function  $h : \mathcal{U} \to \{0, 1, ..., m-1\}$  by formula

$$h(x) = |x|$$

Then h is a simple uniform hashing with respect to the normalization of n-dimensional Lebesgue measure on  $[0, m]^{\wedge n}$ .

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**Definition 3.5.** Let  $\mathcal{U}$  be a measurable space. We consider  $\mathcal{U}^{\wedge n}$  as the measurable subspace of a product space  $\mathcal{U}^n$ . Suppose that P is a probability distribution on  $\mathcal{U}^{\wedge n}$ . Let  $h: \mathcal{U} \to \{0, 1, ..., m-1\}$  be a hash function for some  $m \in \mathbb{N}_+$ . Fix a real number  $\epsilon > 0$  and suppose that

$$P(h(k_i) = h(k_j) | (k_1, ..., k_n) \in \mathcal{U}^{\wedge n}) = \frac{1}{m} + \epsilon$$

for every pair of distinct elements  $i, j \in \{1, ..., n\}$ . Then h is a simple  $\epsilon$ -uniform hashing with respect to P.

**Example 3.6.** Let  $\mathcal{U} = \{0, 1, ..., m^2 - 1\}$  for some  $m \in \mathbb{N}_+$ . Then  $\mathcal{U}$  is a measurable space with respect to the power algebra  $\mathcal{P}(\{0, 1, ..., m^2 - 1\})$ . Consider  $\mathcal{U}^{\wedge n}$  as a probability space with respect to distribution describing random sampling of n-elements without replacement from  $\mathcal{U}$ . We define a hash function  $h: \mathcal{U} \to \{0, 1, ..., m-1\}$  by formula

$$h(x) = x \mod m$$

where *m* is a divisor of *N*. Fix distinct  $i, j \in \{1, ..., n\}$  and note that

$$P(h(k_i) = h(k_j) | (k_1, ..., k_n) \in \mathcal{U}^{\wedge n}) = \frac{m}{m^2} = \frac{1}{m}$$

4. HASH TABLES WITH CHAINING AS A SOLUTION TO DICTIONARY PROBLEM

In this section we present the solution to the dictionary problem and discuss its efficiency.

**Definition 4.1.** Let  $\mathcal{U}$  and  $\mathcal{X}$  be sets. Let  $h: \mathcal{U} \to \{0, 1, ..., m-1\}$  be a hash function for some  $m \in \mathbb{N}_+$ . We consider an m-element array  $D_h$  such that  $D_h[i]$  is a linked list storing values from  $\mathcal{U} \times \mathcal{X}$  for every  $i \in \{0, 1, ..., m-1\}$ . We describe dictionary operations.

INSERT $(D_h, (k, x))$ 

Inserts pair (k, x) to the linked list  $D_h[h(k)]$  as its new head.

DELETE( $D_h, k$ )

Deletes a pair with first entry k from the linked list  $D_h[h(k)]$ .

 $SEARCH(D_h, k)$ 

Searches for the pair with the first entry k in the list  $D_h[h(k)]$ . If such pair is found, then returns its second entry. Otherwise returns nil.

Then  $D_h$  together with these operations is a solution of dictionary problem for  $\mathcal{U}$  and  $\mathcal{X}$ . We call it *the hash table with collisions resolved by chaining*.

For the sequel we need the notion of sampling without replacement.

**Definition 4.2.** Let  $(\Omega, \mathcal{F}, P)$  be a probability space and let  $\mathcal{U}$  be a measurable space. We fix a random variable  $\mathcal{K}: \Omega \to \mathcal{U}$  and consider independent and identically distributed random variables  $\mathcal{K}_1, ..., \mathcal{K}_n : \Omega \to \mathcal{U}$  for  $n \in \mathbb{N}_+$  with distributions identical to  $\mathcal{K}$ . Define

$$\Delta = \left\{ \left(k_1, ..., k_n\right) \in \mathcal{U}^n \,\middle|\, \forall_{i \neq j} \, k_i \neq k_j \right\}$$

Then  $(\mathcal{K}_1,...,\mathcal{K}_n): \Omega \to \mathcal{U}^n$  is a random variable which gives rise to a probability distribution on a measurable space  $\mathcal{U}^n$ . Hence it also gives rise to a probability distribution  $\mu_{\mathcal{K},n}$  on its subspace  $\mathcal{U}^n \setminus \Delta$ . Then  $\mu_{\mathcal{K},n}$  is the distribution of sampling without replacement with respect to  $\mathcal{K}$ .

**Definition 4.3.** Let  $n \in \mathbb{N}_+$  be the number of elements stored in D. Then  $\alpha = \frac{n}{m}$  is called *load factor*.

**Theorem 4.4.** Let  $\mathcal{U}$  be a measurable space and let  $\mathcal{X}$  be a set. Let  $h: \mathcal{U} \to \{0, 1, ..., m-1\}$  be a hash function for some  $m \in \mathbb{N}_+$ . Suppose that  $\mathcal{K}$  is a random variable with target  $\mathcal{U}$  such that h is a simple uniform hashing with respect to  $\mathcal{K}$ . For a sequence of keys chosen randomly according to distribution  $\mu_{\mathcal{K},n}$  and stored in the hash table  $D_h$  the expected time of an unsuccessful search is  $\Theta(\frac{n}{m})$ .

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Proof.  $\Box$