AI Planning for Autonomy

Problem Set III: Choosing Heuristics

1. Consider a $m \times m$ manhattan grid, and a set of coordinates V to visit in any order, and a set of inaccessible coordinates (walls) W.

Using the state space below:

$$S = \{\langle x, y, v \rangle | x, y \in [0..m] \land v \subseteq V\}$$

$$S_0 = \langle 0, 0, V \rangle$$

$$A(\langle x, y, v \rangle) = \{\langle dx, dy \rangle | dx, dy \in \{-1, 0, 1\}\}$$

$$\wedge |dx| + |dy| = 1$$

$$\wedge \langle x + dx, y + dy \notin W \}$$

$$t(\langle dx, dy \rangle, \langle x, y, v \rangle) = \langle x + dx, y + dy,$$

$$v - \{\langle x + dx, y + dy \rangle\} \rangle$$

$$c(a, s) = 1$$

$$G = \{\langle x, y, v \rangle | \langle x, y, v \rangle \in S \land v = \emptyset\}$$

- Explain the meaning of x, y and v in each state $s \in S$
- Define 3 different heuristics for this problem.
- Which of your heuristics is admissible? consistent? dominates the others?
- Estimate the complexity of calculating each of your heuristics.
- Which would you use in A*? Why?
- 2. Reformulate the state-model from Q1 as a STRIPS problem $P = \langle F, O, I, G \rangle$.
- 3. Write pseudo code for the following search algorithms:

 Feel free to implement these in python in the appropriate places in search.py for assignment 1.
 - Breadth First
 - Depth First
 - A Star
 - Uniform Cost



