

ELECTRICAL PARAMETER	
NUMBER OF PHASE	2
BASIC STEP ANGLE	1.8°±5%
RATED CURRENT(PHASE)	6.4A
RESISTANCE(PHASE) @25°C	0.8Ω±0.15Ω
INDUCTANCE(PHASE) @1kHz 1Vrms	7.3mH±20%
HOLDING TORQUE	12.8Nm±15% [113.3lb-in] NOTE)1.
ROTOR INERTIA	APPROX 4000g.cm²
WEIGHT	APPROX 5.6kg
DIELECTRIC STRENGTH	500V A.C 1 MINUTE
INSULATION RESISTANCE	100MΩ MIN.
INSULATION CLASS(UL)	B (130°C) [266°F]
TEMPERATURE RISE	80K MAX. NOTE)2.
OPERATION AMBIENT TEMPERATURE	-20°C ~ +50°C [-4°F ~ 122°F]
OPERATION AMBIENT HUMIDITY	15%RH ~ 95%RH

NOTE) :
 1.AT RATED CURRENT,TWO PHASE ON.
 2.MEASURED BY RESISTANCE METHOD.MOUNT WITH ALUMINUM HEAT SINK 258*258*T5
 AT TWO WINDING BE EXCITED BY RATED VOLTAGE,0PPS,2PHASE ON.

2 PHASE SEQUENCE(FULL STEP)
VIEW FROM MOUTING SIDE (CW/CCW)

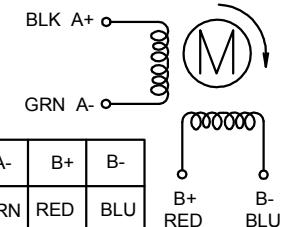
CW	STEP	A+	B+	A-	B-
	1	+	+	—	—
	2	—	+	+	—
	3	—	—	+	+
	4	+	—	—	+
	5	+	+	—	—
	6	—	+	+	—

↑
↓
CCW

ENCODER SPECIFICATIONS

INPUT VOLTAGE	DC 5V
OUTPUT WAVE	SQUARE WAVE
OUTPUT SIGNAL	CHA CHB
OUTPUT SIGNAL VOLTAGE	DC 5V
ENCODER RESOLUTION	1000 CPR/PHASE

MOTOR WIRING DIAGRAM



MOTOR LEAD	A+	A-	B+	B-
LEAD COLOR	BLK	GRN	RED	BLU

ENCODER LEAD	VCC	GND	PA+	PA-	PB+	PB-
LEAD COLOR	RED	BLK	BLU	BLU	GRN	GRN

MODEL
86HBD5401-37K5Ø14EN

TOLERANCE	±0.3±3°	REV.	DATE	REVISIONS		BY
				SCALE	1:1	
DRAWN						CLOSED LOOP STEPPER MOTOR SPECIFICATION
DESIGNED						YEJMKJ
CHECKED						
						FIRST ANGLE PROJECTION
						SHEET 1/1

Product characteristics

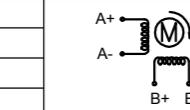
- Unique algorithm, low heat, large torque
- Voltage range: AC18~AC80V/DC18~DC110V
- 16 sub-division, can be customized according to customer requirements
- Signal input 5~24V compatible, no external series resistance required
- Maximum response frequency 400KHZ
- The torque attenuation is small, the maximum speed can reach 3000rmp
- External alarm and in place output port, convenient monitoring and control
- Intelligent current regulation reduces power consumption at low loads and increases torque at high loads
- The effective current can be set through the dip switch to adapt to different motors
- Dip switch set single and double pulse, factory default pulse + direction control
- Dip switch set pulse delay, factory default 40ms
- Excellent high-speed performance and rigidity, perfect integration of servo and stepper advantages in one.

Typical application

Mainly used in engraving machine, special industrial sewing machine, stripping machine, marking machine, cutting machine, laser phototypesetting, plotter, CNC machine tools, dispensing machine, screw machine and other automation equipment and instruments

Indicator Light and Interface Description

Marker Symbols	Function	Notes
PWR/FLT	Voltage and fault indicator light	Green light flashes: the driver is normal and no pulse signal is received; green light is always on: the pulse signal is received and the motor is rotating; one red and one green: overcurrent or phase short circuit fault; two red and one green: the motor is not detected or the motor wiring is wrong; three red and one green: overvoltage fault; four red and one green: undervoltage fault; five red and one green: tracking error out of tolerance fault.
PUL+	Pulse input signal photoelectric isolation positive end	Pulse signal voltage 3.3~24V can be driven
PUL-	Pulse input signal photoelectric isolation negative end	The falling edge is effective, every time the pulse changes from high to low, the motor moves one step, and the pulse width is greater than 2.5 microseconds
DIR +	Direction input signal photoelectric isolation positive end	Direction signal voltage 3.3~24V can be driven
DIR-	Direction input signal photoelectric isolation negative end	Used to change the direction of the motor. The falling edge is effective. Every time the pulse changes from high to low, the motor moves one step. The pulse width is greater than 2.5 microseconds.
EN+	Enable input signal photoelectric isolation positive end	Enable signal voltage 3.3~24V can be driven
EN-	Enable input signal photoelectric isolation negative end	When effective (low level), the motor coil current is turned off, the motor is in a free state and the alarm signal is cleared
EX+	In-position signal output positive end	When the driver completes the given pulse, the arrival signal is valid (output light is turned on). EX+ is connected to 24V+, EX- is connected to the PLC input port, and the maximum drive current is 10mA
EX-	In-position signal output negative end	
ALM+	Alarm signal output positive end	When the red light flashes, the alarm signal is valid (output light is on, normally open by default). ALM+ connects to 24V+, ALM- connects to PLC input port, maximum drive current 10mA
ALM-	Alarm signal output negative end	
VCC	Encoder power supply positive	Encoder 5V power supply positive terminal
EGND	Encoder power supply ground	Encoder power supply ground
EB+	Encoder B phase input positive end	Connect to encoder B channel positive input
EB-	Encoder B phase input negative end	Connect to encoder B channel negative input
EA+	Encoder A phase input positive end	Connect to encoder A channel positive input
EA-	Encoder A phase input negative end	Connect to encoder A channel negative input
V-	Driver power supply negative end	Driver power supply negative
V+	Driver power supply positive end	Voltage range: AC18~AC80V/DC18~DC110V
A+	Motor wiring A+	
A-	Motor wiring A-	
B+	Motor wiring B+	
B-	Motor wiring B-	



Performance Indicators

1.Electrical Specifications

illustrate	704-0042-00(BH86)			
	Minimum	Typical Value	Maximum	unit
Output current (peak)	2.2	-	6	A
Supply voltage	18	60	110	VAC
	18	60	160	VDC
Control signal current	5	10	20	mA
Step pulse frequency	0	-	300	KHz
Step pulse width	2	-	-	us
Direction signal width	100	-	-	us
Undervoltage protection point	-	7.5	-	VDC
Oversupply protection point	-	170	-	VDC
Insulation resistance	500	-	-	MΩ

2.Environmental indicators

Cooling method	Natural cooling or forced air cooling
occasion	Do not place it near other heating equipment. Avoid dust, oil, corrosive gas, high humidity and strong vibration. Do not
Usage Environment	temperature 0~+50°C
humidity	40~90%RH
vibration	10~55Hz/0.15mm
Storage temperature	-20°C~65°C
weight	470g

Dial setting

Number of subdivisions	2	4	8	16	32	64	128	256	5	10	20	25	40	50	100	200
Pulse/rev	400	800	1600	3200	6400	12800	25600	51200	1000	2000	4000	5000	8000	10000	20000	40000
SW1	ON	OFF	ON	OFF	ON	OFF	ON	OFF	ON	OFF	ON	OFF	ON	OFF	ON	OFF
SW2	ON	ON	OFF	OFF	ON	ON	OFF	OFF	ON	ON	OFF	OFF	ON	ON	OFF	OFF
SW3	ON	ON	ON	ON	OFF	OFF	OFF	OFF	ON	ON	ON	ON	OFF	OFF	OFF	OFF
SW4	ON	ON	ON	ON	ON	ON	ON	ON	ON	ON	OFF	OFF	OFF	OFF	OFF	OFF

SW5:Motor rotation direction setting

OFF = Clockwise ON=Counterclockwise

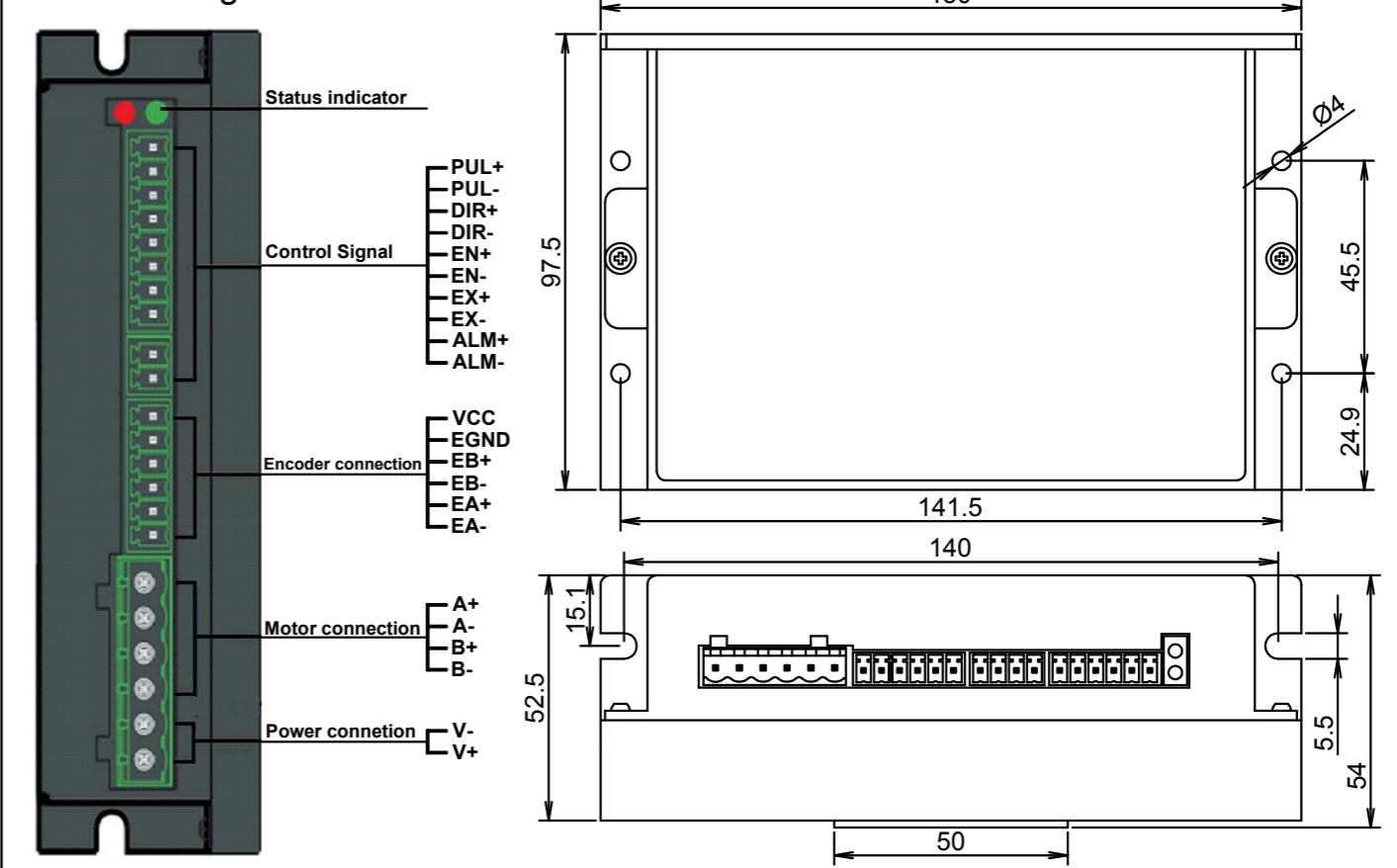
SW6:Single and double pulse setting

OFF=Pulse+Direction ON=Double Pulse

SW7,SW8Pulse delay setting

Pulse Delay(ms)	0	4	20	40
SW7	ON	OFF	ON	OFF
SW8	ON	ON	OFF	OFF

Product Diagram



CLOSED LOOP STEPPER DRIVER

MODEL BH86

DWG NO. 704-0042-00

YEJMKJ